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Impact of Lead Time on Aggregate EV Flexibility for Congestion Management Services

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Abstract—Increased electrification of energy end-usage can lead to network congestion during periods of high consumption. Flexibility of loads, such as aggregate smart charging of Electric Vehicles (EVs), is increasingly leveraged to manage grid congestion through various market-based mechanisms. Under such an arrangement, this paper quantifies the effect of lead time on the aggregate flexibility of EV fleets. Simulations using real-world charging transactions spanning over different categories of charging stations are performed for two flexibility products (redispatch and capacity limitations) when offered along with different business-as-usual (BAU) schedules. Results show that the variation of tradable flexibility depends mainly on the BAU schedules, the duration of the requested flexibility, and its start time. Further, the implication of these flexibility products on the average energy costs and emissions is also studied for different cases. Simulations show that bidirectional (V2G) charging outperforms unidirectional smart charging in all cases.

Index Terms—Aggregation, congestion management, electric vehicle, flexibility, lead time

I. INTRODUCTION

The widespread electrification of sectors such as heating, transportation, and industries is increasingly straining electricity networks. Especially with the large-scale adoption of Electric Vehicles (EVs), power networks face challenges in safely accommodating their aggregate charging needs. This has resulted in congestion, where parts of the network (such as cables, transformers, etc.) risk overloading during high-demand times. The resulting congestion in power networks is already prominent in North America [1] and mainland Europe, including the Netherlands [2]. It is only a matter of time before these issues become prevalent worldwide. One reason for the congestion is that the power networks were originally not designed for such a degree of electrification, and the simultaneity of high-power loads further exacerbates it. As a result, the grid needs to be adapted and reinforced to accommodate the growing loads. However, these need substantial investments and a longer time, making the pursuit of short-term alternatives increasingly critical [3].

Different short-term approaches, such as hard curtailments on charging power during anticipated congestion or refusal of new network connections until the congestion situation im-

proves, are some solutions that network operators in countries like the Netherlands and Germany adopt [4]. However, such solutions manage congestion at the cost of end-user satisfaction, which is diminished due to lower charging speed, cost of charging, or restricted autonomy by these mandates. Mandate-based (direct-control) solutions offer limited flexibility to end-users and aggregators, potentially slowing the adoption of EVs. To address this, Distribution System Operators (DSOs) and policymakers increasingly favour incentive-based congestion management, which encourages voluntary participation from aggregators and end-users [5]. The voluntary participation for EVs is possible without compromising on operational constraints due to EV's flexibility.

EVs inherently offer charging and storage (in the case of Vehicle-to-grid (V2G) through discharging) flexibility. In other words, the time required to fully charge an EV is typically disproportionate to its average connection duration. Leveraging this, smart charging (and V2G) offers significant potential to mitigate (or exacerbate) network congestion. Influencing individual charging profiles through time-of-use has been used extensively in Europe, ranging from simple dynamic energy prices to network tariffs or combinations of both [6], [7]. Price-based approaches can help limit aggregate charging peaks; however, if not carefully designed, they can create newer peaks or penalize consumers unfairly [8].

Alternatively, leveraging aggregate flexibility to manage congestion has proven highly efficient, as it can mitigate the uncertainties associated with an individual EVs [9]. In addition to direct control of aggregate EVs, market-based methods are one of the most cost-effective and scalable solutions to leverage this flexibility for congestion management. These offer scalability, incentivize flexible energy usage, and promote competition among participants [10].

Market-based congestion management services are currently being developed in several territories as alternatives. Market-based capacity management can typically be achieved through reduction options, activation before anticipated congestion, or direct trading. In the Netherlands, the energy regulatory body has defined network congestion, assigned specific responsibilities to stakeholders participating in congestion management services and described the characteristics of market products that can help alleviate congestion [11]. These include on-demand capacity limitation contracts and location-based redispatch, linked to intra-day markets [9].

