## TU Delft

## BACHELOR END PROJECT

# The Random Energy Model for Compact Heteropolymer Folding

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## Abstract

In this thesis, the Random Energy Model (REM) is applied to the highly complex problem of random heteropolymer folding. The relevance of the REM lies in the fact that it is an analytically solvable model, which makes it possible to learn more about the (thermodynamical) behaviour of folding proteins.

Firstly, a rigorous proof of the existence of a critical point in the REM with non-zero mean is presented. The mathematical properties of the REM with non-zero mean are used to derive the thermodynamical properties of this special case of the REM, such as the free energy. In the second part of this thesis, applications of the model to folding polymers are investigated and a simple simulation of protein folding using the REM is suggested. It turns out that this simulation is barely useful, so a more realistic version of the REM for polymer folding is suggested.

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## Chapter 1

## Introduction

The folding of heteropolymers is one of the most crucial biological processes within the human body. For instance, our DNA consists of long chains of polymers that are folded in extremely dense configurations, and are partially unfolded for DNA replication. Interactions between proteins - a kind of heteropolymers - guide many processes in the cell, such as proliferation (cell growth) and differentiation (changing cell type)[1]. For example, many allergies are caused by a misfolding of certain polymers, as the human immune system produces antibodies only for certain protein structures[2]. The folding of heteropolymers is a complex process that is not fully understood and existing models require much computing time. In this thesis, an analytically solvable model is applied to the problem of protein folding. This model has its origin in the field of spin glasses and is called the Random Energy Model.

In this introduction chapter, we begin with a brief summary of the theory of spin glasses. We try to explain the origin and relevance of the Random Energy Model and describe the system we want to apply the theory to.

## 1.1 Spin glasses and the Random Energy Model

In 1980, the Random Energy Model (REM) was created by Bernard Derrida[3] as a simple toy model to try to understand the behaviour of disordered systems. This model later became widely accepted in the field of spin glasses.[4]

The field of spin glass theory has its origin in the attempt to describe the behaviour of glass and systems with a glasslike build-up. The difficulty in describing such a system lies in the way glasslike materials are built up. At first sight, these kind of materials seem to be ordered in patterns on the microscopic scale, but they turn out to be fairly unstructured. This will be further explained in the next chapter. The lack of symmetry of glass leads to many mathematical complications in trying to describe a glasslike system deterministically. Therefore, the REM describes the system stochastically.

#### 1.1.1 Description and relevance of the original model

In the original paper of Derrida, a very simple form of the Random Energy Model was formulated. The model consisted of a set of N spins that can either be spin up or spin down. The energy of each of the spins is described in terms of the Hamiltonian. The Hamiltonian[5] of each spin is not correlated with the state of the others, but is driven with a centred Gaussian distribution. We will go into the details of this model later, but for now it is enough to observe the relative simplicity of the model. Despite this simplicity, Derrida was able to show the existence of a phase transition - a sudden change in behaviour - in this model. That is, there exists a certain critical point (for instance a critical temperature) at which some properties (for example the free energy) of the system change drastically.

It can be claimed [6] that the REM is the simplest statistical physics model of a disordered system which exhibits a phase transition. The relevance of the REM lies in the existence of this phase transition, which is useful in many different contexts. Most obviously, the REM is used as a toy model to study mathematical and physical properties of disordered systems, and is in some cases good enough to represent an actual system [7]. However, there are applications besides of that as well. For instance, the REM was used to model number partitioning in the field of stochastic optimization [8]. That is, given n numbers  $X_1, ..., X_n$  drawn i.i.d. from some distribution, one is asked to find the partition into two subsets such that the sum of the numbers in one subset is as close as possible to the sum of the numbers in the other set.

## 1.2 Application

In this report, we will adjust the REM in such a way that it is applicable to describe the behaviour of folding compact heteropolymers[9], like proteins. As mentioned before, this is a difficult process that is very relevant in chemistry and nanobiology, for example to study the structure of DNA. Due to the complexity of these polymers, it is hard to quantify the way heteropolymers structure and the REM can help to gain more insight in this problem, as it can be studied analytically. However, the regular REM is hard to implement in the context of folding polymers, as it is centred around states with zero energy[10]. Therefore, we will have to study a REM with a non-zero mean in the rest of this report.

## Chapter 2

# The original REM

In this chapter, we take a closer look to the original Random Energy Model of Derrida. The model will be quantified, different properties will be studied and a few useful results that are already known for this model will be stated. Furthermore, we will introduce some relevant lemmas and definitions.

## 2.1 Quantification of the original model

The REM stated in the first chapter will now be fully characterized as a standard statistical mechanics model, which is usually defined by a set of configurations and an energy function defined on this space. In our model, the set of the possible spins is called the state space  $S_N = \{-1, +1\}^N$ . This set consist of N different elements on a lattice which can be either spin up or spin down. The number of possible configurations now is  $2^N$  and the space looks similar to Figure 2.1.

Note that the spacing between the spin elements is periodic. This is different to the build-up of glasslike materials on the atomic scale, as shown in Figure 2.2. It is clear from this Figure that the structure of glass is only seemingly symmetric: there is some kind of pattern, but we can not recognize any symmetries. These kind of systems are sometimes called quasi-symmetric. To understand why the REM can describe such a quasi-symmetric system, a slight change of view should be made. Instead of considering the atoms to be located randomly according to each other (which is the case in a glasslike material), the energies of the different components are taken to be random and the locations to be periodic in the REM. This approach essentially leads to the same properties, but has mathematical advantages.

The energy in our system will be fully determined by the Hamiltonian, which has the following form:

$$H_N(\sigma) = \sum_{i=1}^{N} E_i \sigma_i \tag{2.1}$$

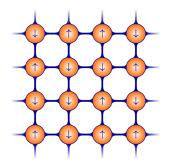


Figure 2.1: State space with spins up and down

Figure 2.2: Glasslike structure

where  $E_i$  are i.i.d. standard normal random variables and  $\sigma_i \in S_N$ . So, every spot on the lattice contributes a random energy  $E_i$  multiplied by a  $\sigma_i \in \{+1, -1\}$  to the Hamiltonian. Note that for large N the sum of Gaussian variables is Gaussian again, so the Hamiltonian in the REM is a Gaussian.

### 2.2 Free energy, the partition function

To study the properties of statistical physics models, a few concepts should be known, first of which is the partition function Z. We can define this function as[11]:

$$Z_N = \sum_{\sigma \in S_N} e^{-\beta H_N(\sigma)}$$

where  $\beta = \frac{1}{k_B T}$  is a parameter  $\geq 0$  representing the inverse temperature (up to the Boltzmann constant). The partition function can be used to measure the (Gibbs) probability of the system to be in a certain state[12]:

$$\mathbb{P}(\sigma) = \frac{1}{Z_N} e^{-\beta H_N(\sigma)} \tag{2.2}$$

Note that the probability in (2.2) is a stochastic variable itself. One could say that the REM contains two different layers of randomness.

Furthermore, the partition function can be used to compute the free energy  $F_N$ :

$$F_N = -\frac{1}{\beta} \ln Z_N$$

This free energy is the total energy needed to create the system at a temperature T, minus the heat you can get 'for free' from an environment at T. It is convenient to look at a quantity f that is very much alike the free energy (we will call it the free energy density[12]):

$$f = \frac{1}{N} \ln Z_N$$

As claimed before, this quantity exhibits a phase transition (for example: see Bovier[7]). The computation gives the following important result. Note the dramatic change in free energy at the critical point  $\beta_c$ .

**Theorem 1.** In the REM as described above <sup>1</sup>

$$Lim_{N\to\infty}\mathbb{E}(f) = \begin{cases} \frac{\beta^2}{2}, & \text{if } \beta \le \beta_c\\ \frac{\beta^2}{2} + (\beta - \beta_c)\beta_c, & \text{if } \beta \ge \beta_c \end{cases}$$
 (2.3)

where  $\beta_c = \sqrt{2 \ln 2}$ .

