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# Efficient Method-of-Moments Analysis of Linear Cavity-Backed Slot Arrays With a Reduced Number of Basis Functions

Jinglin Geng<sup>1</sup>, *Graduate Student Member, IEEE*, and Daniele Cavallo<sup>2</sup>, *Senior Member, IEEE*

**Abstract**—This work deals with the efficient analysis of linear arrays of cavity-backed slot antennas. The considered array elements can be single or multiple slots radiating in the presence of a rectangular cavity. A spectral method of moments (MoM) is used to estimate the impedance and the patterns of the slot array. The method is rendered computationally efficient by considering, for each slot, only two basis functions that suitably describe the magnetic current distribution. The first basis function is derived by solving the auxiliary problem where only the cavity walls parallel to the slot axes are considered. The second basis function is obtained by solving the problem of a closed rectangular cavity excited by a magnetic current distributed on the slot region. The proposed method allows to simulate entire finite arrays in a few seconds per frequency point and can be exploited to aid the design and optimization of cavity-backed slot arrays.

**Index Terms**—Cavity-backed slot, method of moments (MoM), slot arrays, spectral-domain method.

## I. INTRODUCTION

C AVITY-BACKED slots are common antenna elements in array designs for radar and communication applications. The cavity allows to increase the front-to-back ratio and the gain of the slot elements while isolating the antennas from the surrounding environment. These characteristics are particularly advantageous at millimeter-wave (mmWave) frequencies, for which highly integrated arrays are favorable. The cavity and the metal plane where the slots are etched allow to shield the radiating elements from the electronic circuits, which can be placed closer to the antennas to reduce interconnection losses. Several successful cavity-backed slot array designs have been reported based on various technologies, such as gap waveguide [1], [2], full-metal implementation [3], substrate integrated waveguide [4], printed circuit board [5], and antenna-in-package [6]. These types of arrays can also be scaled to higher frequencies, in the subterahertz range, by exploiting high-precision printed circuit board or advanced packaging technologies [7]. In addition to direct radiating

arrays, cavity-backed slots can also be used in combination with quasi-optical systems. For example, in [8], an array of cavity-backed slots is used as a feed array for a dielectric lens antenna.

Concerning the analysis aspects of cavity-backed slots, several approaches have been proposed based on method of moments (MoM) [9], [10], [11], characteristic mode analysis [12], and finite-difference time-domain methods (FDTDs) [13], [14]. However, unlike MoM approaches that discretize only the slots' region, FDTD methods mesh the entire volume, including the space between the slots, with increased complexity for large arrays. One of the advantages of spectral-domain MoM analyses is that they could be combined with stratified media Green's function and easily generalized for slot arrays embedded in dielectric layers.

When specifically considering MoM solutions, however, the works in [9], [10], and [11] considered small-domain basis functions, chosen as piecewise sinusoidal; thus, the computational complexity increases rapidly with the size of the array. Different types of basis functions were considered in other works, e.g., Chebyshev polynomials in [15] or sinusoidal current profiles in [16]. However, these assumptions for the current distribution do not include the reactance at the feed and end points of the slots. The use of two trial functions on the slot, based on a "sin" and "1-cos" profiles, was proposed in [17], but it is not applicable to arbitrary slot length and does not remain valid over large frequency ranges. To describe properly the distribution on the slots with sinusoidal basis functions, the field on the slot was expanded in a series of sinusoids, up to 39 per slot, in [18]. Nevertheless, this approach still results in a large MoM matrix for large arrays.

In this work, we propose a method to greatly reduce the number of basis functions for the analysis of slot arrays with rectangular cavities. We consider only two basis functions per slot element. The two basis functions are resulting from the solution of two auxiliary problems: one is the case where only the cavity walls parallel to the slot axes are considered, while the transverse walls are not present; the second problem assumes the rectangular cavity excited by a magnetic current distributed on the slot region, while the perfectly magnetic conductor is assumed to be above the slot.

The proposed basis functions accurately represent the distribution of the current on the slot over a very large frequency range, even when higher order modes are supported inside the

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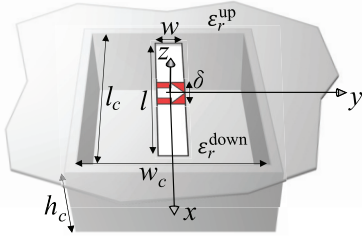


Fig. 1. Cavity-backed slot with defined geometrical parameters.

cavity. The proposed method enables the simulation of entire finite arrays in just a few seconds per frequency point, making it suitable for the design and optimization of cavity-backed slot arrays.

## II. SINGLE-SLOT FORMULATION

Let us consider a single slot radiating in the presence of a rectangular cavity with dimensions  $w_c \times l_c \times h_c$ , as depicted in Fig. 1. The cavity is filled with a dielectric of relative permittivity of  $\epsilon_r^{\text{down}}$ . The slot, with length  $l$  and width  $w$ , is oriented along the  $x$ -axis and is excited by a delta-gap generator with length  $\delta$ . The upper semi-infinite space is assumed to have a relative permittivity of  $\epsilon_r^{\text{up}}$ .

From the equivalence theorem, we can replace the original problem with an equivalent problem where the slot region is filled with a perfect electric conductor and a magnetic current density  $\vec{m}$  is located above and below the slot region. A magnetic field integral equation can be set up as in [19], by imposing the boundary conditions on the slot plane. For an electrically thin slot, the current is assumed to have only the  $x$ -component ( $\vec{m} = m_x \hat{x}$ ). Imposing the boundary conditions for the  $x$ -component of the scattered magnetic field on the slot plane results in the following integral equation:

$$[m_x * g_{xx}^{\text{up}}](x, y) + [m_x * g_{xx}^{\text{down}}](x, y) = -j_y(x, y) \quad (1)$$

where the scattered magnetic field is expressed as the convolution between the magnetic current and the  $xx$ -component of the dyadic space domain Green's functions for the structure above and below the slot ( $g_{xx}^{\text{up}}$  and  $g_{xx}^{\text{down}}$ ). The term  $j_y$  represents the  $y$ -component of the surface current density flowing in the feed and the slot terminations. The 2-D convolution can be written explicitly as a double integral over the slots' aperture

$$[m * g](x, y) = \iint_{\text{Slot}} m(x', y') g(x, x', y, y') dx' dy'. \quad (2)$$

Observing on the slot axis ( $y = 0$ ), we expand the current in the sum of two basis functions

$$j_y(x, y = 0) = i_\delta f_\delta(x) + i_g f_g(x) \quad (3)$$

where  $f_\delta$  is a function equal to 1 on the delta-gap feed and 0 elsewhere, while  $f_g$  is an edge singular distribution describing the diffraction at the slot terminations and its expression can be found in [21]. It should be noted that, in this article, the distribution  $f_g$  is assumed to be symmetric at the two ends of the slot, which is only valid if the slot is centered along  $x$  with respect to the cavity. However, although not considered

here, this assumption can be dropped by considering two independent weights for the two terminations, i.e.,  $i_g f_g(x)$  becomes  $i_{g1} f_{g1}(x) + i_{g2} f_{g2}(x)$ .

The coefficient  $i_\delta$  is assumed to be known, as it represents the amplitude of the impressed current on the feeding gap. Contrarily, the amplitude of the current at the terminations  $i_g$  is unknown.

The unknown magnetic current is assumed to be variable separable, i.e.,

$$m_x(x', y') = v(x') m_t(y') \quad (4)$$

where the transverse distribution is assumed to be edge singular  $m_t(y') = 2/(w\pi) \times [1 - (2y'/w)^2]^{-1/2}$  and the longitudinal distribution  $v(x')$  is unknown. By defining the terms

$$d^{\text{up/down}}(x) = \int_{-w/2}^{w/2} m_t(y') g_{xx}^{\text{up/down}}(x, -y') dy' \quad (5)$$

the integral equation for observing on the slot axis can be written as

$$[d^{\text{up}} * v](x) + [d^{\text{down}} * v](x) = -i_\delta f_\delta(x) - i_g f_g(x) \quad (6)$$

where symbol “\*” denotes the 1-D convolution.

