Corrigendum to

Overcoming the cohesive zone limit in composites delamination: modeling with slender structural elements and higher-order adaptive integration (International Journal for Numerical Methods in Engineering, (2020), 121, 24, (5511-5545), 10.1002/nme.6497)

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CORRIGENDUM

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Overcoming the cohesive zone limit in composites delamination: modeling with slender structural elements and higher-order adaptive integration (*Int. J. Numer. Meth. Engng*. 2020, 121(24): 5511-5545; DOI:10.1002/nme.6497)

The authors would like to point out three writing mistakes that have been found after the publication of the original paper:

- Equation (13) should be written as:

$$\mathbf{q}^{\mathrm{CE}} = \begin{bmatrix} \mathbf{u}^{\mathrm{bot}} \\ \mathbf{a}^{\mathrm{bot}} \\ \mathbf{u}^{\mathrm{top}} \\ \mathbf{a}^{\mathrm{top}} \end{bmatrix} \tag{1}$$

  to correctly represent the intended column vector of the element's degrees of freedom.

- Equation (49) and (50) should be written as:

$$\begin{aligned} \frac{\partial^2 \gamma_\xi}{\partial \xi \partial \mathbf{q}^{\mathrm{CE}}} = \frac{1}{2}\left[\frac{\partial \mathbf{N}^u}{\partial \xi}, -\frac{h^{\mathrm{bot}}}{2}\cos\theta^{\mathrm{bot}}\frac{\partial \mathbf{N}^\theta}{\partial \xi}, \frac{\partial \mathbf{N}^u}{\partial \xi}, \frac{h^{\mathrm{top}}}{2}\cos\theta^{\mathrm{top}}\frac{\partial \mathbf{N}^\theta}{\partial \xi}\right] \\ + \frac{1}{2}\mathbf{q}^{\mathrm{CE}^{\mathrm{T}}}\begin{bmatrix} \mathbf{0} \\ \frac{h^{\mathrm{bot}}}{2}\sin\theta^{\mathrm{bot}}\frac{\partial \mathbf{N}^\theta}{\partial \xi}\otimes\frac{\partial \theta^{\mathrm{bot}}}{\partial \mathbf{q}^{\mathrm{CE}}} \\ \mathbf{0} \\ -\frac{h^{\mathrm{top}}}{2}\sin\theta^{\mathrm{top}}\frac{\partial \mathbf{N}^\theta}{\partial \xi}\otimes\frac{\partial \theta^{\mathrm{top}}}{\partial \mathbf{q}^{\mathrm{CE}}} \end{bmatrix} \end{aligned} \tag{2}$$

$$\begin{aligned} \frac{\partial^2 \gamma_\eta}{\partial \xi \partial \mathbf{q}^{\mathrm{CE}}} = \frac{1}{2}\left[\mathbf{0}, \frac{\partial \mathbf{N}^v}{\partial \xi} - \frac{h^{\mathrm{bot}}}{2}\sin\theta^{\mathrm{bot}}\frac{\partial \mathbf{N}^\theta}{\partial \xi}, \mathbf{0}, \frac{\partial \mathbf{N}^v}{\partial \xi} + \frac{h^{\mathrm{top}}}{2}\sin\theta^{\mathrm{top}}\frac{\partial \mathbf{N}^\theta}{\partial \xi}\right] \\ + \frac{1}{2}\mathbf{q}^{\mathrm{CE}^{\mathrm{T}}}\begin{bmatrix} \mathbf{0} \\ -\frac{h^{\mathrm{bot}}}{2}\cos\theta^{\mathrm{bot}}\frac{\partial \mathbf{N}^\theta}{\partial \xi}\otimes\frac{\partial \theta^{\mathrm{bot}}}{\partial \mathbf{q}^{\mathrm{CE}}} \\ \mathbf{0} \\ \frac{h^{\mathrm{top}}}{2}\cos\theta^{\mathrm{top}}\frac{\partial \mathbf{N}^\theta}{\partial \xi}\otimes\frac{\partial \theta^{\mathrm{top}}}{\partial \mathbf{q}^{\mathrm{CE}}} \end{bmatrix} \end{aligned} \tag{3}$$

  to keep the vector format consistent across the terms. The derivations afterwards are not affected by this change.

- Equation (63) should have no minus sign on the second term of the second row, that was a typographical error. The correct Equation (63) should be written as:

$$\mathbf{B}^{\boldsymbol{\Delta}} = \mathbf{N}^{\mathrm{CE}} + \begin{bmatrix} \mathbf{0}, & \mathbf{0}, & \mathbf{0}, & \mathbf{0} \\ \mathbf{0}, & \frac{h^{\mathrm{bot}}}{2}\mathrm{N}^\theta, & \mathbf{0}, & \frac{h^{\mathrm{top}}}{2}\mathbf{N}^\theta \end{bmatrix} \tag{4}$$

The above mistakes appear only in the writing of the manuscript, not in the actual implementation of the method. Hence, the results and conclusions in the original paper remain unchanged.

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