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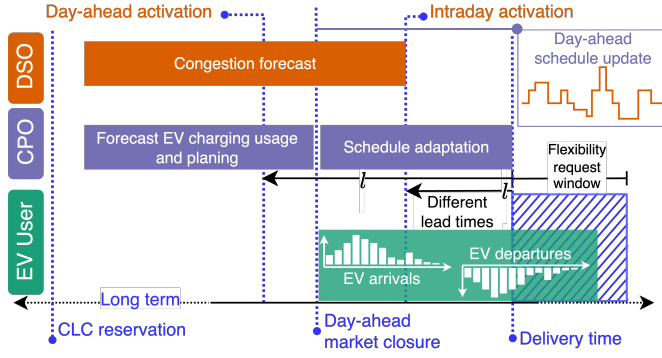


Fig. 1. Schematic showcasing various market interactions alongside market timeline for capacity limitation products.

However, barriers exist to exchanging congestion management services by Charging Point Operators (CPOs) to the DSOs. Besides technical challenges, such as bundling connections and communicating with numerous assets, it is unclear how much flexibility a fleet of assets can reliably offer and how it depends on the service type and the advance notice given for activation. This paper investigates how lead times and length of flexibility request windows influence the magnitude of two congestion management products—redispatch and capacity limitation—across different categories of Charging Stations (CSs) and dispatch strategies. We further compare the capabilities of V2G or bidirectional charging with unidirectional charging (also called smart charging). The congestion management products in The Netherlands are used as a reference for model development.

II. MECHANISM OF CONGESTION MANAGEMENT

Fig. 1 illustrates different market interactions with respect to the time horizon for the redispatch and capacity limitation products in the Netherlands. When delivering services using EVs to relieve congested distribution grids, three stakeholders (EV users, DSO and CPO) interact. For simplicity, the CPO controls the charging of EVs and acts as the aggregator. The DSO is responsible for forecasting the periods of congestion along with its duration and magnitude. Based on these forecasts, it sends activation signals to the flexibility aggregators. Based on the arrangements, activation can be done either a day ahead (≥ 24 hours, or, more accurately, before clearing of the day-ahead market) or within the intraday time frame, with lead times ranging from as short as 1 hour up to the day-ahead market time frame. We define lead time as the time available to the aggregators for schedule adaption between activation and delivery of the flexibility services. This paper considers a range of 1 to 23 hours.

Until the aggregators are notified of activation, they schedule their EVs according to Business as usual (BAU) schedules. Once notified, the day-ahead schedules are adjusted to deliver the specified product effectively. Based on these interactions, the ability to trade a specific product depends on several factors such as lead time, duration of flexibility request window,

charging strategy (unidirectional or V2G), lead time, BAU scheduling strategy and the type vehicles in the fleet.

Shorter lead times provide more room to efficiently utilize the network's available capacity while maximizing the CPO's revenue based on BAU schedules. However, longer lead times may reduce the attractiveness of congestion management products for the DSO as the uncertainty surrounding the occurrence of congestion increases. Conversely, shorter lead times can critically hinder the aggregators' ability to deliver these products, increasing the chances of enforced measures such as load curtailment, which could negatively impact end-user experience. The duration for which a particular product is requested also influences the magnitude of the product. As the window length increases, the magnitude keeps on diminishing.

Assuming that an EV fleet has a certain energy demand to be fulfilled within a specified time frame but with scope to adjust the schedule; we consider the fleet to have *potential flexibility*. This translates into *feasible flexibility* once all operational and technical constraints are accounted for, including those derived from day-ahead BAU charging schedules, and a model representation is used. The aggregator aims to maximize its revenue using congestion management products, for which it must determine the *tradable flexibility* in flexibility markets - which also depends on the product requirements and lead times. Previous work [9] analysed the aggregate flexibility of EV charging stations to deliver redispatch and offer aggregate capacity limitations (without sacrificing the quality of service). This was done for three distinct categories of CSs (residential, commercial and shared) and two charging strategies (unidirectional and V2G). This paper further investigates the impact of the following factors:

- BAU schedules (cost minimised, Marginal Emission Factor (MEF) minimized and unoptimized)
- Lead time
- Duration of the requested flexibility window

III. MODELS AND METHODS

This section explains how different charging models are simulated based on real charging transactions to quantify the flexibility potential of EV fleets in delivering the two congestion management products - redispatch and capacity limitation.

