

# Bidirectional enrichment of CityGML and Multi-View Stereo Mesh models

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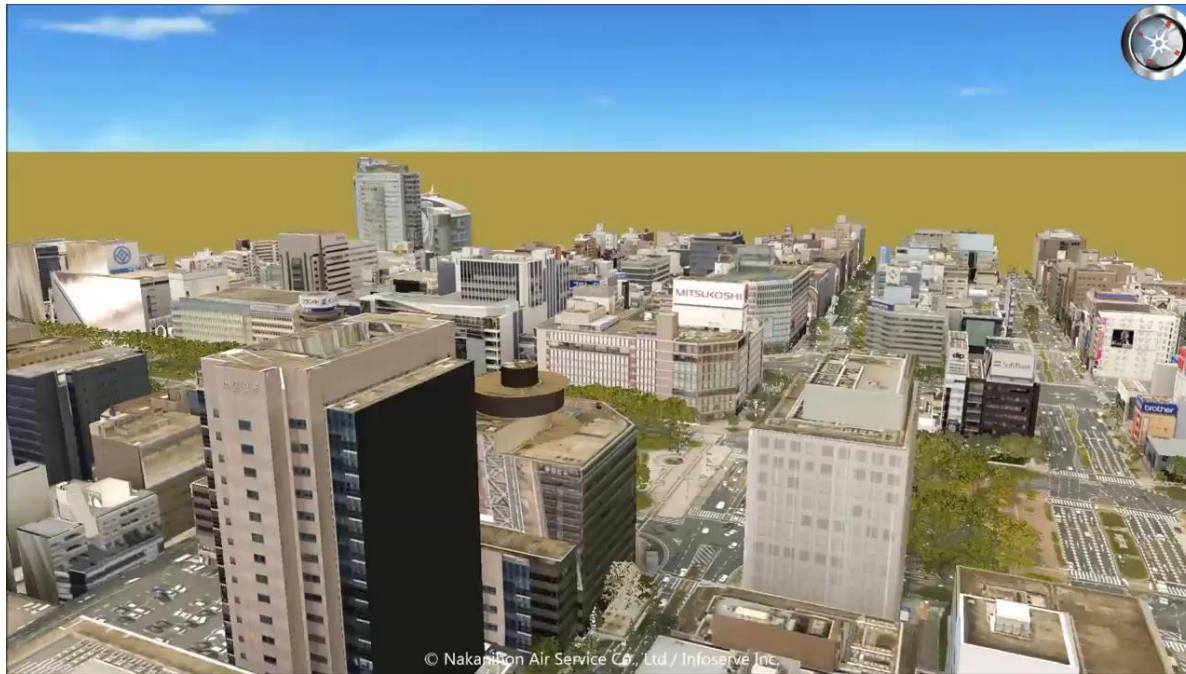
# Outline

1. Background & Research objectives
2. Bidirectional enrichment
3. Proposed methodology & Analysis
4. Conclusions & Future work

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# 3D city model



Source: *Nagoya city - 3D CityGML modeling example*

Link: *<https://www.youtube.com/watch?v=9CTbQTKPtsg>*

# 3D city model

- Helsinki 3D+ (2016)
- Solar Irradiation Analysis Rennes (2016)
- Berlin Solar Atlas (2017)

# 3D city model

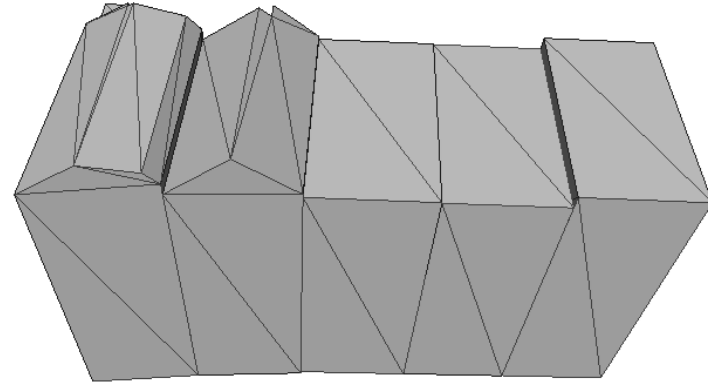


Source: *virtualcityMAP - Demonstration of Solar Irradiation Analysis Rennes, France*

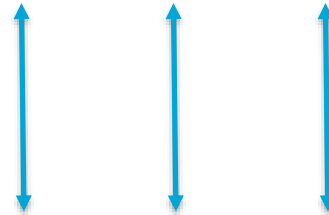
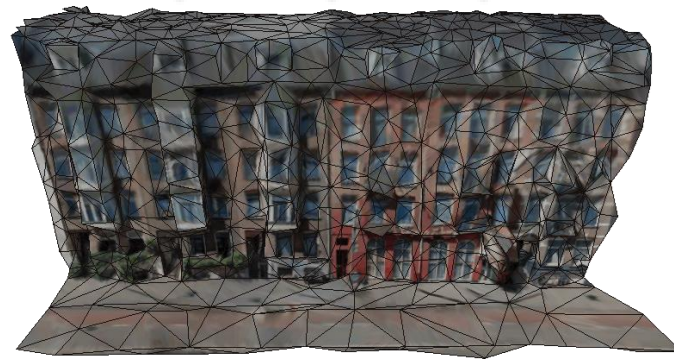
Link: <https://www.youtube.com/watch?v=OzVGzPi1Me0>

# Problem

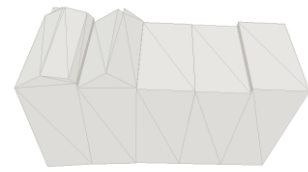
CityGML model



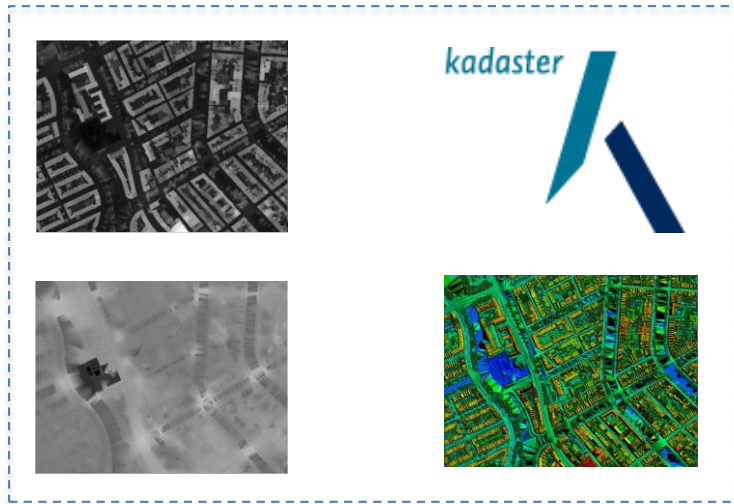
MVSM model



# CityGML model



Creation:



Source: Biljecki et al. (2016)

Characteristics:

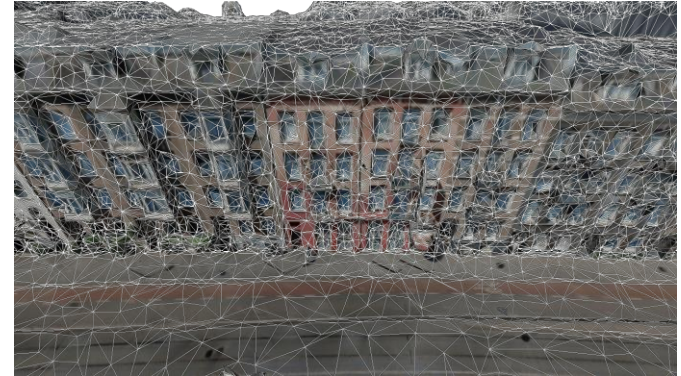
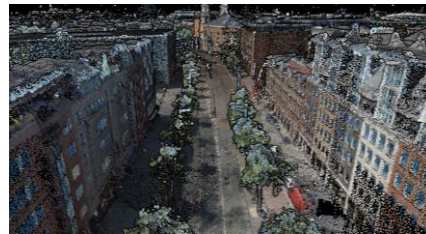
- Rich in semantics (e.g. roof, wall, ground)
- Semi-automatic construction
- Plain (not all geometric aspects)



# Multi – View Stereo Mesh model



Creation:



Characteristics:

- Fully automatic construction
- Plenty of geometric information
- Rich textures
- No semantics

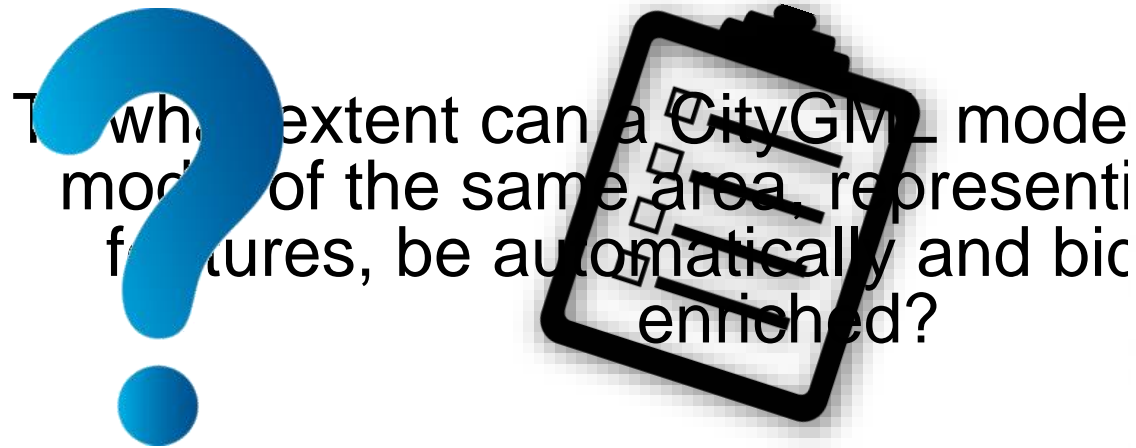
# CityGML vs MVSM models

<i>Standard\ Criteria</i>	<i>CityGML</i>	<i>MVSM</i>
<i>Geometry</i>	B-rep	Mesh
<i>Semantics</i>	Rich in semantics	No semantics
<i>LOD</i>	5 discrete LODs	Not supported
<i>Texture</i>	Basic support	Rich textures
<i>Construction</i>	Semi-automatic	Fully automatic

Source: Kavisha and Saran (2015)

# Research objectives

To what extent can a CityGML model and a MVSM model of the same area, representing the same features, be automatically and bidirectionally enriched?



Bidirectional  
enrichment

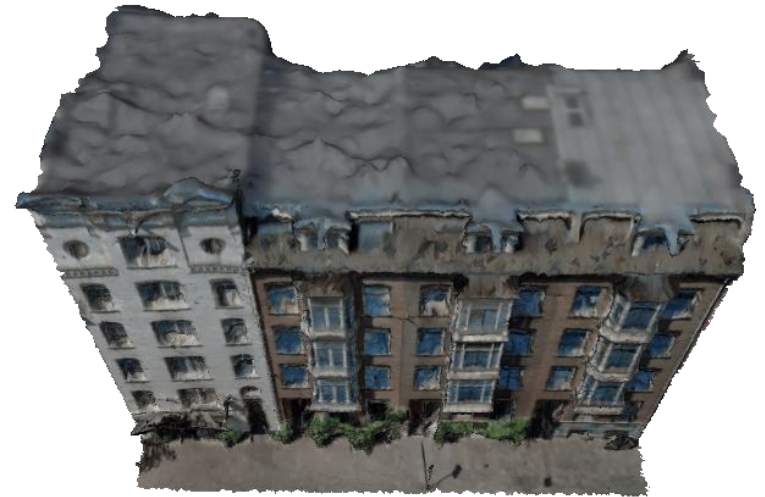
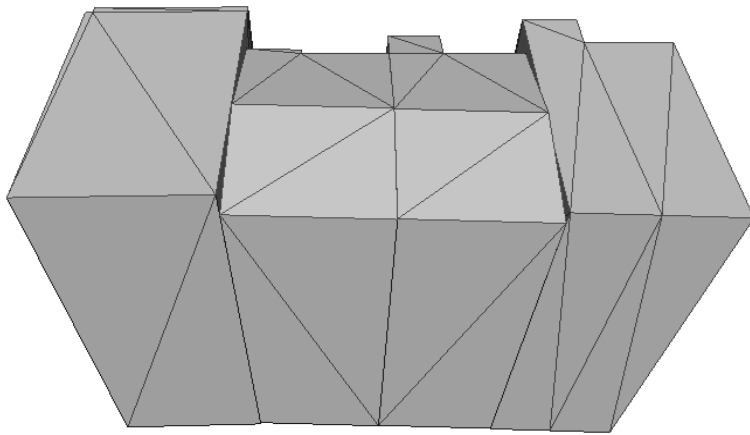
Bidirectional  
enrichments  
between models



Bidirectional  
enrichment  
methodologies

# Research objectives

To what extent can a CityGML model and a MVSM model of the same area, representing the same features, be automatically and bidirectionally enriched?



