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# New Nine-Level Common-Ground Multilevel Inverter With Boosting Capability for Renewable Energies

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**ABSTRACT** In recent years, several common-ground switched-capacitor transformerless (CGSC-TL) dc–ac multilevel power converters have been introduced, providing advantages such as multilevel output voltage, voltage boosting, and mitigated leakage current. However, these structures mostly suffer from drawbacks, such as limited output voltage levels (like only five levels), lack of voltage-boosting capability, and high charging current spikes of the capacitors. This article proposes a new single-stage CGSC-TL nine-level (9L) multilevel inverter (MLI) with voltage-boosting capability and limited spikes of charging current of the capacitor, designed to be employed as a single-stage power-electronics-based interface device between renewable energy sources, such as photovoltaic (PV) systems and power grid and/or load. The proposed MLI provides several merits, such as a common-ground structure that suppresses PV-to-ground leakage current associated with PV parasitic capacitances, active and reactive power support, a wide input voltage range, and higher output voltage levels (9L) compared with other structures in the same class. Comprehensive comparative analyses, as well as simulation and experimental results, are presented to verify the performance of the proposed inverter.

**INDEX TERMS** Common ground (CG), current spikes, leakage current elimination, multilevel dc–ac inverter, renewable energy, single stage, solar energy, switched capacitor (SC), voltage boosting.

## I. INTRODUCTION

These days, power-electronics-based devices such as power converters are broadly employed in many industrial applications [1], [2], [3], [4]. In recent years, among several types of power converters, multilevel inverters (MLIs) have attracted much attention and have been broadly employed in numerous medium- and high-power applications such as renewable energy source (RES)-based systems such as electric vehicles, photovoltaic (PV) systems [5], [6], [7], [8], and flexible ac transmission systems [9], [10]. With the growing penetration

of RESs in power systems, transformerless (TL) inverters with common-ground (CG) structures have been widely studied for grid-connected applications. These topologies are credited with suppressing leakage current, improving overall efficiency, and providing favorable power density relative to both size and cost. It is noteworthy that in these inverters, the leakage current is eliminated since their input dc voltage source and the grid/load have a CG [11], [12], [13], i.e., their negative and neutral points are connected. On the other hand, ensuring compatibility between the grid-voltage peak value and the dc

voltage source from renewable resources such as PV string panels is another important objective. In addition, as another objective, the power quality enhancement (PQE) problem should be considered here. The PQE has an undeniable impact on both the filter design and the quality of the current injected into the main grid [11]. So far, several TL inverters with a CG structure have been introduced, which are capable of providing a static voltage gain (equal to one) [14], [15].

In such topologies, a dc-link capacitor is required and is charged during the first half-cycle and discharged during the second half-cycle of the grid voltage. During the second half-cycle, the voltage stored in the first half-cycle is delivered to the output port. However, these inverters typically provide only two or three output voltage levels, which can adversely affect PQE. In [16] and [17], two- and three-level (2L and 3L) TL inverters with the CG feature have been, respectively, developed. A flying inductor is used in these topologies rather than the virtual dc-link capacitor. In [18], a five-level (5L) CG-based TL inverter has been introduced, which is not based on the virtual dc-link capacitors or flying inductor concepts. This inverter employs an inductor-based switched-boost (SB) module with a dc-link capacitor-based dual T-Type cell. All these structures achieve the feature of dynamic voltage gain, which is an invaluable achievement in single-stage energy conversion operations. However, these converters are large due to their flying or SB-module-based inductors and may cause an inappropriate total power density per output power.

To enhance the static voltage gain, flying capacitors and/or switched-capacitor (SC) networks can be incorporated into conventional CG-TL inverters, including the 3L designs of [19] and [20], the 5L designs of [21] and [22], and the seven-level (7L) design of [23]. With these integrations, fewer PV modules are required on the dc side to meet the grid-voltage amplitude. However, achieving this boosting capability is accompanied by undesirable charging current spikes that occur when the capacitors are charged in parallel with the dc input source [24], [25]. Consequently, the applicability of CGSC-TL inverters is constrained for low-power grid-connected systems. Recent CGSC-TL implementations typically provide only a 5L output voltage. Adopting an extendable structure is therefore advantageous, as it enables a higher number of output voltage levels and yields notable improvements in PQE and reliability [26].

In summary, for PV grid-tied systems, several CG-TL inverter topologies have been introduced to eliminate leakage current while maintaining high efficiency [11], [12], [13], [14], [15]. However, early CG structures were mainly limited to 2L or 3L output voltages [16], [17], leading to poor output quality and large filter requirements. To overcome this, multilevel CG inverters with SC or SB modules were developed [18], [19], [20], [21], [22]. These inverters can offer higher output voltage levels and voltage-boosting capability. Nevertheless, they often suffer from drawbacks, such as excessive charging current spikes in capacitors, increased device stress, and limited scalability [23], [24], [25], [26].

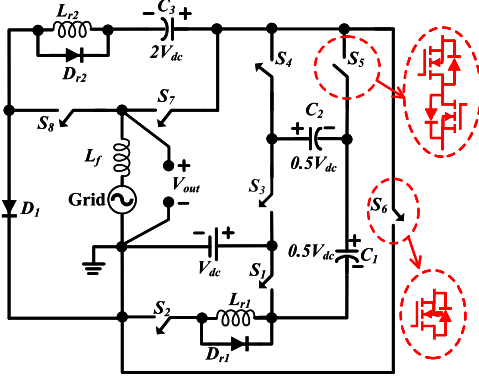
Recently, several advanced CG-SC inverter topologies have emerged. Azad et al. [27] introduced a 9L CG-SC inverter that effectively suppresses leakage currents, although its boosting gain and device count remain limiting factors. In [28], a 7L CG inverter with triple boosting and natural voltage balancing is presented, suffering from higher capacitor stress. Moreover, in [29], a self-balanced CG-SC inverter with a single dc source is introduced, but its voltage gain is restricted to lower values. Liu et al. [30] addressed dc bias and asymmetry in CG-SC inverters, focusing on waveform quality without considering boosting limitations. In 2025, a single-source 7L CG inverter was introduced, demonstrating good leakage suppression but still limited in boosting [31]. More recently, a CG boosting inverter with lower switch stress is presented in [32]; however, this structure faces tradeoffs in terms of increased switching losses.

Based on the literature, while progress has been made in integrating boosting, leakage elimination, and CG features, there is still a need to develop a topology that can simultaneously provide advantages such as a high number of output voltage levels (equal to or higher than nine), substantial boosting gain (approximately  $2\times$ ), elimination of leakage current, suppression of capacitor charging current spikes, and a competitive component count with moderate device stresses. For this aim, this article proposes a new CGSC-TL MLI, employing eight power switches for modern applications such as RESs. This inverter can provide nine voltage levels at the output port, which is higher than most of the previously introduced structures, with fewer or a comparable number of power components. The main advantages of the proposed MLI can be listed as follows:

- 1) employing fewer/comparable number of components;
- 2) being CG, leading to leakage current elimination;
- 3) voltage-boosting ability;
- 4) active and reactive power supporting capability;
- 5) limited capacitors' charging current spikes (CCCS) resulting in lower power losses, longer life cycle for capacitors, and mitigated electromagnetic interference (EMI);
- 6) extensive input voltage capability;
- 7) TL structure;
- 8) no sensors for balancing the voltages of capacitors;
- 9) lower or similar voltage stress on the components.

Clearly, these advantages make the proposed MLI a strong candidate for modern industrial applications such as PV applications. It is noteworthy that compared to previously published MLIs, the proposed MLI is a 9L SC-TL MLI that simultaneously provides both CG and CCCS features. For validating the performance of the converter, thorough analysis, comparisons, and simulation and experimental results are presented.

The rest of this article is organized as follows. Section II introduces the proposed inverter and its operating principles. Section III provides detailed comparisons with existing topologies. Section IV discusses the simulation and experimental results. Finally, Section V concludes this article.



**FIGURE 1.** Circuit configuration of the proposed CGSC-TL 9L MLI.

## II. PROPOSED INVERTER AND ITS OPERATING PRINCIPLES

Here, the configuration, operating principles, and main analysis of the proposed MLI are presented.

### A. PROPOSED 9L MLI

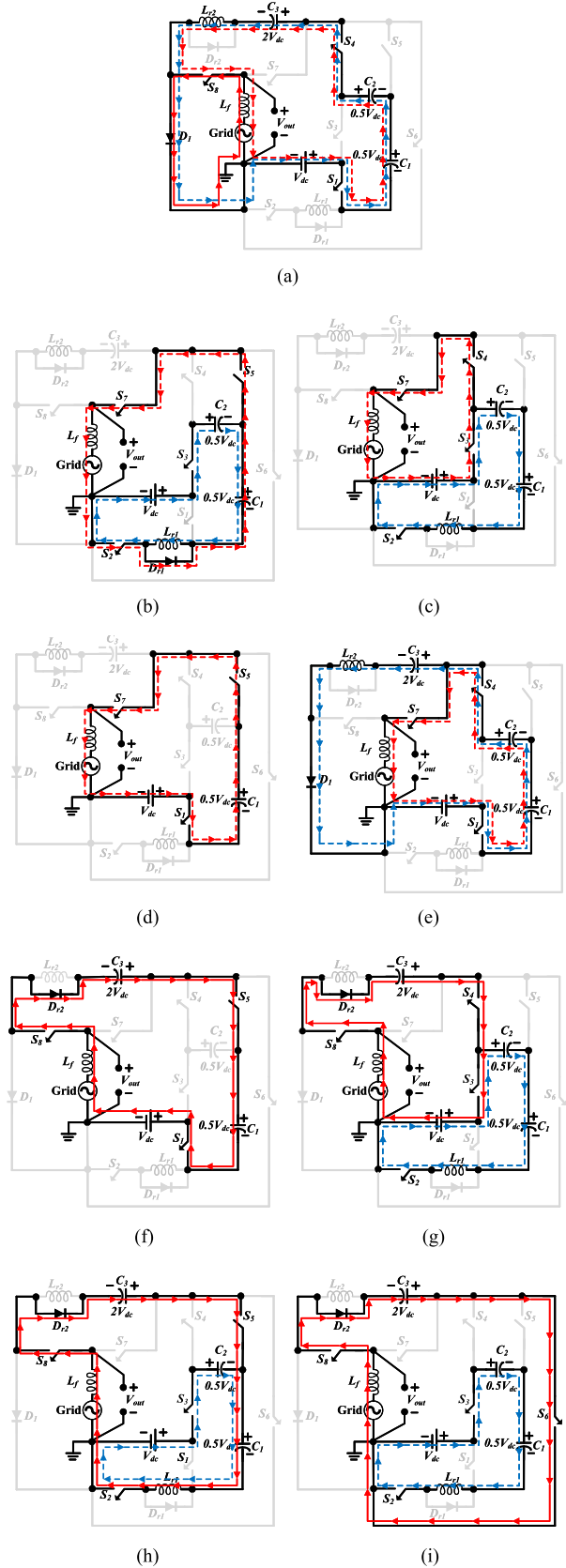
In Fig. 1, the circuit configuration of the proposed CGSC-TL MLI is presented. This topology can generate a 9L output voltage by employing a new SC cell consisting of eight power switches and three diodes. It is noteworthy that the switches used here include seven unidirectional ( $S_1, S_2, S_3, S_4, S_6, S_7$ , and  $S_8$ ) and one bidirectional switch ( $S_5$ ). Here, it is essential to use this bidirectional switch due to its bipolar voltage stress. To obtain boosting capability for the proposed inverter, three capacitors ( $C_1, C_2$ , and  $C_3$ ), paralleled with a single input dc source ( $V_{dc}$ ), are used in this MLI, as seen in Fig. 1. Besides, for reducing the capacitor current spikes as one of the main problems in SC-based inverters, this MLI employs two units, including one inductor paralleled with one diode ( $L_{r1}$  with  $D_{r1}$  and  $L_{r2}$  with  $D_{r2}$ ), in the capacitors' charging current path. As seen in Fig. 1, the grid neutral point is directly connected to the negative terminal of the source, classifying this MLI as a CG inverter. This feature, important for TL grid-tied systems, enables the mitigation of the leakage current in this MLI. Furthermore, both reactive and active power exchange with the grid are supported.