Then, we can write the left-hand side and the right-hand side of (6) as inverse Fourier transform (IFT) of their spectral-domain counterpart, following similar steps as [19], [20]:

$$\begin{aligned} & \frac{1}{2\pi} \int_{-\infty}^{\infty} D^{\text{up}}(k_x) V(k_x) e^{-jk_x x} dk_x \\ & + \frac{1}{l_c} \sum_{m_x, \text{odd}} D^{\text{down}}(k_{xm}) V(k_{xm}) e^{-jk_{xm} x} \\ & = -\frac{1}{2\pi} \int_{-\infty}^{\infty} [i_\delta F_\delta(k_x) + i_g F_g(k_x)] e^{-jk_x x} dk_x. \end{aligned} \quad (7)$$

One can note that the spectrum of the scattered field above the slot is continuous and the resulting IFT is an integral. In contrast, the cavity problem leads to a discrete spectrum of the scattered field below the slot so that the corresponding IFT becomes a Floquet sum, where  $k_{xm} = -\pi m_x / l_c$  and  $m_x$  are odd integers from  $-\infty$  to  $\infty$ , as described in Appendix A.

The explicit expression of the function  $D^{\text{up}}$  is known in closed form [19] and is given by

$$D^{\text{up}}(k_x) = \frac{-1}{2k_0 \zeta_0} K^2 J_0 \left( K \frac{w}{4} \right) H_0^{(2)} \left( K \frac{w}{4} \right) \quad (8)$$

where  $K = (k_{\text{up}}^2 - k_x^2)^{1/2}$ ;  $k_{\text{up}} = k_0(\epsilon_r^{\text{up}})^{1/2}$ ;  $k_0$  and  $\zeta_0$  are the free-space wavenumber and impedance, respectively;  $J_0$  is the zeroth-order Bessel function; and  $H_0^{(2)}$  is the Hankel function of zeroth order and the second kind.

The explicit expression of the function  $D^{\text{down}}$  is derived in Appendix A and is given by a modal expansion, because of the  $x$ -oriented cavity walls

$$D^{\text{down}}(k_x) = \frac{k_{\text{down}}^2 - k_x^2}{2w_c k_0 \zeta_0} \sum_{m_y = -\infty}^{\infty} \frac{j \cot(k_{zm} h_c)}{k_{zm}} J_0 \left( \frac{k_{ym} w}{2} \right) \quad (9)$$

where  $k_{\text{down}} = k_0(\epsilon_r^{\text{down}})^{1/2}$ ,  $k_{ym} = -2\pi m_y / w_c$ , and  $k_{zm} = (k_{\text{down}}^2 - k_{ym}^2 - k_x^2)^{1/2}$ .

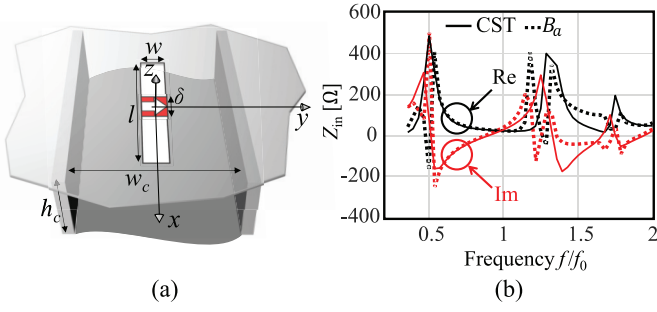


Fig. 2. (a) Auxiliary problem “a” to define the basis function and (b) comparison of the input impedance of the slot between CST and MoM using the basis function  $B_a$ .

### III. PROPOSED BASIS FUNCTIONS FOR SINGLE SLOT

To solve (7) for the unknown voltage spectrum, one cannot equate the spectra at the left- and right-hand sides as in [22] since the spectrum of the voltage is appearing both in a continuous and a discrete form. To overcome this issue, we propose to expand the unknown voltage in terms of known basis functions that we construct from auxiliary problems.

#### A. Basis Functions $B_a$ and $B_a^{Tr}$

As the first attempt, we assume that the voltage spectrum can be expressed as

$$V(k_x) = v_a B_a(k_x) \quad (10)$$

where  $v_a$  is an unknown coefficient and the basis function  $B_a(k_x)$  is chosen as the normalized solution of an auxiliary problem, which is simpler to solve with respect to the original problem. The auxiliary problem, denoted as “a,” is depicted in Fig. 2(a) and represents the same geometry of the original slot, but without the y-oriented walls of the cavities. In this case, the discrete term of (7) becomes continuous, leading to

$$\begin{aligned} \frac{1}{2\pi} \int_{-\infty}^{\infty} (D^{\text{up}}(k_x) + D^{\text{down}}(k_x)) V_a(k_x) e^{-jk_x x} dk_x \\ = -\frac{1}{2\pi} \int_{-\infty}^{\infty} [i_\delta^a F_\delta(k_x) + i_g^a F_g(k_x)] e^{-jk_x x} dk_x. \end{aligned} \quad (11)$$

The voltage spectrum  $V_a(k_x)$  for this auxiliary problem can be easily solved by equating the spectra at the left- and right-hand sides of (11) as

$$V_a(k_x) = -\frac{i_\delta^a F_\delta(k_x) + i_g^a F_g(k_x)}{D^{\text{up}}(k_x) + D^{\text{down}}(k_x)}. \quad (12)$$

Weights  $i_\delta^a$  and  $i_g^a$  are not independent, but they should satisfy the condition that the voltage on the slot metal termination is equal to zero. To impose this condition, we defined the projection between two functions  $f_1(x)$  and  $f_2(x)$  as

$$\langle f_1, f_2 \rangle = \int_{-\infty}^{\infty} f_1(x) f_2(x) dx. \quad (13)$$

It can be shown that the projection can also be evaluated in terms of the Fourier transforms  $F_1(k_x)$  and  $F_2(k_x)$ , as described in [23]

$$\langle f_1, f_2 \rangle = \frac{1}{2\pi} \int_{-\infty}^{\infty} F_1(k_x) F_2(-k_x) dk_x. \quad (14)$$

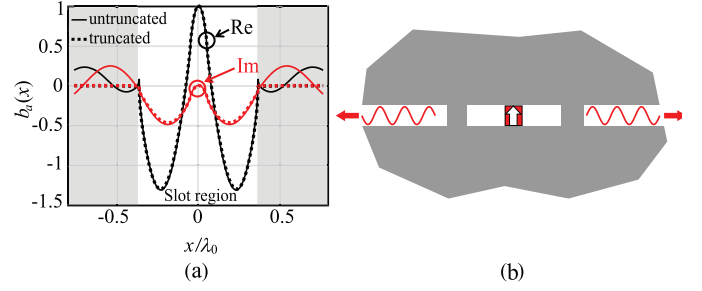


Fig. 3. (a) Solution of the normalized voltage distribution for auxiliary problem “a,” with and without truncation, and (b) sketch of the finite metal terminations with unrealistic waves propagating beyond the slot region.

Thus, projecting the voltage distribution onto the test function  $f_g$  associated with the slot terminations and equating to 0 leads to

$$\frac{-1}{2\pi} \int_{-\infty}^{\infty} \frac{i_\delta^a F_\delta(k_x) + i_g^a F_g(k_x)}{D^{\text{up}}(k_x) + D^{\text{down}}(k_x)} F_g(-k_x) dk_x = 0. \quad (15)$$

From (15), one can find the relation between  $i_g^a$  and  $i_\delta^a$  and express the voltage spectrum as

$$V_a(k_x) = -i_\delta^a \frac{F_\delta(k_x) - \left( \frac{Z_{g\delta}^a}{Z_{gg}^a} \right) F_g(k_x)}{D^{\text{up}}(k_x) + D^{\text{down}}(k_x)} \quad (16)$$

where impedances  $Z_{g\delta}^a$  and  $Z_{gg}^a$  are defined as

$$Z_{gi}^a = -\frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{F_i(k_x) F_g(-k_x)}{D^{\text{up}}(k_x) + D^{\text{down}}(k_x)} dk_x \quad (17)$$

with  $i$  being either  $g$  or  $\delta$ .