Match faces

Semantic  
segmentation

Transfer  
attributes

Segment  
per building

# Research objectives

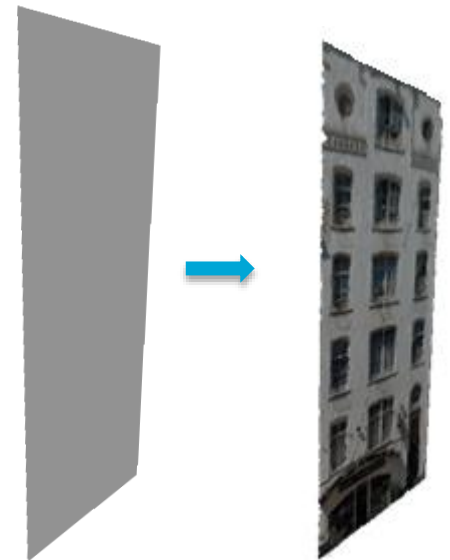
To what extent can a CityGML model and a MVSM model of the same area, representing the same features, be automatically and bidirectionally enriched?



Validation of  
the matching



Detection  
of errors



Texturing

# Related work

- Interoperability of information
- Straightening of meshes
- Semantic enrichment of 3D models
- Matching of meshes
- Mesh comparison

# Related work

- Straightening of meshes
- Interoperability of information
- Semantic enrichment of 3D models
- Matching of meshes
- Mesh comparison

*Veltkamp  
(2001)*

*Ericson  
(2004)*

*Eberly  
(2006)*

*Guezlec  
(2001)*

Point-to-polygonal-mesh  
distance

Hausdorff distance

# Outline

1. Background & Research objectives
- 2. Bidirectional enrichment**
3. Proposed methodology & Analysis
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# Bidirectional enrichment





# Enrichments



- **Semantic segmentation**
- **Transfer attributes**
- Straightening
- Simplification

- **Texturing**
- **Validation**
- Update
- Creation of 3D CityGML model



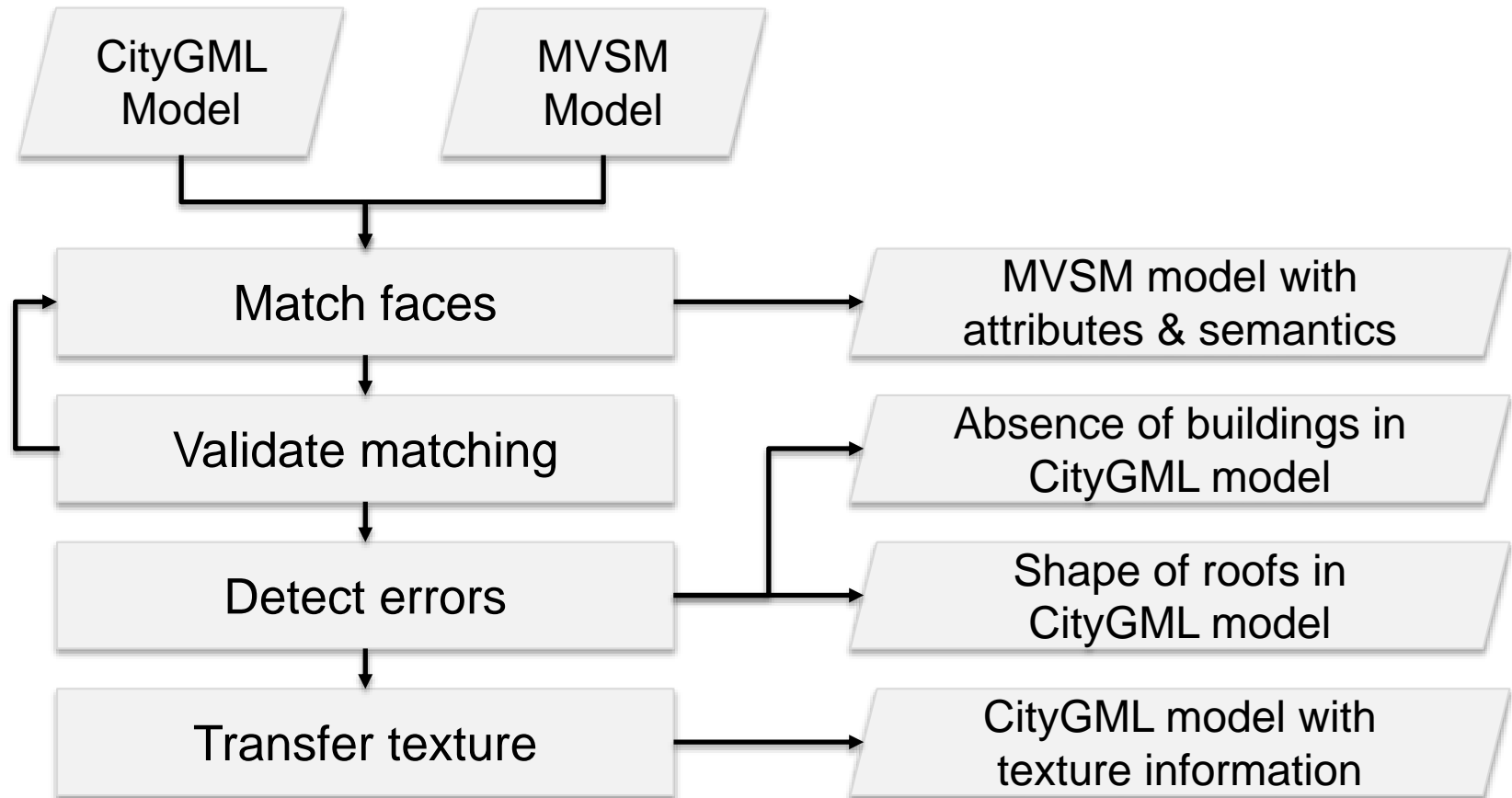
# Enrichment methodologies

- Creation and comparison of planes
- Probabilistic methods
- Predefined shapes of features
- Template matching techniques
- Machine learning techniques
- Clustering techniques
- **Heuristic rules**
- **Distance computation methods**

# Outline

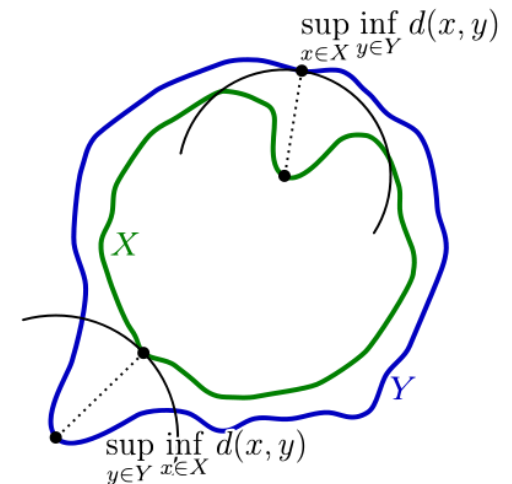
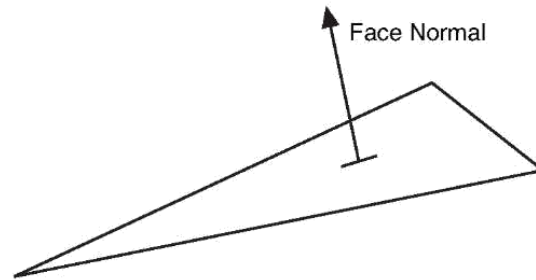
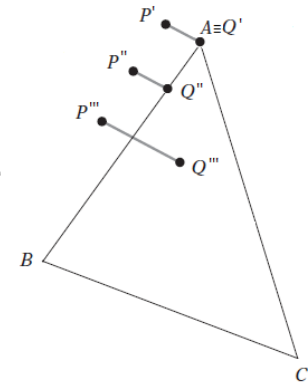
1. Background & Research objectives
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# Proposed methodology



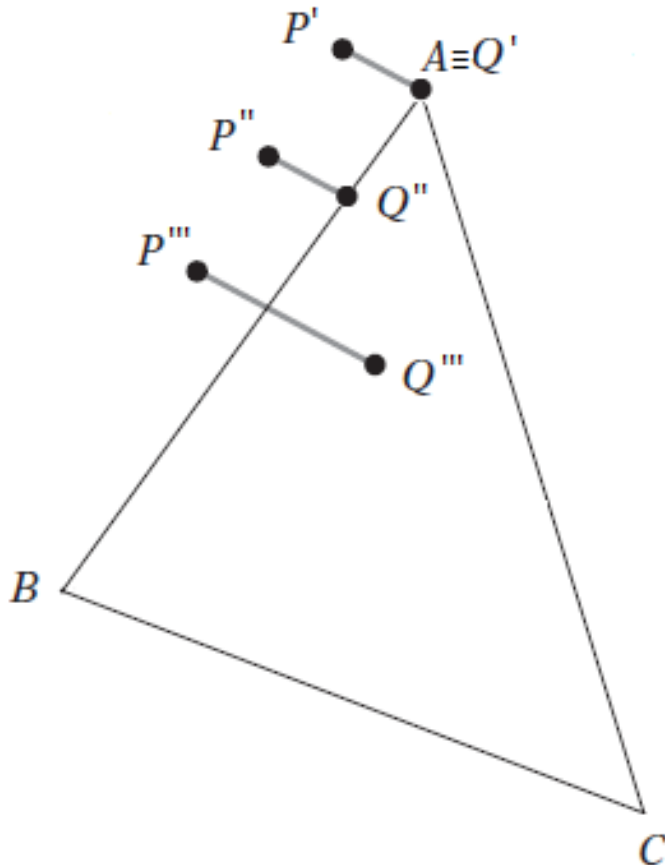
# Proposed methodology

- Use point-to-polygonal-mesh distance
- Use Hausdorff distance
- Compute the normals of the triangles
- Create heuristic rules

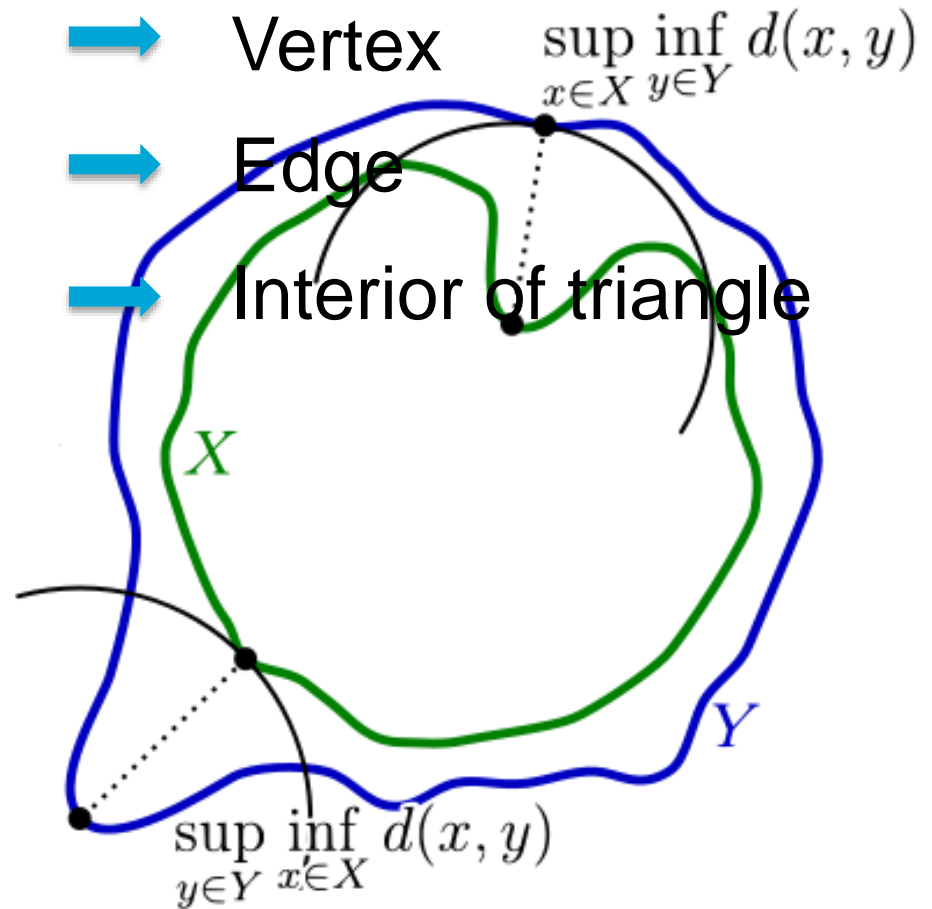


# Proposed methodology

Point to polygonal mesh distance:



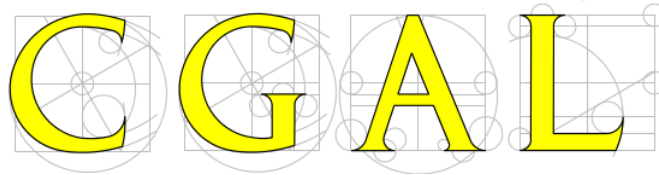
Hausdorff distance:



# Tools

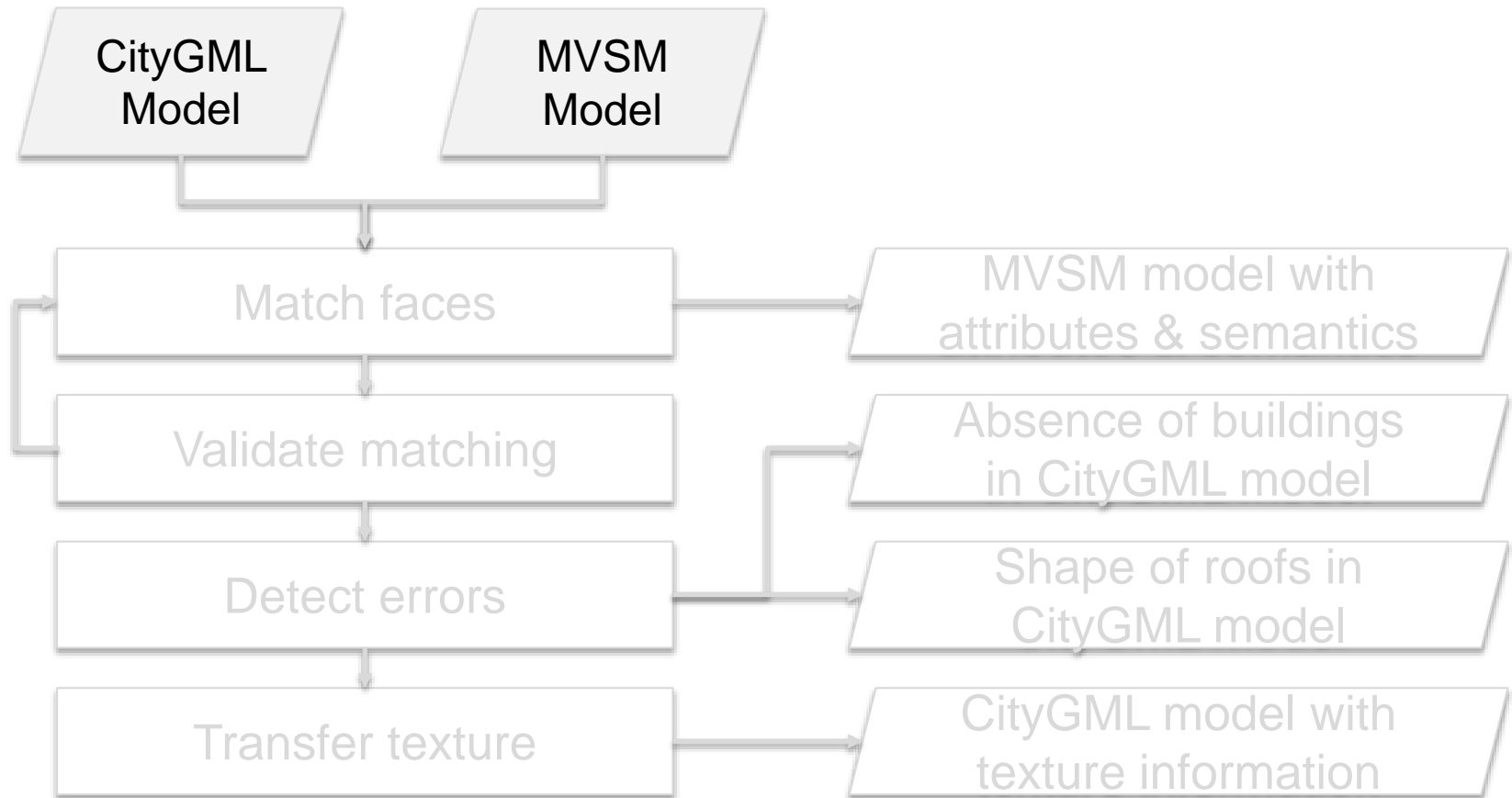


L<sup>A</sup>T<sub>E</sub>X





# Proposed methodology



# Data



655 buildings



$\approx 720000.000 \text{ m}^2$



Same CRS

CityGML model:



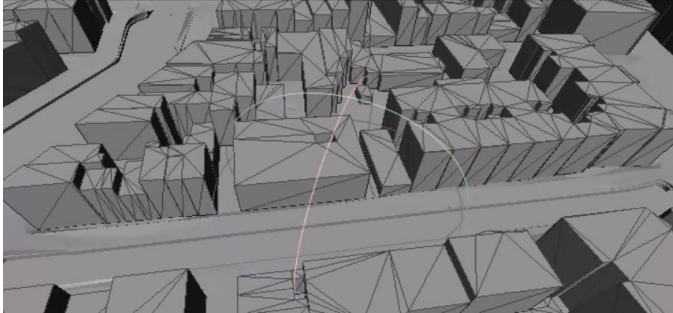
$< 1$  point per  $\text{m}^2$

MVSM model:

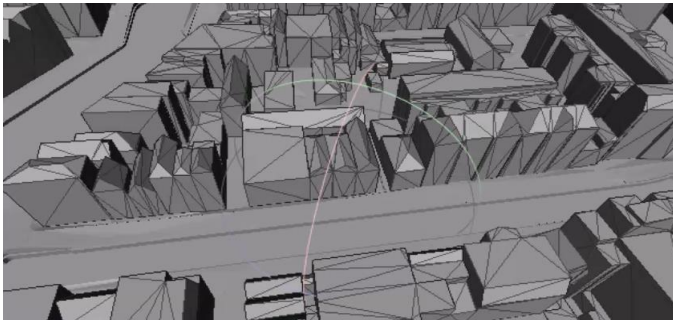


$\approx 60$  points per  $\text{m}^2$

# Data



.xml  
file format



LOD2 virtualcitySYSTEMS

.dae  
COLLADA  
file format



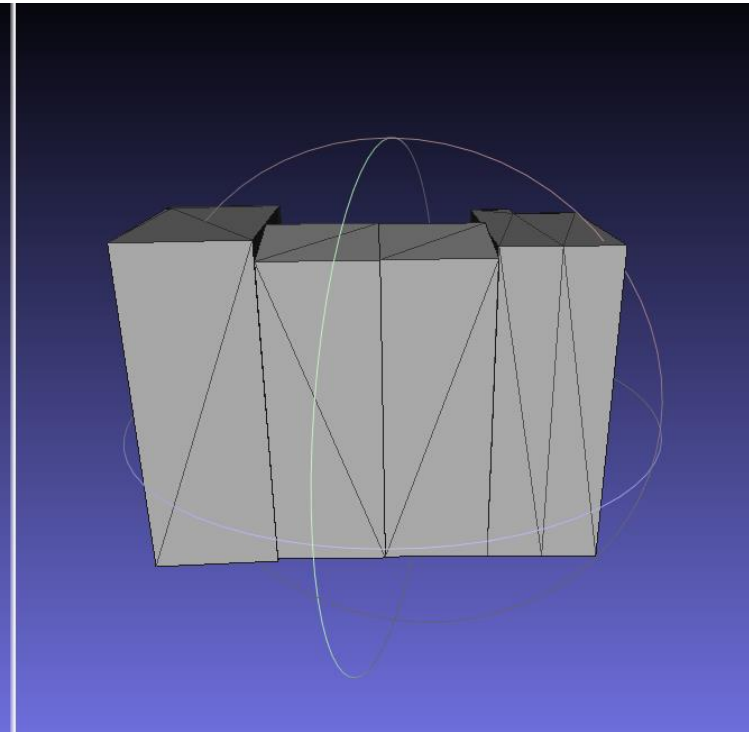
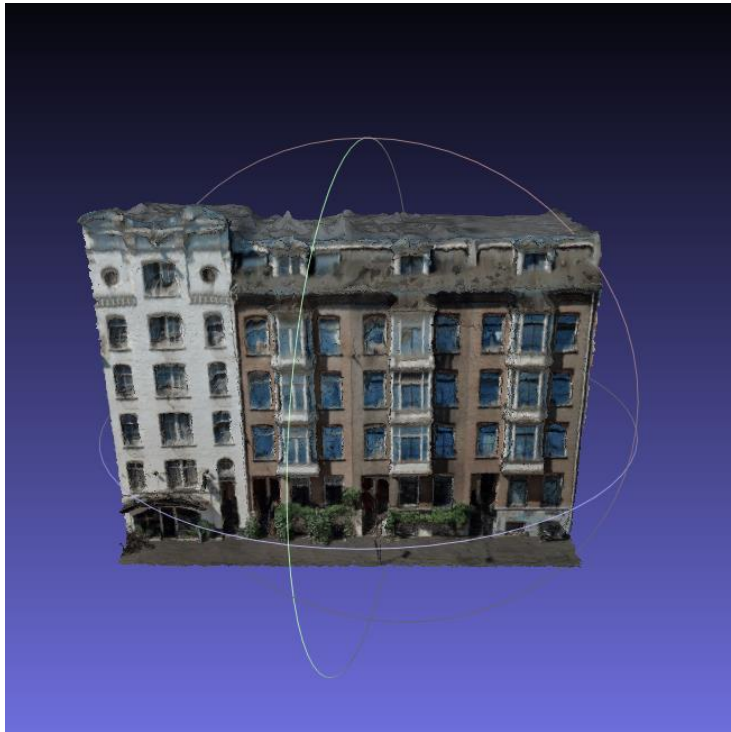
# 1<sup>st</sup> Implementation

# Testing dataset

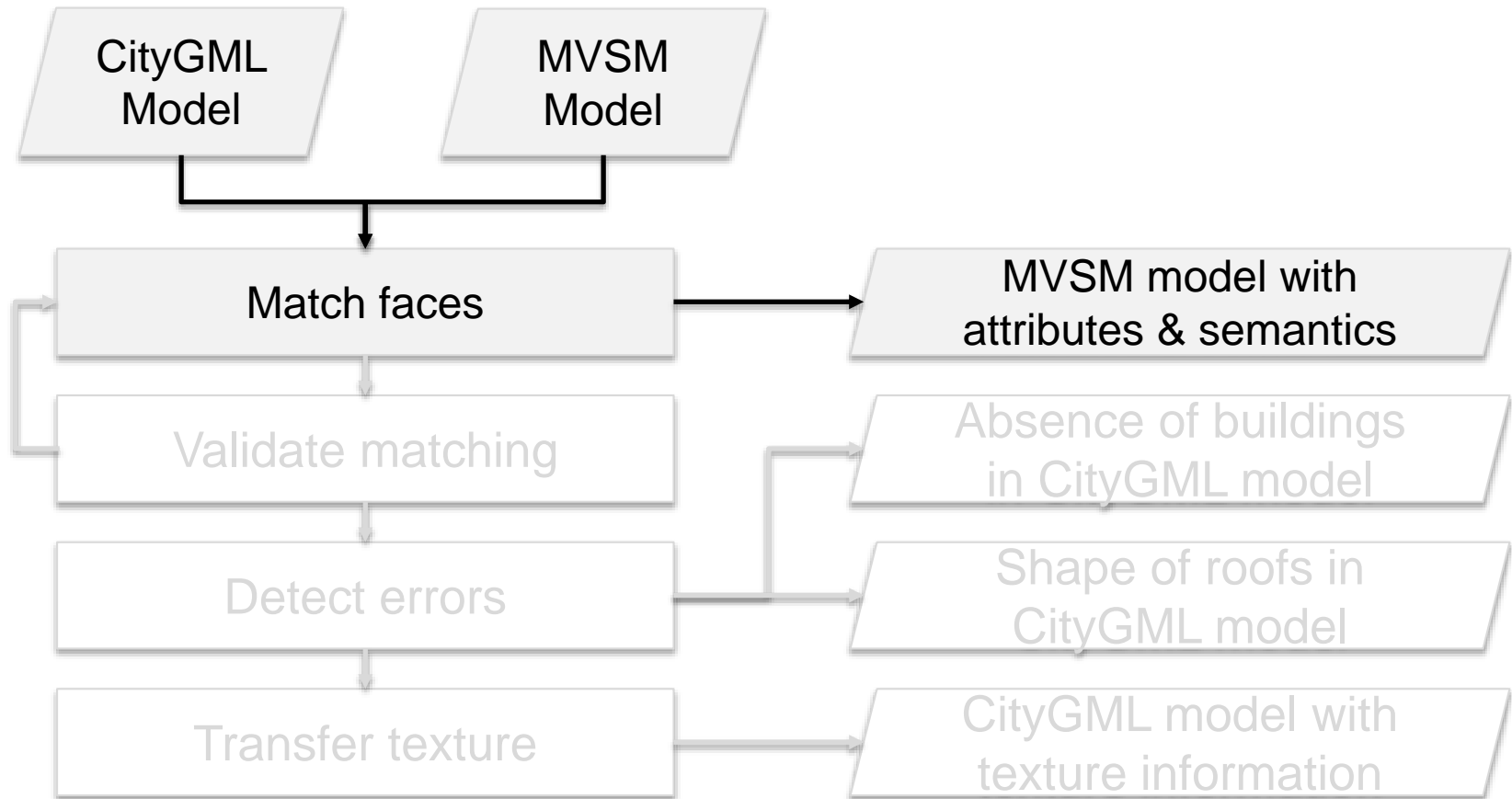
1<sup>st</sup> Implementation  
4 buildings