### 2.3 Entropy, density of states

Another important concept from statistical physics is the density of states  $\Omega$ , which represents the number of ways arranging things in the system. If we call the total number of states in the system  $g'_N$ , then the density of states is just that number multiplied by the probability distribution function:

$$\Omega(E) = g'_N p(E)$$

From this we can calculate the entropy S of the system:

$$S(E) = k_B \ln \Omega(E) \tag{2.4}$$

This quantity has a few interesting physical properties. Entropy and temperature are linked via  $T^{-1} = dS/dE$ . Temperature is always positive, so dS/dE > 0. Furthermore, the entropy can never be negative.

#### 2.4 Useful theorems and definitions

In the next chapter, we will go deeper into the mathematical structure behind the phase transition of the REM. To do so, we need some definitions and theorems from statistics. The first two are standard.

Markov's inequality: For any non-negative random variable X:  $\mathbb{P}(X \geq t) \leq \frac{\mathbb{E}(X)}{t}$  for t > 0.

Chebyshev's inequality: For any random variable Y with  $\mathbb{E}(Y) < \infty$ :  $\mathbb{P}(|Y| \ge t) \le \frac{1}{t^2} \mathbb{E}(Y^2)$ .

The most important lemmas for the next chapter are those of Borel-Cantelli and Varadhan. The lemma of Borel-Cantelli is useful for proving a statement to be almost sure. Almost sure convergence is a strong convergence of a sequence of random variables and is widely used in

<sup>&</sup>lt;sup>1</sup>That is: using the Hamiltonian with i.i.d. standard normal energies as described in equation (2.1) and the state space  $S_N$ .

probability theory. We say that the sequence  $(X_n, n \ge 1)$  converges almost surely to X if  $\mathbb{P}(\{\omega \in \Omega : Lim_{n\to\infty}X_n(\omega) = X(\omega)\}) = 1$ . It is more common to state the Borel-Cantelli lemma reversed, so for an event to happen almost surely not (probability 0)[13].

Borel-Cantelli lemma: Let  $E_1, E_2, ...$  be a sequence of events in some probability space. If  $\sum_{n=1}^{\infty} \mathbb{P}(E_n) < \infty$ , then  $\mathbb{P}(\limsup_{n \to \infty} E_n) = \mathbb{P}(\bigcap_{n=1}^{\infty} \bigcup_{k \ge n}^{\infty} E_k) = 0$ 

Varadhan's lemma requires a function with large deviation properties, so we have to introduce these first. Large deviations have to do with the asymptotic behaviour of remote tails of sequences of probability distributions and are closely linked to disordered systems. Therefore we will use them later in this thesis. To get a feeling about what a *large* deviation is, we formulate the central limit theorem in the following way[14]:

Central Limit Theorem Let  $X_1, X_2, ...$  be i.i.d. random variables. Let  $\mathbb{E}(X_1) = \mu$ ,  $\mathrm{Var}(X_1) = \sigma^2$  and  $S_n = X_1 + ... + X_n$ . Then:

$$\frac{1}{\sigma\sqrt{n}}(S_n - \mu n) \xrightarrow[n \to \infty]{} Z$$

Where Z is a standard normal random variable.

We see that the CLT quantifies the probability that  $S_n$  and  $\mu n$  differ an amount of order  $\sqrt{n}$ . When we speak about large deviations, we mean differences or order n. This means the deviations we talk about are indeed *large*.

We now state a few definitions on large deviations:

**Definition 1.** A function I is called lower semi-continuous[15] if  $\forall l \geq 0$  the sets  $\{x : I(x) \leq l\}$  are closed for x in the domain of I.

**Definition 2.** A function  $I: X \to [0, \infty]$  is called a rate function [16] if it is lower semi-continuous

**Definition 3.** A rate function  $I: X \to [0, \infty]$  is called a good rate function[16] if  $\{x: I(x) \le l\}$  is compact in  $X \ \forall l < \infty$ .

**Definition 4.** Let I be a rate function on X,  $(\gamma_n)$  a sequence with  $\gamma_n \to \infty$  on X and  $(\mu_n)$  a sequence of probability measures on X. We say that  $(\mu_n)$  satisfies a large deviation principle[16] (LDP) with rate I and speed  $\gamma_n$ , if:

- 1. For all open sets  $O \subset X$  we have  $\liminf_{(n)} \frac{1}{\gamma_n} \ln \mu_n(O) \ge -\inf_{x \in O} I(x)$ .
- 2. For all closed sets  $C \subset X$  we have  $\limsup_{n \to \infty} \frac{1}{\gamma_n} \ln \mu_n(C) \ge -\inf_{x \in C} I(x)$

Varadhan's lemma states a useful property of a function that satisfies a LPD. We will use this lemma in the next chapter.

Varadhan's lemma[17]: Suppose  $P_N$  satisfies a LDP with rate function I. If  $F:\chi\to\mathbb{R}$  is continuous and bounded above, then  $\lim_{N\to\infty}\frac{1}{N}\ln\int_\chi e^{NF(x)}\,\mathrm{d}P_N(x)=\sup_{(x\in\chi)}(F(x)-I(x)).$ 

## Chapter 3

# Adding a mean

In this chapter, a minor modification of the Random Energy Model is studied. Instead of a Gaussian distribution centred around zero, we will look at the properties of the REM with Gaussian distributed variables around a non-zero mean. This means that the random energies as described in the Hamiltonian in (2.1) are shifted. This leads to a new (and more general) version of the model described in the previous chapter, so we want to explore what effect adding a mean has on the free energy. Our goal is to find out whether or not the phase transition in the model mentioned before still remains. If so, the new model could be applicable in the context of heteropolymers.

### 3.1 Define model

The basic setup is equivalent to the normal REM as described in the introductory chapter. We still define a spin system with independently distributed random variables, but we will add a mean  $\mu$  (and a less important variance term  $J^2$ ). All  $X_{\sigma}$ 's have the following probability density:

$$p_N(E) = \frac{1}{\sqrt{2\pi J^2 N}} e^{-(E-N\mu)^2/(2NJ^2)}$$
(3.1)

And we define for any given set of energies  $\{E_i\}$  the distribution function  $F_N$  by:

$$F_N(x) = \frac{1}{2^N} \#\{i : E_i \le xN\}$$
 (3.2)

Where # counts the number of elements in the set. Note that  $F_N$  is random itself, so we have 'two layers of randomness'. We can write the partition function  $Z_N(\beta) = \sum_{i=1}^{2^N} e^{-\beta E_i}$  as:

$$Z_N(\beta) = 2^N \int_{-\infty}^{\infty} e^{-N\beta x} \, \mathrm{d}F_N(x)$$

We can define the free energy density of the system as:

$$f(\beta) = -\frac{1}{\beta N} \ln Z_N(\beta) \tag{3.3}$$

## 3.2 Large deviation properties

We want to show that these distribution functions satisfy a large deviation property and that there exists a certain critical value  $x_c$  at which a sudden change in behaviour occurs. We describe the system for values smaller and larger than this  $x_c$ . The proof will follow a similar approach as that of T.C. Dorlas[18], but with a nonzero mean added.

### 3.2.1 $|x| > x_c$

**Lemma 1.** For  $|x| > x_c = J\sqrt{2 \ln 2} + \mu$ :  $\limsup_{N \to \infty} \frac{1}{N} \ln(1 - F_N(x)) = -\infty$ 

Proof. First, consider:

$$1 - F_N(x) = \frac{2^N}{2^N} - \frac{\sum_{i=1}^{2^N} \mathbb{1}_{\{E_i \le xN\}}}{2^N} = \frac{1}{2^N} \sum_{i=1}^{2^N} \mathbb{1}_{\{E_i > xN\}}$$

Therefore:

$$\{\{E_i\}: F_N(x) = 1\} = \{\{E_i\}: \sum_{i=1}^{2^N} \mathbb{1}_{\{E_i > xN\}} = 0\}$$

But every  $\mathbb{1}_{\{E_i>xN\}}$  gives either 0 or 1, so equivalently:

$$\{\{E_i\}: F_N(x) = 1\} = \{\{E_i\}: \sum_{i=1}^{2^N} \mathbb{1}_{\{E_i > xN\}} < 1\}$$

