In colaboration with:



WET CLEANING FUNCTION FOR ROBOT VACUUM CLEANERS

by: Fermin Espin Franco

APPENDICES

Master Thesis

Wet Cleaning Function for Robot Vacuum Cleaners

APPENDICES

Disclaimer

This master thesis is written in context of the master Integrated Product Design at the faculty of Industrial Design Engineering at the Delft University of Technology in The Netherlands.

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I.I Comments & Ratings

COMMENT MODEL the pads are quite expensive+A2:A109 Braava Jet240 Mopping pad replacements are expensive Braava Jet240 Washable mopping pads are not included Braava Jet240 Exchangeable parts: rotational brush or accessory to just vaccum long hairs Ecovacs Deebot M81Pro plenty of features fro the money you pay Ecovacs Deebot M81Pro it comes with a lot of accessories Moneual ME685 it comes with some replacements which is quite convenient Proscenic 790T WIFI batteries for the remote control are not included Proscenic 790T WIFI It can handle a large area of laminate floor Braava 390t It is good for basic cleaning jobs Braava 390t It only does a small room before you need to recharge Braava Jet240 good for small apartments Braava Jet240 It works well as a complement of a roomba or a previous cleaning Braava Jet240 each mopping pad last only for 20-25 square meters Braava Jet240 small coverage area Braava Jet240 The supplied virtual wall doesn't work verv well Haier T325 Pathfinder We use it in between hoovering to keep on top of dog hair Haier T325 Pathfinder does not support virtual wall technology Proscenic 790T WIFI A good choice for small space cleaning Roomba Scooba 450 Does a good job on small to medium sized rooms or room sections Roomba Scooba 450 You need sometime before You know how to properly divide your house with the virtual walls to get good results Roomba Scooba 450 When the battery runs fully empty (when trapped), the computer is locking down and makes the robot unusable. Neither re-charging nor on-off switching do cure these lock downs Haier T325 Pathfinder the battery is easy to take appart in case it has to be replace Proscenic 790T WIFI battery last for only 40 minutes Roomba Scooba 450 battery keep on breaking Roomba Scooba 450 built-in battery makes you have to change the whole unit if it breakes Roomba Scooba 450 It compacts the dit in the dustbin very well so it can vacuum for longer before the full dustbin message pops out Ecovacs Deebot M81Pro Emptying the container is easy enough. Ecovacs Deebot R95 MKII has a large dustbin Proscenic 790T WIFI Low maintenance Braava 390t It's really simple to prep, use, and clean up after Braava Jet240 easy to use Braava Jet240 easy setup Ecovacs Deebot M81Pro

Ecovacs Deebot M81Pro

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It does not reach every spot in the house because it does not make a map of the house I Life V5s Pro	It does not reach every spot in the house because it does not make a map of the house	l Life V5s Pro

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t does not have a charging dock Barave Int240 brave Int24	cannot change the room mid-cyclie	Roomba Scooba 450
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it comes back to the dock automatically for the service of the ser	it does not have a charging dock	Braava Jet240
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	You can adjust the amount of water it sprays using the associated bluetooth control via the iPhone app	Braava Jet240
	You can reduce the water spray volume if preferred, say on laminate or wood	Braava Jet240
	if you want to reduce the water output for instance, no option but to use the mobile app	Braava Jet240