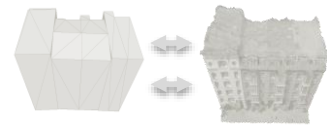


$\approx 1222.406m^2$

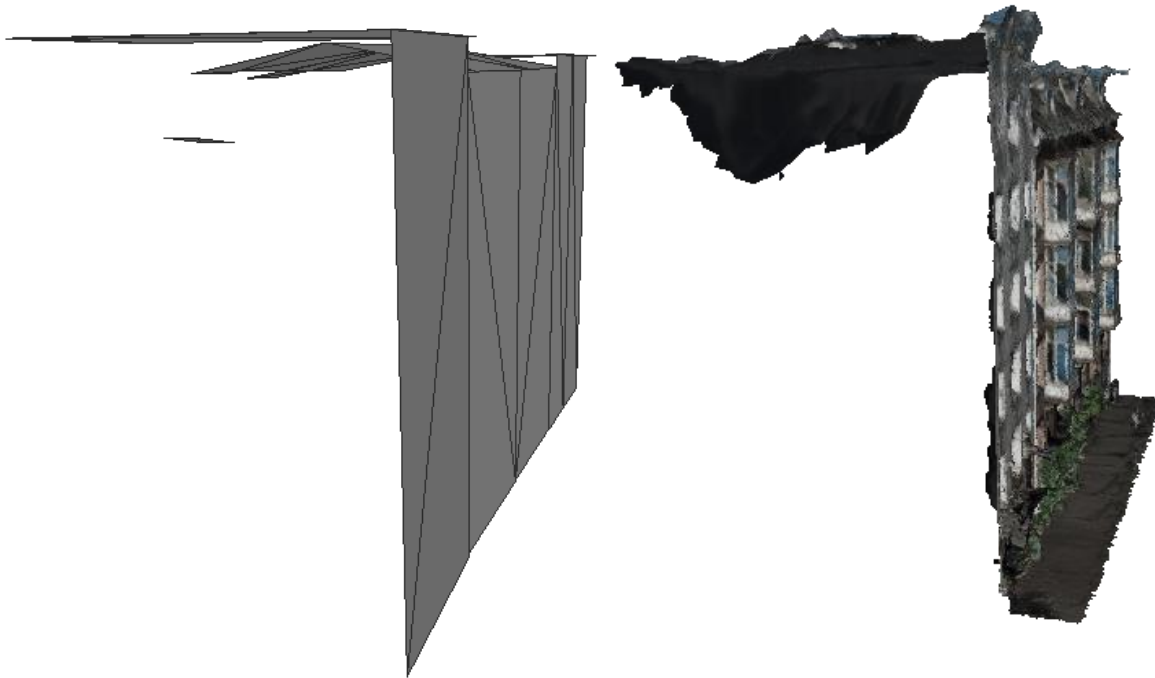


# Proposed methodology





# Match faces



Roof



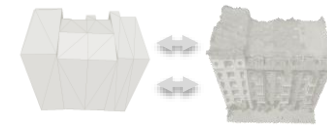
Wall



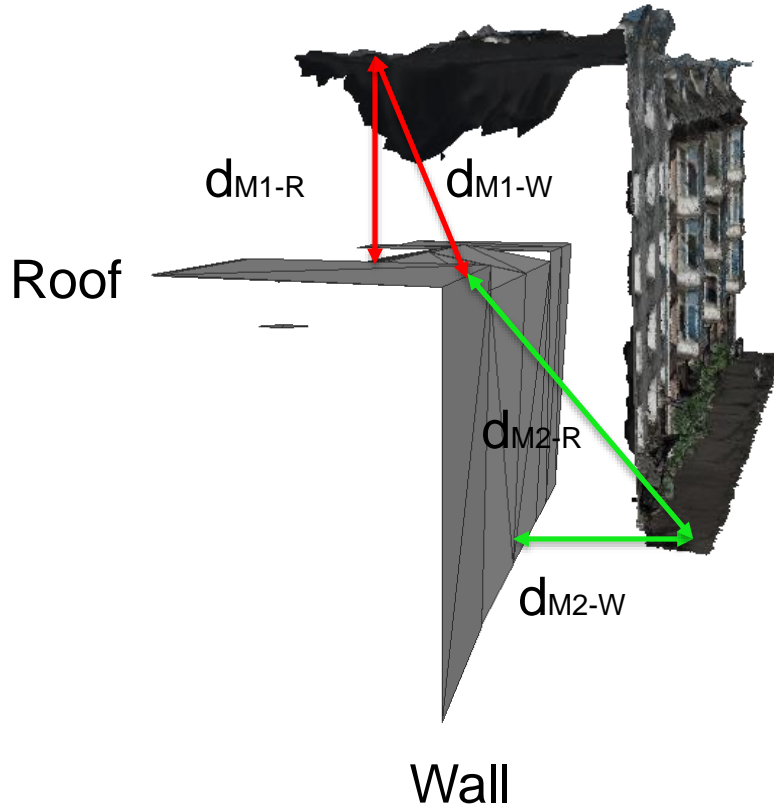
Uncertain



3 Heuristic Rules (HR)

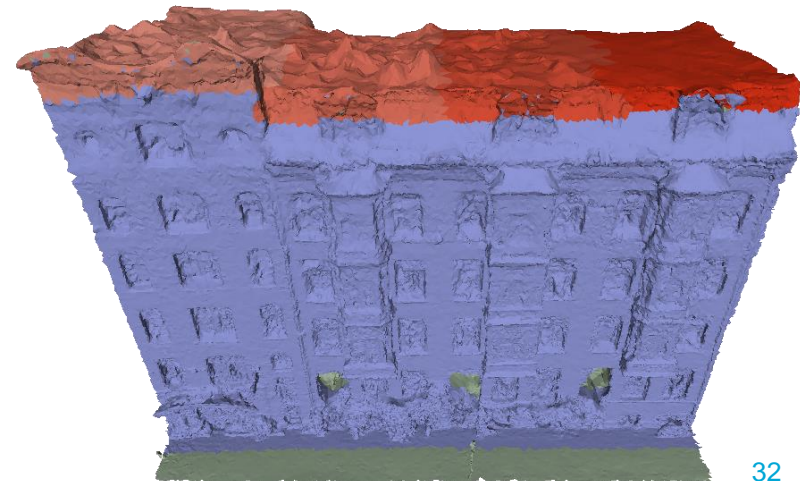


# Match faces

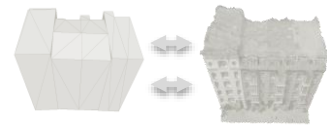


HR 1: Closer to roof,  
then **roof**.

HR 2: Closer to wall and  
larger than  $T_d$ ,  
then **uncertain**.

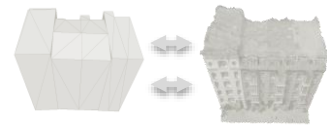






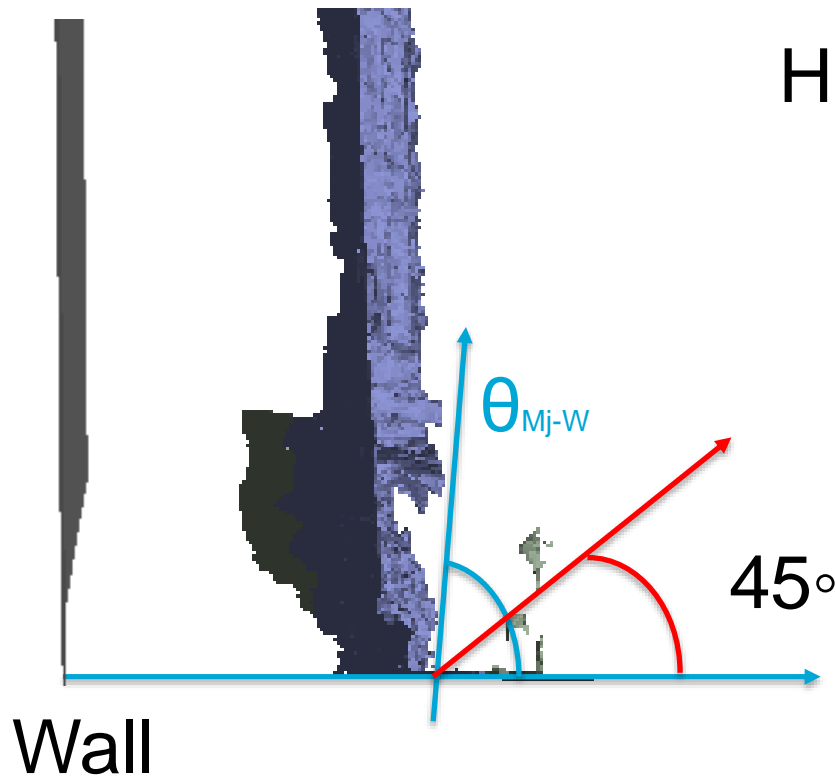
# Match faces



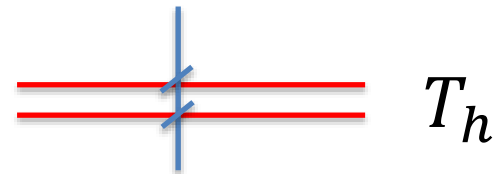


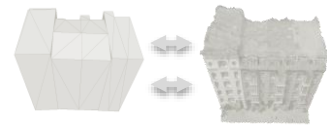
# Match faces

Vertical sections:

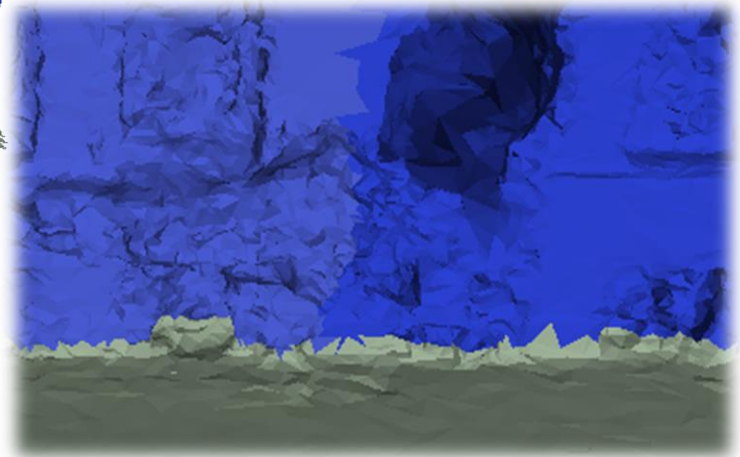
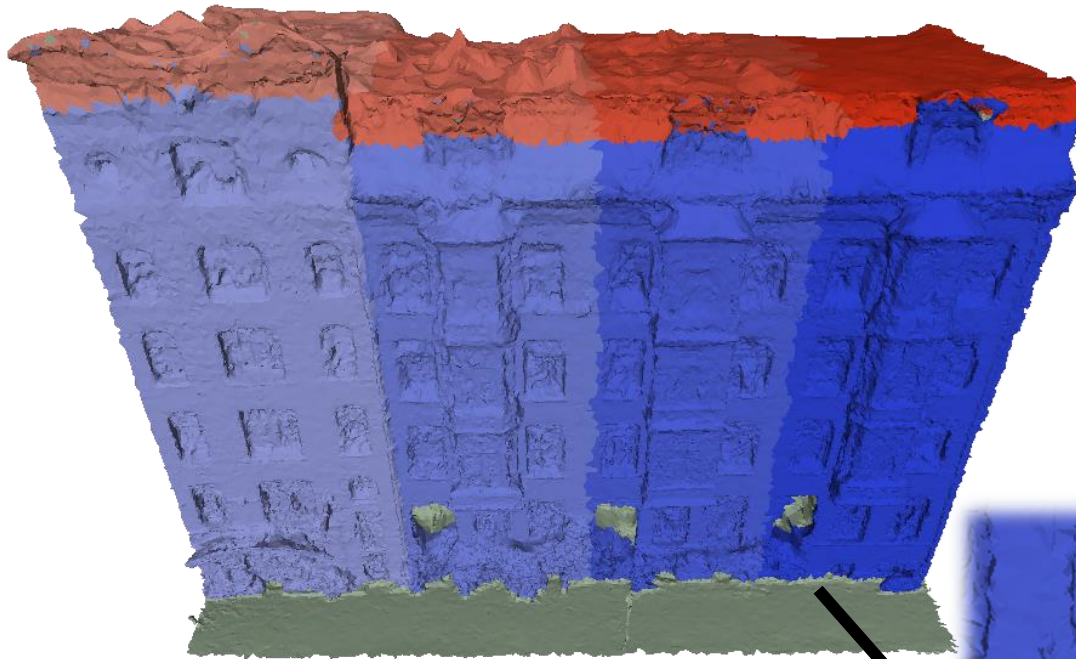


HR 3:  $h_{Mj} < h_{min} + T_h$   
and  
 $\theta_{Mj-W} > 45^\circ$ ,  
then **uncertain**.