The basis functions  $B_a(k_x)$  can be derived by normalizing the voltage spectrum  $V_a(k_x)$  such that the IFT of the basis function  $b_a(x)$  has an average value of 1 in the feeding gap

$$B_a(k_x) = \frac{V_a(k_x)}{\frac{1}{2\pi} \int_{-\infty}^{\infty} V_a(k_x) F_\delta(-k_x) dk_x}. \quad (18)$$

One can note that the amplitude of the impressed current on the feeding gap  $i_\delta^a$  for the auxiliary problem “a” is arbitrary, as it cancels out with the normalization.

By applying Galerkin projection for both sides of (7) onto  $B_a(k_x)$  and using (10), one can find the relation between the impressed current and the resulting average voltage across the feeding gap as

$$v_a Y_a = i_\delta^a \quad (19)$$

with

$$\begin{aligned} Y_a = \frac{1}{2\pi} \int_{-\infty}^{\infty} B_a(-k_x) D^{\text{up}}(k_x) B_a(k_x) dk_x \\ + \frac{1}{l_c} \sum_{m_x, \text{odd}} B_a(-k_{xm}) D^{\text{down}}(k_{xm}) B_a(k_{xm}) \end{aligned} \quad (20)$$

where the input impedance on the feeding gap can simply be found as  $Z_{\text{in}} = 1/Y_a$ .

Fig. 2(b) shows the comparison of the input impedance computed with commercial software CST and using (20), for a cavity-backed slot with parameters  $l = 0.7\lambda_0$ ,  $\delta = 0.1\lambda_0$ ,  $w = 0.06\lambda_0$ ,  $l_c = 0.79\lambda_0$ ,  $w_c = 0.57\lambda_0$ , and  $h_c = 0.16\lambda_0$ , where  $\lambda_0$  is the wavelength at the frequency  $f_0$  and  $\epsilon_r^{\text{up}} = \epsilon_r^{\text{down}} = 2.34$ .

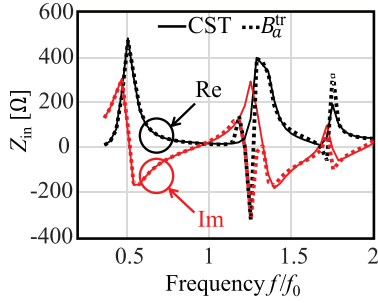


Fig. 4. Comparison of the input impedance of the slot between CST and MoM when using the truncated basis function  $B_a^{\text{tr}}$ .

It can be seen that the agreement is quite poor. To explain the cause of such inaccuracy, the spatial basis function  $b_a(x)$  is plotted in solid lines in Fig. 3(a). One can observe that while the voltage given by the basis function is zero at the slot edges, it continues to exist beyond the slot terminations. This effect is due to the assumption of finite size metal terminations at the slot edges as shown in Fig 3(b). This assumption is convenient because it allows the use of infinite slot spectral Green's function in (8) and (9), as in [21]. However, this results in an unrealistic propagating wave outside the slot region, which contributes to errors in the impedance estimation in the presence of the cavity. Therefore, it is necessary to find the spectrum of the truncated basis function  $B_a^{\text{tr}}(k_x)$ , which includes only the voltage distribution in the slot region. The truncated spectrum can be obtained by convolution with a sinc function as

$$B_a^{\text{tr}}(k_x) = \frac{l}{2\pi} \int_{-\infty}^{\infty} B_a(k'_x) \text{sinc}\left(\frac{(k_x - k'_x)l}{2}\right) dk'_x. \quad (21)$$

The evaluation of the integrals in (21) can be computationally expensive, and thus, we resort to an efficient approach to compute  $B_a^{\text{tr}}(k_x)$  by means of fast Fourier transform (FFT), as described in Appendix B. The resulting truncated voltage distribution is shown in Fig. 3(a) by the dashed curves.

After introducing the truncation of the basis function, the MoM predicts well the input impedance for most of the frequency range, as shown in Fig. 4, except at frequencies around  $f = 1.2f_0$  and  $f = 1.7f_0$ . These discrepancies correspond to higher order resonances being excited in the cavity, which are not accounted for in  $B_a^{\text{tr}}$  as we consider only the  $x$ -oriented wall.

### B. Basis Function $B_b$ and $B_b^{\text{tr}}$

To include the effect of the excited higher order resonances in the cavity, we introduce another basis function  $B_b^{\text{tr}}$  in the voltage spectrum expansion

$$V(k_x) = v_a B_a^{\text{tr}}(k_x) + v_b B_b^{\text{tr}}(k_x) \quad (22)$$

where  $B_b$  is the solution of a second auxiliary problem “b,” in which the original rectangular cavity is located below the slot and a perfect magnetic conductor (PMC) is filling the medium above the slot, as shown in Fig. 5(a). This allows us to isolate only the effect of the  $x$ -oriented cavity walls on the slot field

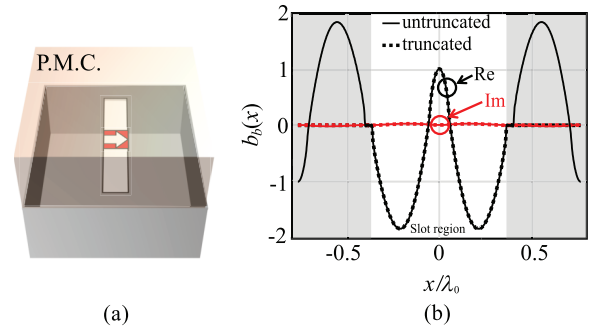


Fig. 5. (a) Auxiliary problem “b” to define the basis functions. (b) Solution of the normalized voltage distribution for auxiliary problem “b” with and without truncation.

distribution. Similar to problem “a,” the solution of the voltage spectrum for the second problem  $V_b(k_{xm})$  can be found as

$$V_b(k_{xm}) = -i_\delta^b \frac{F_\delta(k_{xm}) - (Z_{g\delta}^b/Z_{gg}^b) F_g(k_{xm})}{D^{\text{down}}(k_{xm})} \quad (23)$$

with

$$Z_{gi}^b = -\frac{1}{l_c} \sum_{m_x, \text{odd}} \frac{F_g(-k_{xm}) F_i(k_{xm})}{D^{\text{down}}(k_{xm})} \quad (24)$$

where  $i$  can be either  $g$  or  $\delta$ . Then, the untruncated basis function of the second auxiliary problem  $B_b(k_{xm})$  can be derived by using a similar normalization as in (18).

It is noted that the untruncated basis function  $B_b(k_{xm})$  cannot be used directly in (22) because it is discrete. However, a continuous equivalent of the spectrum can be found by truncating the spatial distribution over the finite slot length. As in (21), this corresponds to a convolution with a sinc function in the spectral domain

$$B_b^{\text{tr}}(k_x) = \frac{l}{l_c} \sum_{m_x, \text{odd}} B_b(k_{xm}) \text{sinc}\left(\frac{(k_x - k_{xm})l}{2}\right). \quad (25)$$

Fig. 5(b) shows the untruncated and truncated solutions of the voltage distribution along the slot for the second auxiliary problem, calculated from  $B_b(k_{xm})$  and  $B_b^{\text{tr}}(k_x)$ , respectively. One can note that the untruncated voltage distribution contains periodic replicas with alternatively changing signs, according to the image theorem applied to the  $y$ -oriented walls.