it offers a mapping system only available in high and products is a mid and product	
it offers a mapping system only available in high end products in a mid end product	Ecovacs Deebot M81Pro
very pratical wifi connection to program or drive it through your phone	Ecovacs Deebot M81Pro
The settings programmed through the remote control are not visible on the app and viceversa	Ecovacs Deebot M81Pro
the app is really handy to program the areas you want to clean or schedule the cleaning	Ecovacs Deebot R95 MKII
the app is pretty cool for checking its progress/setting it a specific task	Ecovacs Deebot R95 MKII
WIFI connection	Ecovacs Deebot R95 MKII
Difficulties connecting the App	Ecovacs Deebot R95 MKII
it has a count down timer not a clock, so scheduling things at first can be confusing the instruction manual is not very clear on this	Haier T325 Pathfinder
It cannot be scheduled by days	l Life V5s Pro
commands from the app reach the robot with delay	Proscenic 790T WIFI
connects to wifi	Proscenic 790T WIFI
the app is really handy to program the days you want to clean	Proscenic 790T WIFI
some problems connecting to the App	Proscenic 790T WIFI
It is not possible to see the current location of the robot or the mapping of the areas which have been cleaned already	Proscenic 790T WIFI
there is no automated schedule	Roomba Scooba 450
You cannot programm it when you are out	Roomba Scooba 450
I was very surprised by the amount of dust and dirt it had collected for the short time it had been running	Ecovacs Deebot M81Pro
Good performance on hard floors	Ecovacs Deebot M81Pro
Good vacuuming performance	Ecovacs Deebot R95 MKII
It vacuum s really well	Ecovacs Deebot R95 MKII
It works well on short haired rug carpets	Ecovacs Deebot R95 MKII
Vacuum performance is just normal	Ecovacs Deebot R95 MKII
It doesn't work in carpets	Haier T325 Pathfinder
It picks up only dust and not much else	Haier T325 Pathfinder
The little brushes come off easily when caught on something	Haier T325 Pathfinder
It vacuum pretty well	l Life V5s Pro
It vacuums really well	l Life V5s Pro
good vacuuming perofrmance	Moneual ME685
Is very efficient handling pet hair	Proscenic 790T WIFI
has a strong suction mechanism	Proscenic 790T WIFI
actually works on carpets	Proscenic 790T WIFI
it handles pet hair without problem	Proscenic 790T WIFI
that the cloth seems to get dry after 30mins of use as the wick in the dispenser does not let sufficient water out	
took 40 minutes to do what I can do in 5	Braava 390t
	Braava 390t
the wet mop does a fantastic job	Braava 390t