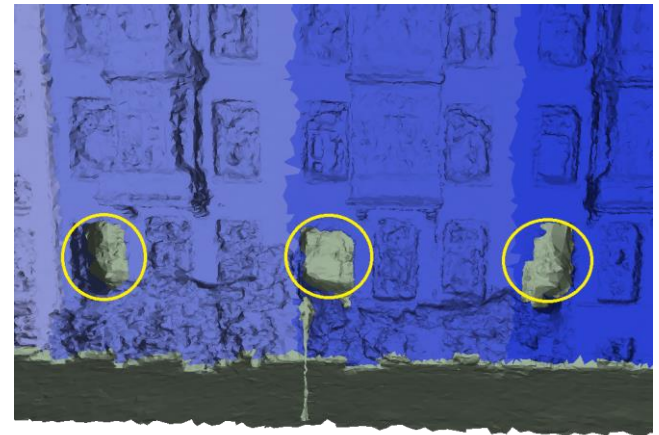
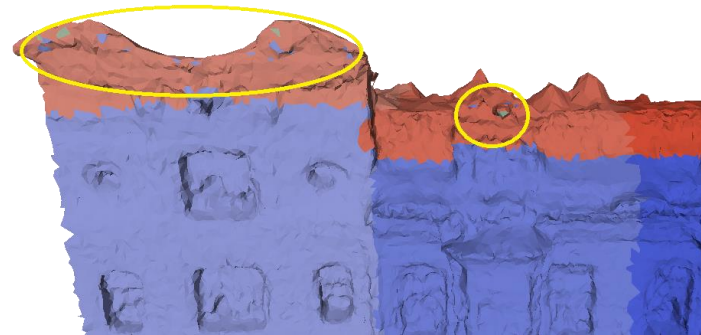
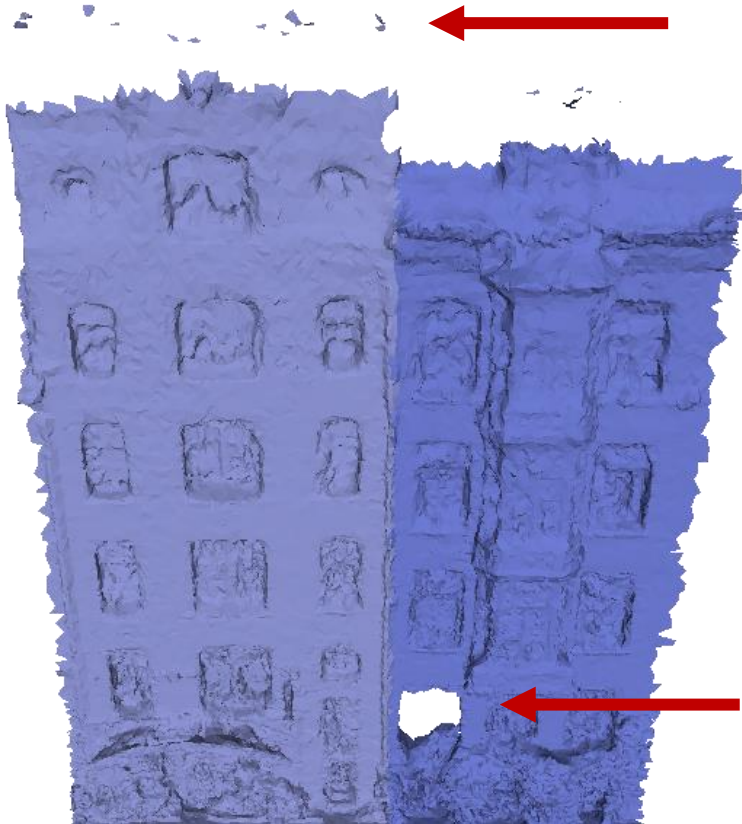




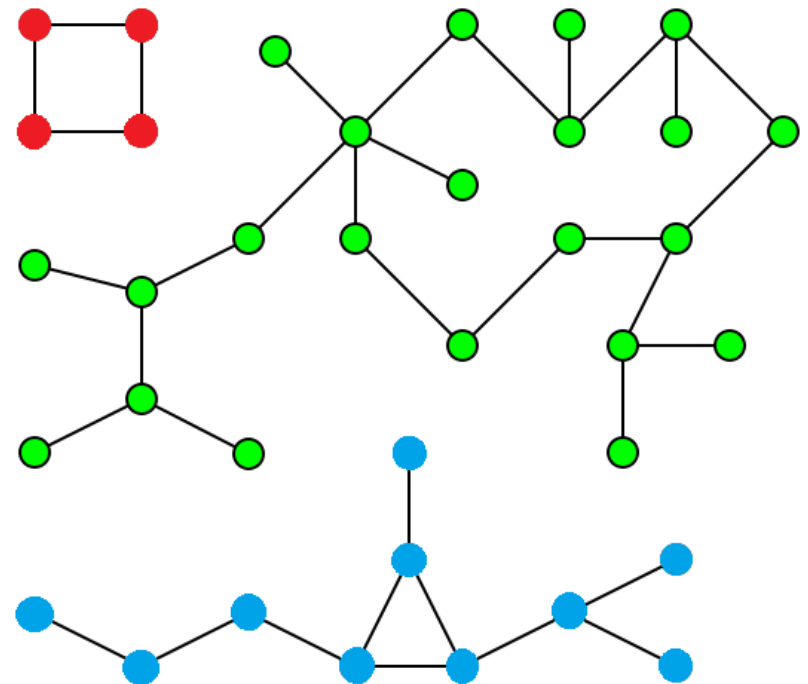
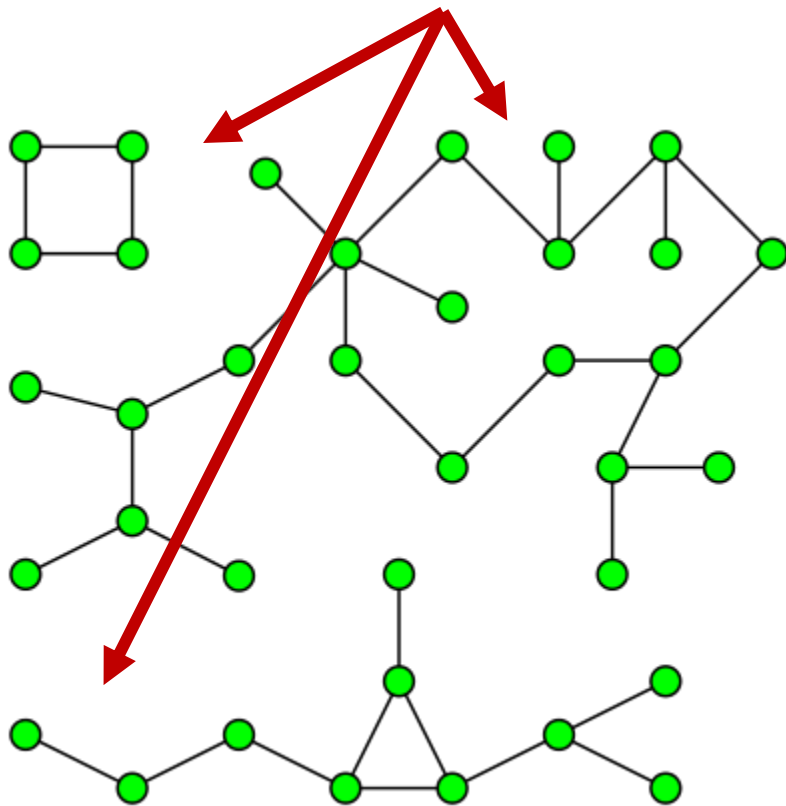
# Match faces



# Connected components

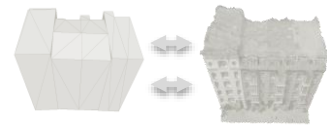


# Connected components

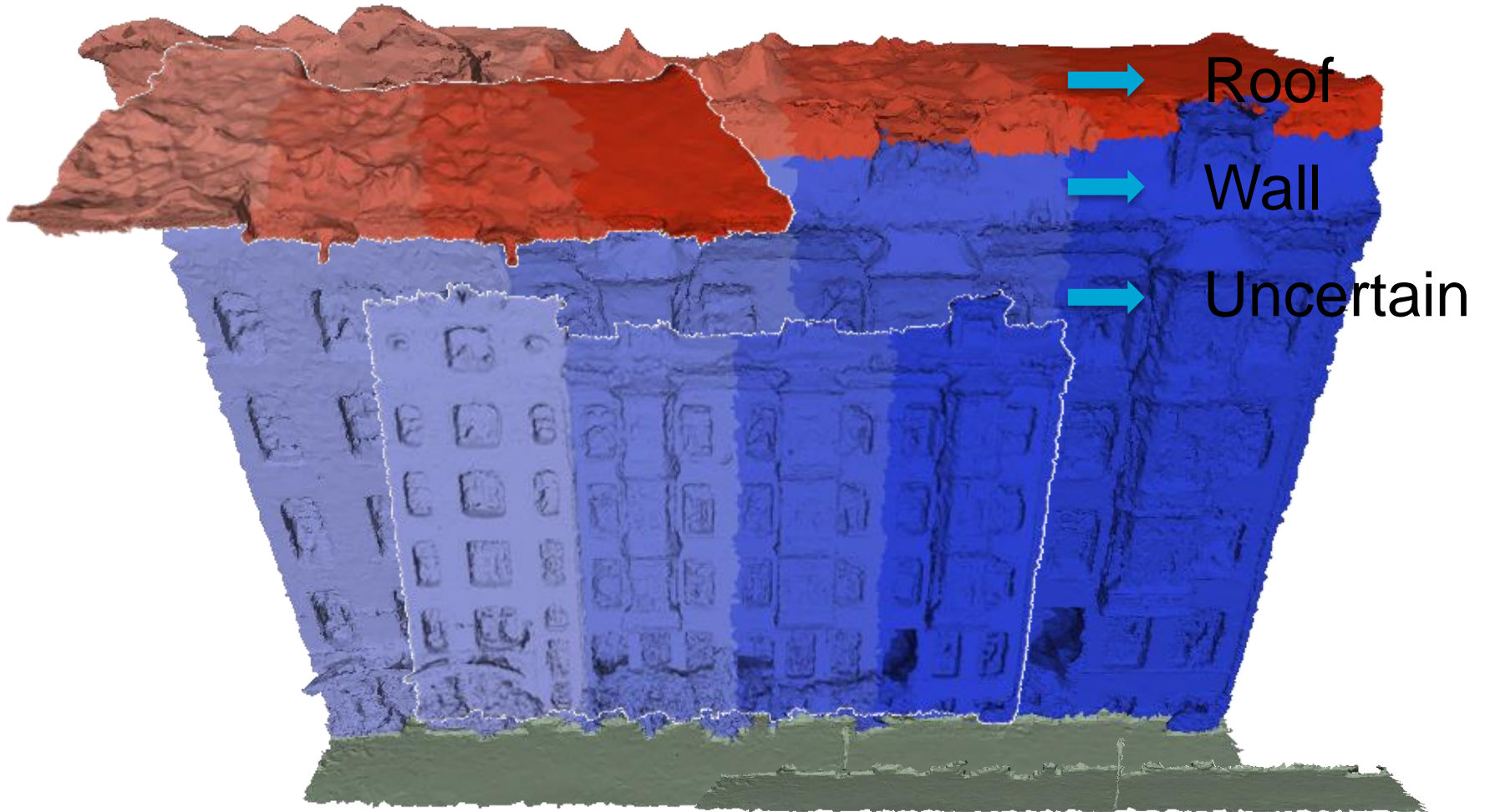


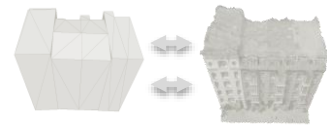
Source: <https://breakingcode.wordpress.com>





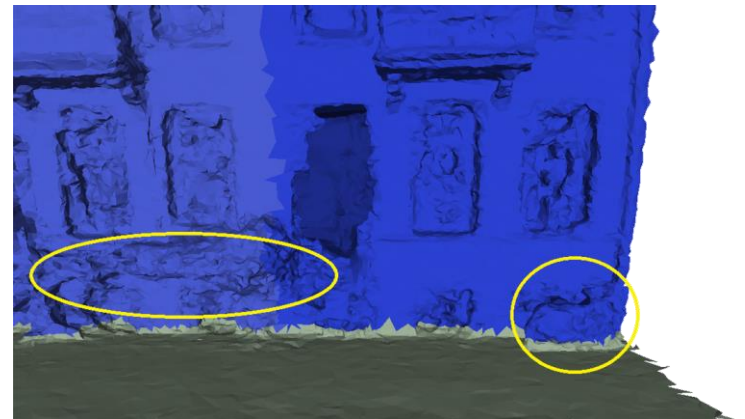
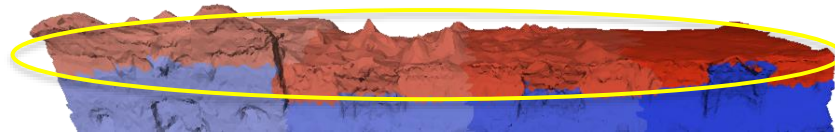
# Match faces