Substituting (22) into (7) and projecting with the Galerkin method onto the functions  $B_a^{\text{tr}}(k_x)$  and  $B_b^{\text{tr}}(k_x)$ , one can solve the unknown  $v_a$  and  $v_b$  as

$$\begin{bmatrix} v_a \\ v_b \end{bmatrix} = \begin{bmatrix} Y_{aa} & Y_{ab} \\ Y_{ba} & Y_{bb} \end{bmatrix}^{-1} \begin{bmatrix} i_\delta \\ i_\delta \end{bmatrix} \quad (26)$$

with

$$Y_{ij} = Y_{ij}^{\text{up}} + Y_{ij}^{\text{down}} = \frac{1}{2\pi} \int_{-\infty}^{\infty} B_i^{\text{tr}}(-k_x) D^{\text{up}}(k_x) B_j^{\text{tr}}(k_x) dk_x + \frac{1}{l_c} \sum_{m_x, \text{odd}} B_i^{\text{tr}}(-k_{xm}) D^{\text{down}}(k_{xm}) B_j^{\text{tr}}(k_{xm}) \quad (27)$$

where  $i$  and  $j$  can be either  $a$  or  $b$ . The input impedance of the slot can be found as

$$Z_{\text{in}} = \frac{v_a + v_b}{i_\delta}. \quad (28)$$

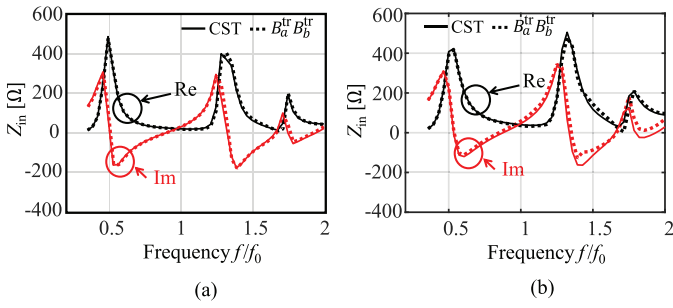


Fig. 6. Comparison of the input impedance of the slot between CST and MoM when using both the truncated basis functions  $B_a^{\text{tr}}$  and  $B_b^{\text{tr}}$ . (a)  $w = 0.06\lambda_0$ . (b)  $w = 0.12\lambda_0$ .

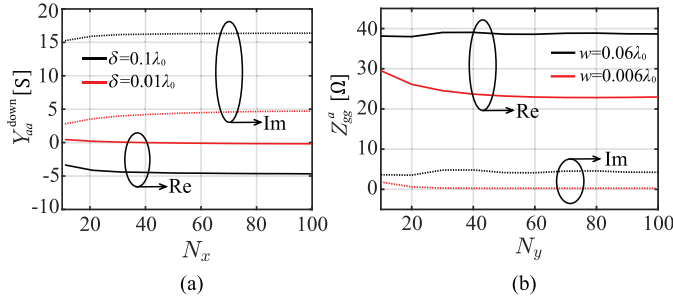


Fig. 7. Convergence of the Floquet sums as a function of modes. (a)  $Y_{aa}^{\text{down}}$  for slot width  $w = 0.06\lambda_0$  and two different feed sizes  $\delta = 0.1\lambda_0$  and  $\delta = 0.01\lambda_0$ . (b)  $Z_{gg}^a$  for  $\delta = 0.1\lambda_0$  and two different values of the slot width  $w = 0.06\lambda_0$  and  $w = 0.006\lambda_0$ .

Fig. 6 shows the input impedance computed by the method in comparison with CST simulations. The parameters in Fig. 6(a) are  $l = 0.7\lambda_0$ ,  $\delta = 0.1\lambda_0$ ,  $w = 0.06\lambda_0$ ,  $l_c = 0.79\lambda_0$ ,  $w_c = 0.57\lambda_0$ , and  $h_c = 0.16\lambda_0$ , where  $\lambda_0$  is the wavelength at the frequency  $f_0$  and  $\epsilon_r^{\text{up}} = \epsilon_r^{\text{down}} = 2.34$ . It is seen that the proposed MoM gives an excellent impedance estimation in the entire frequency band, after adding the second type of basis function  $B_b$  in the formulation. To highlight the limits of our method, which assumes the slot width to be small with respect to the wavelength, we also consider in Fig. 6(b) the results for a larger slot width  $w = 0.12\lambda_0$ . The input impedance computed with our method starts to deviate from the CST result at frequencies above  $1.4f_0$ , for which the width of the slot is around a quarter of the wavelength in the medium.

The solution of the considered problem requires the evaluation of infinite Floquet sums, such as the sum in  $m_y$  in (9), used in (17), and the sum in  $m_x$  odd to calculate  $Y_{ij}^{\text{down}}$  in (27). To truncate these sums to a finite number of modes  $N_x$  and  $N_y$ , we study the convergence of the terms  $Y_{aa}^{\text{down}}$  and  $Z_{gg}^a$  in Fig. 7 as a function of  $N_x$  and  $N_y$ , respectively. It can be seen that the convergence of the sums depends mainly on the electrical size of the feed  $\delta$  for  $N_x$  and on the slot width  $w$  for  $N_y$ . However, all considered cases require less than 100 modes to converge.

#### IV. SLOT ARRAY

The problem of an array of cavity-backed slots can also be solved with a procedure similar to the single-slot case. In this section, the steps of the single-slot formulation will be generalized to the multiple-slot case. As an example, we consider an array of  $M$  double-slot elements radiating in the

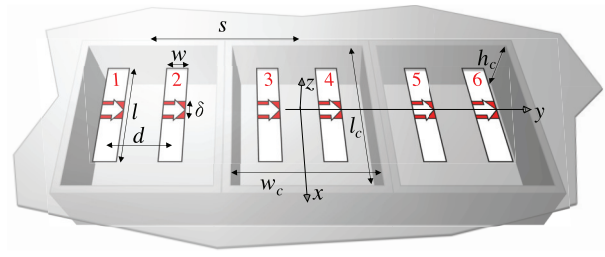


Fig. 8. Array of cavity-backed double slots ( $M = 3$ ) with the definition of the geometrical parameters.

presence of rectangular cavities, as shown in Fig. 8. The distance between the slots in each double-slot element is indicated by  $d$ , while the spacing between the double-slot elements is  $s$ .

Accounting for the presence of multiple slots, the spectral integral equation in (7), for the  $m$ th slot, becomes

$$\sum_{m'=1}^{2M} \left[ \frac{1}{2\pi} \int_{-\infty}^{\infty} D_{mm'}^{\text{up}}(k_x) V_{m'}(k_x) e^{-jk_x x} dk_x + \frac{1}{l_c} \sum_{m_x \text{ odd}} D_{mm'}^{\text{down}}(k_{xm}) V_{m'}(k_{xm}) e^{-jk_{xm} x} \right] = -\frac{1}{2\pi} \int_{-\infty}^{\infty} [i_{\delta,m} F_{\delta}(k_x) + i_{g,m} F_g(k_x)] e^{-jk_x x} dk_x. \quad (29)$$

The explicit expression of the function  $D_{mm'}^{\text{up}}$  is known in a closed form [22]

$$D_{mm'}^{\text{up}}(k_x) = \begin{cases} \frac{-1}{2k_0 \zeta_0} K^2 J_0 \left( K \frac{w}{4} \right) H_0^{(2)} \left( K \frac{w}{4} \right), & \text{for } m = m' \\ \frac{-1}{2k_0 \zeta_0} K^2 H_0^{(2)}(K|y_m - y_{m'}|), & \text{for } m \neq m' \end{cases} \quad (30)$$

where  $y_m$  and  $y_{m'}$  represent the location of the axes of the  $m$ th slot and the  $m'$ th slot, respectively.