We consider a set $\mathcal{N}$ of charging transactions indexed by n , each requiring a total charge of $\bar{e}_n$ to be delivered between their arrival time (t_n^a) and departure time (t_n^d). Charging occurs in discrete time intervals (Δt), during which the charging power ($p_{n,t}$) of each EV is constant. The charging power $p_{n,t}$ is a continuous variable, constrained between a maximum power ($\bar{p}_n$) and a minimum power ($\underline{p}_n$). For bidirectional charging, $\underline{p}_n = -\bar{p}_n$; otherwise, $\underline{p}_n = 0$. $\mathcal{T}$ (indexed by t) represents the set of time intervals over which the optimization problem is solved. In contrast, $\mathcal{T}_f \subseteq \mathcal{T}$ denotes the subset of time intervals during which a specific congestion product is requested.

Each charging transaction is required to fulfil the energy volume derived from historical data, which may be less than

the battery capacity (because the EV was not empty at the start of the session or not full at the end). For bi-directional charging, the batteries' state of charge (SOC) cannot drop below their initial SOC, ensuring that EV owners never find their vehicles with a lower SOC than at the start. Because EVs are restricted from charging beyond their historical charge volumes, resulting in a conservative estimate of feasible flexibility. Data originally recorded in seconds is resampled to 15-minute intervals, with arrival and departure times rounded to the nearest 15 minutes. Transactions that become infeasible after rounding due to insufficient connection time are excluded (less than 0.1% of transactions). The maximum connection duration for an EV is capped at 24 hours (96 time steps).

A. BAU dispatch strategies

This paper considers three BAU dispatch strategies: cost minimized, MEF minimized and unoptimized. The BAU optimized profile ($\tilde{p}_{n,t}^*$) is calculated by solving the following linear optimization problem.

Objective (1a) minimizes the total cost of charging based on day-ahead prices (Π_t^{da} , €/kWh), (1b) minimizes the marginal emissions (Π_t^{mef} , kgCO₂/kWh) and (1c) makes sure all the EVs are charged as fast as possible (unoptimized or 'dumb' charging). Further, all the EVs are constrained by (2)-(6), which holds the above assumptions.

$$\min_p f(p); \quad f(p) = \begin{cases} \sum_{t \in \mathcal{T}} \sum_{n \in \mathcal{N}} \Pi_t^{\text{da}} p_{n,t} \Delta t & (1a) \\ \sum_{t \in \mathcal{T}} \sum_{n \in \mathcal{N}} \Pi_t^{\text{mef}} p_{n,t} \Delta t & (1b) \\ \sum_{t \in \mathcal{T}} \sum_{n \in \mathcal{N}} e_{n,t} & (1c) \end{cases}$$

subject to:

$$e_{n,t} = 0, \quad t \leq t_n^a, \quad n \in \mathcal{N} \quad (2)$$

$$e_{n,t} = e_{n,t-1} + p_{n,t-1} \Delta t, \quad t_n^a < t < t_n^d, \quad n \in \mathcal{N} \quad (3)$$

$$e_{n,t} = \bar{e}_n, \quad t \geq t_n^d, \quad n \in \mathcal{N} \quad (4)$$

$$p_{n,t} = 0, \quad t < t_n^a \vee t \geq t_n^d, \quad n \in \mathcal{N} \quad (5)$$

$$\underline{p}_n \leq p_{n,t} \leq \bar{p}_n, \quad t_n^a \leq t < t_n^d, \quad n \in \mathcal{N} \quad (6)$$

As illustrated in Fig. 2, the daily peak consumption occurs at different hours of the day for different BAU schedules. Optimized profiles based on day-ahead prices and unoptimized profiles exhibit higher peaks than unoptimized charging. The magnitude of these peaks depends on the density of EV arrivals at a given hour and the timing of lower electricity prices or MEF, with the MEF-minimized profile showing a more diffuse pattern. Hence, due to these distinct variations, it is important to investigate the impact of different BAU schedules on the delivery of congestion management products.