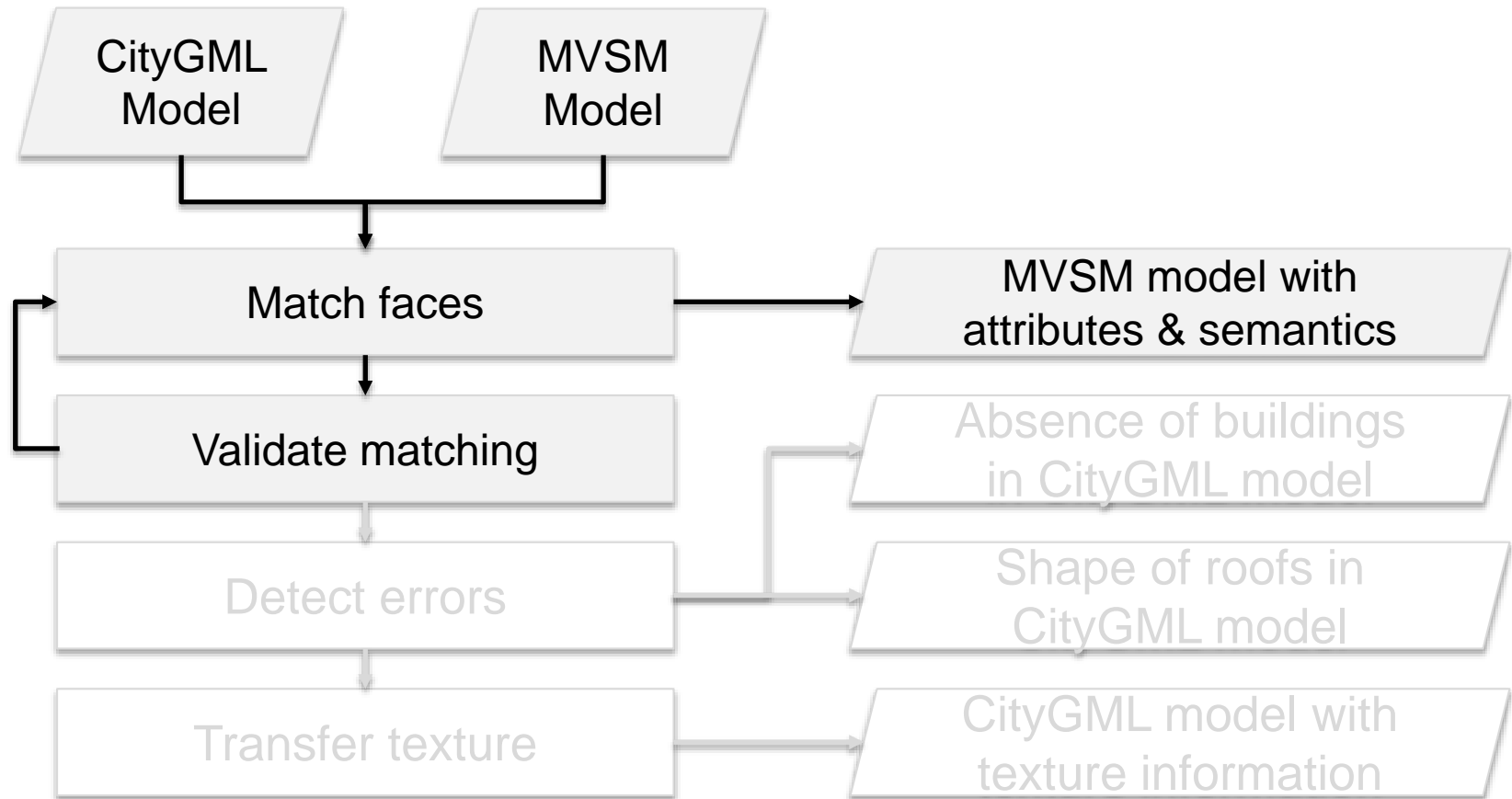


# Match faces

- Roof class contains parts of the wall class
- Wall class contains parts of the uncertain



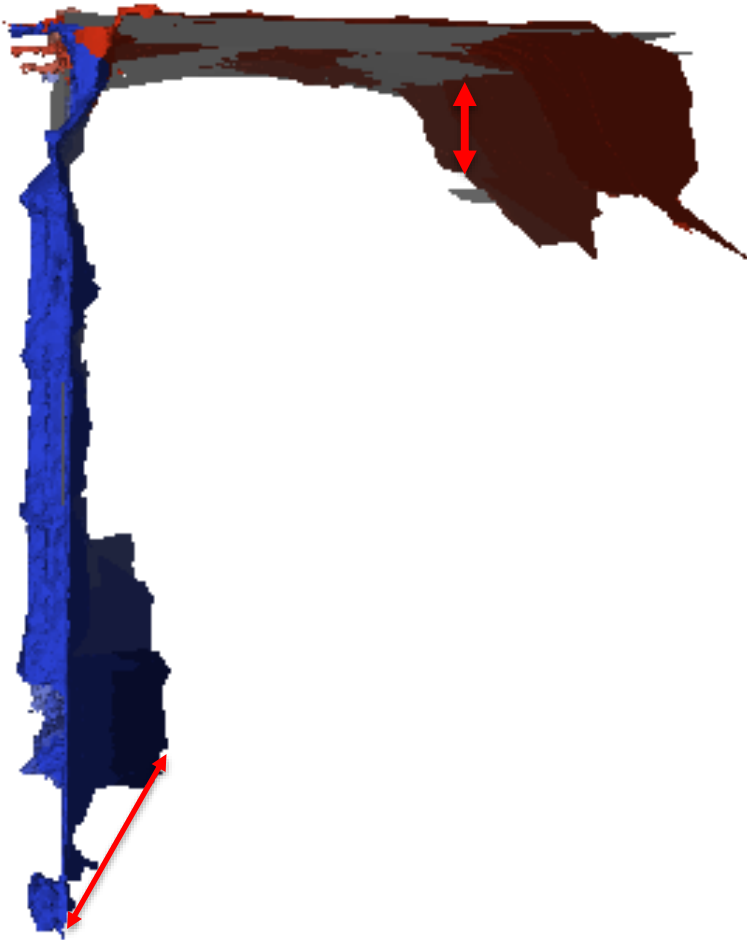
# Proposed methodology







# Validate matching



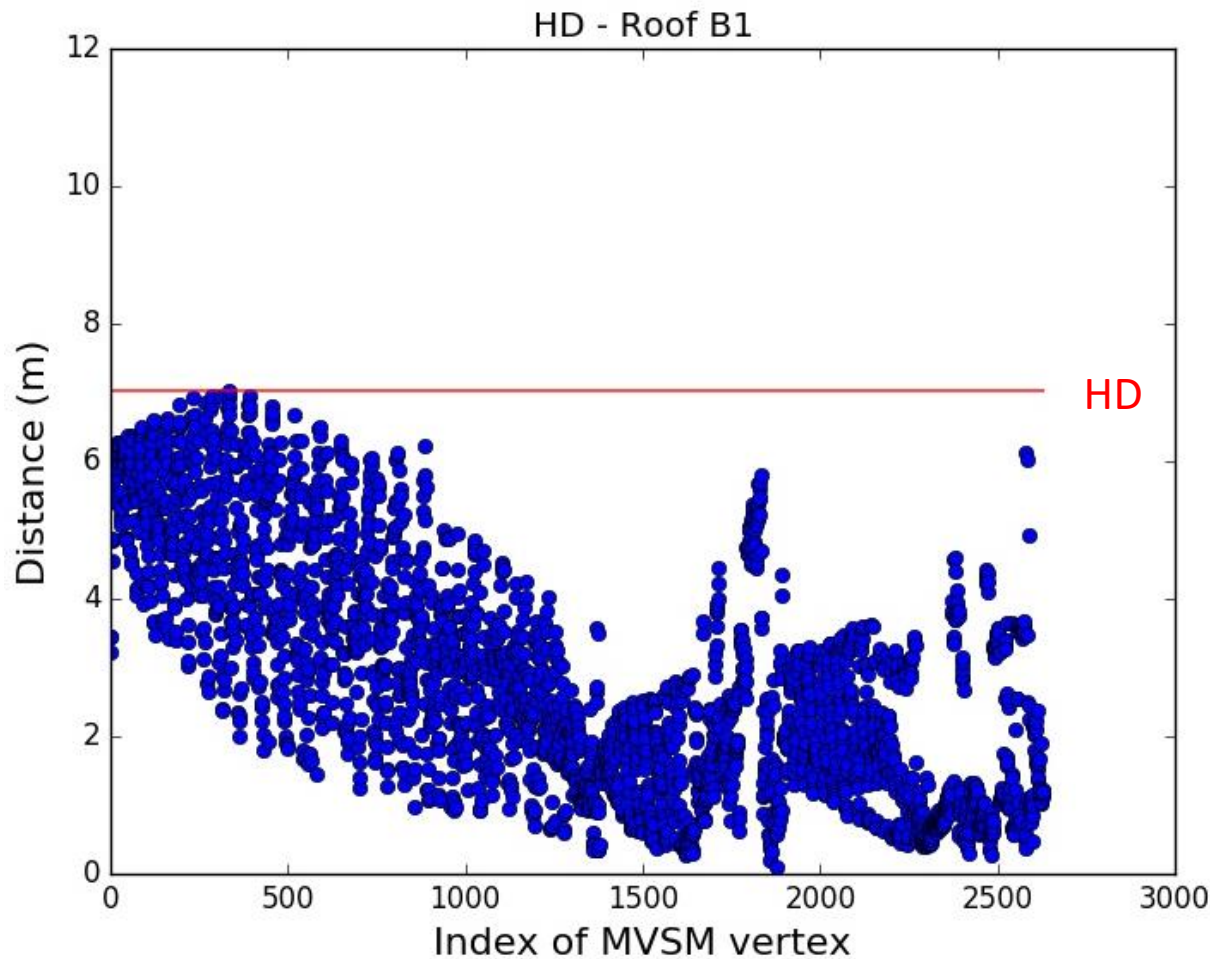
Category	Interval of HD
Excellent	0m – 5m
Good	5m – 8m
Medium	8m – 11m
Bad	> 11m

→  $T_d$  (HR 2)

→  $T_h$  (HR 3)