The explicit expression of  $D_{mm'}^{\text{down}}$  for the double-slot array case is

$$D_{mm'}^{\text{down}}(k_x) = \frac{k_{\text{down}}^2 - k_x^2}{2w_c k_0 \zeta_0} \sum_{m_y=-\infty}^{\infty} \frac{j \cot(k_{zm} h_c)}{k_{zm}} J_0 \left( \frac{k_{ym} w}{2} \right) \times [1 + e^{-jk_{ym}(w_c - d)}] e^{jk_{ym}(y_m - y_{m'})} \alpha_{mm'} \quad (31)$$

where  $k_{ym} = -\pi m_y / w_c$ ,  $k_{zm} = (k_{\text{down}}^2 - k_{ym}^2 - k_x^2)^{1/2}$ , and  $\alpha_{mm'} = 1$  if indexes  $m$  and  $m'$  correspond to slots in the same cavity and 0 otherwise.

#### A. Formulation

For the sake of compact notation, the integral equations for all slots can be combined in a matrix form as

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} \mathbf{D}^{\text{up}}(k_x) \mathbf{V}(k_x) e^{-jk_x x} dk_x + \frac{1}{l_c} \sum_{m_x \text{ odd}} \mathbf{D}^{\text{down}}(k_{xm}) \mathbf{V}(k_{xm}) e^{-jk_{xm} x} = -\frac{1}{2\pi} \int_{-\infty}^{\infty} [\mathbf{i}_{\delta} F_{\delta}(k_x) + \mathbf{i}_g F_g(k_x)] e^{-jk_x x} dk_x \quad (32)$$

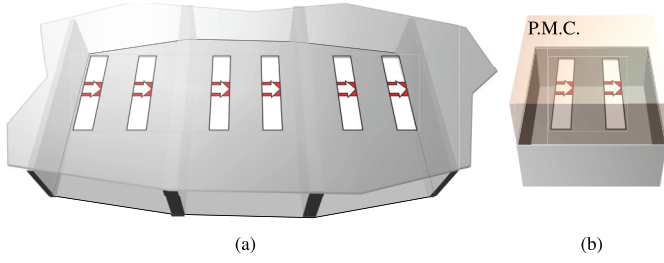


Fig. 9. (a) Sketch of auxiliary problem “a”: same slot array without y-oriented walls of the cavity and (b) sketch of auxiliary problem “b”: a double-slot element with PMC filling the medium above the slots.

where  $\mathbf{D}^{\text{up/down}}$  is the  $2M \times 2M$  matrix whose elements are defined in (30) and (31);  $\mathbf{V}$  is a column vector with the voltage spectra of each slot, i.e.,  $\mathbf{V}(k_x) = \{V_1(k_x), V_2(k_x), \dots, V_{2M}(k_x)\}^T$ ; and  $\mathbf{i}_\delta$  and  $\mathbf{i}_g$  are column vectors with currents  $i_{\delta,m}$  and  $i_{g,m}$ , respectively.

Similar to the case of a single slot, we consider the following expansion:

$$\mathbf{V}(k_x) = \mathbf{B}_a^{\text{tr}}(k_x)\mathbf{v}_a + \mathbf{B}_b^{\text{tr}}(k_x)\mathbf{v}_b \quad (33)$$

where matrices  $\mathbf{B}_a^{\text{tr}}$  and  $\mathbf{B}_b^{\text{tr}}$  are chosen as the solutions of the two auxiliary problems depicted in Fig. 9. The first problem consists of the same slot array, but without the y-oriented walls of the cavities, as shown in Fig. 9(a). For the second problem, we consider that the same cavity is located below the slots and a PMC is filling the medium above the slots, as shown in Fig. 9(b).

Although the steps are not reported for the sake of brevity, a matrix  $\mathbf{V}_a$  can be found similar to the case of the single slot as

$$\mathbf{V}_a(k_x) = [\mathbf{D}^{\text{up}}(k_x) + \mathbf{D}^{\text{down}}(k_x)]^{-1} \times \left[ (\mathbf{Z}_{gg}^a)^{-1} \mathbf{Z}_{g\delta}^a F_g(k_x) - F_\delta(k_x) \mathbf{1} \right] \quad (34)$$

where  $\mathbf{1}$  is a matrix of ones of size  $2M \times 2M$ . This expression results from imposing the condition that the voltage across the slot terminations must be zero and is written in terms of the impedance matrices  $\mathbf{Z}_{g\delta}^a$  and  $\mathbf{Z}_{gg}^a$ , whose elements are defined as

$$Z_{gi,mm'}^a = \frac{-1}{2\pi} \int_{-\infty}^{\infty} [\mathbf{D}^{\text{up}}(k_x) + \mathbf{D}^{\text{down}}(k_x)]_{mm'}^{-1} \times F_g(-k_x) F_i(k_x) dk_x \quad (35)$$

where  $i$  can be either  $g$  or  $\delta$ . Likewise, the matrix  $\mathbf{V}_b$  can be found as

$$\mathbf{V}_b(k_{xm}) = [\mathbf{D}^{\text{down}}(k_{xm})]^{-1} \times \left[ (\mathbf{Z}_{gg}^b)^{-1} \mathbf{Z}_{g\delta}^b F_g(k_{xm}) - \mathbf{1} F_\delta(k_{xm}) \right] \quad (36)$$

with

$$Z_{gi,mm'}^b = -\frac{1}{l_c} \sum_{m_x \text{ odd}} [\mathbf{D}^{\text{down}}(k_{xm})]_{mm'}^{-1} F_g(-k_{xm}) F_i(k_{xm}) \quad (37)$$

where  $i$  can be either  $g$  or  $\delta$ .

The elements of the matrices  $\mathbf{V}_a$  and  $\mathbf{V}_b$  are modified to impose the truncation of the voltage on the slot region. This is done by applying (66)–(68) for  $\mathbf{V}_a$  as described in

Appendix B and using (23) for  $\mathbf{V}_b$ , defining  $\mathbf{V}_a^{\text{tr}}(k_x)$  and  $\mathbf{V}_b^{\text{tr}}(k_x)$ , respectively.

The basis functions are then obtained by normalizing the voltage solutions of the two auxiliary problems as follows:

$$\mathbf{B}_i^{\text{tr}}(k_x) = \left[ \frac{1}{2\pi} \int_{-\infty}^{\infty} \mathbf{I} \odot \mathbf{V}_i^{\text{tr}}(k_x) F_\delta(-k_x) dk_x \right]^{-1} \mathbf{V}_i^{\text{tr}}(k_x) \quad (38)$$

where  $i$  is either  $a$  or  $b$  and  $\mathbf{I}$  is the identity matrix of size  $2M \times 2M$ . Symbol  $\odot$  represents the element-wise product between two matrices and the operation  $\mathbf{I} \odot \mathbf{V}_i$  maintains only the diagonal elements of the matrix  $\mathbf{V}_i$  and gives zeros for the off-diagonal elements.

Substituting (33) into (32) and projecting the  $m$ th integral equation onto  $\mathbf{B}_{a,mm}^{\text{tr}}$  and  $\mathbf{B}_{b,mm}^{\text{tr}}$ , one can solve the unknown  $\mathbf{v}_a$  and  $\mathbf{v}_b$  as

$$\begin{bmatrix} \mathbf{v}_a \\ \mathbf{v}_b \end{bmatrix} = \begin{bmatrix} \mathbf{Y}_{aa} & \mathbf{Y}_{ab} \\ \mathbf{Y}_{ba} & \mathbf{Y}_{bb} \end{bmatrix}^{-1} \begin{bmatrix} \mathbf{i}_\delta \\ \mathbf{i}_g \end{bmatrix} \quad (39)$$

with

$$\mathbf{Y}_{ij} = \frac{1}{2\pi} \int_{-\infty}^{\infty} [\mathbf{I} \odot \mathbf{B}_i^{\text{tr}}(-k_x)] \mathbf{D}^{\text{up}}(k_x) \mathbf{B}_j^{\text{tr}}(k_x) dk_x + \frac{1}{l_c} \sum_{m_x \text{ odd}} [\mathbf{I} \odot \mathbf{B}_i^{\text{tr}}(-k_{xm})] \mathbf{D}^{\text{down}}(k_{xm}) \mathbf{B}_j^{\text{tr}}(k_{xm}) \quad (40)$$

where  $i$  and  $j$  can be either  $a$  or  $b$ . Once the unknowns  $\mathbf{v}_a$  and  $\mathbf{v}_b$  are found, one can obtain the voltage spectrum on each slot from (33) and, by IFT, find the magnetic current density distribution in each slot. Other relevant quantities can be computed, such as mutual coupling, active input impedance, and radiated far field of the array.