B. Flexibility products

This paper analyses two congestion management products the aggregator must deliver during the requested flexibility window $\mathcal{T}_f$. The information about the delivery window ($\mathcal{T}_f$) is

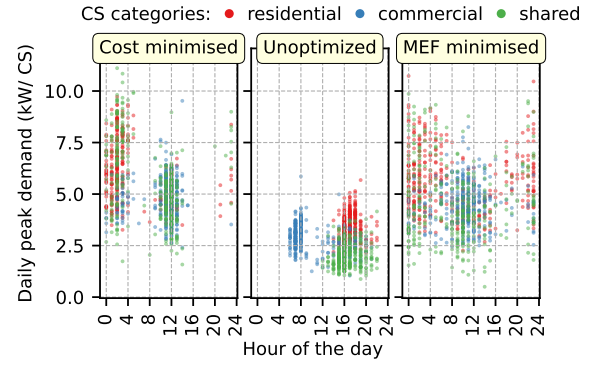


Fig. 2. Relationship between daily peak power usage and the hour of the day across all days in the year 2023. Each point represents the peak power recorded at a specific hour for a particular BAU schedule and CS category.

assumed to be known to the aggregator only l hours (lead time) in advance. In our case study, we consider a single aggregator who also serves as the CPO, responsible for scheduling the EVs. The optimized profiles are obtained by solving a linear programming problem described below.

1) *Optimal downward redispatch*: The optimal downward redispatch strategy aims to maximize the downward deviation between the aggregated power profile and the optimized BAU profile ($\tilde{p}_{n,t}^*$). We assume perfect knowledge of the arrival and departure times of all EVs. The optimal downward redispatch (c^r) is calculated by maximizing (7), where the secondary objective based on the desired BAU case is multiplied with an auxiliary parameter (ϵ). Based on sensitivity analysis, the value of ϵ was fixed to $1 * 10^{-6}$.

$$\max_{c^r, p, \epsilon} c^r + \epsilon f(p) \quad (7)$$

subject to:

constraints (2)-(6)

$$\sum_{n \in \mathcal{N}} p_{n,t} \leq \tilde{p}_{n,t}^* - c^r, \quad \forall t \in \mathcal{T}_f \quad (8)$$

$$p_{n,t} = \tilde{p}_{n,t}^*, \quad \forall t < \min(\mathcal{T}_f) - l/\Delta t, \quad \forall n \in \mathcal{N} \quad (9)$$

2) *Optimal capacity limitation*: Optimal capacity limitation strategies dispatch EVs to minimize the maximum aggregate power during a given flexibility request window. Like the optimal redispatch policy, this strategy also assumes perfect knowledge of all EV arrival and departure times. The optimal capacity limitation (c^l) is also calculated using a linear optimization problem, where it is assumed that $c^l \geq 0$. Similar to the redispatch product, this can be solved for different BAU profiles.

$$\min_{c^l, p, \epsilon} c^l + \epsilon (f(p)) \quad (10)$$

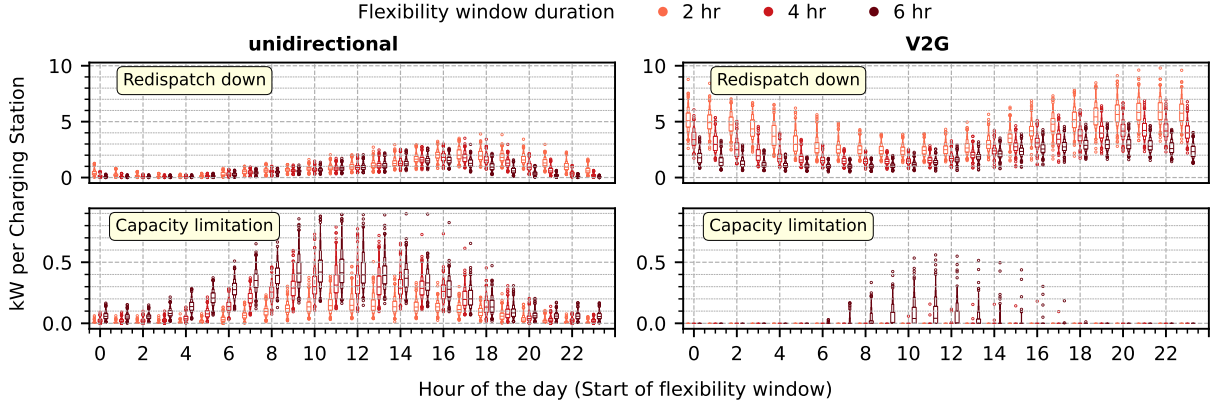


Fig. 3. Distribution of flexibility (redispatch and capacity limitation) for unoptimized BAU schedule shown for different start of flexibility request windows of 1 hour. For the purpose of illustration, only residential charging stations are shown.