### B. OPERATING MODES

The operating modes of the proposed MLI are presented and discussed here. Fig. 2 illustrates these modes along with their current paths. In each charging mode, the capacitors  $C_1$  and  $C_2$  are charged to  $0.5V_{dc}$ , while the capacitor  $C_3$  is charged to  $2V_{dc}$ . Detailed descriptions of the operating modes are provided in the following.

#### 1) MODE 1

The first operating mode for both half-cycles is illustrated in Fig. 2(a). In the negative half-cycle ( $V_{zero,N}$ ), the zero voltage level is produced with  $S_8$  and  $D_1$  conducting. In the positive half-cycle ( $V_{zero,P}$ ), the zero level is obtained with  $S_1, S_4$ , and



**FIGURE 2.** Operating modes of the proposed MLI. (a) Mode 1. (b) Mode 2. (c) Mode 3. (d) Mode 4. (e) Mode 5. (f) Mode 6. (g) Mode 7. (g) Mode 8. (i) Mode 9.

$S_8$  turned ON. With  $S_1$ ,  $S_4$ , and  $D_1$  ON, the charging loop is formed, as indicated by the blue dashed path in Fig. 2(a). In this configuration,  $C_3$  is connected in series with  $C_1$ ,  $C_2$ , and the input dc source, thereby allowing  $C_3$  to be charged to  $2V_{dc}$ . The voltage relations for this operating mode are given as follows:

$$V_{C3} = V_{C1} + V_{C2} + V_{dc} = 2V_{dc} \quad (1)$$

$$V_{zero,N} = 0 \quad (2)$$

$$V_{zero,P} = -V_{dc} - V_{C1} - V_{C2} + V_{C3} = 0. \quad (3)$$

## 2) MODE 2

The second operating mode, which provides the first output voltage level in the positive half-cycle, is illustrated in Fig. 2(b). In this mode,  $S_2$ ,  $S_5$ ,  $S_7$ , and  $D_{r1}$  are turned ON. To charge  $C_1$  and  $C_2$  to  $0.5V_{dc}$ ,  $S_2$  and  $S_3$  are placed in conduction. During the charging interval, the capacitors' charging current (blue dashed path) flows through  $L_{r1}$ , thereby limiting the charging spike. In this mode,  $C_3$  is isolated from both the dc and ac sides. The stored energy in  $C_1$  is delivered to the output, establishing the first voltage level in the positive half-cycle. The voltage relations for this mode are given as follows:

$$V_{Ci} = 0.5V_{dc} \text{ for } i = 1, 2 \quad (4)$$

$$V_{out} = V_{C1} = 0.5V_{dc}. \quad (5)$$

## 3) MODE 3

Mode 3 is shown in Fig. 2(c). The second output voltage level in the positive half-cycle is obtained by directly connecting the dc source ( $V_{dc}$ ) to the output with  $S_3$ ,  $S_4$ , and  $S_7$  turned ON. In this mode, no capacitor is included in the load current path (red dashed line). As indicated in Fig. 2(c),  $C_1$  and  $C_2$  are recharged to  $0.5V_{dc}$  ( $V_{C2} = V_{C1} = 0.5V_{dc}$ ) by switching  $S_2$  and  $S_3$  ON. The voltage equations for this mode are given as follows:

$$V_{out} = V_{dc}. \quad (6)$$

## 4) MODE 4

As illustrated in Fig. 2(d), the third output voltage level in the positive half-cycle is obtained with  $S_1$ ,  $S_5$ , and  $S_7$  turned ON. The output voltage is obtained by summing the voltages of the capacitor  $C_1$  and the dc source, that is,  $V_{out} = 1.5V_{dc}$ . In this mode,  $C_1$  is in discharging operation, while  $C_2$  and  $C_3$  are isolated from the circuit. The voltage relation for this mode is expressed as follows:

$$V_{out} = V_{dc} + V_{C1} = 1.5V_{dc}. \quad (7)$$

## 5) MODE 5

This mode's equivalent circuit is illustrated in Fig. 2(e), where the fourth output voltage level in the positive half-cycle is generated. In this condition,  $D_1$ ,  $S_1$ ,  $S_4$ , and  $S_7$  are conducting, and the output voltage is formed by adding the voltages of  $C_1$ ,  $C_2$ , and the dc source. In this mode,  $C_3$  is being charged. The voltage relation for this mode is obtained by the following

equation:

$$V_{out} = V_{C1} + V_{C2} + V_{dc} = 2V_{dc}. \quad (8)$$

## 6) MODE 6

Fig. 2(f) illustrates this operating condition, under which the first negative output level ( $-0.5V_{dc}$ ) is produced. In this configuration,  $S_1$ ,  $S_5$ ,  $S_8$ , and  $D_{r2}$  are placed in the ON state, and  $C_1$  and  $C_3$ , together with the input source, are connected in series and applied to the inverter output port. As shown in Fig. 2(f),  $C_2$  remains isolated from the circuit. The voltage relation for this mode can be written as follows:

$$V_{out} = -V_{C3} + V_{C1} + V_{dc} = -0.5V_{dc}. \quad (9)$$

## 7) MODE 7

This operating condition is depicted in Fig. 2(g), wherein the second output voltage level during the negative half-cycle is established with  $S_3$ ,  $S_4$ ,  $S_8$ , and  $D_{r2}$  placed in the ON state. As indicated in Fig. 2(g), activation of  $S_2$  and  $S_3$  connects  $C_2$  and  $C_1$  to the dc source, and each capacitor is charged to  $0.5V_{dc}$ . During this charging interval, the blue dashed current path is routed through  $L_{r1}$ , by which the charging spike is limited. In the same mode,  $C_3$  operates in discharge. The output voltage for this mode is therefore obtained as follows:

$$V_{out} = V_{C1} - V_{C3} + V_{C2} = -V_{dc}. \quad (10)$$

## 8) MODE 8

The eighth operating mode of the proposed MLI is illustrated in Fig. 2(h) and generates the third negative level of the output voltage waveform. In this condition,  $C_1$  and  $C_3$  are placed in series with  $S_2$ ,  $S_5$ ,  $S_8$ , and  $D_{r2}$  conducting. In addition,  $S_3$  is held ON, whereby  $C_2$  and  $C_1$  are charged. Accordingly, the inverter output-port voltage is given by the following relation:

$$V_{out} = -V_{C3} + V_{C1} = -1.5V_{dc}. \quad (11)$$

## 9) MODE 9

In this mode, the fourth output voltage level during the negative half-cycle is provided. This operation is depicted in Fig. 2(i), where  $S_6$ ,  $S_8$ , and  $D_{r2}$  are turned ON, thereby discharging  $C_3$  to the inverter output port. Consequently, the peak output voltage equals twice the dc source voltage, which realizes the voltage-boosting feature of the proposed MLI. Meanwhile, with  $S_2$  and  $S_3$  ON,  $C_1$  and  $C_2$  are placed in series with the dc input source and brought to  $0.5V_{dc}$  (blue dashed path). During this interval,  $C_3$  remains in discharging operation. The voltage equations for this mode are given as follows:

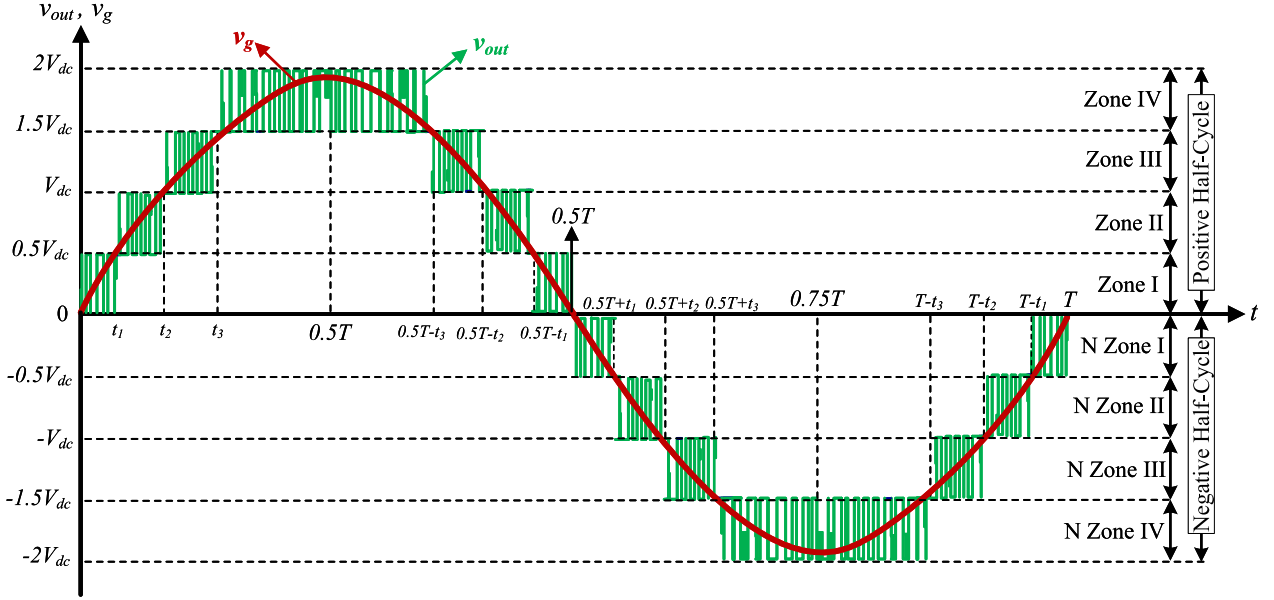
$$V_{C1} = V_{C2} = 0.5V_{dc} \quad (12)$$

$$V_{out} = -V_{C3} = -2V_{dc}. \quad (13)$$

Table 1 lists the operational modes of the proposed MLI and related switching states, figures, and equations.