Introduce  $A_N := \{ \{E_i\} : \sum_{i=1}^{2^N} \mathbb{1}_{\{E_i > xN\}} \ge 1 \}$ . To be able to use the Borel-Cantelli lemma, we want to show that:

$$\sum_{N=1}^{\infty} \mathbb{P}(A_N) < \infty \tag{3.4}$$

Noticing that  $\sum_{i=1}^{2^N} \mathbb{1}_{\{E_i > xN\}} \ge 0$ , Markov's inequality implies:

$$\mathbb{P}(A_N) = \mathbb{P}\{\sum_{i=1}^{2^N} \mathbb{1}_{\{E_i > xN\}} \ge 1\} \le \mathbb{E}\{\sum_{i=1}^{2^N} \mathbb{1}_{\{E_i > xN\}}\}$$

$$= 2^{N} \mathbb{P} \{ E_{i} > xN \} = 2^{N} \int_{xN}^{\infty} p_{N}(E) dE$$
$$= \frac{2^{N}}{\sqrt{2\pi J^{2} N}} \int_{xN}^{\infty} e^{-(E-N\mu)^{2}/(2NJ^{2})} dE$$

We consider two cases, the first of which is  $x > \mu$ . We first change the boundaries of the integral.

$$\frac{2^N}{\sqrt{2\pi J^2 N}} \int_{xN}^{\infty} e^{-(E-N\mu)^2/(2NJ^2)} dE = \frac{2^N}{\sqrt{2\pi J^2 N}} \int_{(x-\mu)N}^{\infty} e^{-E^2/(2NJ^2)} dE$$
 (3.5)

Within the boundaries of this integral we see that:  $E \ge (x - \mu)N$ , thus  $\frac{E}{N(x-\mu)} \ge 1$  (where we used that  $x > \mu$ ) and we obtain:

$$\frac{2^N}{\sqrt{2\pi J^2 N}} \int_{(x-\mu)N}^{\infty} e^{-E^2/(2NJ^2)} dE \le \frac{2^N}{\sqrt{2\pi J^2 N}} \int_{(x-\mu)N}^{\infty} \frac{E}{(x-\mu)N} e^{-E^2/(2NJ^2)} dE$$

$$= \frac{2^N}{\sqrt{2\pi J^2 N}} \frac{J^2}{x-\mu} e^{-(x-\mu)^2 N/2J^2} = \frac{2^N}{\sqrt{2\pi N}} \frac{J}{x-\mu} e^{-(x-\mu)^2 N/2J^2}$$

In short, for  $x > \mu$ :

$$\frac{2^N}{\sqrt{2\pi J^2 N}} \int_{(x-\mu)N}^{\infty} e^{-E^2/(2NJ^2)} dE \le \frac{2^N}{\sqrt{2\pi N}} \frac{J}{x-\mu} e^{-(x-\mu)^2 N/2J^2}$$
(3.6)

We now consider the case where  $x \leq \mu$ . Equation (3.5) still holds, but now  $x - \mu \leq 0$ . We split the integral in two parts:

$$\frac{2^N}{\sqrt{2\pi J^2 N}} \int_{(x-\mu)N}^{\infty} e^{-E^2/(2NJ^2)} dE = \frac{2^N}{\sqrt{2\pi J^2 N}} \left( \int_{(x-\mu)N}^{0} e^{-E^2/(2NJ^2)} dE + \int_{0}^{\infty} e^{-E^2/(2NJ^2)} dE \right)$$

The second integral is just a normal distribution over a half-infinite interval, so we can say that this is integral is no larger than  $\frac{1}{2}$  (it even is  $\frac{1}{2}$ ). Within the boundaries of the first integral we see that:  $0 \ge E \ge (x - \mu)N$ , thus  $\frac{E}{N(x-\mu)} \ge 1$  and we obtain a similar upper bound as before:

$$\int_{(x-\mu)N}^{0} e^{-E^2/(2NJ^2)} dE \le \int_{(x-\mu)N}^{0} \frac{E}{N(x-\mu)} e^{-E^2/(2NJ^2)} dE = \frac{J^2}{x-\mu} [e^{-(x-\mu)^2 N/2J^2} - 1]$$

This gives:

$$\int_{(x-\mu)N}^{\infty} e^{-E^2/(2NJ^2)} dE \le \left(\frac{J^2}{x-\mu} e^{-(x-\mu)^2 N/2J^2} - 1\right) + 1/2$$

And so:

$$\frac{2^N}{\sqrt{2\pi J^2 N}} \int_{(x-\mu)N}^{\infty} e^{-E^2/(2NJ^2)} \, \mathrm{d}E \leq \frac{2^N}{\sqrt{2\pi J^2 N}} [(\frac{J^2}{x-\mu} e^{-(x-\mu)^2 N/2J^2} - 1) + 1/2]$$

$$= \frac{2^N}{\sqrt{2\pi J^2 N}} \left[ \frac{J^2}{x - \mu} e^{-(x - \mu)^2 N/2J^2} - 1/2 \right]$$

Thus for  $x < \mu$ :

$$\frac{2^N}{\sqrt{2\pi J^2 N}} \int_{(x-\mu)N}^{\infty} e^{-E^2/(2NJ^2)} dE \le \frac{2^N}{\sqrt{2\pi J^2 N}} \left[ \frac{J^2}{x-\mu} e^{-(x-\mu)^2 N/2J^2} - 1/2 \right]$$
(3.7)

So in both cases it is true that (see equations (3.6) and (3.7)):

$$\mathbb{P}(A_N) \le \frac{2^N}{\sqrt{2\pi J^2 N}} \int_{xN}^{\infty} e^{-(E-N\mu)^2/(2NJ^2)} \, \mathrm{d}E \le \frac{2^N}{\sqrt{2\pi N}} \frac{J}{x-\mu} e^{-(x-\mu)^2 N/2J^2}$$
(3.8)

We assumed that  $|x| > x_c = J\sqrt{2 \ln 2} + \mu$ , so  $\frac{(x-\mu)^2}{2J^2} > \ln 2$ . Furthermore, the following series converges to a value c:

$$\sum_{N=1}^{\infty} \frac{J}{\tilde{x}\sqrt{2\pi N}} e^{N(\ln 2 - \tilde{x}^2/(2J^2))} \to c \tag{3.9}$$

Noticing that  $e^{N \ln 2} = 2^N$  we obtain by equation (3.9) (replacing  $\tilde{x} = x - \mu$ ):

$$\sum_{N=1}^{\infty} \frac{\tilde{J}}{\tilde{x}\sqrt{2\pi N}} e^{N(\ln 2 - \tilde{x}^2/(2J^2))} = \sum_{N=1}^{\infty} 2^N \frac{2J^2}{(x-\mu)\sqrt{2\pi N}} e^{-N(x-\mu)^2/(2J^2)} \ge \sum_{N=1}^{\infty} \mathbb{P}(A_N) \quad (3.10)$$

This proves equation (3.4). By the Borel-Cantelli lemma:

$$\mathbb{P}[\bigcap_{k=1}^{\infty} \bigcup_{N=k}^{\infty} A_N] = 0$$

But then:

$$1 = \mathbb{P}[\{\bigcap_{k=1}^{\infty} \bigcup_{N=k}^{\infty} A_N\}^c] = \mathbb{P}[\{E_i\} \in \{\bigcap_{k=1}^{\infty} \bigcup_{N=k}^{\infty} A_N\}^c] = \mathbb{P}[\{E_i\} \in \bigcap_{k=1}^{\infty} \bigcup_{N=k}^{\infty} A_N^c]$$

So  $\{E_i\} \in \bigcap_{k=1}^{\infty} \bigcup_{N=k}^{\infty} A_N^c$  almost surely for all i. This means that:

$$\forall i \exists k \in \mathbb{N} : \forall N \ge k : \{E_i\} \in A_N^c$$

But:

$${E_i} \in A_N^c \implies {E_i} \in {\{E_i\} : \frac{1}{2^N} \sum_{i=1}^{2^N} \mathbb{1}_{\{E_i > (x+\mu)N\} < 1\}}} = {\{E_i\} : F_N(x) = 1\}}$$

So almost surely for  $|x| > x_c$ :  $\{E_i\} \in \{\{E_i\} : F_N(x) = 1\}$ . This proves the lemma:

$$\limsup_{N \to \infty} \frac{1}{N} \ln(1 - F_N(x)) = \lim_{x \to 1} \ln(1 - x) = -\infty, a.s.$$