1) *Mutual Impedance*: To find the mutual impedances, we impress the current on the  $n$ th slot equal to  $i_{\delta,n}$  and zeros elsewhere. By solving the weights of the basis functions using (39) and substituting them in (33), one can obtain the resulting voltage spectra  $\mathbf{V}(k_x)$  on each slot due to such current excitation, and then, the average voltage across the  $m$ th slot' feeding gap can be found as follows:

$$v_{\delta,m} = \frac{1}{2\pi} \int_{-\infty}^{\infty} V_m(k_x) F_\delta(-k_x) dk_x. \quad (41)$$

By definition, the term  $Z_{mn}$  in the mutual impedance matrix  $\mathbf{Z}$  can be obtained as

$$Z_{mn} = \frac{v_{\delta,m}}{i_{\delta,n}} \Big|_{i_{\delta,k}=0, \text{ for } k \neq n}. \quad (42)$$

2) *Active Input Impedance*: Once the impedance matrix  $\mathbf{Z}$  is obtained, the active input impedance of each feed can be calculated assuming Norton generators with source currents  $i_{\delta,m}$  and impedance  $Z_L$ , as shown in Fig. 10. The active current flowing in each of the feeds can be obtained as

$$\mathbf{i}_A = [\mathbf{Z} + \mathbf{Z}_L]^{-1} \mathbf{Z}_L \mathbf{i}_\delta \quad (43)$$

where  $\mathbf{Z}_L$  is a diagonal matrix with its diagonal elements equal to  $Z_L$ . Then, the voltage across the feeding gap can be computed as  $\mathbf{v}_A = \mathbf{Z} \mathbf{i}_A$ , and the active impedance at each of the feeding gaps is given by

$$Z_{A,m} = \frac{v_{A,m}}{i_{A,m}}. \quad (44)$$

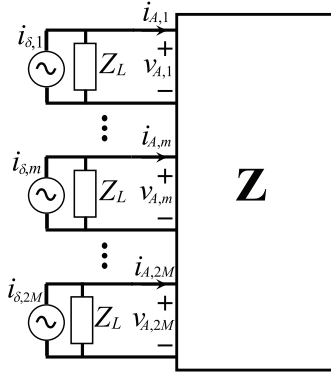


Fig. 10. Norton equivalent circuit of the feeding ports of the array, each connected to a load impedance of  $Z_L$ .

TABLE I

COMPARISON OF COMPUTATION TIME AND RELATIVE ERROR BETWEEN CST FREQUENCY-DOMAIN SIMULATIONS AND OUR METHOD

Method	Number of Unknowns	Time	Error
CST	140k	1573 sec	1
CST	114k	1288 sec	4%
CST	103k	1209 sec	11%
CST	65k	877 sec	15%
This work	12	169 sec	8%

3) *Radiated Field*: Once the active currents flowing in the feeds are known, the voltage spectra  $V_{m'}(k_x)$  on each slot can be obtained by using (39) and (33), from which the scattered magnetic field at an arbitrary point  $(x, y, z)$  can be calculated using

$$\vec{h}(x, y, z) = \frac{1}{4\pi^2} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \vec{G}^{\text{up}}(k_x, k_y, z, z') \vec{M}(k_x, k_y) \times e^{-jk_x x} e^{-jk_y y} dk_x dk_y \quad (45)$$

where  $\vec{G}^{\text{up}}$  is magnetic field spectral-domain Green's dyad for a magnetic current on a ground plane;  $z'$  is the location of the slot plane; and  $\vec{M}(k_x, k_y)$  is the 2-D Fourier transform of the magnetic current, which can be written as

$$\vec{M}(k_x, k_y) = \sum_{m'=1}^{2M} V_{m'}(k_x) M_t(k_y) e^{jk_y y_{m'}} \hat{x} \quad (46)$$

where  $M_t(k_y) = J_0(k_y w/2)$ .

The radiated far field at an observation point  $(\theta_o, \phi_o, r_o)$  can be approximated from (45) using the stationary phase point method as

$$h_{\xi}(\theta_o, \phi_o, r_o) \approx jk_{zo} G_{\xi x}^{\text{up}}(k_{xo}, k_{yo}, z, z') \times M(k_{xo}, k_{yo}) e^{jk_{\text{up}}|z-z'|} \frac{e^{-jk_{\text{up}} r_o}}{2\pi r_o} \quad (47)$$

where  $h_{\xi}$  can indicate the  $x$ -,  $y$ -, or  $z$ -component of the radiated magnetic field;  $G_{\xi x}^{\text{up}}$  is the  $\xi x$  component of Green's dyad;  $k_{xo} = k_{\text{up}} \sin \theta_o \cos \phi_o$ ;  $k_{yo} = k_{\text{up}} \sin \theta_o \sin \phi_o$ ; and  $k_{zo} = k_{\text{up}} \cos \theta_o$ .

### B. Validation

To validate the method, an array of three double-slot elements is simulated using CST frequency-domain solver and the proposed method, with each element consisting of two

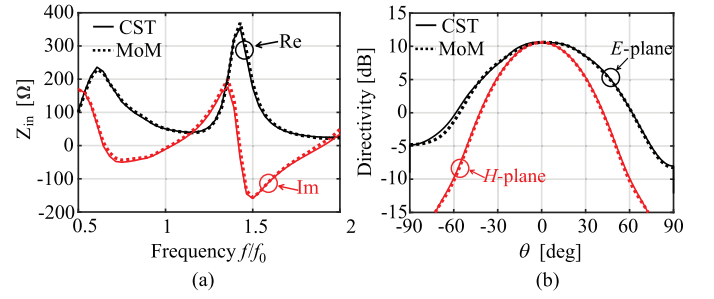


Fig. 11. Comparison between CST and MoM of a three-element cavity-backed double-slot array in terms of (a) active input impedance and (b) directivity of the array at  $f = f_0$  when the two slots of the edge element are excited and all other slots are passively terminated.

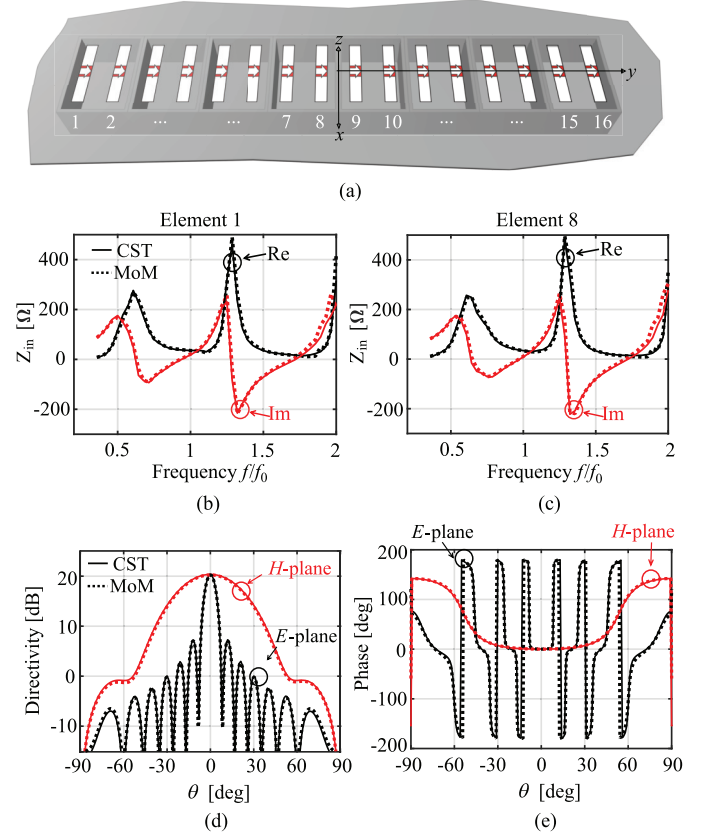


Fig. 12. (a) Array of  $M = 8$  cavity-backed double slots. Active input impedance at (b) port 1 and (c) port 8, (d) directivity, and (e) radiated far-field phase of the array at  $f = f_0$  when all the elements are excited with equal amplitude and phase.