**TABLE 1. Operational Modes of the Proposed MLI and Related Switching States, Figures, and Equations**

Modes	Generated output voltage			On-state Switching devices	Capacitors in charging state	Disconnected capacitors	Figure	Voltage equations
	level	+/- half-cycle	Value					
1	Zero	+	$V_{out} = V_{zero,P} = 0$	$S_1, S_4, S_8, D_1$	$C_3$	NA	Fig. 2(a)	(1),(2),(3)
		-	$V_{out} = V_{zero,N} = 0$	$S_1, S_4, S_8, D_1$	$C_3$	NA		NA
2	1st	+	$V_{out} = 0.5V_{dc}$	$S_2, S_5, S_7, D_{r1}, S_3$	$C_1, C_2$	$C_3$	Fig. 2(b)	(4),(5)
3	2nd	+	$V_{out} = V_{dc}$	$S_2, S_3, S_4, S_7$	$C_1, C_2$	$C_3$	Fig. 2(c)	(6)
4	3rd	+	$V_{out} = 1.5V_{dc}$	$S_1, S_5, S_7$	NA	$C_2, C_3$	Fig. 2(d)	(7)
5	4th	+	$V_{out} = 2V_{dc}$	$D_1, S_1, S_4, S_7$	$C_3$	NA	Fig. 2(e)	(8)
6	1st	-	$V_{out} = -0.5V_{dc}$	$S_1, S_5, S_8, D_{r2}$	$C_1$	$C_2$	Fig. 2(f)	(9)
7	2nd	-	$V_{out} = -V_{dc}$	$D_{r2}, S_2, S_3, S_4, S_8$	$C_1, C_2$	NA	Fig. 2(g)	(10)
8	3rd	-	$V_{out} = -1.5V_{dc}$	$S_2, S_3, S_5, S_8, D_{r2}$	$C_1, C_2$	NA	Fig. 2(h)	(11)
9	4th	-	$V_{out} = -2V_{dc}$	$S_2, S_3, D_{r2}, S_6, S_8$	$C_1, C_2$	NA	Fig. 2(i)	(12),(13)


**FIGURE 3. Output voltage of the proposed MLI, the grid voltage, and the operating zones of the proposed MLI.**

### C. DUTY CYCLE CALCULATIONS FOR SWITCHES

In this section, the switching duty cycles for the various operating modes of the proposed MLI are derived. Fig. 3 depicts the voltage waveform of the inverter output and the grid over both half-cycles, with four zones defined for each half-cycle (Zones I–IV for the positive half-cycle and N Zone I–N Zone IV for the negative half-cycle). The inverter maximum switching frequency and the sampling frequency are denoted by  $f_s$  and  $f_{SA}$ , respectively, with  $f_{SA} = 2f_s$ . By applying the inductor volt-second balanced (IVSB) method to the voltage across the output-filter inductor ( $L_f$ ) over the full switching period ( $T_s$ ), the duty cycles for these zones are obtained by (16)–(27). Generally, the grid voltage and current can be, respectively, written as follows:

$$v_g(t) = V_{g,max} \sin(\omega t) \quad (14)$$

$$i_g(t) = I_{g,max} \sin(\omega t). \quad (15)$$

Note that  $V_{out}$ ,  $i_g$ , and  $v_g$ , respectively, denote the inverter's output voltage and the grid's current and voltage. In addition,

$I_{g,max}$ , and  $V_{g,max}$ , respectively, present the maximum values of the grid's current and voltage.

#### 1) ZONE I

As indicated in Fig. 3, the inverter output voltage in this zone lies between 0 and  $0.5V_{dc}$ . By applying the IVSB principle to the output inductor voltage over the sampling interval, the inverter duty cycle  $d_1(t)$  is obtained as (16)–(18) for  $0 \leq t < t_1$

$$\int_0^{d_1 T_s} (-v_g + 0.5V_{dc}) dt + \int_{d_1 T_s}^{T_s} (-v_g) dt = 0 \quad (16)$$

$$d_1(t) = \frac{v_g}{0.5V_{dc}}. \quad (17)$$

Using (14) in (17), the duty cycle of Zone I is acquired as follows:

$$d_1(t) = \frac{2V_{g,max} \sin(\omega t)}{V_{dc}}. \quad (18)$$

**TABLE 2.** Applied PCC Operation Approach of Switching Pulses for Positive Half-Cycle

Zones	Positive half-cycle			
	Active power mode		Reactive power mode	
	$V_g > 0 \ \& \ i_{ref} > 0$		$V_g > 0 \ \& \ i_{ref} < 0$	
	$i_g > i_{ref}$	$i_g < i_{ref}$	$i_g < i_{ref}$	$i_g > i_{ref}$
Zone I: $0 < V_g < 0.5V_{dc}$	$S_1, S_4, S_8$	$S_2, S_3, S_5, S_7$	$S_2, S_3, S_5, S_7$	$S_1, S_4, S_8$
Zone II: $0.5V_{dc} < V_g < V_{dc}$	$S_2, S_3, S_5, S_7$	$S_2, S_3, S_4, S_7$	$S_2, S_3, S_4, S_7$	$S_2, S_3, S_5, S_7$
Zone III: $V_{dc} < V_g < 1.5V_{dc}$	$S_2, S_3, S_4, S_7$	$S_1, S_5, S_7$	$S_1, S_5, S_7$	$S_2, S_3, S_4, S_7$
Zone IV: $1.5V_{dc} < V_g < 2V_{dc}$	$S_1, S_5, S_7$	$S_1, S_4, S_7$	$S_1, S_4, S_7$	$S_1, S_5, S_7$

## 2) ZONE II

As seen in Fig. 3, in Zone II, the inverter's output voltage lies between  $0.5V_{dc}$  and  $V_{dc}$ . By applying the IVSB principle to the output-filter inductor's voltage over the sampling interval, the duty cycle ( $d_2(t)$ ) is obtained, for  $t_1 \leq t < t_2$ , as follows:

$$\int_0^{d_2 T_s} (-v_g + V_{dc}) dt + \int_{d_2 T_s}^{T_s} (-v_g + 0.5V_{dc}) dt = 0 \quad (19)$$

$$d_2(t) = \left( 2\left(\frac{v_g}{V_{dc}}\right) - 1 \right) = \left( \frac{2V_{g,max} \sin(\omega t)}{V_{dc}} - 1 \right). \quad (20)$$

Considering (18), (20) can be rewritten as

$$d_2(t) = d_1(t) - 1. \quad (21)$$

## 3) ZONE III

As indicated in Fig. 3, the inverter output voltage in Zone III lies between  $V_{dc}$  and  $1.5V_{dc}$ . By applying the IVSB principle to the output-filter inductor voltage over the sampling interval, the duty cycle  $d_3(t)$  is obtained, for  $t_2 \leq t < t_3$ , as follows:

$$\int_0^{d_3 T_s} (1.5V_{dc} - v_g) dt + \int_{d_3 T_s}^{T_s} (V_{dc} - v_g) dt = 0 \quad (22)$$

$$d_3(t) = \left( \frac{2v_g}{V_{dc}} - 2 \right) = \left( \frac{2V_{g,max} \sin(\omega t)}{V_{dc}} - 2 \right). \quad (23)$$

Using (20), (23) can be expressed as follows:

$$d_3(t) = d_2(t) - 1. \quad (24)$$

## 4) ZONE IV

As illustrated in Fig. 3, the inverter's output voltage in Zone IV lies between  $1.5V_{dc}$  and  $2V_{dc}$ . By applying the IVSB principle to the output-filter inductor voltage over the sampling interval in this zone, the duty cycle  $d_4(t)$  is obtained, for  $t_3 \leq t < (T/2 - t_3)$ , as follows:

$$\int_0^{d_4 T_s} (2V_{dc} - v_g) dt + \int_{d_4 T_s}^{T_s} (1.5V_{dc} - v_g) dt = 0 \quad (25)$$

$$d_4(t) = \frac{2v_g - 3V_{dc}}{V_{dc}} = \frac{2V_{g,max} \sin(\omega t) - 3V_{dc}}{V_{dc}}. \quad (26)$$

Based on (23), (26) can be expressed as follows:

$$d_4(t) = d_3(t) - 1. \quad (27)$$

In (27), based on Fig. 3,  $t_k$ , where  $k = 1, 2, 3$ , can be defined as

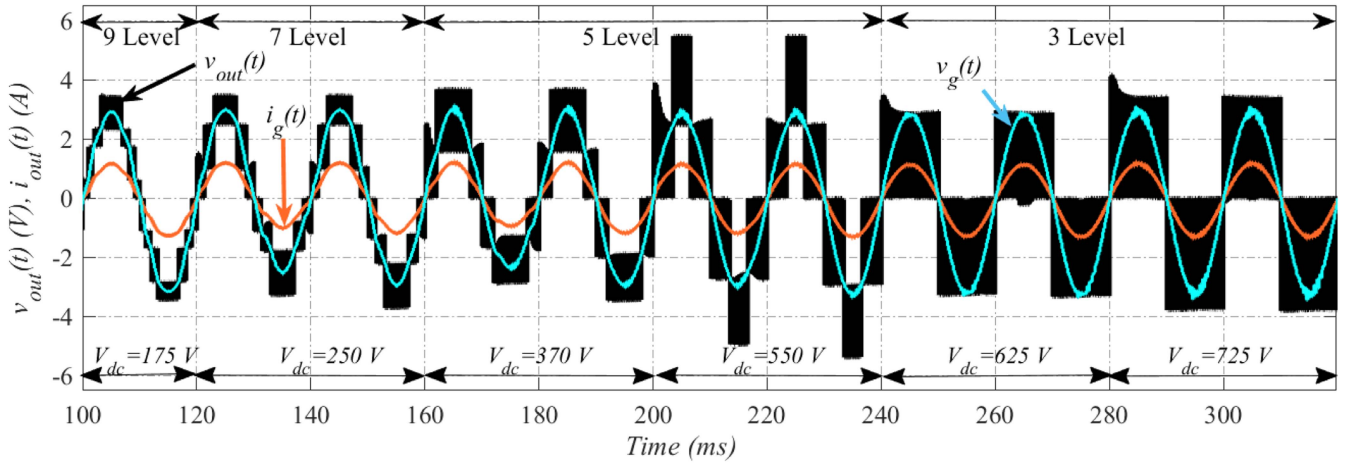
$$t_1 = \frac{1}{\omega} \sin^{-1} \left( \frac{V_{g,max}}{0.5k(V_{dc})} \right). \quad (28)$$

In the proposed MLI, for handling both reactive and active powers and also generating the switches' gate pulses ( $S_1$ – $S_8$ ), the strategy of the peak current controller (PCC) is used [19]. Table 2 shows the applied PCC operating approach of switching pulses for the positive half-cycle. It is noteworthy that the switching zones of the negative half-cycle can be obtained by performing the similar done for the positive half-cycle.