3.2.2  $|x| < x_c$ 

**Lemma 2.** For 
$$0 < |x| < x_c$$
:  $\lim_{N \to \infty} \frac{1}{N} \ln(1 - F_N(x)) = -\frac{(x-\mu)^2}{2J^2}$ 

*Proof.* Let  $G_N$  be the scaled distribution function to the density  $p_N$ :

$$G_N(x) = \int_{-\infty}^{xN} p_N(E) dE$$
(3.11)

Then, by Chebyshev's inequality, for  $\epsilon \in (0, 1)$ :

$$P[|G_N(x) - F_N(x)| \ge \epsilon (1 - G_N(x))] \le \frac{1}{\epsilon^2 (1 - G_N(x))^2} E[(G_N(x) - F_N(x))^2]$$
 (3.12)

Working out the last term, by noticing that the function  $G_N(x)$  is deterministic and using the linearity of the expectation:

$$E[(G_N(x) - F_N(x))^2] = E[G_N^2(x) - 2G_N(x)F_N(x) + F_N^2(x)]$$
$$= G_N^2(x) - 2E[F_N(x)]G_N(x) + E[F_N^2(x)]$$

Recall that  $F_N(x) = \frac{1}{2^N} \sum_{i=1}^{2^N} \mathbb{1}_{\{E_i \leq xN\}}$  to obtain:

$$E[F_N(x)] = \frac{1}{2^N} 2^N \int_{-\infty}^{xN} p_N(E) dE = G_N(x)$$
(3.13)

We are now left with:

$$G_N^2(x) - 2E[F_N(x)]G_N(x) + E[F_N^2(x)] = G_N^2(x) - 2G_N(x)G_N(x) + E[F_N^2(x)]$$

$$= -G_N^2(x) + \left(\frac{1}{2^N} \sum_{i=1}^{2^N} \mathbb{1}_{\{E_i \le xN\}}\right)^2$$

$$= \frac{1}{2^{2N}} \sum_{i=1}^{2^N} \sum_{j=1}^{2^N} (E[\mathbb{1}_{\{E_i \le xN\}}]E[\mathbb{1}_{\{E_j \le xN\}}]) - G_N^2(x)$$
(3.14)

If i = j, both terms in the expected value will be the same (either 0 or 1), so the power 2 can be left out. We can thus split the sum in the above equation and rewrite to:

$$\frac{1}{2^{2N}} \left[ \sum_{i \neq j} \left( E[\mathbb{1}_{\{E_i \leq xN\}}] E[\mathbb{1}_{\{E_j \leq xN\}}] \right) + \sum_{i=1}^{2^N} E[\mathbb{1}_{\{E_i \leq xN\}}] \right] - G_N^2(x)$$

$$= \frac{1}{2^{2N}} \left[ \sum_{i \neq j} G_N^2(x) + \sum_{i=1}^{2^N} G_N(x) \right] - G_N^2(x)$$

As the term in the sums does not depend on i or j whatsoever, we can say:

$$= \frac{1}{2^{2N}} [2^N (2^N - 1)G_N^2(x) + 2^N G_N(x)] - G_N^2(x)$$
$$= 2^{-N} (2^N - 1 - 2^N)G_N^2(x) + 2^{-N} G_N(x) = 2^{-N} G_N(x)(1 - G_N(x))$$

So altogether we can say that

$$E[(G_N(x) - F_N(x))^2] = 2^{-N}(2^N - 1 - 2^N)G_N^2(x) + 2^{-N}G_N(x) = 2^{-N}G_N(x)(1 - G_N(x))$$
(3.15)

Plugging in equation (3.15) into equation (3.12) gives:

$$P[|G_N(x) - F_N(x)| \ge \epsilon (1 - G_N(x))] \le \frac{G_N(x)}{\epsilon^2 2^N (1 - G_N(x))}$$

To get an upper bound for the last term in the above equation, we use the following inequality[19]:

$$\int_{a}^{\infty} e^{-u^{2}/2} \, \mathrm{d}u > \frac{1}{a+a^{-1}} e^{-a^{2}/2} \tag{3.16}$$

To use this inequality we rewrite our expression for  $G_N(x)$ , using equations (3.1) and (3.11) and then change variables:

$$G_N(x) = 1 - \int_{xN}^{\infty} \frac{1}{\sqrt{2\pi J^2 N}} e^{-(E - N\mu)^2/(2NJ^2)} dE$$
$$= 1 - \frac{1}{\sqrt{2\pi J^2 N}} \int_{\sqrt{N}}^{\infty} \frac{e^{-u^2/2}}{u^2} du$$

So with the inequality (3.16) we obtain:

$$G_N(x) < 1 - \frac{1}{\sqrt{2\pi}} \frac{1}{\sqrt{N} \frac{x-\mu}{J} + \frac{J}{\sqrt{N}(x-\mu)}} e^{-\frac{N(x-\mu)^2}{2J^2}}$$

In a similar way:

$$1 - G_N(x) > \frac{1}{\sqrt{2\pi}} \frac{1}{\sqrt{N} \frac{x - \mu}{J} + \frac{J}{\sqrt{N}(x - \mu)}} e^{-\frac{N(x - \mu)^2}{2J^2}}$$

This leads to:

$$P[|G_N(x) - F_N(x)| \ge \epsilon (1 - G_N(x))] \le \frac{1}{\epsilon^2 2^N}$$

But then for N large enough, by the Borel-Cantelli lemma almost surely:

$$|G_N(x) - F_N(x)| < \epsilon (1 - G_N(x))$$

And therefore:

$$(1 - \epsilon)(1 - G_N(x)) < 1 - F_N(x) < (1 + \epsilon)(1 - G_N(x))$$

This proves the lemma.

3.2.3 
$$|x| = x_c$$

**Lemma 3.** For  $x = x_c$ :  $\limsup_{N \to \infty} \frac{1}{N} \ln(1 - F_N(x_c)) \le -\frac{(x_c - \mu)^2}{2J^2}$ 

*Proof.* Use Chebyshev (notice that  $F_N(x) < 1$ ):

$$P[1 - F_N(x_c) > N2^{-N}] = P[|1 - F_N(x_c)| > N2^{-N}] \le \frac{2^{2N}}{N^2} E[(1 - F_N(x_c))^2]$$

$$= \frac{1}{N^2} \sum_{i=1}^{2^N} \sum_{j=1}^{2^N} E[\mathbb{1}_{\{E_i > x_c N\}} \mathbb{1}_{\{E_i > x_c N\}}]$$

$$= \frac{1}{N^2} [\sum_{i \neq j} (1 - G_N(x_c))^2 + \sum_{i=1}^{2^N} 1 - G_N(x_c)]$$

$$= \frac{1}{N^2} [2^N (2^N - 1)(1 - G_N(x_c))^2 + 2^N (1 - G_N(x_c))]$$

$$= \frac{2^N}{N^2} (1 - G_N(x_c))(1 + (2^N - 1))(1 - G_N(x_c)) \le \frac{1}{N^2 \sqrt{N}}$$

Where in the last inequality we used that:

$$1 - G_N(x) = \int_{x_c N}^{\infty} \frac{1}{\sqrt{2\pi J^2 N}} e^{-(E - N\mu)^2/(2NJ^2)} dE$$

So by equation (3.11) with  $x = x_c$ :

$$1 - G_N(x) \le \frac{1}{\sqrt{2\pi N}} \frac{J}{x_c - \mu} e^{-(x_c - \mu)^2 N / 2J^2} = \frac{1}{2\sqrt{\pi N \ln 2}} e^{-N \ln 2} = \frac{2^{-N}}{2\sqrt{\pi N \ln 2}}$$

Now we see that  $\frac{1}{N^2\sqrt{N}} \to 0$  for  $N \to \infty$ , so for N large enough we have with probability 1 that  $1 - F_N(x_c) \le N2^{-N}$ . We finish the proof of this lemma by noticing that  $-\frac{(x_c - \mu)^2}{2J^2} = -\ln 2$ .