slots backed by a closed cavity, as depicted in Fig. 8. The parameters are  $l = 0.7\lambda_0$ ,  $\delta = 0.1\lambda_0$ ,  $w = 0.06\lambda_0$ ,  $l_c = 0.79\lambda_0$ ,  $w_c = 0.57\lambda_0$ ,  $h_c = 0.16\lambda_0$ ,  $\epsilon_r^{\text{up}} = \epsilon_r^{\text{down}} = 2.34$ ,  $d = 0.285\lambda_0$ , and  $s = 0.57\lambda_0$ . The two slots of the edge element (indicated as 1 and 2 in Fig. 8) are excited with equal amplitude and phase, while all other slots are passively terminated on a  $50\text{-}\Omega$  load. Fig. 11 shows a good agreement between our model and CST in terms of active input impedance and the far-field pattern. Table I compares the computation time required to calculate 47 frequency points using CST and our proposed method, for varying mesh settings of CST. Considering the finest mesh (140k cells) as a reference solution, we report the accuracy for different CST simulations with a lower number of mesh cells and our method. The accuracy is defined in terms

of the maximum error of active input impedance of the edge slot with respect to the reference CST simulation

$$\epsilon = \frac{\max_f(|Z_{in} - Z_{ref}|)}{\max_f(|Z_{ref}|)}. \quad (48)$$

Our method achieves a speedup factor of 7 with respect to CST, for comparable error. A similar speedup was observed for larger arrays.

Another validation is done for a larger array of eight double-slot elements, as shown in Fig. 12(a), with the same parameters as used in the previous example except for the relative permittivity of the medium filling the cavities, which is now  $\epsilon_r^{\text{down}} = 3.5$ . In this case, all 16 slots in the array are excited with the same amplitude and phase. As an example, the computed active input impedances at ports 1 and 8 are plotted in Fig. 12(b) and (c), respectively, as it is seen that they match closely with the results from the CST simulation. The computed radiated far-field properties also exhibit good agreements with the CST finite array simulation, both in terms of directivity and phase patterns, as shown in Fig. 12(d) and (e), demonstrating the accuracy of the method.

## V. CONCLUSION

We presented a numerical method based on spectral-domain MoM for the efficient analysis of linear arrays of cavity-backed slot antennas. To reduce computational complexity, the method employs only two basis functions per slot. The first basis function is determined as the solution of an auxiliary problem considering only the cavity walls parallel to the slot axes, while the second basis function is obtained as the solution of another problem where the slots are located in a closed rectangular cavity.

Validations of the method are done by comparison with CST simulations, demonstrating the method's accuracy in terms of active input impedance and radiation properties. This approach enables the simulation of entire finite arrays within seconds per frequency point, offering significant potential for the design and optimization of such antennas.

## APPENDIX A

### SPECTRAL-DOMAIN REPRESENTATION OF MAGNETIC FIELD IN THE CAVITY

In this section, we report the steps to derive the spectral-domain expression of the scattered magnetic field in the cavity, used in (7). We start from the expression of the  $x$ -component of the scattered magnetic field in the cavity, observed on the slot axis

$$h_x^{\text{down}}(x) = \iint_{\text{Slot}} v(x') m_t(y') g_{xx}^{\text{down}}(x, x', y = 0, y') dx' dy'. \quad (49)$$

By applying the image theorem for the vertical walls, we can replace the single current distribution in the cavity with infinite periodic replicas radiating within a parallel plate waveguide, with two infinite ground planes at  $z = 0$  and  $z = -h_c$

$$h_x^{\text{down}}(x) = \sum_{n_x=-\infty}^{\infty} \sum_{n_y=-\infty}^{\infty} \int_{n_x l_c - l/2}^{n_x l_c + l/2} \int_{n_y w_c - w/2}^{n_y w_c + w/2} v(x') m_t(y') \times g_{xx}^{\text{ppw}}(x - x', -y') dx' dy' \quad (50)$$

where  $g_{xx}^{\text{ppw}}$  is Green's function of the parallel plate waveguide. The periodic current distribution satisfies the following conditions:

$$\begin{aligned} v(x' + n_x l_c) &= (-1)^{n_x} v(x') \\ m_t(y' + n_y w_c) &= m_t(y'). \end{aligned} \quad (51)$$

By using the change of variable  $x'' = x' - n_x l_c$  and  $y'' = y' - n_y w_c$  and the condition (51), we can write (50) as

$$h_x^{\text{down}}(x) = \sum_{n_x=-\infty}^{\infty} \sum_{n_y=-\infty}^{\infty} \int_{-l/2}^{l/2} \int_{-w/2}^{w/2} (-1)^{n_x} v(x'') m_t(y'') \times g_{xx}^{\text{ppw}}(x - x'' - n_x l_c, -y'' - n_y w_c) dx'' dy''. \quad (52)$$

Defining  $d^{\text{down}}$  as

$$d^{\text{down}}(x) = \sum_{n_y=-\infty}^{\infty} \int_{-w/2}^{w/2} m_t(y'') g_{xx}^{\text{ppw}}(x, -y'' - n_y w_c) dy'' \quad (53)$$

we can write (52) as

$$\begin{aligned} h_x^{\text{down}}(x) &= [d^{\text{down}} * v](x) \\ &= \sum_{n_x=-\infty}^{\infty} \int_{-l/2}^{l/2} (-1)^{n_x} v(x'') d^{\text{down}} \\ &\quad \times (x - x'' - n_x l_c) dx''. \end{aligned} \quad (54)$$

By introducing the Fourier transforms  $D^{\text{down}}(k_x)$  and  $V(k_x)$  of  $d^{\text{down}}(x)$  and  $v(x)$ , respectively, we obtain after a few algebraic steps

$$h_x^{\text{down}}(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} D^{\text{down}}(k_x) V(k_x) \sum_{n_x=-\infty}^{\infty} (-1)^{n_x} \times e^{jk_x(n_x l_c - x)} dk_x \quad (55)$$

where  $D^{\text{down}}$  can be written as

$$\begin{aligned} D^{\text{down}}(k_x) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} G^{\text{ppw}}(k_x, k_y) J_0\left(\frac{k_y w}{2}\right) \\ &\quad \times \sum_{n_y=-\infty}^{\infty} e^{jk_y n_y w_c} dk_y. \end{aligned} \quad (56)$$

We now apply the Poisson formula to the infinite sums of exponential terms with indexes  $n_x$  and  $n_y$

$$\begin{aligned} \sum_{n_x=-\infty}^{\infty} (-1)^{n_x} e^{jk_x n_x l_c} &= \sum_{n_x=-\infty}^{\infty} e^{jk_x 2n_x l_c} - \sum_{n_x=-\infty}^{\infty} e^{jk_x (2n_x - 1) l_c} \\ &= (1 - e^{-jk_x l_c}) \frac{\pi}{l_c} \sum_{m_x=-\infty}^{\infty} \delta(k_x - k_{xm}) \end{aligned} \quad (57)$$

$$\sum_{n_y=-\infty}^{\infty} e^{jk_y n_y w_c} = \frac{2\pi}{w_c} \sum_{m_y=-\infty}^{\infty} \delta(k_y - k_{ym}) \quad (58)$$

where  $k_{ym} = -2\pi m_y / w_c$ ,  $k_{xm} = -\pi m_x / l_c$ , and  $\delta(k)$  is the Dirac delta function. The term  $(1 - e^{-jk_x l_c})$  is equal to 0 when  $m_x$  is an even number and is equal to 2 when  $m_x$  is an odd number. Therefore, (57) can be written as

$$\sum_{n_x=-\infty}^{\infty} (-1)^{n_x} e^{jk_x n_x l_c} = \frac{2\pi}{l_c} \sum_{m_x \text{ odd}} \delta(k_x - k_{xm}). \quad (59)$$