As previously discussed, a key advantage of the proposed 9L MLI is its capability to inject power into the grid over a wide range of input dc voltages. In general, the boosting capability of the inverter imposes a first theoretical lower bound on the required dc-link voltage. This bound, however, is not sufficient on its own, because the highest output voltage level of the inverter before the output filter must exceed the grid peak voltage. For example, for a 220-V RMS grid (with a peak voltage of 311 V), this boosting-based criterion yields a theoretical minimum dc-link voltage of 156 V, whereas the actual dc-link voltage must be selected higher than this limit in order to satisfy the aforementioned design requirement. To verify this advantage, precise simulations have been performed using MATLAB/Simulink. The obtained results are presented in Fig. 4. This figure shows that the input voltage varies between 175 and 725 V. In proportion to this change, the output voltage changes from 9L to 3L, so that the proposed topology can properly inject power into the grid under this condition. As seen in Fig. 4, by step changing the input voltage from 175 to 250 V at  $t = 120$  ms, the output voltage changes from 9L to 7L. In addition, this figure shows that changing the input voltage from 250 to 370 V at  $t = 160$  ms changes the output voltage from 7L to 5L. Besides, when the input voltage changes from 550 to 625 V at  $t = 240$  ms, the output voltage changes from a 5L to a 3L waveform; in other words, the proposed MLI can operate with a broad input voltage range if application requires it.

## D. SIZING CAPACITORS AND OUTPUT FILTER

Initially, the capacitors of the proposed MLI are sized according to each device's longest discharging cycle (LDC). For  $C_1$ ,  $C_2$ , and  $C_3$ , the LDC occurs during the positive and negative half-cycles, respectively. The peak discharging current for a



**FIGURE 4.** Simulation results of the proposed MLI for a wide input voltage.

capacitor over its LDC is obtained as

$$I_{\text{Cap}} = \frac{dQ_{\text{Cap}}}{dt} = \frac{d}{dt} \left( \int I_{\text{Cap}} dt \right). \quad (29)$$

Furthermore, the sizes of  $C_1$ ,  $C_2$ , and  $C_3$  are determined by calculation [33]. Here,  $I_{g,\text{max}}$  denotes the maximum amplitude of the injected current. In addition,  $\phi$  is the phase shift between the injected current and the voltage of grid. The output voltage is modeled as a multilevel waveform; therefore, the maximum charge drawn from capacitor  $C_i$  during the half-cycle is given as follows:

$$Q_{Ci} = \int_{(\Delta t_i)} I_{g,\text{max}} \sin(\omega t - \phi) dt \quad (30)$$

where  $i = 1, 2, 3$ ;  $I_{g,\text{max}}$  is the peak injected grid current,  $T$  is the grid-voltage period, and the fundamental angular frequency of the output voltage is represented by  $\omega$ . The interval  $\Delta t$  corresponds to the LDC of each capacitor, which differs for  $C_1$ ,  $C_2$ , and  $C_3$ . With  $\Delta V_{\text{max}}$  taken as the permissible voltage ripple, the required capacitance satisfies the following:

$$C_{\text{opt},i} \geq \frac{Q_{Ci}}{\Delta V_{\text{max}}}. \quad (31)$$

In the proposed system, the maximum current ripple of the output-filter inductor occurs at unity power factor and at the peak of the injected grid current ( $t = T/4$ ). At  $t = T/4$ , the proposed MLI operates in mode 5 with  $V_{\text{out}} = 2V_{\text{dc}}$ . Over one switching period, the inductor current is obtained as

$$i_{Lf}(t) = \frac{1}{L_f} \int_0^t V_{Lf} dt + i_{Lf}(0) \quad (32)$$

where  $V_{Lf}$  is the output-filter voltage. From (32), the output-filter current ripple is calculated as follows:

$$\Delta I_{Lf} = i_{Lf}(d_4 T_s) - i_{Lf}(0) = \frac{(2V_{\text{dc}} - V_g)d_4(t)}{L_f f_s} \quad (33)$$

with  $d_4(t)$  the Zone IV duty cycle given in (26). Accordingly,  $L_f$  is obtained as

$$L_f = \frac{4V_{g,\text{max}} \sin(\omega t) - 6V_{\text{dc}} + 3V_{g,\text{max}} \sin(\omega t)}{\Delta I_{Lf} f_s} - \frac{2(V_{g,\text{max}} \sin(\omega t))^2}{\Delta I_{Lf} f_s V_{\text{dc}}}. \quad (34)$$

For the maximum inductor current ripple,  $L_f$  evaluates to

$$L_f = \frac{7V_{g,\text{max}} - 6V_{\text{dc}}}{\Delta I_{Lf,\text{max}} f_s} - \frac{2(V_{g,\text{max}})^2}{\Delta I_{Lf,\text{max}} f_s V_{\text{dc}}}. \quad (35)$$

### III. COMPARISON

Here, the proposed 9L MLI is thoroughly compared with different previously published MLIs employing a single dc input source. Table 3 lists the main parameters and characteristics of the MLIs involved in this section. In Table 3,  $V_g$ ,  $L_f$ ,  $N_s$ ,  $N_c$ , and  $N_d$ , respectively, denote the voltage gain, and the number of output voltage levels, capacitors, diodes, and switches. In addition, NA, NP, and CCCS, respectively, stand for Not Applicable, Not Provided, and Capacitors' Charging Current Spikes. As seen, the proposed inverter uses even comparable number of switching devices compared to some of the MLIs, providing fewer output voltage levels. For instance, the proposed MLI employs eight switches, which is less than or comparable to that of 5L MLI of [33], and 7L MLIs of [34], [35], and [36]. It is worth noting that apart from [23], other 5L and 7L MLIs have a switch-per-level ratio ( $N_s/L$ ) larger than 1. Clearly, this ratio for the proposed MLI is less than 1.

To compare the proposed MLI fairly, the main focus should be on the MLIs with similar output voltage levels. As clearly seen, in most of the 9L SC-based MLIs, including [37], [38], [39], [40], [41], [42], [43], [44], [45], [46], [47], the number of switches is greater than their number of output voltage levels. In other words, the switch-per-level ratio ( $N_s/L$ ) of these MLIs is greater than 1. In the case of inverters of [48], [49], [50], and [51], this ratio is equal to 1. Among these MLIs,

**TABLE 3.** Comparing the Proposed MLI With the Previously Published Single-Phase MLIs

MLIs	$L_V$	$N_S$	$N_D$	$N_C$	$\frac{V_{ds,max}}{V_{o,max}}$	$TSV_{sw}$	$TSV_d$	$\frac{V_{C,max}}{V_{o,max}}$	$V_G$	NPC or CG	CCCS	$C$ (mF)	$f_s$ (kHz)	$V_{dc} \rightarrow V_{o,max}$ (V)	$\eta\%$ & $P_o$ (W) & $f_g$ (Hz)
[25]	5	6	2	2	1	4.5	1.5	1 + 0.5	2	Yes	No	1.0 + 0.47	20	180→360	98.2 & 600 & 50
[33]		9	0	1	0.5	4.5	NA	0.5	2	No	No	3.3	2.5	100→200	97.9 & NP & 50
[23]		6	4	3	1	4	2	1 + 0.67 + 0.33	3	Yes	No	0.22 × 2 + 4	25	130→390	96.13 & 800 & 50
[34]	7	10	0	1	0.67	6	NA	0.67	1.5	Yes	No	0.47	2.5	200→300	96.0 & 1000 & 50
[35]		9	0	2	1.33	7.667	NA	0.67 × 2	1.5	Yes	No	4.7 × 2	5	100→150	98.3 & 150 & 50
[36]		8	0	1	0.67	5.33	NA	0.67	1.5	Yes	No	4.4	-(ffm)	50→150	96.76 & 250 & 60
[37]		11	0	3	1	5.5	NA	0.5 × 2 + 0.25	4	No	No	4.3 × 2 + 2	20	80→320	96.0 & 1000* & 50
[38]		19	0	3	0.25	4.725	NA	0.25 × 3	4	No	No	4.7 × 3	2	48→192	88.93 & NP & 50
[52]		8	1	2	1	6.5	0.25	0.25 × 2	2	No	No	1.0 × 2	NP	200→400	95.5 & 1000 & 50
[39]		10	0	2	0.5	5.5	NA	0.25 × 2	2	No	No	4.7 × 2	2.5	160→320	NP & 400 & 50
[53]		8	4	4	1	4	1.5	0.5 × 2 + 0.25 × 2	4	No	No	2.3 × 2 + 4.7 × 2	4	70→280	92.75 & 1000 & 50
[54]		8	3	3	1	4	1.25	0.5 × 2 + 0.25	4	No	No	3.3 × 2 + 3.3	4	80→320	93.0 & 500 & 50
[48]		9	3	3	0.75	5.25	0.75	0.25 × 2 + 0.75	4	Yes	No	1.0 × 2 + 3.3	10	100→400	95.2 & 1000 & 50
[49]		9	0	4	1	5.5	NA	0.5 × 2 + 0.25 × 2	1	No	No	2.2 × 2 + 4.7 × 2	2.5	200→200	97.4 & 500* & 50
[40]		17	4	4	1	6	NP	0.25 × 4	4	Yes	No	4.7 × 4	5	40→227 (160 rms)	NP & 275 & 50
[41]		10	NA	3	0.5	5	NA	0.5 + 0.25 × 2	2	No	No	2.2 × 3	2.5	70→140	97.8 & 100 & 50
[55]	9	8	2	3	1	4.5	1	0.25 + 0.5 × 2	2	No	No	1.6 × 3	2	100→200	NP & NP & 50
[42]		10	3	3	1	5.5	0.75	0.25 × 3	4	No	Yes	4.7 × 3	3	80→320 (221.15 rms)	96 & 1400 & 50
[43]		12	0	2	0.5	5.25	NA	0.25 + 0.5	4	No	No	2.2 × 3.3	2.5 × 8 + (ffm) × 4	75→300	NP & 1500 & 50
[44]		11	0	3	0.5	5.25	NA	0.5 + 0.25 × 2	2	No	No	2.2 × 2 + 4.7	NP	100→200	95.5 & 250 & 50
[45]		10	3	2	0.5	4.5	1.25	0.5 + 0.25	4	No	No	4.7 × 3.3	HF×8 + (ffm) × 2	100→400	95.2 & 989.4 & 50
[46]		14	0	2	0.5	4.75	NA	0.5 + 0.25	4	No	No	2.2 × 2	2	30→120	93 & 250 & 50
[47]		10	0	2	0.5	5.5	NA	0.25 × 2	2	No	No	4.7 × 3.4	2.5	120→240	96.5 & 480 & 50
[50]		9	2	2	1	6.25	NP	0.25 × 2	2	No	No	1 + 1	40	200→400	96.4* & 1000* & 50
[51]		9	1	3	1	5	1	0.25 + 0.5 × 2	2	Yes	No	0.33 × 2 + 0.48	20	200→400	97.5 & 1200 & 400
[P]		8	3	3	1	5.25	1	1 + 0.25 × 2	2	Yes	Yes	1.0 × 2 + 2.2	20	200→400	97.9* & 250 & 50

**TABLE 4.** Parameters Used in the Simulations

Parameter	Symbol	Value
Grid Voltage (rms)	$V_g$	220 V
First and second Switched-Capacitor	$C_1$ & $C_2$	1.2 mF
Third Switched-Capacitor	$C_3$	2.2 mF
Grid Frequency	$f_g$	50 Hz
Switching Frequency	$f_s$	30 kHz
Output Filtering Inductor	$L_f$	2 mH
Charging Current's Spike Inductor	$L_{r1}$ & $L_{r2}$	0.3 mH

the MLIs of [49] and [50] also do not have CG topologies. In terms of the number of power switches, the best MLIs are the proposed MLI and the inverters of [52], [53], [54], and [55]; the ratio of  $N_S/L$  is less than 1 for these converters. Although the number of switches employed by the inverters of [52], [53], [54], and [55] is equal to the proposed one, their structures are not CG, unlike the proposed MLI. This means that they (see [52], [53], [54], and [55]) cannot eliminate the leakage current of PV panels, making them inappropriate options for solar applications. According to Table 3, the proposed converter is the only inverter that provides both CCCS and CG features, leading to advantages like less EMI, longer life cycle for capacitors, and leakage current elimination. These merits make the proposed MLI the best option for modern industrial applications like solar systems among the MLIs in the same class.