#### 3.2.4 Open and closed sets

We now found a function that can possibly describe a large deviation property (LDP). This is the function I(x):

$$I(x) = \begin{cases} \frac{(x-\mu)^2}{2J^2} := K(x), & \text{if } |x| \le x_c\\ \infty, & \text{if } |x| > x_c \end{cases}$$
(3.17)

where  $x_c = J\sqrt{2\ln 2} + \mu$ . This function  $I: \mathbb{R} \to [0, \infty]$  is a good rate function. Firstly, we can easily see that this function is lower semi-continuous (the value  $x_c$  is  $\frac{x_c^2}{2J^2}$  and not  $+\infty$  and has only two discontinuities). Furthermore  $\{x: I(x) \leq l\}$  has to be compact in  $\mathbb{R} \ \forall l < \infty$ .

We see that the set  $\{x: I(x) \leq l\}$  is bounded and closed as all  $x < \infty$  lie in the interval  $[-x_c, x_c]$ .

There are two things left to prove in order to show that I(x) is the rate of the LDP on the distribution functions  $F_N$ . First we show that

$$\forall O \subset \mathbb{R} \text{ open} : \liminf_{N \to \infty} \frac{1}{N} \ln(1 - F_N(O)) \ge \inf_{x \in O} I(x)$$
 (3.18)

If  $|x| > x_c$ , we can use the first lemma. In this case, we have that  $I(x) = +\infty$  and thus  $-I(x) = -\infty$ . So for all x in the open set  $(x_c, \infty) \subset \mathbb{R}$  we can say that  $I(x) = -\infty$  as well. We can use a similar approach for  $(-\infty, -x_c)$ . Choose an open set O in the subset  $(x_c, \infty)$ . Then in O we have that  $\lim\inf_{N\to\infty}\frac{1}{N}\ln(1-F_N(O))\leq \limsup_{N\to\infty}\frac{1}{N}\ln(1-F_N(O))=-\infty$ . It now follows that  $\lim\inf_{N\to\infty}\frac{1}{N}\ln(1-F_N(O))\geq -\inf_{x\in O}I(x)$ , which shows that (3.18) is true.

The second thing to prove is:

$$\forall C \subset \mathbb{R} \text{ closed} : \limsup_{N \to \infty} \frac{1}{N} \ln(1 - F_N(C)) \le -\inf_{x \in C} I(x)$$
 (3.19)

If  $|x| \leq x_c$ , we can use lemma 2 and 3. In this case, we have that for  $0 < |x| < x_c$ :  $\lim_{N \to \infty} \frac{1}{N} \ln(1 - F_N(x)) = -K(x)$ . Then by definition  $\lim\sup_{N \to \infty} \frac{1}{N} \ln(1 - F_N(x)) = -K(x)$ . For  $x = x_c$  we have that:  $\limsup_{N \to \infty} \frac{1}{N} \ln(1 - F_N(x_c)) \leq -K(x)$ , so for the total closed interval  $[-x_c, x_c]$ , we have that  $\limsup_{N \to \infty} \frac{1}{N} \ln(1 - F_N(C)) \leq -K(x)$ . Since K(x) is strictly convex on the interval  $[-x_c, x_c]$ , there exists an infimum of K, namely at  $x = \mu$ . Notice that  $K(x = \mu) = 0$  and that  $\mu \leq x_c$ . For every closed set C within  $-x_c, x_c$  we can find such an infimum. It then follows that  $\limsup_{N \to \infty} \frac{1}{N} \ln(1 - F_N(C)) \leq -\inf_{x \in C} K(x)$ , which proves the statement in (3.19).

#### 3.2.5 Main theorem

Using the lemmas obtained in the previous section we can set up the following theorem to describe a LDP of the system.

**Theorem 2.** With probability 1, the random probability measures with distribution functions  $F_N$  satisfy a LDP with rate function I given by

$$I(x) = \begin{cases} \frac{(x-\mu)^2}{2J^2}, & \text{if } |x| \le x_c\\ \infty, & \text{if } |x| > x_c \end{cases}$$
 (3.20)

where  $x_c = J\sqrt{2 \ln 2} + \mu$ .

### 3.3 Finding the free energy

We now want to prove the next expression for the free energy in the system by making use of Varadhan's lemma:

**Theorem 3.** The free energy density f of the REM as described in section 3.1 is:

$$-\beta f(\beta) = \begin{cases} \ln 2 + -\beta^2 J^2 + \beta \mu - \frac{(\beta J^2 - \mu)^2}{2J^2}, & \text{if } \beta J^2 - \mu \le x_c \\ \beta (J\sqrt{2\ln 2} + \mu), & \text{if } \beta J^2 - \mu > x_c \end{cases}$$

*Proof.* Take a function  $F: \chi \to \mathbb{R}$  that maps  $x \mapsto -\beta x$ . We choose  $\chi$  to be the interval  $[-x_c, x_c] \subset \mathbb{R}$ . It is obvious that the function F is continuous and bounded above on  $\chi$ , as  $x_c$  is finite and  $\beta$  is a constant (with respect to N and x). From the above theorem, we take the rate function I on the specific interval. Then by Varadhan's lemma:

$$\lim_{N \to \infty} \frac{1}{N} \ln \int_{\chi} e^{-\beta Nx} \, dF_N(x) = \sup_{(x \in \chi)} \left[ -\beta x - \frac{(x-\mu)^2}{2J^2} \right]$$
 (3.21)

We see from equation (3.3) that the left hand side is equal to  $-\beta f(\beta)$  up to a factor  $\ln 2$ . So:

$$-\beta f(\beta) - \ln 2 = \sup_{(x \in \chi)} \left[ -\beta x - \frac{(x - \mu)^2}{2J^2} \right]$$
 (3.22)

To find the value of this supremum, split the expression in two separate parts. If  $\beta J^2 - \mu \leq x_c$  we use just that value to calculate the supremum. So the supremum is  $(-\beta x - \frac{x^2}{2J^2})|_{x=\beta J^2 - \mu} = -\beta^2 J^2 + \beta \mu - \frac{(\beta J^2 - \mu)^2}{2J^2}$ . If  $\beta J^2 - \mu > x_c$ , the supremum will arise if we choose  $-\beta x$  as large as possible, so  $x = -x_c$  and we get  $(-\beta x - \frac{x^2}{2J^2})|_{x=-x_c} = \beta(J\sqrt{2\ln 2} + \mu) - \ln 2$ . So if we plug these results into equations (3.21) and (3.22) we obtain Theorem 3.

This result is remarkable in the existence of the critical point  $x_c$ . That is, there exists a point where the free energy of the system suddenly makes a transition between two regimes. This means there still exists a certain critical temperature  $T_c$  in the REM with non-zero mean Gaussian distributed energies.

## 3.4 Entropy of the system

In the first chapter we introduced the concept of entropy. Using the fact that each component in our system consists of only two different spin states, we can say that (using equations (3.1) and (2.4)):

$$S(E) = k_B \ln(2^N p(E)) = k_B [\ln 2^N + \ln(\frac{1}{\sqrt{2\pi J^2 N}}) - \frac{(E - N\mu)^2}{2NJ^2}]$$
$$= k_B [N \ln 2 - \frac{1}{2} \ln(2\pi J^2 N) - \frac{(E - N\mu)^2}{2NJ^2}]$$

If we assume that  $\ln(2\pi J^2 N)$  is small enough compared to the other terms, we see that:

$$S(E) \approx k_B [N \ln 2 - \frac{(E - N\mu)^2}{2NJ^2}]$$
 (3.23)

Which can be written as:

$$\frac{S(E)}{Nk_B} \approx -\frac{1}{2J^2} \left[ \frac{E}{N} \right]^2 - \frac{\mu}{J^2} \left[ \frac{E}{N} \right] + \ln 2 + \frac{\mu^2}{2J^2}$$

This is a parabolic expression and has the following form:

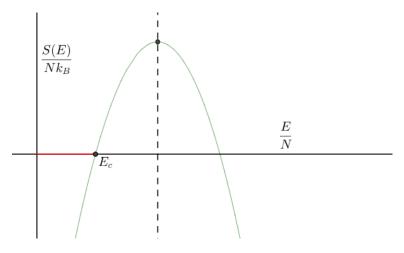


Figure 3.1: Shape of the entropy function. Only the first half positive part of the parabola is physical

Via equation (3.23) we can now easily obtain an approximate value for  $E_c$ , as  $S(E_c) = 0$ :

$$\frac{(E_c - N\mu)^2}{2NI^2} = N \ln 2 \implies E_c - N\mu = NJ\sqrt{2\ln 2}$$

And this expression leads to a critical temperature  $T_c$ :

$$\frac{1}{T_c} = \frac{dS}{dE}|_{E=E_c} = -k_B \left(\frac{E_c - N\mu}{NJ^2}\right) = \frac{k_B \sqrt{2\ln 2}}{J}$$

This leads to a critical  $\beta_c = \frac{\sqrt{2 \ln 2}}{J}$ . Furthermore, note that  $\frac{E_c}{N} = \mu + J\sqrt{2 \ln 2}$  is exactly the  $x_c$  we found in the first theorem of this chapter. This means that the assumption we made in (3.23) is true almost surely for  $N \to \infty$ .