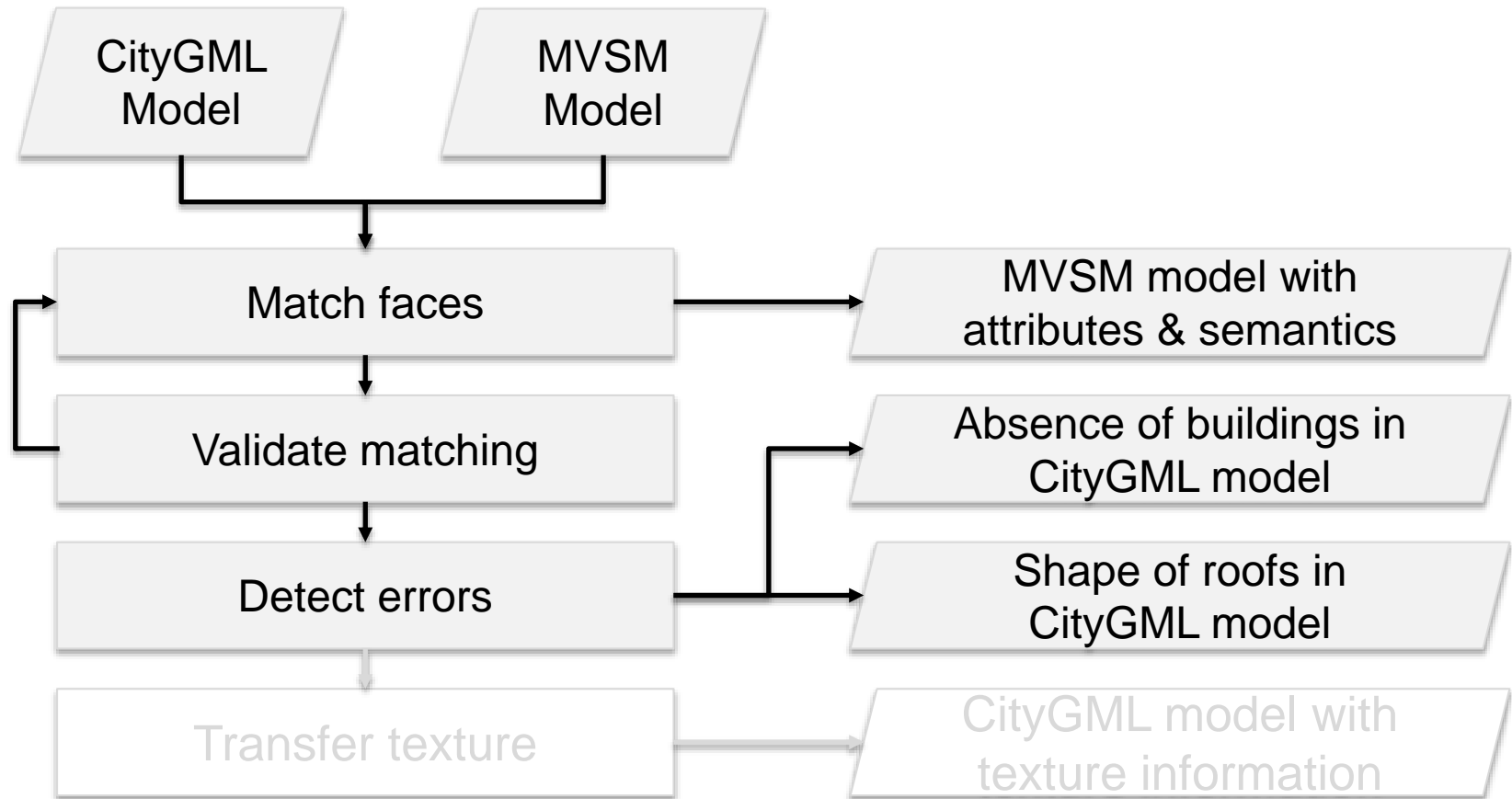


# Validate matching



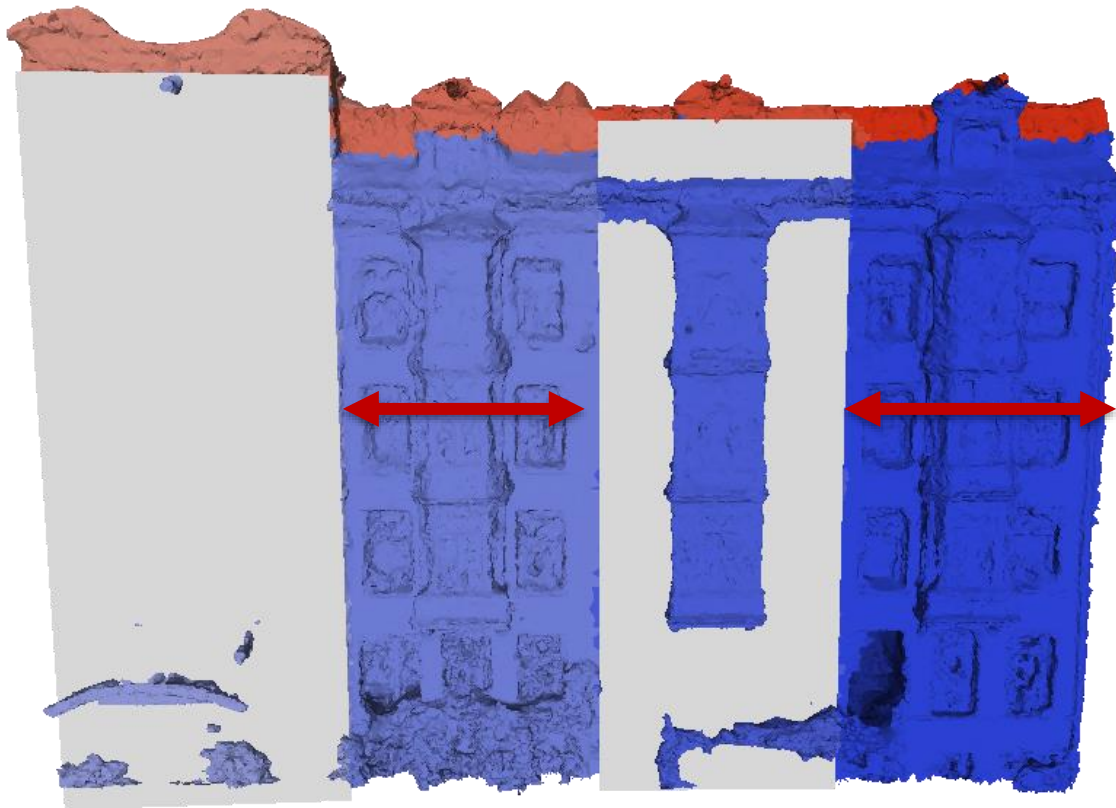
→ Good

# Proposed methodology





# Detect errors

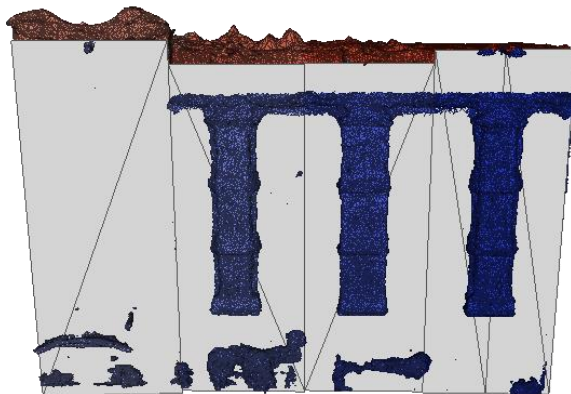




# Detect errors

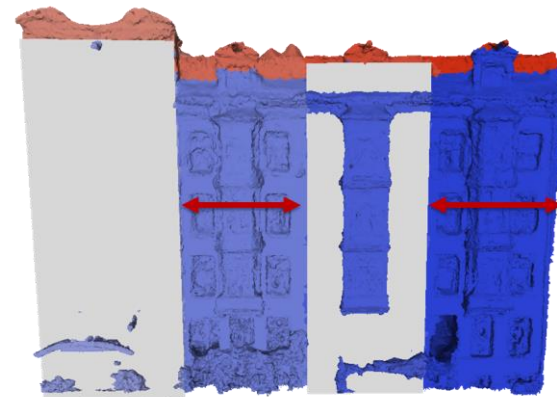
All buildings:

Building	HD (m)	Absence
B1	10.209	No
B2	9.527	No
B3	9.458	No
B4	9.399	No

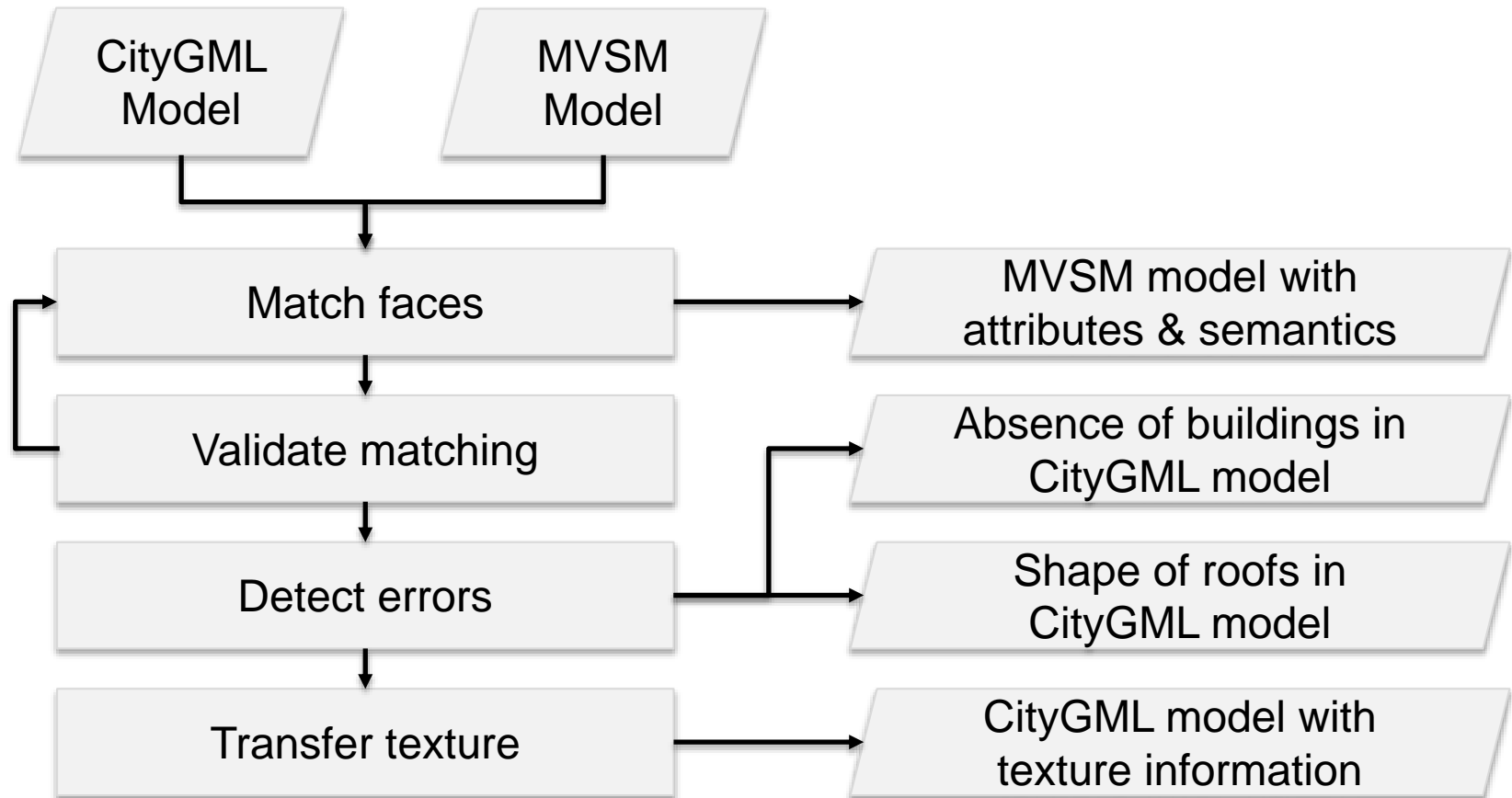


B2 and B4 are missing:

Building	HD (m)	Absence
<b>B1</b>	10.209	No
<b>B2</b>	<b>11.549</b>	<b>Yes</b>
<b>B3</b>	9.458	No
<b>B4</b>	<b>11.048</b>	<b>Yes</b>