As seen in Table 3, the ratio of maximum voltage stress on the components to the maximum value of the output voltage is used to have fair comparisons, i.e.,  $V_{ds,max}/V_{o,max}$  and  $V_{C,max}/V_{o,max}$ . Here,  $V_{ds,max}$ ,  $V_{C,max}$ , and  $V_{o,max}$ , respectively, denote the maximum voltage stress on the switches, maximum voltage stress on the capacitors, and the maximum output voltage value. According to Table 3, in terms of the ratio of maximum voltage stress on the power switches (with minimum and maximum values of 0.25 and 1.33) and the ratio of maximum voltages of the capacitors (with minimum and maximum values of 0.25 and 1), the proposed MLI is comparable to the previously published structures. In the proposed MLI, the ratios of maximum voltage stress on its different

capacitors are equal to 0.25, 0.25, and 1. Moreover, the ratio of maximum voltage stress on its switches is equal to 1, which is less than that of other inverters. For synthesizing both the voltage stresses and numbers of the semiconductors, the normalized values of total standing voltages (TSVs) of the diodes and switches are, respectively, defined as follows:

$$TSV_d \text{ (p.u.)} = \frac{1}{V_{o,max}} \sum_1^{N_D} V_{di} \quad (36)$$

$$TSV_{sw} \text{ (p.u.)} = \frac{1}{V_{o,max}} \sum_1^{N_S} V_{dsi} \quad (37)$$

As seen in Table 3, considering all of the compared MLIs, the maximum and minimum values of  $TSV_{sw}$  and  $TSV_d$  are, respectively, equal to (4 and 7.667) and (0.25 and 2). For the proposed inverter, these values are less than the maximum values of these parameters. By focusing on only 9L MLIs, the maximum values of these parameters, i.e.,  $TSV_{sw}$  and  $TSV_d$ , are, respectively, equal to 6.5 and 1.5. This means that the proposed MLI imposes voltage stresses less than the maximum values of 9L MLIs. As seen, the proposed MLI provides a lower  $TSV_{sw}$  compared to 9L MLIs introduced in [37], [39], [40], [42], [47], [49], [50], and [52]. In terms of  $TSV_d$ , the proposed MLI provides a lower or comparable value compared with the MLIs in [45], [51], [53], [54], and [55]. The lowest  $TSV_d$  values are achieved by Barzegarkhoo et al. [52], followed by the authors in [42] and [48]. In addition, the sizes of capacitors used in these MLIs are listed in Table 3. As seen, the sizes of the capacitors used in the proposed MLI are also close to or smaller than those of other MLIs.

For RES applications like solar energy, it is essential for TL inverters to eliminate the leakage current of PV panels. Considering this fact, the proposed MLI and the inverter of [40], [48], and [51] are the only structures that are suitable for the mentioned application. However, in contrast to the proposed MLI, the MLIs of [40], [48], and [51], suffer from high charging current spikes of their capacitors, causing serious

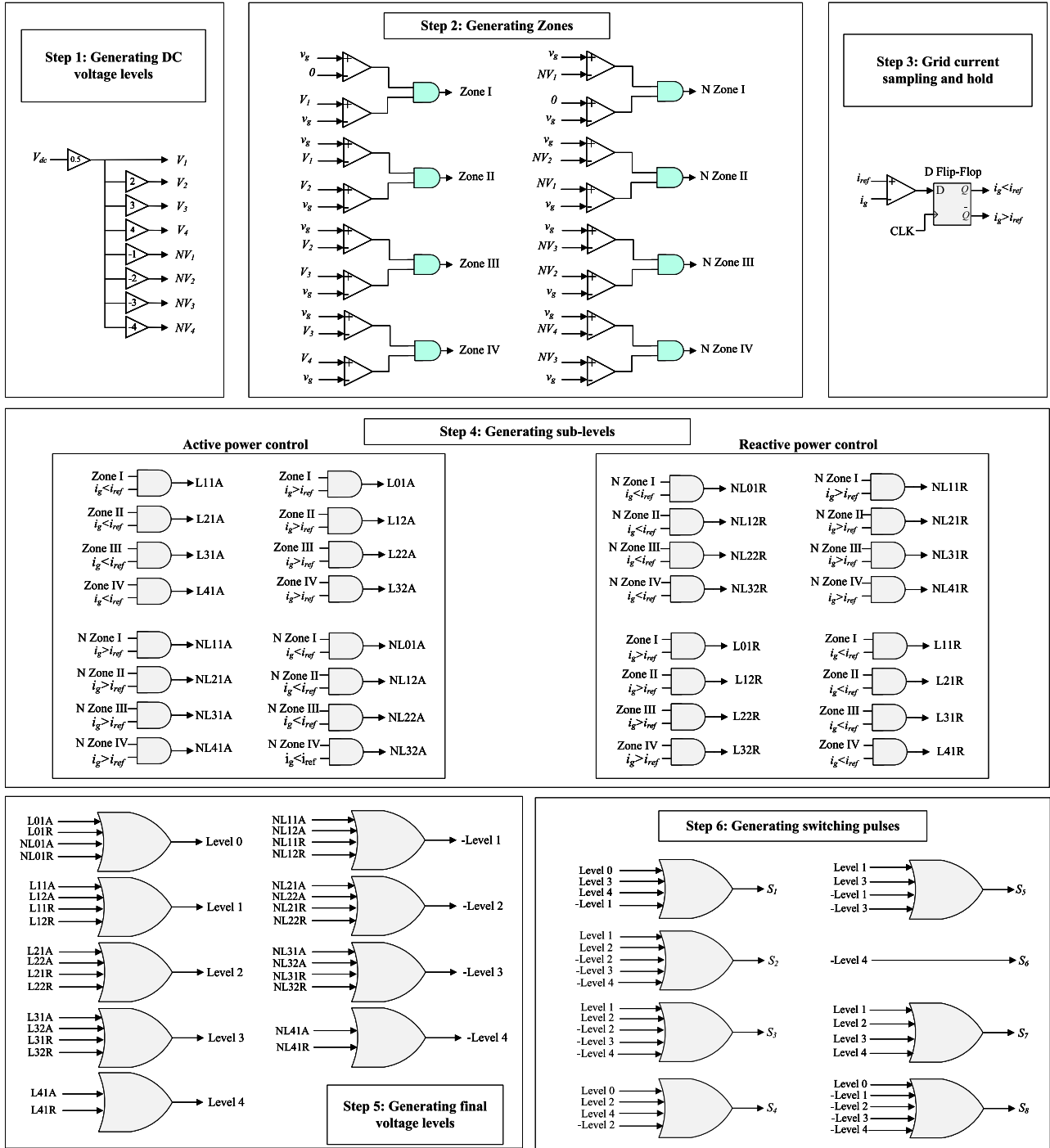


FIGURE 5. Block diagram of the employed PCC.

drawbacks like increased power losses, higher EMI, and shortening the life cycle of their capacitors. Besides the proposed MLI, only the MLI of [42] can provide CCCS. However, this MLI employs more switches and power components than the proposed one and does not have a CG structure. Notably, the MLI of [55] employs a much larger number of switches and components than the proposed one. Compared to these four MLIs, i.e., [40], [48], [51], and [55], the voltage stress on the switches, diodes, and capacitors, and the size of the

passive components of the proposed MLI are close or less. It is noteworthy that in the case of the MLI of [51], the sizing of the capacitors has been done by considering the network/grid frequency of 400 Hz. Considering  $f_g = 50\text{Hz}$  and based on [51], these capacitors will be sized as 2.62, 2.62, and 3.84 mF. In addition, the proposed inverter has a high efficiency among 9L inverters based on Table 3. Hence, the proposed MLI is the superior option for RES applications, like solar PV systems.

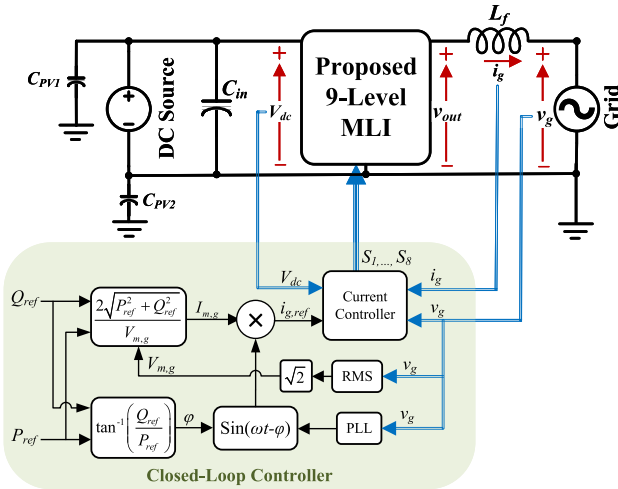


FIGURE 6. Block diagram of the test system used in the simulation.

## IV. RESULTS AND DISCUSSIONS

### A. SIMULATION RESULTS

Here, simulation results are presented to demonstrate the performance of the proposed MLI. All results are obtained in MATLAB/Simulink environment using nonideal device and passive models. The parameters used in the simulations are listed in Table 4. The block diagram of the test system, containing the designed closed-loop controller, is shown in Fig. 6. This controller can inject the required active and reactive power into the grid if their reference values ( $P_{ref}$  and  $Q_{ref}$ ) are given. The closed-loop controller presented in [50] is used here. The switching pulses are generated based on the current controller. Fig. 5 shows the controller workflow in detail. In general, at each sampling instant, the grid current ( $i_g$ ) is measured and compared with the reference current. The modulation zone is determined from the instantaneous grid voltage, and the two admissible voltage levels are identified; if  $|i_g| < |i_{ref}|$ , select the upper level; otherwise, select the lower level. Finally, the corresponding switching state is generated and sent to the inverter. This direct comparison-based logic provides fast current tracking with low computational burden and maintains robust operation under varying conditions due to sample-by-sample updates and zone-based voltage selection. In this article, the sinusoidal reference current  $i_{ref}$  is generated from the commanded active/reactive powers ( $P_{ref}$ ,  $Q_{ref}$ ).