subject to:

constraints (2)-(6)

$$c^l \geq 0 \quad (11)$$

$$\sum_{n \in \mathcal{N}} p_{n,t} \leq c^r, \quad t \in \mathcal{T}_f \quad (12)$$

$$p_{n,t} = \tilde{p}_{n,t}^*, \quad \forall n \in \mathcal{N} \quad t \leq \min(\mathcal{T}_f) - l/\Delta t \quad (13)$$

IV. RESULTS

A. Sampling of real EV transactions

The analysis considers over 350,000 real charging transactions in the Netherlands during 2023. In the selected data, there are 668 unique charging stations, with 313 in the residential category, 254 in the commercial category, and 101 in the shared category. The categorization of the CSs was done as explained in [9]. The transactions are distributed among three categories of CSs - residential (57.6 %), commercial (31 %), shared (11.4 %). Each CS has two connectors that can be connected to separate EVs.

In the analysis, each day of the year was taken as an independent sample. All transactions with arrivals on the sample date and the previous day are considered to simulate the *sampled date*. The optimization horizon spans one day before and one day after the sample day, ensuring that all transactions can be fully charged. In the analysis, day-ahead energy prices for 2023 were used from the ENTSO-E Transparency platform*. The MEF data was obtained from the authors of [12].

B. Variation of flexibility window duration

With the increase in the length of the flexibility window, the ability to minimise the power decreases due to the reduction in charging flexibility for both the products, as illustrated in Fig. 3 for residential CSs with an unoptimized BAU schedule. The available redispatch flexibility increases with the arrival density of EVs. However, the minimum required capacity

peaks (so the ability to constrain capacity drops) around mid-day when short charging sessions dominate. The overall magnitude of tradable flexibility sharply increases for V2G, while still reducing gradually with increase in the flexibility request duration.

C. Variation in lead time

Two different lead times - day-ahead activation and activation 1 hour ahead of expected delivery are chosen as two possible extreme cases, which also illustrate the trend for in-between cases. Fig. 4-(a) illustrates the reduction in the EV fleets' ability to limit their consumption during the requested flexibility windows of one hour for the two chosen lead times. The results are compared across the three charging station categories for different BAU schedules, considering only unidirectional smart charging. Tradable flexibility significantly decreases with shorter lead times for all BAU schedules, except in the unoptimized case. This is because unoptimized charging is a greedy strategy that is unaffected by the lead time. Higher average reductions in tradable flexibility coincide with lower average day-ahead and MEF prices. During such a period, limiting power depends largely on schedule adaption before the delivery. Hence, with shorter lead time, the EV schedules are less able to adapt because they were originally scheduled to charge during lower cost periods.

Fig. 4-(b) illustrates similar results, but for the redispatch product. As a general trend, the magnitude of redispatch capability depends on the density of EV arrivals and the timing of lower energy/ emission costs. It further scales with the maximum charging power, occupancy of CSs and the energy needs, which are highly dependent on the charging station's category. Notably, the *reduction* in tradable flexibility as a result of a reduction in lead time is the same as for the capacity limitation product. This can be understood because the reduction depends only on the ability to adjust schedules between activation and delivery, which is the same irrespective of the product.