## Chapter 4

# **Application**

## 4.1 Problem description

We will now take a deeper look into the problem of compact heteropolymers. A heteropolymer is a long molecule formed from subunits (monomers) that are not all the same, such as a protein composed of various amino acid subunits. The long strings of the proteins can interact with other proteins, making them fold together. Biophysicists usually view them as shown in Figure 4.1, which simplifies the underlying chemical structure. Interactions between proteins play a key role in many biological processes[1], as it is closely linked to the folding and copying of DNA. Due to the complexity of the structure of a protein, most models that describe protein folding require heavy mathematics, leading to high simulation and computing times. To avoid this, the REM was suggested in the context of heteropolymers.

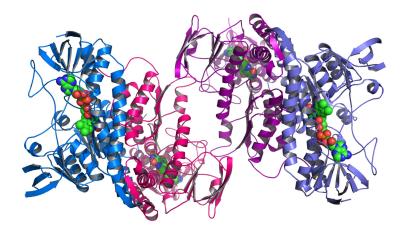
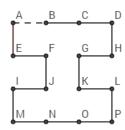


Figure 4.1: A typical example of folded proteins

We will first make a rough approximation about the shape of heteropolymers. In the light of this report, it should be enough to regard them shaped as chains of monomers. Looking at a collection of heteropolymers, the configuration is remarkably compact in many biological



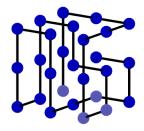


Figure 4.2: A compact configuration in 2D

Figure 4.3: A compact configuration in 3D

processes. For instance, a typical human DNA molecule would have an approximate length of 0.2 mm[9] if it behaved like a random chain, whereas a typical cell nucleus diameter is in the order of microns. Therefore, the structure of the folded polymers has to be extremely compact, which we can see mathematically as a collection of all maximally compact configurations on a lattice. Figure 4.1 shows a maximally compact configuration of a 4x4 lattice (N=16): every lattice point is visited once by the polymer. This Hamiltonian walk is by no means unique and does not necessarily have to be a circuit. For a fixed volume, a higher number of N will lead to a more closely packed lattice. In Figure 4.2 a 3D polymer on a 3x3x3 cubic lattice is shown. This 27-mer has become a standard for heteropolymer studies. In general biophysicists are most interested in three-dimensional globular shapes [20].

Every configuration of the polymers will cost a different amount of energy, so the way the polymers are structured will be dependent of temperature. For low temperatures, the low energy states will most likely be preferred. A decreasing temperature will force the polymers to rearrange and there could even exist a certain temperature at which the system 'freezes' into a single configuration: a transition to the ground state. Such a transition typically exists [21], which motivates the application of the REM.

## 4.2 REM for heteropolymers

To model a system of folding proteins, we start with stating that there are still two possibilities for each point on the lattice: it is either occupied by a certain monomer, or not. The state space thus remains  $S_N = \{-1, +1\}^N$  (or one could rename -1 to 0). 1 represents a lattice point that is occupied by a monomer, -1 an empty spot. The energy of each configuration of the heteropolymer will be dependent on the interaction between neighbouring lattice points. The closer two monomers are, the more they will influence each other. Furthermore, interactions amongst proteins appear to be dominated by the short-range role of hydrophobicity[21]. For each pair of monomers we define the interaction energy B between the two monomers<sup>1</sup>. To avoid too many mathematical complications, we make a nearest-neighbour approximation.

<sup>&</sup>lt;sup>1</sup>For now we will talk about monomers, but normally a single lattice point is not necessarily representing a single monomer, but a small arrangement of amino acids[22]. So to be precise, we should talk about "quasimonomers".

Let us define the Hamiltonian of a certain monomer  $s_i$  at a certain position  $r_i$  on the lattice in the following way:

$$H(s_i, \mathbf{r}_i) = \sum_{i,j}^{N} B_{ij} \Delta(\mathbf{r}_i - \mathbf{r}_j)$$
(4.1)

Where we have a finite number q of different monomers such that  $s_i \in \{1, ..., q\}$  on the lattice. The dirac function  $\Delta$  makes the nearest neighbour approximation:  $\Delta(a) = 1$  and  $\Delta(a > r) = 0$  where a is the lattice spacing.

The interaction energies B are still chosen according to the REM:

$$\mathbb{P}(B_{ij}) = \frac{1}{\sqrt{2\pi N J^2}} e^{-(B_{ij} - N\mu)^2 / 2NJ^2}$$
(4.2)

So, in order to apply the REM, we have to assume that the overall energy levels of the different configuration possibilities are Gaussian i.i.d. distributed (and thus do not influence each other). We also see now the necessity of adding a mean to the REM. We can interpret the variable  $\mu$  as the mean interaction energy  $\bar{B}$ , which is typically nonzero.

### 4.3 Different states of the heteropolymers

In the heteropolymer model we used in this chapter, the total system is defined by two parameters:  $\mu$  and J. Therefore, we expect the model to have three different phases. These 3 phases are respectively the folded, glassy and random phase and are indeed found in the REM[24].

In the random state, an exponential number of globular conformations dominate equilibrium. In the glassy state, conformations that are not the target conformation dominate below the critical temperature  $T_c$ . In the folded state, the target conformation dominates equilibrium.

## 4.4 Folding mechanism and the Metropolis algorithm

Let us return to the REM for folding of random heteropolymers and consider a system in 2D. We will study the folding behaviour of a polymer by using the Metropolis algorithm[25]. In our case, this algorithm first chooses a random configuration of a polymer string on the lattice. We will later adjust this configuration step by step, creating a Markov chain. We take the probability for the configuration X to arise according to the Boltzmann distribution, so the distribution  $\rho$  of the configurations is:

$$\rho(X) = e^{-\beta H\{X\}} \tag{4.3}$$

We now select a monomer randomly and calculate how much the total energy would change if we place it to another position. We then get a new configuration X', with probability  $e^{-\beta H\{X'\}}$ 

The difference in energy can easily be calculated using the Hamiltonian defined in equation (4.1):

$$\Delta E = H(X) - H(X') \tag{4.4}$$

But what is the probability of such a transition from configuration X to X' to occur? If H(X') < H(X), the transition is energetically favourable, so we take the transition probability  $T(X \to X')$  equal to 1.