In the context of TL PV inverters, leakage current typically refers to the PV-to-ground common-mode leakage current. This current flows through the parasitic capacitances between ground and PV. In Fig. 6, the parasitic capacitors of the PV panel are represented by  $C_{PV1}$  and  $C_{PV2}$ . It is noteworthy that the sizes of these capacitors are very small. For  $C_{PV2}$ , the voltage across its terminals is zero, i.e.,

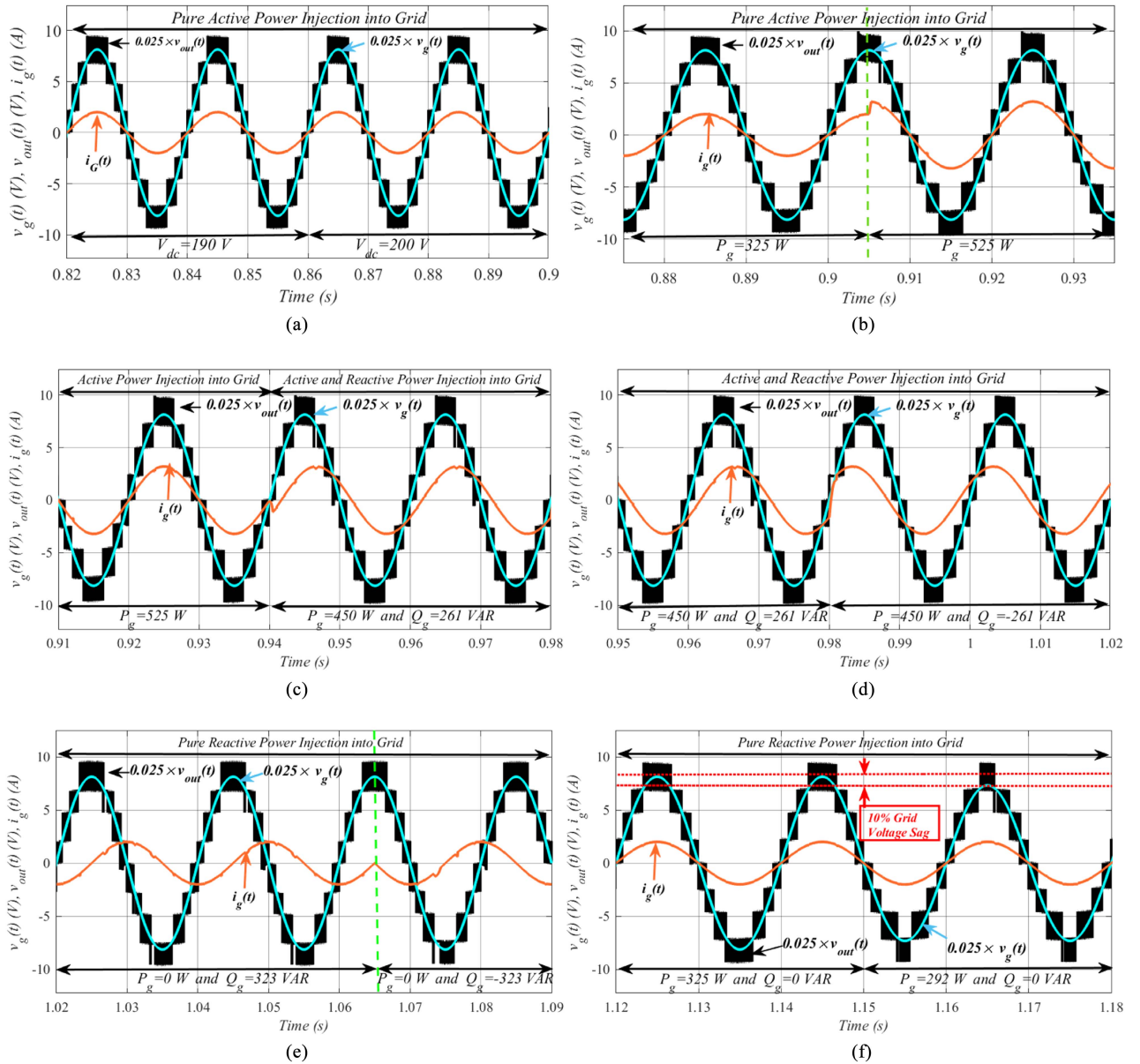
$$v_{C_{PV2}}(t) = 0 \Rightarrow i_{C_{PV2}}(t) = C_{PV2} \frac{dv_{C_{PV2}}(t)}{dt} = 0 \quad (38)$$

which means no leakage current flows through  $C_{PV2}$ . For  $C_{PV1}$ , the voltage across the capacitor is constant and equal to the dc-link voltage  $V_{dc}$ , hence

$$i_{C_{PV1}}(t) = C_{PV1} \frac{dv_{C_{PV1}}(t)}{dt} = C_{PV1} \frac{dV_{dc}}{dt} \approx 0 \quad (39)$$

which results in only a negligible current. Therefore, the CG structure of the proposed converter ensures an effective reduction of the leakage current associated with these parasitic capacitances. To be more specific, the proposed CG structure maintains a constant common-mode voltage across the modeled PV parasitic capacitances, thereby suppressing the dominant PV-to-ground leakage current component linked to these capacitances. It should be noted that, in practice, the CG structure significantly reduces the PV-to-ground leakage current compared with conventional TL topologies without a CG feature, while acknowledging that small residual leakage may still exist through other parasitic paths.

The simulation results of the proposed MLI are illustrated in Fig. 7. Unlike Fig. 7(a) and (b) where only active power injection into the grid is aimed, the proposed MLI exchanges both reactive and active powers with respect to the grid in Fig. 7(c) and (d). As seen in Fig. 7(a), the proposed inverter has a desirable and stable performance under applying a step change in input dc voltage ( $V_{dc}$ ), i.e., increasing dc voltage from 190 to 200 V at  $t = 0.86$  s does not affect the output voltage and current. In Fig. 7(b), the reference active power is suddenly increased from 325 to 525 W at  $t = 0.905$  s, leading to an increase in the amplitude of the injected current into the grid. As clearly shown, the proposed inverter can maintain its stable performance under this step change. As seen in Fig. 7(c), the proposed MLI can operate properly even under the step changes of both reference active and reactive powers. As seen, the applied step change in reactive power leads to a remarkable change in the injected current's phase angle into the grid. In Fig. 7(d), the amplitude of the apparent power injected into the grid is constant, and the step change has been applied in the phase angle of the injected current into the grid, leading to a step change only in the injected reactive power. In Fig. 7(e), the pure reactive power performance of the proposed MLI is demonstrated. It can be observed that the inverter maintains desirable operation even when a step change in the reactive power reference occurs at  $t = 1.065$  s. Moreover, Fig. 7(f) illustrates that the proposed MLI can successfully sustain the injected current into the grid unchanged, even in the presence of a grid disturbance, here represented by a sudden voltage drop (10% sag) of the grid-voltage amplitude. In Fig. 8, the proposed inverter's performance in mitigating the CCCS is shown. As mentioned, the diodes  $D_{r1}$  and  $D_{r2}$  along with the inductors  $L_{r1}$  and  $L_{r2}$  are used for this aim. In other words, while charging the capacitors, the current passes through the mentioned inductors, leading to the mitigated CCCS. Unlike Fig. 8(a) where the proposed inverter circuit lacks the mentioned components ( $D_{r1}$ ,  $D_{r2}$ ,  $L_{r1}$ , and  $L_{r2}$ ), it is clearly shown in Fig. 8(b) that the proposed MLI can remarkably mitigate CCCS. This can lead to several merits,



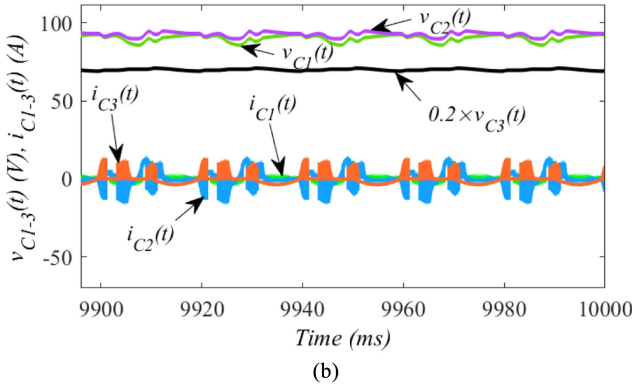
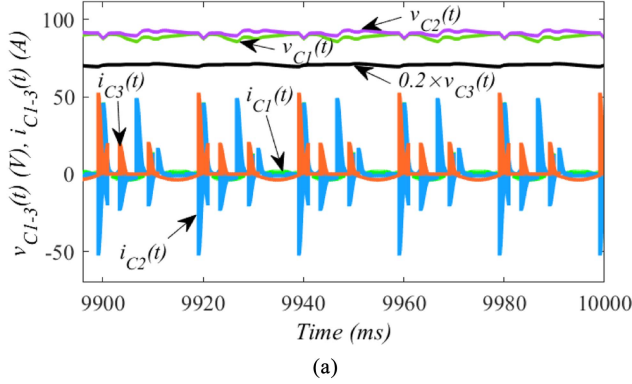
**FIGURE 7.** Simulation results of the proposed MLI demonstrating dynamic performance under various operating conditions. (a) Step change in the input dc voltage. (b) Step change in the reference active power. (c) Step change in both active and reactive power references. (d) Step change in the reference reactive power. (e) Injection of pure reactive power into the grid with a step change in its reference. (f) Response to a grid disturbance (10% voltage sag) during pure active power injection.

such as less EMI, higher efficiency, and longer life cycle of the capacitors. In particular, the reduction of high- $di/dt$  currents suppresses high-frequency components, which are a major contributor to EMI. Moreover, the decrease in current spikes reduces both conduction and switching losses, thereby improving the overall efficiency. Finally, the reduction of ripple current stress in electrolytic capacitors alleviates thermal aging, which is a well-known determinant of their service life. These advantages are widely recognized in the power electronics literature [56], [57], [58]. It should be noted that the observed voltage ripple is inherent to SC operation and does not contradict the self-balancing property.

In Fig. 9, the harmonic spectra of the injected grid current are illustrated for three different operating conditions of the proposed 9L MLI. In the case of pure active power injection (325 W), the total harmonic distortion (THD) is found to be 0.98%, which satisfies the grid interconnection standards. For pure reactive power injection (323 Var), the harmonic content increases, leading to a THD of 3.36%. When both active and reactive powers are injected simultaneously (281 W and 162 Var), the measured THD is 1.30%. These results confirm that the proposed inverter maintains low distortion levels under various loading scenarios, thereby ensuring high-quality current injection into the grid.