Substituting (59) into (55), one can write

$$h_x^{\text{down}}(x) = \frac{1}{l_c} \sum_{m_x, \text{ odd}} D^{\text{down}}(k_{xm}) V(k_{xm}) e^{-jk_{xm}x} \quad (60)$$

and by substituting (58) into (56),  $D^{\text{down}}(k_x)$  can be written as

$$D^{\text{down}}(k_x) = \frac{1}{w_c} \sum_{m_y=-\infty}^{\infty} G^{\text{ppw}}(k_x, k_{ym}) J_0\left(\frac{k_{ym}w}{2}\right) \quad (61)$$

where the spectral-domain Green's function for the parallel waveguide can be solved using an equivalent transmission line model and results into (9).

## APPENDIX B

### EFFICIENT TRUNCATION OF THE VOLTAGE SOLUTION

As in [22], the truncated spectrum is found by applying an IFT to  $V_a(k_x)$ , multiplying by a window function with domain  $[-l/2, l/2]$ , and reapplying a Fourier transform (FT)

$$B_a^{\text{tr}}(k_x) = \int_{-l/2}^{l/2} \left( \frac{1}{2\pi} \int_{-\infty}^{\infty} B_a(k'_x) e^{-jk'_x x} dk'_x \right) e^{jk_x x} dx. \quad (62)$$

The double integral in (62) can be expressed as

$$B_a^{\text{tr}}(k_x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} B_a(k'_x) \text{sinc}\left(\frac{(k_x - k'_x)l}{2}\right) dk'_x. \quad (63)$$

The truncated spectrum in (63) is first computed numerically by discretizing  $k'_x$  over the range  $(-400k_0, 400k_0)$  using  $N_{k'_x} = 10^5$  equidistant points, with a midpoint quadrature rule. This choice of  $N_{k'_x}$  resulted from a study on the convergence of the integral. The spectrum values obtained by approximating (63) with the discrete summation, while varying the number of equispaced points in the interval  $(-400k_0, 400k_0)$  up to  $1.5 \times 10^5$ , oscillate until convergence is achieved starting at  $10^5$  points. The spectrum computed with  $N_{k'_x} = 10^5$  points is then taken as the reference for accuracy and computation time comparison and is denoted as  $B_{\text{ref}}$ .

The numerical integral is computationally expensive as it requires a large number of  $k'_x$ -integrals, for each value of  $k_x$ . However, one can expect that since the truncated and untruncated voltage distributions differ by waves propagating at a significant electrical distance from the feed, the difference between their spectra would asymptotically tend to 0 for large values of  $k_x$ . Therefore, one can reduce the number of integrals by only calculating  $B_a^{\text{tr}}(k_x)$  for a smaller domain of  $k_x \in (-L, L)$ , assuming that  $B_a^{\text{tr}}(k_x)$  can be approximated as  $B_a(k_x)$  for larger values of  $k_x$ . Hence, we obtain an approximated solution by imposing

$$B_L(k_x) = \begin{cases} B_{\text{ref}}(k_x), & \text{for } |k_x| \leq L \\ B_a(k_x), & \text{for } |k_x| > L. \end{cases} \quad (64)$$

Fig. 13(a) shows the relative error committed by this approximation as a function of the domain of calculation  $L$ , where the relative error is  $\epsilon_r$ , defined as

$$\epsilon_r = \sqrt{\frac{\int |B_L(k_x) - B_{\text{ref}}(k_x)|^2 dk_x}{\int |B_{\text{ref}}(k_x)|^2 dk_x}}. \quad (65)$$

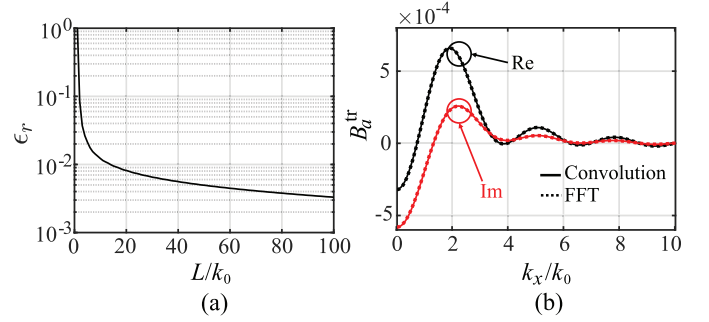


Fig. 13. (a) Real and imaginary parts of the truncated spectrum  $B_a^{\text{tr}}(k_x)$ . (b) Relative error of compared with  $B_{\text{ref}}^{\text{tr}}(k_x)$  as a function of calculation domain.

TABLE II

TIME AND RELATIVE ERROR RELATED TO THE CALCULATION OF THE TRUNCATED SPECTRUM  $B_a^{\text{tr}}(k_x)$

Method	Computation Time	Relative Error
No Acceleration	56.5 sec	/
Smaller domain ( $L = 40k_0$ )	5.5 sec	0.56%
IFFT/FFT	0.003 sec	0.58%

It can be seen that an error  $\epsilon_r \approx 0.56\%$  is obtained by choosing  $L = 40k_0$ , which corresponds to only one tenth of the total number of integrals.

A more efficient method to obtain the truncated spectrum is to replace the IFT and FT operations in (62) with their fast Fourier transform counterparts (FFT and IFFT). First, the spatial-domain voltage distribution is obtained by applying an IFFT on the untruncated spectrum  $B_a(k_x)$  in MATLAB

$$b_a(x_n) = \text{ifft}\{\text{fftshift}\{B_a(k_x)\}\} \quad (66)$$

where  $n = 1, 2, \dots, N_{k_x}$ . The function “fftshift” rearranges the order of elements in  $B_a(k_x)$  such that its negative frequency components are mirrored to the right side of the array, which is required by the IFFT process. The resulting spatial sampling  $x_n$  also has its negative components mirrored in a similar manner, and it is related to the sampling frequency  $k_{x,\text{lim}}$  by  $x_n = (n-1)\pi/k_{x,\text{lim}}$ . Then, the voltage distribution is truncated by applying a rectangular window that includes only the slot region

$$b_a^{\text{tr}}(x_n) = b_a(x_n) \cdot \text{fftshift}\{\text{rect}_l(x_n)\} \quad (67)$$

where  $\text{rect}_l(x_n)$  is equal to 1 for  $x_n \in [-l/2, l/2]$  and 0 otherwise. Finally, the truncated spectrum is obtained by applying an FFT to  $b_a^{\text{tr}}(x_n)$  and rearranging its negative frequency components back

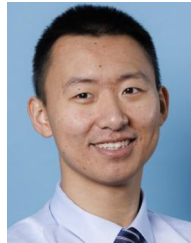
$$B_a^{\text{tr}}(k_x) = \text{fftshift}\{\text{fft}\{b_a^{\text{tr}}(x_n)\}\}. \quad (68)$$

The resulting truncated spectrum using (68) is plotted in Fig. 13(b), showing a good agreement ( $\epsilon_r \approx 0.58\%$ ) with the reference spectrum  $B_{\text{ref}}^{\text{tr}}(k_x)$  that is calculated for the entire domain of  $k_x$  using (63).

The computation time and relative error related to the calculation of the truncated spectrum is listed in Table II, showing a clear advantage of the IFFT/FFT method in terms of computation efficiency.

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