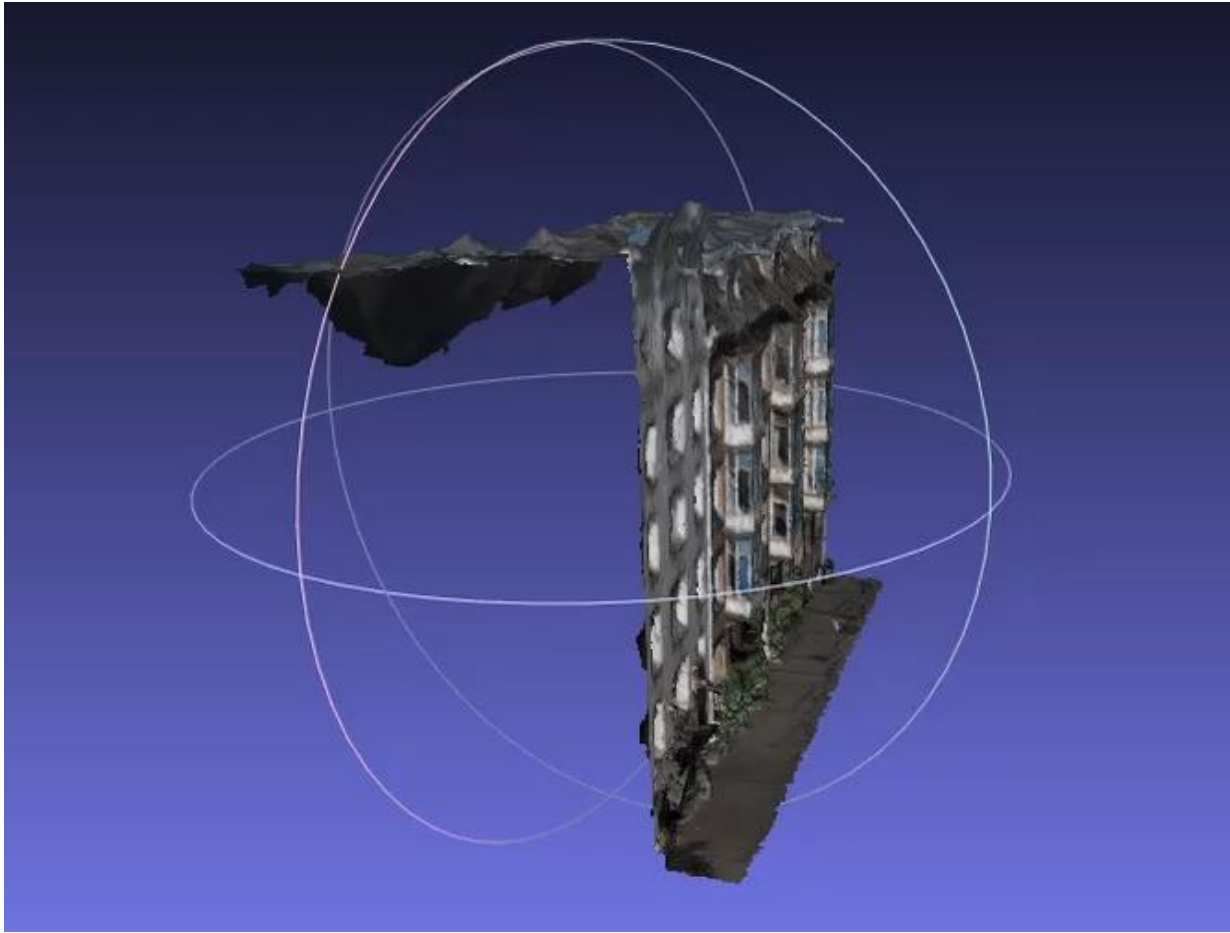


# Proposed methodology



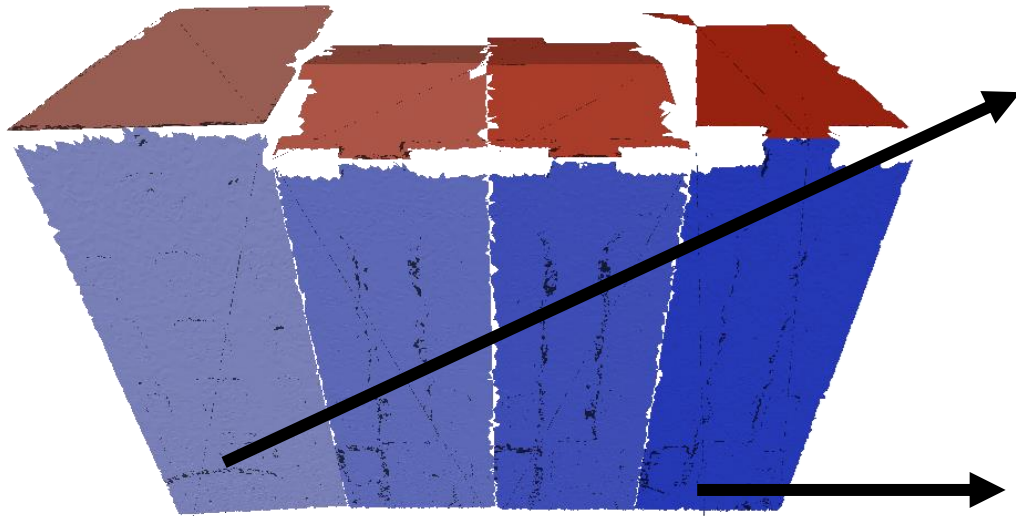


# Transfer texture





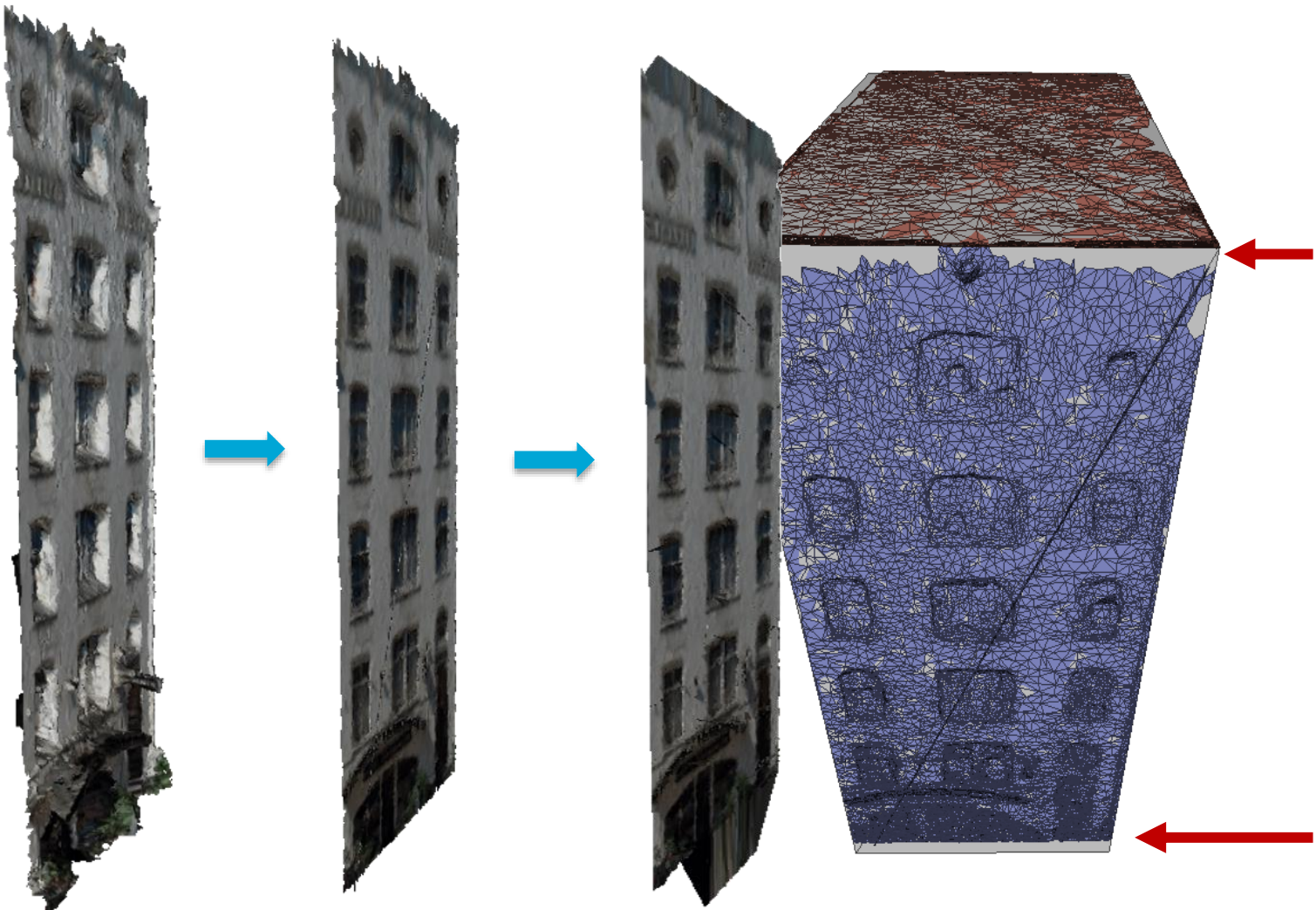
# Transfer texture







# Transfer texture





# Transfer texture

- Stretch to the corners of the boundary lines
- Close the holes of the MVSM model



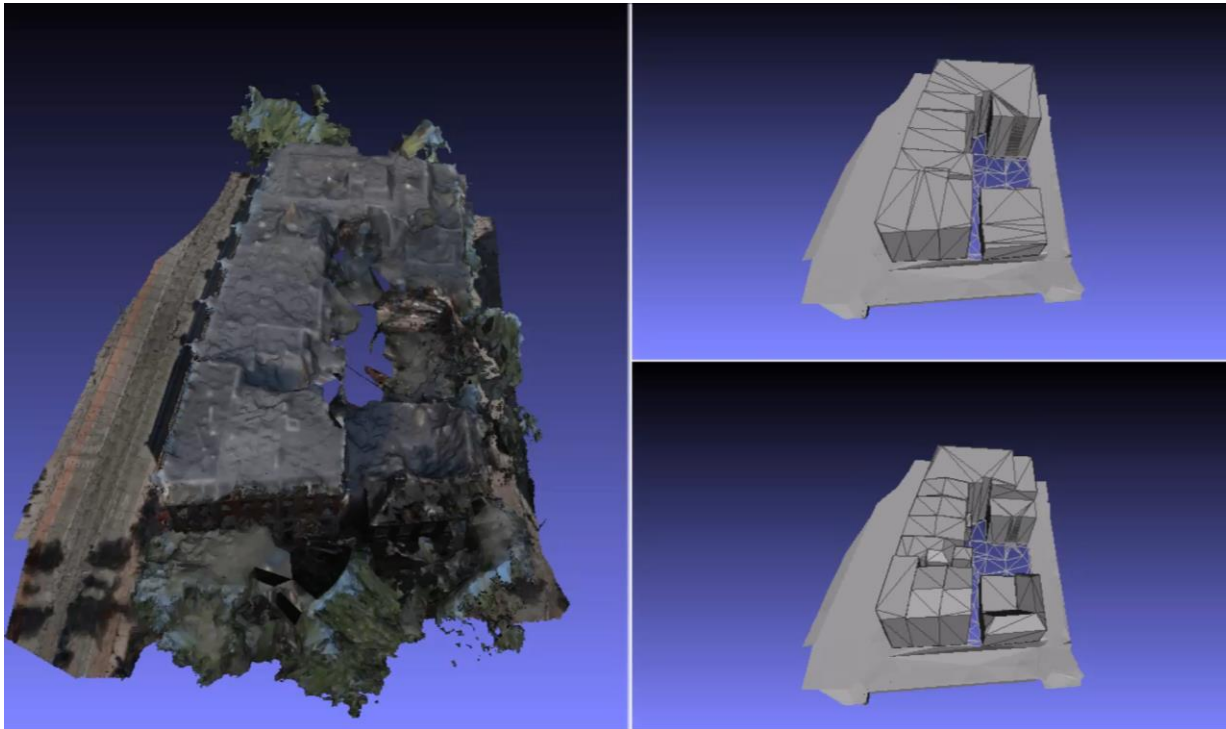
# 2<sup>nd</sup> Implementation

# Testing dataset

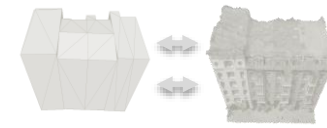
2<sup>nd</sup> Implementation  
Building block



$\approx 14247.427m^2$

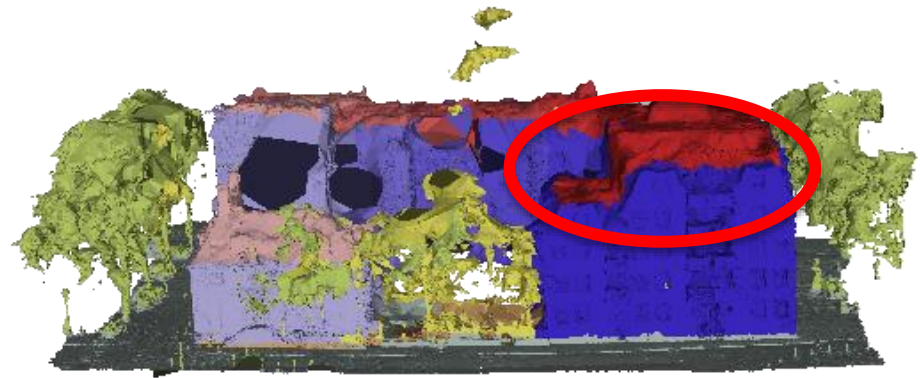
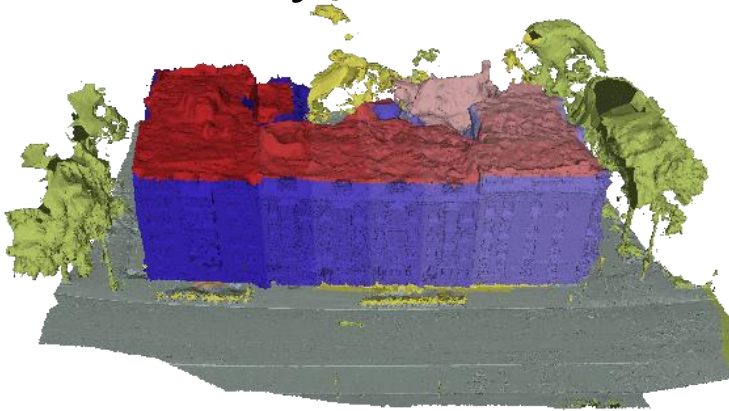




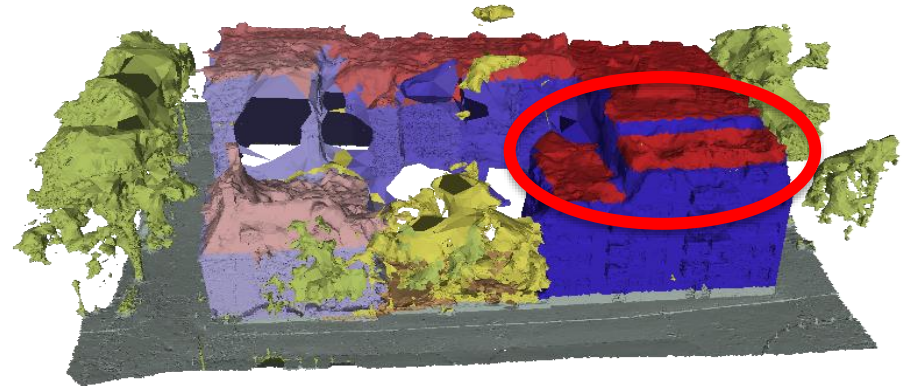
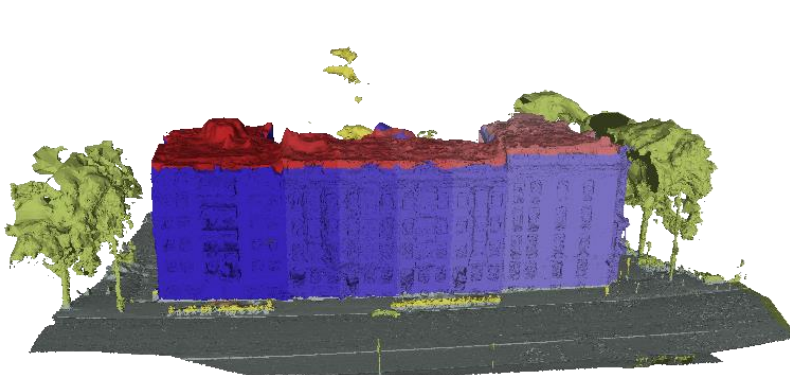


# Matching faces

LOD1 CityGML and MVSM models:  Bad



LOD2 CityGML and MVSM models:  Good





# Detect errors





# Transfer texture

LOD1 CityGML and MVSM models:



LOD2 CityGML and MVSM models:



# Outline

1. Background & Research objectives
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3. Proposed methodology & Analysis
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# Conclusions

To what extent can a CityGML model and a MVSM model of the same area, representing the same features, be automatically and bidirectionally enriched?

- ✓ Bidirectional enrichment
  - ✓ Bidirectional enrichments between models
  - ✓ Bidirectional enrichment methodologies
  - ✓ Match faces
  - ✓ Semantic segmentation
  - ✓ Transfer attributes
  - ✓ Segment per building
  - ✓ Validation of the matching
  - ✓ Detection of errors
  - ✓ Texturing
- LOD1 vs LOD2:
- ✓ Roof structures

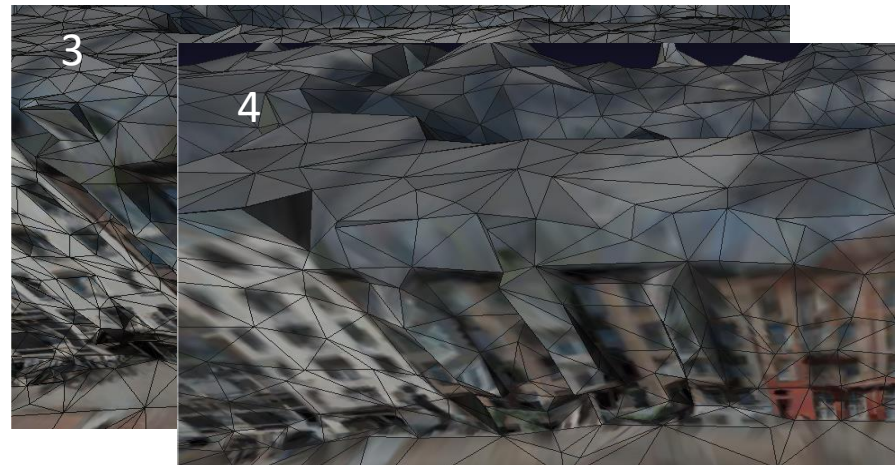
# Future work

- Extend the table of the enrichments.
- Explore practically more enrichment methodologies.
- Improve the proposed methodology.
- Extend the proposed methodology to other thematic classes e.g.vegetation, water bodies
- Fix the errors in the MVSM model e.g.holes



# Future work and recommendations

- Test with LOD3 CityGML model
- Test with smoother and simplified MVSM models
- Test in different building types (more complex)
- Reduce the execution time





virtualcitySYSTEMS

Thank you for your  
attention!

CityGML