**TABLE 5. Parameters and Components Used in the Experiments**

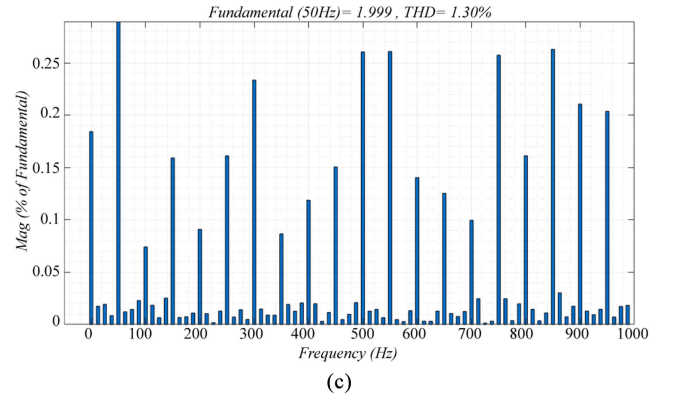
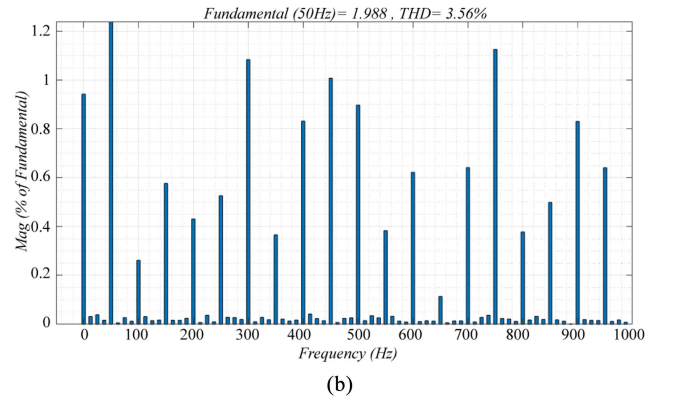
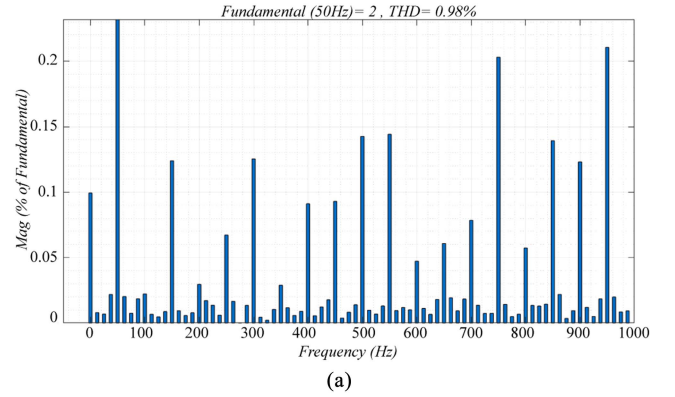
Parameter/component	Symbol	Value	Description
Load Voltage (rms)	$V_L$	220 V	load voltage
1st and 2nd Switched-Capacitors	$C_1, C_2$	1.2 mF	Electrolyte capacitors
3rd Switched-Capacitor	$C_3$	2 mF	Electrolyte capacitors
Fundamental Frequency	$f_g$	50 Hz	-
Switching Frequency	$f_s$	20 kHz	-
Output Filtering Inductor	$L_f$	1.5 mH	Ferrite core inductor
Charging Current's Spike Inductors	$L_{r1}, L_{r2}$	0.3 mH	-
Power Switches	$S_1, \dots, S_8$	-	IPW65R041CFD MOSFETs
Power Diodes	$D_{r1}, D_{r2}$ & $D_1$	-	C3D10060A power diodes
Micro-controller	DSP	-	TMS320F280049 DSP controller



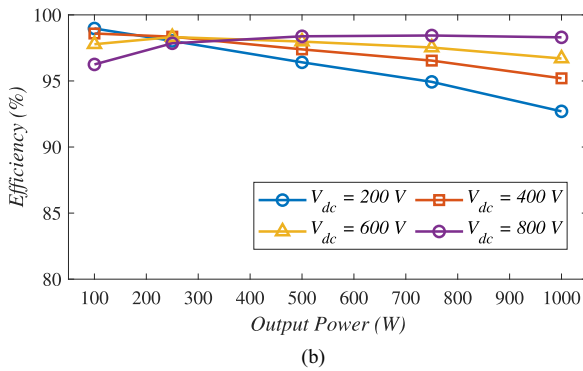
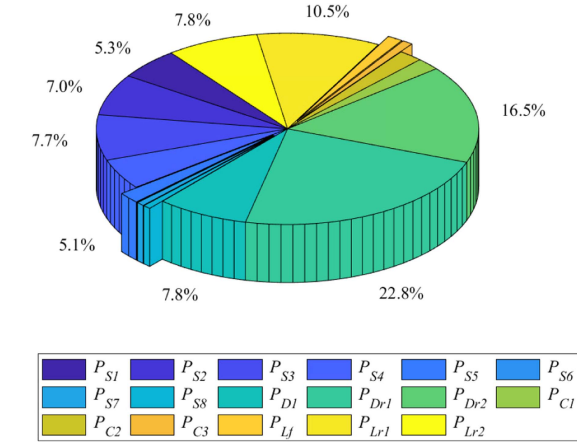
**FIGURE 8. Simulation results of the proposed MLI including voltages and currents of its capacitors. (a) Without CCCS. (b) With CCCS.**

In Fig. 10, the efficiency of the proposed converter for different output powers and power loss breakdown per components are shown. As seen, the results are acceptable. It should be noted that shown power loss breakdown is obtained when the output power, dc voltage, and maximum inverter voltage are, respectively, considered around 325 W, 200 V, and 400 V.

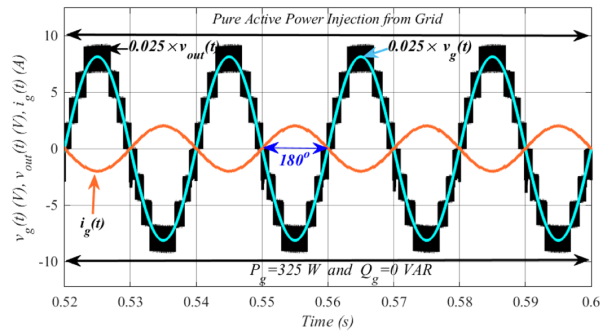
At this stage, the capability of the proposed MLI for bidirectional operation is evaluated. In Fig. 1, by replacing  $D_1$  with a power switch equipped with a body diode, the proposed inverter can also operate in the bidirectional mode. The switching pattern of this additional switch follows that of  $D_1$ . In other words, during the intervals when  $D_1$  is expected to conduct (i.e., the voltage levels of  $\pm$  half-cycle zero and the +fourth level, corresponding to modes 1 and 5 in Table 1), the switch is turned ON, and vice versa. The simulation results



**FIGURE 9. THD of the injected current to the grid by the proposed 9L MLI under different power injection scenarios. (a) Pure active power injection (325 W). (b) Pure reactive power injection (323 Var). (c) Active and reactive power injection (281 W and 162 Var).**



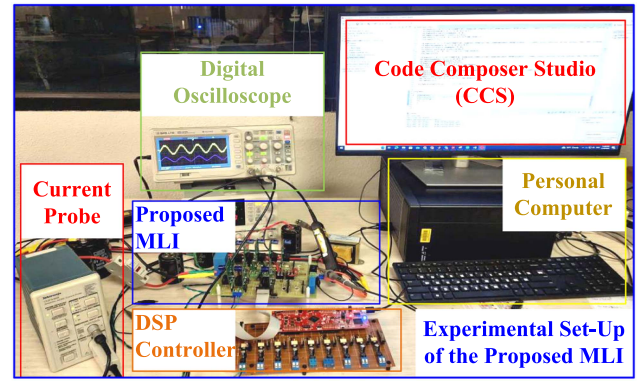
**FIGURE 10.** Power loss distribution of the proposed MLI. (a) Breakdown by components. (b) Efficiency versus output power for different dc-link voltages.



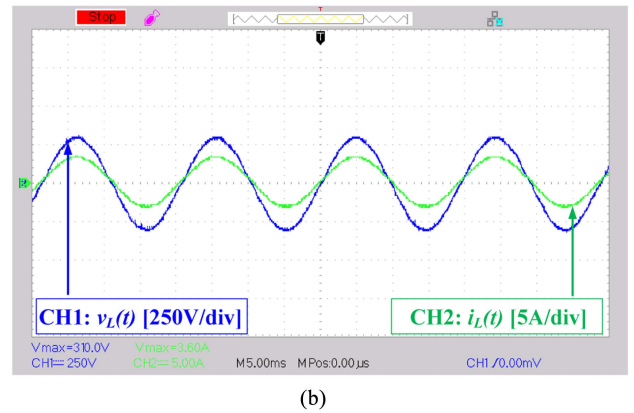
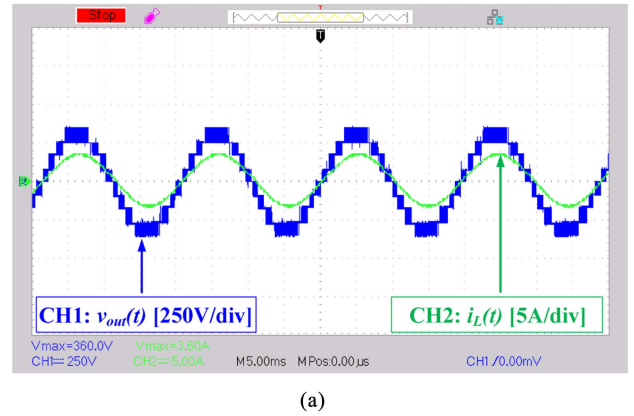
**FIGURE 11.** Simulation results of the proposed MLI ( $D_1$  replace by a power switch) for bidirectional operation.

presented in Fig. 11 confirm this bidirectional capability. As observed, the grid voltage and current are  $180^\circ$  out of phase, meaning that active power is transferred from the grid side back to the input dc side. Hence, the proposed structure can function as an active rectifier simply by replacing a single diode with a power switch.

Consequently, the proposed 9L CGSC-TL MLI has a desirable performance under different operating conditions, including the step changes of the input dc voltage source and the