If H(X') > H(X), we have to take a closer look. It is unclear what the probability  $T(X \to X')$  will be, but we know the probability distribution of being in configuration X at a certain step t in the Markov chain:  $\rho(X,t)$ . Two values of  $\rho(X)$  at different time steps t and t+1 will differ because of transitions between state X and the possible states X'. The next equation, which is called the master equation, evaluates this difference in order to arrive at a time evolution equation.

$$\rho(X, t+1) - \rho(X, t) = -\sum_{X'} T(X \to X') \rho(X, t) + \sum_{X'} T(X' \to X) \rho(X', t)$$
(4.5)

We are looking for the folded state of the polymer, which is a stationary state (we assume the protein is stable once it has been folded). Therefore, the master equation should equal 0 and we immediately see a special solution:

$$T(X \to X')\rho(X) = T(X' \to X)\rho(X') \tag{4.6}$$

Note that the exact value of t is in this case not relevant, as the stationary solution should be valid for all  $t \ge t_f$  for some  $t_f$ . Rewrite equation (4.6) to obtain:

$$\frac{T(X \to X')}{T(X' \to X)} = \frac{\rho(X')}{\rho(X)} = \frac{e^{-\beta H(X')}}{e^{-\beta H(X)}} = e^{-\beta(H(X') - H(X))}$$
(4.7)

We have assumed that H(X') > H(X), so  $T(X' \to X) = 1$ . But then:

$$T(X \to X') = e^{-\beta(H(X') - H(X))}$$
 (4.8)

We can now summarize the Metropolis algorithm in the following way. First choose an initial configuration. Then:

- 1. Select a random monomer and place it somewhere else (within restrictions of the polymeric bounds), creating a configuration X'.
- 2. Calculate the energy difference  $\Delta E$  that this change in configuration would cause.
- 3. If  $\Delta E < 0$ , make X' the new distribution. Otherwise, make X' the new distribution with probability  $e^{-\beta \Delta E}$ .
- 4. Repeat.

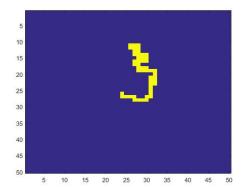
By using this algorithm, we find a stationary solution that is energetically favourable to the system. We want to study under which circumstance (parameters  $\beta$ , chain length, ...) the proteins fold.

#### 4.4.1 Notes on implementation

To generate an initial polymer configuration, a random chain on a lattice is generated. Every point on the lattice is represented by either a 0 (an empty space) or a letter (a certain monomer). Two examples of starting configurations are plotted in Figure 4.4. On the left is a 50-monomer-long polymer, on the right the polymer consists of 100 monomers. Both images show a  $50 \times 50$  lattice, blue represents an open spot, yellow a monomer.

We chose for a lattice in which the upper row is connected to the lower row and the left column to the right column. In this way, the two dimensional space represents the spherical outer surface of a torus. We see this effect in the Figure on the right in Figure 4.4. In later simulations, the model could be extended to three dimensions as well.

The random heteropolymers were created by the program as shown in the Appendix. From a starting point on the lattice a random walk is generated, creating a random polymer.



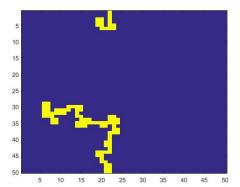


Figure 4.4: Two starting configurations on a  $50 \times 50$  lattice. Blue lattice points represent an empty spot, yellow stands for a certain monomer.

Once an initial configuration is obtained, we can start using the Metropolis algorithm. A certain monomer is selected and placed to another position. The positions that are allowed by the polymeric bounds are the neighbouring lattice points, as long as they are not occupied by another monomer yet. Acceptance of the new structure is determined by using the energy expressions described in step 2 and 3 of the algorithm.

From some preliminary studies [26] the parameters were taken to be  $\mu = -2$ , J = 1, with units in quantities of  $k_BT$ . The used program can be found in the Appendix.

#### 4.4.2 Simulation results

After running the algorithm for different values of  $\beta$ , sequences were unable to fold to a compact conformation within  $10^8$  Monte Carlo steps. Results give conformations of polymers that are very similar to the arbitrarily chosen initial configurations: the configuration are not observably more compact. As an example, the result of a simulation for  $\beta = 0.01$  is shown below. If the value of  $\beta$  is increased, the effects are even smaller. This means our model is

not yet good enough to describe the folding process. In the next sections, we will investigate a better approach.

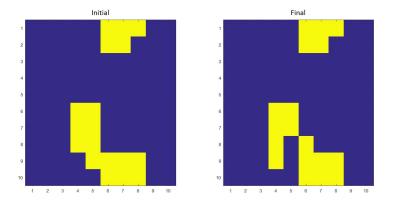


Figure 4.5: Simulation result for  $\beta = 0.01$ . The initial configuration on the left has barely changed compared to the final configuration after  $10^8$  steps.

## 4.5 Validity of the REM for heteropolymer folding

At first sight the REM can only be true for a system that actually behaves as if the interactions act independently<sup>2</sup>. It was shown that the REM is a good model for these kind of systems (see Shakhnovich and Gutin[23]) for small configurations. However, it is not always true that two polymer configurations have interactions that are independent from each other. Pande, Yu et al. [24] give a good example of that: take two polymer configurations that are very much alike except for a small rearrangement (let us call them 'similar packings'). These two configurations are of course close in energy. Therefore, the REM approach can only give an approximation to the compact folding problem. Luckily these kind of 'similar packings' are very rare<sup>3</sup>, which makes the REM a very good approximation in this setting.

However, the REM has some disadvantages in modelling protein folding. One of these is a problem known by biophysicists as the speed-stability paradox[27]: for a protein, the lowest possible energy state occurs significantly more frequently at a temperature below  $T_c$ . Thus, the folding of the polymer happens at a very low temperature, which means the dynamics of the system are slow as the number of states in the system decreases drastically and (as mentioned above) the different energy configurations do not have much in common. So, to change to the lowest energy state, the polymer has to rearrange many of its monomers. This contradicts the observation that most proteins fold easily and fast. Of course, the REM is created to describe random heteropolymers and naturally occurring polymers (such as DNA) are a special kind of polymers. It has been suggested that biological heteropolymers were

<sup>&</sup>lt;sup>2</sup>The interactions at different sites are uncorrelated.

<sup>&</sup>lt;sup>3</sup>This is due to the heavy constraints that the required compactness lies upon the configuration.

modified to more easily foldable versions over time due to evolution. We want to describe naturally occurring proteins with the REM, so in the next section we will extend our model.

### 4.6 Designed REM

To design a model that describes the folding of naturally occurring proteins in a better way, we add a single state with low energy. We call this energy the native energy  $E_n$  and it is now the lowest energy state possible  $(E_n < E_c)$ . In the figure below, the new system is drawn in the same way as in Figure 3.1.

The probability to find the system in the native state now is  $\frac{e^{-\beta E_n}}{Z_n(\beta)}$  with  $Z_n(\beta) = e^{-\beta E_n} + Z(\beta)$  and  $Z(\beta)$  the partition function of the normal REM.

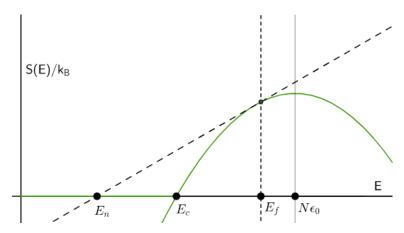


Figure 4.6: Shape of the entropy function for the designed REM. Again, only the first half positive part of the parabola is physical

What are the properties of this new system? First of all, there will be a new folding temperature  $T_f$ , which we want to compute. There will also be a new folding energy  $E_f$ , a new folding  $\beta_f$ , etc. Using a "tangent construction" shown in the above Figure, we see that  $\frac{dS}{dE}|_{E_f} \simeq \frac{S(E_f)/k_B}{E_f - E_n}$ . Now we can derive an expression for the folding temperature by using equation (3.23) for  $E = E_f$ :

$$\beta_f = \frac{1}{k_B T_f} = \frac{1}{k_B} \frac{dS}{dE} |_{E_f} = \frac{N \ln 2 - \frac{(E_f - N\mu)^2}{2NJ^2}}{E_f - E_n}$$
(4.9)

We now notice that  $E = N\mu - NJ^2\beta$  (so  $E_f = N\mu - NJ^2\beta_f$  and  $E_n = N\mu - NJ^2\beta_n$ ) and  $\frac{1}{2}(\beta_c\sigma)^2 = \ln 2$ . Plug this into equation (4.9) to get:

$$\beta_f = \frac{N_{\frac{1}{2}}(\beta_c \sigma)^2 - \frac{(N\mu - NJ^2\beta_f - N\mu)^2}{NJ^2}}{N\mu - NJ^2\beta_f - N\mu + NJ^2\beta_n} = \frac{\beta_c^2 - \beta_f^2}{2(\beta_n - \beta_f)}$$

This equation can be solved for  $\beta_f$ :

$$\beta_f^2 - 2\beta_n \beta_f + \beta_c^2 = 0$$

$$\beta_f = \beta_n \pm \sqrt{\beta_n^2 - \beta_c^2}$$

Where we should use the minus sign in the last equation, as the other one is not physical. From this expression we see that we can make the model fold at higher temperature levels by increasing the energy difference between  $E_n$  and  $E_c$ .