*<https://newtransparency.entsoe.eu/>

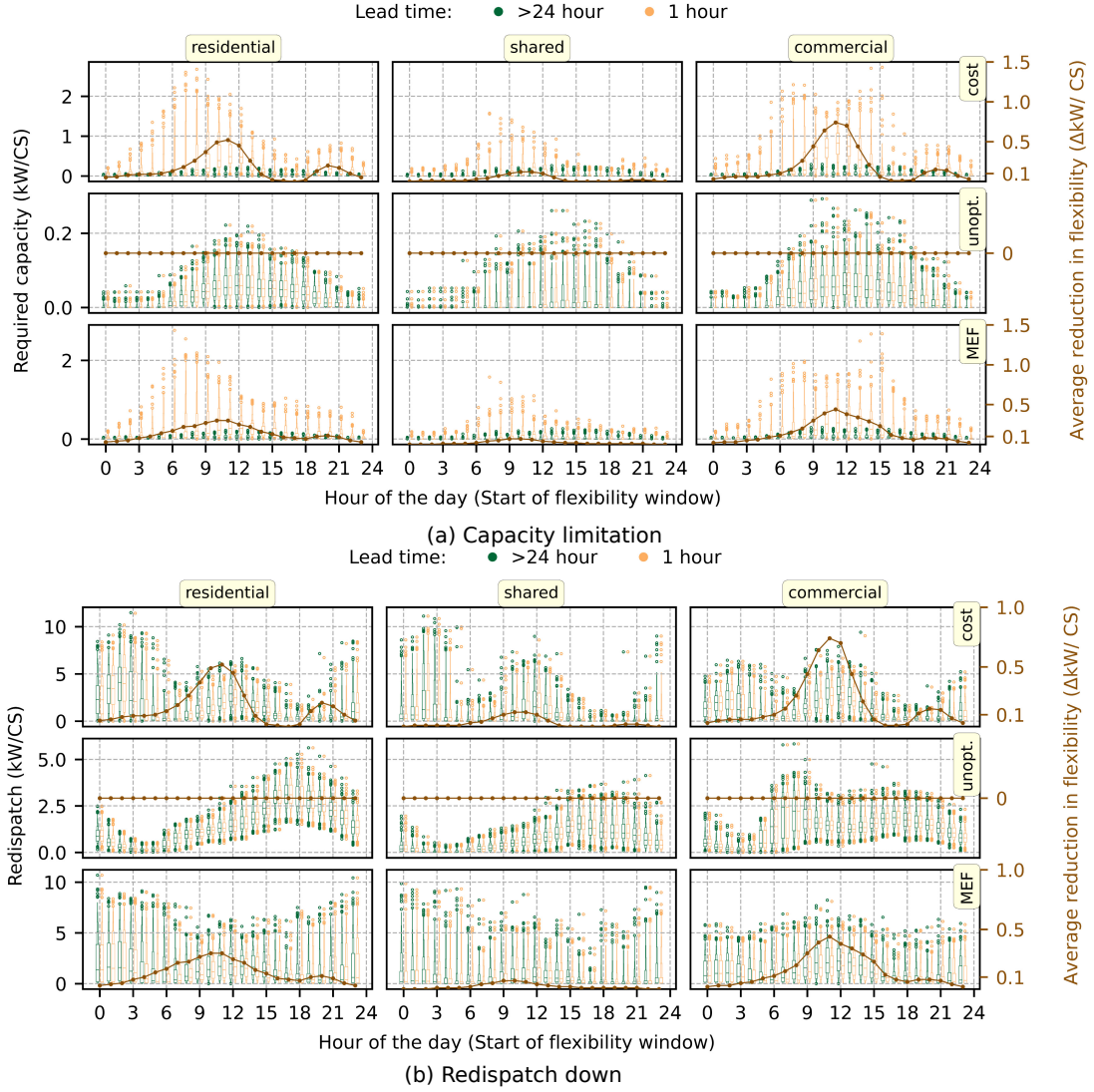


Fig. 4. Impact of different lead times compared across different CS categories and BAU schedules. The difference between the average flexibility magnitude for the two lead times has been plotted using the secondary axis. Flexible windows with different start times and a duration of 1 hour are chosen.

Using V2G, the EVs can more flexibly adapt their schedule between activation and delivery. This is due to the possibility of aggregate power reduction by discharging some EVs while compensating for other EVs that must be charged. This trend is clearly illustrated in Fig. 5, which plots the tradable redispatch flexibility for different one-hour flexibility windows across CS categories for the cost-minimized BAU schedule. Similar trends are also observed for other BAU schedules. The redispatch flexibility increases greatly with V2G. At the same time, although its *reduction* due to a shorter notice period increases more compared to the unidirectional case, the overall magnitude is still higher than unidirectional smart charging. Capacity limitation results are not shown because the flexibility of V2G is such that a capacity reduction to 0kW is feasible for nearly all scenarios.