**FIGURE 12.** Experimental setup of the proposed 9L MLI.

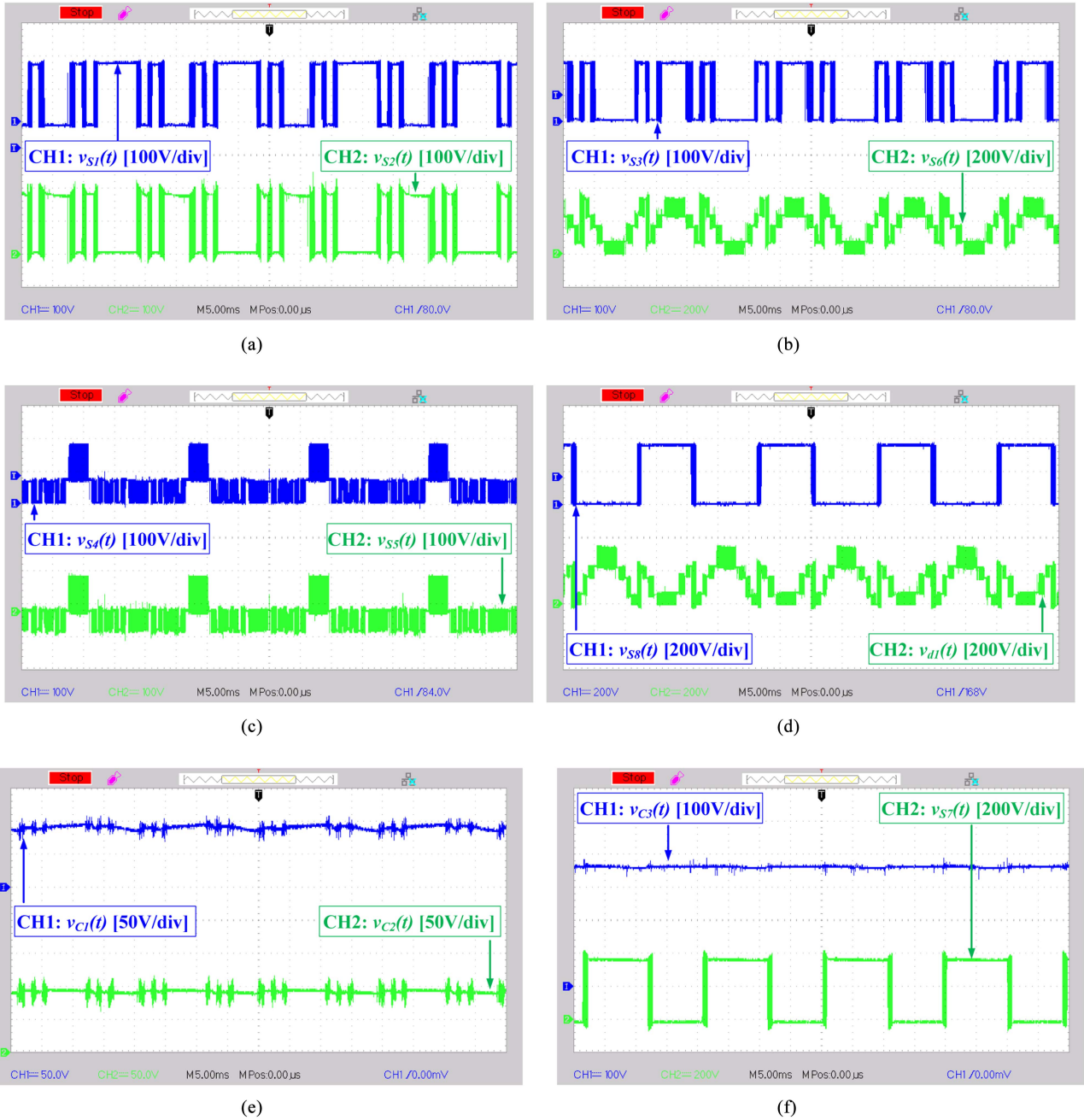


**FIGURE 13.** For resistive load, (a) load current ( $i_L(t)$ ) and the output voltage of the inverter ( $v_{out}(t)$ ) and (b) load current and voltage ( $i_L(t)$  and  $v_L(t)$ ).

reference values of the active and reactive power that should be generated by the inverter and injected into the power grid.

## B. EXPERIMENTAL RESULTS

Here, thorough experimental results for proving the performance of the proposed MLI are presented in the presence of different types of local loads. Fig. 12 shows the experimental setup implemented to obtain the results. In Table 5, the

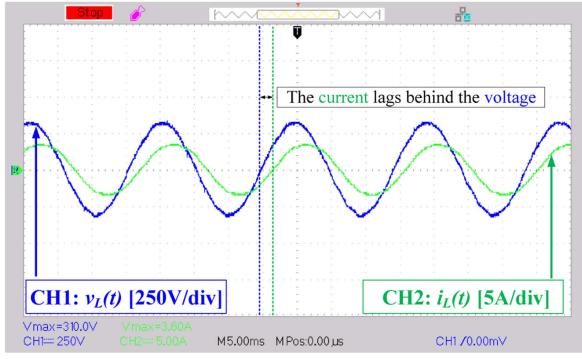


**FIGURE 14.** Voltage waveforms of different components of the proposed MLI. (a)  $v_{S1}(t)$  and  $v_{S2}(t)$ . (b)  $v_{S3}(t)$  and  $v_{S6}(t)$ . (c)  $v_{S4}(t)$  and  $v_{S5}(t)$ . (d)  $v_{S8}(t)$  and  $v_{d1}(t)$ . (e)  $v_{C1}(t)$  and  $v_{C2}(t)$ . (f)  $v_{C3}(t)$  and  $v_{S7}(t)$ .

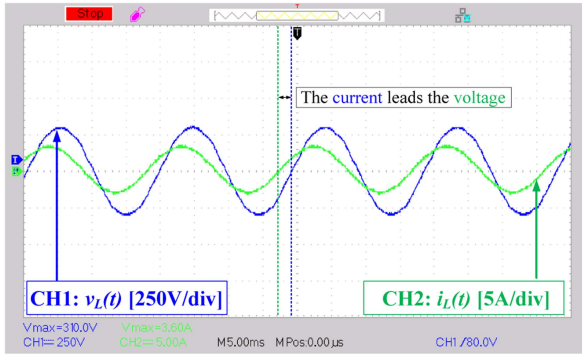
parameters and components description used in the experimental setup are listed.

In the following, the experimental results are presented and discussed in detail. Note that the input dc voltage is equal to 180 V. Initially, the performance of the proposed MLI is proved while having a pure resistive load equal to  $R = 86 \Omega$ . This means that only active power is generated by the inverter. Note that the load is in parallel with a  $1-\mu F$  capacitor. Fig. 13(a) shows the output voltage of the inverter, and the current of load. As clearly seen, the proposed MLI

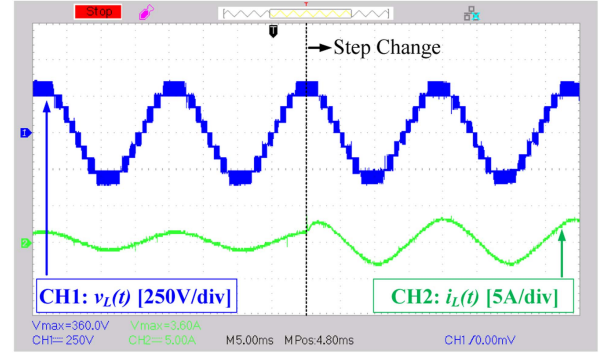
can successfully generate a 9L output voltage with a peak value of 360 V. Here, the load current's peak value is equal to 3.6 A. The load voltage is shown in Fig. 13(b) whose amplitude is about 310 V. As a result, the inverter generates the active power of about 560 W. In Fig. 14, the voltages of the different components of the proposed MLI are presented. As shown, the voltages of the switches and diodes align with the analysis. Based on the results, the maximum value of  $v_{S1}(t)$ ,  $v_{S2}(t)$ ,  $v_{S3}(t)$ ,  $v_{S4}(t)$ ,  $v_{S5}(t)$ ,  $v_{S6}(t)$ ,  $v_{S7}(t)$ ,  $v_{S8}(t)$ , and  $v_{d1}(t)$  are, respectively, about 180, 180, 180, 180, 90, 360, 360, 360,



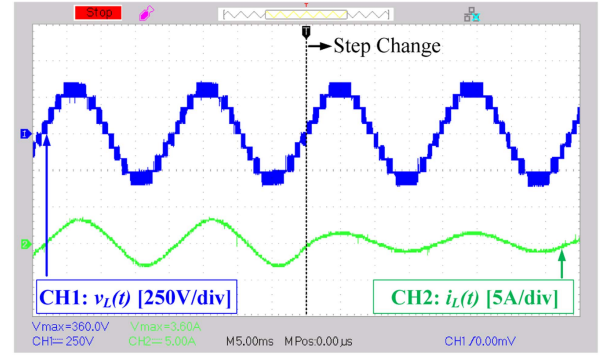
(a)



(b)

**FIGURE 15.** Load current ( $i_L(t)$ ) and the load voltage ( $v_L(t)$ ) (a) for a resistive-inductive load (b) for a resistive-capacitive load.


(a)



(b)

**FIGURE 16.** Load current ( $i_L(t)$ ) and voltage ( $v_L(t)$ ) in presence of step change (a) decreasing load (b) increasing load.

and 360 V. In other words, these values are the maximum voltage stress on the switching devices of the proposed MLI whose minimum and maximum values are equal to 90 and 360 V, respectively. As seen in Fig. 14(e) and (f), the capacitors  $C_1$ ,  $C_2$ , and  $C_3$  are charged to about 90, 90, and 360 V, which are desirable. These experimental waveforms further demonstrate that the capacitor voltages remain close to their intended average values, with bounded ripple and no long-term drift. Hence, the self-balancing feature of the inverter is proved.

The performance of the inverter in the presence of resistive-inductive and resistive-capacitive loads is shown in Fig. 15. As seen in Fig. 15(a), the proposed MLI is able to properly supply a resistive-inductive load ( $R = 110 \Omega$  and  $L = 0.117$  H), where the load current lags behind the voltage of the load. Besides, as shown in Fig. 15(b), the proposed inverter can properly operate in the presence of the resistive-capacitive load ( $R = 110 \Omega$  and  $C = 30$  mF), where the load current leads its voltage. In Fig. 16, the experimental results of the proposed MLI in the case of occurring step changes in the load are shown. In Fig. 16(a), the sudden load decrease from  $R = 110 \Omega$  to  $R = 86 \Omega$  leads to a step change in the load current's amplitude (2.5 to 3.6 A). In Fig. 16(b), the sudden load increase from  $R = 86 \Omega$  to  $R = 110 \Omega$  leads to a step change in the load current from 3.6 to 2.5 A. As seen, the inverter is able to generate the desired 9L output voltage

leading to a sinusoidal current. Hence, the proposed MLI is able to maintain its proper operation despite the changes. All experimental results are obtained on a laboratory prototype of the proposed inverter supplying local loads at 220 V, 50 Hz, chosen to emulate typical grid-connected operating conditions. Although the prototype was operated with these grid-equivalent loads rather than being directly tied to the utility grid, full-scale grid-connected operation (such as the minimum dc-link voltage requirement, active and reactive power injection, and behavior under voltage sag) is analyzed and validated through the detailed simulation studies presented in the previous sections. Consequently, based on both experimental and simulation results, which are all in complete agreement with the analysis, the proposed CG-TL 9L MLI has desirable dynamic performance, making it a suitable option for practical modern applications such as renewable energy systems.

## V. CONCLUSION

In this article, a new eight-switch 9L CGSC-TL MLI is proposed. This inverter can provide advantages, such as employing fewer or comparable number of components, having CG structure resulting in the elimination of leakage current, voltage-boosting ability (maximum value of gain equal to 2), active and reactive power supporting capability, limited CCCS resulting in lower power losses, longer life cycle for

capacitors, and mitigated EMI, extensive input voltage capability, TL structure, no sensors needed for balancing of the voltages of capacitors, and less/close voltage stress on the components. These merits are all proved by comprehensive comparison results. The performance of the proposed MLI is validated in MATLAB/Simulink environment. As proved, under step changes in input dc voltage and reference active and reactive power injection into the grid, the dynamic performance of the inverter is completely desirable. In addition, comprehensive experimental results are presented to prove the performance of the proposed inverter. The aforementioned features make the proposed CGSC-TL 9L MLI a superior option for renewable energy applications such as solar PV systems.

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Dr. Li is an Associate Editor for IEEE TRANSACTIONS ON INDUSTRY APPLICATIONS, *IET Renewable Power Generation*, and *IET Generation, Distribution and Transmission*.

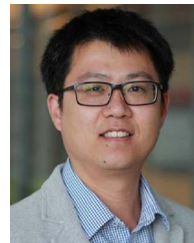


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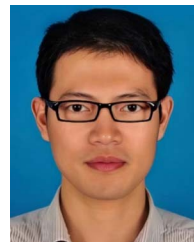


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