## Chapter 5

## Conclusions

Theoretically, it is possible to use the Random Energy Model for studying the folding of random heteropolymers. We proved that a version of the model in which the Hamiltonians satisfy a Gaussian probability distribution around a non-zero mean still leads to a phase transition at a critical point and found an expression for the free energy and entropy.

We wrote a simple model that simulates the behaviour of folding polymers. However, this model is not very accurate in describing the actual process. Other versions of the REM, such as the designed REM, may give a better result, although this was not proven in this thesis. Even without a solid simulation of the difficult protein folding process, the application of the REM in the field of random heteropolymers is still useful to gain insight in the different phases and the transition temperature of a polymer.

Properties of the REM heteropolymer model that are left to explore consist of a simulation of the designed REM as it was suggested in this thesis, the effect of not making the nearest-neighbour approximation or the extension of the simulation to 3D. Some mathematical consequences of the REM were intentionally left out of this thesis. For example, the distinction between annealed and quenched averages was not made, as was the whole concept of replica theory.

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## Chapter 6

# Appendix

### 6.1 Matlab code for creating a random heteropolymer

```
function [state_space, positions] = create_polymer( polymer_length,
       state_space, numSpinsPerDim )
2 %Given a square lattice and a polymer length generates a random
     chain on
з %the lattice
  Alphabet=char ('a' + (1:26) - 1)';
  [I, J] = ndgrid(1:26, 1:26);
6 I=I '; J=J ';
7 XX=[Alphabet (I(:)), Alphabet (J(:))];
  XX=strvcat (Alphabet, XX);
                                            %Is now a random chain of
      letter, but can represent any set of monomers
  polymer = XX(1: polymer_length);
  start_x = round(numSpinsPerDim*rand)+1; %Random starting point on
      lattice
  start_y = round(numSpinsPerDim*rand)+1;
  state_space(start_x, start_y) = polymer(1);
  row = start_x;
  col = start_y;
  positions = [row, col];
                                            %Quick localisation of
     monomers
   for i = 1:(polymer_length - 1)
                                            %Generate random chain
16
       above = mod(row - 1 - 1, size(state\_space, 1)) + 1;
17
      below = mod(row + 1 - 1, size(state\_space, 1)) + 1;
18
       left = mod(col - 1 - 1, size(state\_space, 2)) + 1;
19
       right = mod(col + 1 - 1, size(state\_space, 2)) + 1;
20
       neighbors = [above, below, left, right];
       check = 0;
```

```
counter = 0;
23
       while check == 0;
24
            new = randi(4);
25
            if new == 1
26
                if state_space (above, col) = 0
                     row = above;
                end
29
            elseif new == 2
30
                if state_space(below, col) == 0
31
                     row = below;
32
                end
33
            elseif new == 3
                if state_space(row, left) == 0
                     col = left;
36
                end
37
            elseif new = 4
38
                if state_space(row, right) == 0
39
                     col = right;
40
                end
            end
42
      if state\_space(row, col) = 0
      check = 1;
44
      state\_space(row, col) = polymer(i+1);
45
      positions = [positions, row, col];
46
47
      counter = counter +1;
48
      if counter > 100
49
           check = 1;
      end
51
       end
  end
53
   positions
54
  end
55
```

## 6.2 Metropolis algorithm

```
clear all; close all; clc;
numSpinsPerDim = 10;

%create initial random polymer
state_space = zeros(numSpinsPerDim, numSpinsPerDim);
polymer_length = 20;
[state_space, positions] = create_polymer(polymer_length, state_space, numSpinsPerDim);
```

```
%model parameters
  N = numSpinsPerDim*numSpinsPerDim;
  mu = -2;
  J = 1;
12
   initial = state_space;
   initial_positions = positions;
   new_state_space = state_space;
15
   new_positions = positions;
16
  beta = 0.1;
  E = 0;
  E_{\text{new}} = 0;
   possib = [];
   E_i solution = 0;
   for i=1:100000
23
       %pick a random monomer
24
       pick\_col = 2*randi(numel(positions)/2);
25
       col = positions(pick_col);
26
       row = positions(pick_col -1);
27
       %find its neighbours
       ab = mod(row - 1 - 1, size(state\_space, 1)) + 1;
29
       be = mod(row + 1 - 1, size(state\_space, 1)) + 1;
30
           = \operatorname{mod}(\operatorname{col} - 1 - 1, \operatorname{size}(\operatorname{state\_space}, 2)) + 1;
31
       ri = mod(col + 1 - 1, size(state\_space, 2)) + 1;
32
       neighbors = [ab, be, le, ri];
33
       if state\_space(ab, col) = 0;
34
            possib = [possib, ab, col];
       end
36
       if state\_space(be, col) = 0;
37
            possib = [possib, be, col];
38
       end
39
       if state\_space(row, le) = 0;
40
            possib = [possib, row, le];
41
       end
       if state\_space(row, ri) = 0;
43
            possib = [possib, row, ri];
44
       end
45
        if numel(possib) ~=0
46
            number = randi(numel(possib));
47
            if mod(number, 2) ==0
48
                 new\_col = possib(number);
49
                new\_row = possib (number-1);
            end
```

```
if mod(number, 2) ==1
52
                new\_row = possib (number);
53
                new_col = possib(number+1);
54
           end
55
           new_state_space(new_row, new_col) = state_space(row, col);
           new_state_space(row, col) = 0;
57
           new_positions(pick_col) = new_col;
58
           new_positions(pick_col -1) = new_row;
59
       end
60
61
       %check energy
62
       for row = 1:numSpinsPerDim
63
                for col = 1:numSpinsPerDim
                    n1 = normrnd(N*mu, sqrt(N)*J);
65
                    n2 = normrnd(N*mu, sqrt(N)*J);
66
                    n3 = normrnd(N*mu, sqrt(N)*J);
67
                    n4 = normrnd(N*mu, sqrt(N)*J);
68
                    if state_space(row, col) ~= 0
69
                         E_above = state_space \pmod{row - 1 - 1}, size 
70
                            state\_space, 1)) + 1, col)*n1;
                         E_below = state\_space (mod(row + 1 - 1, size))
71
                            state\_space, 1) + 1, col)*n2;
                         E_left = state_space(row, mod(col - 1 - 1,
72
                            size(state\_space, 2)) + 1)*n3;
                         E_right = state_space(row, mod(col + 1 - 1,
73
                            size(state\_space, 2)) + 1)*n4;
                         E = E + E_{above} + E_{below} + E_{left} + E_{right};
74
                    end
75
                     if new_state_space(row, col) = 0
76
                         E_above_new = new_state_space (mod(row - 1 - 1), row)
77
                             size(new\_state\_space,1)) + 1,col)*n1;
                         E_{below_new} = new_{state_space} \pmod{row + 1 - 1}
78
                             size(new\_state\_space,1)) + 1,col)*n2;
                         E_left_new = new_state_space(row, mod(col - 1))
79
                            -1, size (new_state_space, 2)) + 1)*n3;
                         E_right_new = new_state_space(row, mod(col + 1))
80
                            -1, size (new_state_space, 2)) + 1)*n4;
                         E_{new} = E_{new} + E_{above_{new}} + E_{below_{new}} +
81
                            E_left_new + E_right_new;
                    end
82
                end
83
           end
84
       %better? If not: probability
85
       if E_{new} < E
```

```
state_space = new_state_space;
87
            positions = new_positions;
88
        else
89
            prob = exp(-beta*(E_new-E));
90
            if rand <= prob
                 state_space = new_state_space;
92
                 positions = new_positions;
93
            end
94
        end
95
        new_state_space = state_space;
96
        new_positions = positions;
97
        possib = [];
        E_i isolation =0;
   end
100
101
   figure (1)
102
   subplot (1,2,1)
103
   title('Initial')
104
   image(initial)
105
   subplot (1,2,2)
   title ('Final')
   image(state_space)
```