D. Implication of lead time on average charging costs

When opting to adjust charging to deliver congestion management services, the aggregator's energy costs can increase. To illustrate the impact of the BAU scheduling strategy and the impact of delivering services, Fig. 6 shows the average cost of charging for 2023 and its change when flexibility is provided in the form of the capacity limitation. The energy costs are consistently lower for V2G compared to the unidirectional charging when all other parameters are kept the same. However, this does not consider the required investments in hardware (EV, CS), extra wear and tear and control system requirements. Further, we show the average cost increase when the BAU schedules are updated to deliver flexibility services for congestion management. For unidirectional charging, no cost increase is observed. However, there is an increase in costs under V2G charging depending on the BAU schedule

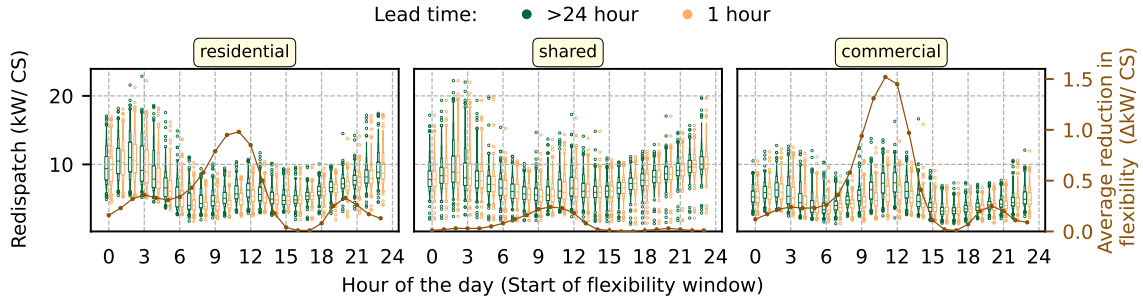


Fig. 5. Effect of different lead times on the flexibility for redispatch with V2G. For the purpose of this illustration, only the case with cost minimized BAU schedule is shown for different categories of CS for a flexibility window of one hour.

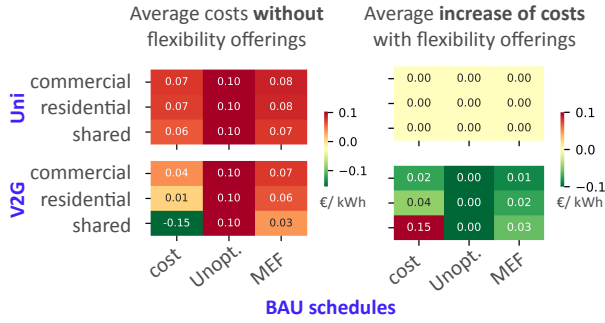


Fig. 6. Heatmap illustrating the hourly averaged energy costs under different BAU schedules (left). The right heatmap shows the corresponding increase in average costs after adapting schedules to deliver flexibility for congestion management (capacity limitation product).

- largely offsetting the cost gains made in the no-flexibility scenario.

The code used to produce the plots and the models used for the simulations are available in [13]. The simulations were carried out on DelftBlue, the supercomputer cluster at TU Delft [14].

V. CONCLUSION

In this paper, we investigated the effects of different lead times and window lengths on the magnitude of tradable flexibility for different products compared to three CS categories and BAU schedules. Shorter lead times reduce tradable flexibility in all cases except in the case of an unoptimized BAU schedule, where charging as soon as connected (a greedy strategy) limits the charging adaptability. V2G enables more flexible adaption of schedules, thereby reducing the effect of lead times on the delivery of flexibility. Reduction trends are also observed with the increased flexibility window duration, which decreases with the adoption of V2G. The paper thus highlights the usefulness of V2G when uncertainty regarding lead times cannot be completely removed.

Further research can extend this analysis by relaxing delivery constraints or the requirements that vehicles are fully charged, subject to suitable penalties. The actual impact of peak reduction on thermal overloads may also be investigated in more detail.

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