6		
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In and before and earns are not ideal as its samply a non-scrubbing, flat weign proton already own a Koomba vacuum deams are not ideal as its samply a non-scrubbing, flat weign proton already own a Koomba vacuum deams are not ideal as its samply vacuum are deams and the scrum and the scrum are not ideal as its samply vacuum are are not ideal as a complement of a reaching of a proton of the scrubbing flat and dual so very rarely vacuum the dry mog, but when have a doas colored it well, but just table to work well as a complement of a reaching or a previous cleaning the wheels leave marks to vacuum and mo is and to an run out of weber would still ary medium size reaces work perfectly the scrubbing of the area but it can run out of weber would still ary medium size reaces work perfectly the scrubbing of proton of proton graphene the scrubbing flat weign graph. The scrubbing of proton of proton graphene the scrubbing of the scrubbing of the scrubbing of proton of proton graphene. The scrubbing of proton of proton graphene the scrubbing of the scrubbing of the scrubbing of proton of proton graphene. The scrubbing of proton of proton graphene the scrubbing of the scr		1
anaged own a Koombe vacuum cleaning robot, but this is a perfect complianct use a notophase for collecting quirt and use to very rarely use the dry mop, but when have it does collect it wull, but just is and area 306. Anaged about set for collecting quirt and use to very rarely use the dry mop, but when have it does collect it wull, but just is and area a 306. Anaged about set for combine of a previous cleaning the wheels leave marks. As all to clean groot the set apprinting proof job of cleaning op thats. The set apprinting proof job of cleaning op thats. As all the or there the bit efferty runs out. It does a surprinting proof job of cleaning op thats. As and a field to be a surprinting proof job of cleaning op thats. The set apprinting proof job of cleaning op thats before setting bits areas a lead of the set apprinting by groot job of cleaning op thats. As and lead to be a surprinting proof job of cleaning op thats. As and lead to be a surprinting broot job of cleaning op thats before setting bits areas a lead of the set apprinting the proof job of cleaning op thats before setting bits areas a lead of the set of the proof in proof	it will wipe but lacks the intensity of roller/scrubbing action or indeed a mop and bucket	Braava 390t
 use a coduction for collecting diff and due to very rarely use the dry mop, but when have it does collect it well, but just have have a 300. Harva 420.0 <l< td=""><td>Tile undulations and seams are not ideal as its simply a non scrubbing, flat wiping motion</td><td>Braava 390t</td></l<>	Tile undulations and seams are not ideal as its simply a non scrubbing, flat wiping motion	Braava 390t
base room with it. Beave 300 twork well as a complement of a noombar or previous cleaning Beave 300 twork well as a complement of a noombar or previous cleaning Beave 300 to table to end mouth Beave 300 address of the approximation of large arease but it can thou of weter Beave 1000 address approximation of large arease but it can thou of weter Beave 1000 address approximation of large arease but it can thou of weter Beave 1000 the does a spreinity of large arease but it can thou of weter Beave 1000 the does a spreinity of large of	I already own a Roomba vacuum cleaning robot, but this is a perfect compliment	Braava 390t
he wheels lace mans problems of large areas but it can run out of water areas and provided and p	I use a robot vac for collecting dirt and dust so very rarely use the dry mop, but when I have it does collect it well, but just takes dust round with it.	Braava 390t
construction praws 390 attery life isn't a problem on large areas built can un out of water praws 1620 would still as medium are noons work perfectiv praws 1620 it use out of water before the battary run out praws 1620 it is ont quick about deaning praws 1620 it is not quick about deaning in som parts praws 1620 it is not quick about deaning in som parts praws 1620 it is not quick about deaning in som parts praws 1611 and water about not praws 1611 a finger praws 1620 it is not quick about the mop on, so you have to remember to add the mop before the cytle praws 1620 and 1620	It works well as a complement of a roomba or a previous cleaning	Braava 390t
attery life init a problem on large areas but it can run out of water Brave Jet20 would still say medium size rooms work perfectly Brave Jet20 it num out of water befree the battery runs out Brave Jet20 it num out of water befree the battery runs out Brave Jet20 it a one a uprinnely good job of clearing up stains. Brave Jet20 it is not quick about cleaning Brave Jet20 id o have a Roomba which i use first for picking up dust before setting this Brave Jet20 id ohave a Roomba which i use first for picking up dust before setting this Brave Jet20 id ohave a Roomba which i use first for picking up dust before setting this Brave Jet20 in and tactum and map at the same time Econect Bebeth MSI Pro is not effective Econect Bebeth MSI Pro is levels of cleaning in one pass Econect Bebeth MSI Pro is levels of the added mop fasture eveny now and then Econect Bebeth MSI Pro is levels of the added mop fasture eveny now and then Econect Bebeth MSI Pro is avait at this robot not just vaccuming-it also wet cleaning floor! Econect Bebeth MSI Pro is avait at this robot not just vaccuming-it also wet cleaning floor! Econect Bebeth MSI Pro is avait at this robot not just vaccumin	The wheels leave marks	Braava 390t
would still say medium size rooms work perfectly. Bases jet240 to use out of water before the battery runs out to use out of water before the battery runs out to use out of water before the battery runs out to use out of water before the battery runs out to do have a Roomba which i use first for picking up dust before setting this to do have a Roomba which i use first for picking up dust before setting this additional pasts are get expensive to do have a Roomba which i use first for picking up dust before setting this additional pasts are get expensive to any any to the same time to cover beelow MMIPPo to cover b	Not able to clean grout	Braava 390t
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t does a surprisingly good job of cleaning up stains. Brave let240 It is not quick about cleaning Brave let240 It is not quick about deaning Brave let240 It is not quick about deaning Brave let240 Bra	I would still say medium size rooms work perfectly	Braava Jet240
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	5 levels of cleaning in one pass	Ecovacs Deebot M81Pro
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	The wet mode works well but does not rmove heavy stains	I Life V5s Pro
the mopping mode does not replace the manual cleaning Moneual ME685	The wet mopping mode does not get the mop wet enough by itself, you have to wet the mop beforehand	Moneual ME685
	the mopping mode does not replace the manual cleaning	Moneual ME685

also mops the floor	Proscenic 790T WIFI
mopping results could be better	Proscenic 790T WIFI
you have to remove the main brush to use the mop. The suction mechanism will work at the same time but the robot is left with only sidebrushes	Proscenic 790T WIFI
the wep mopping mode does get the mop wet enough by itself	Proscenic 790T WIFI
It leaves a lot of water behind	Roomba Scooba 450
three pass cleaning does not work on dry climates	Roomba Scooba 450

I.2 Pugh Matrix

PARTICIPANTS

NAME	SCORES													
	6													
NUMBER OF PARTICIPANTS	0												Spray	
				Orien	Power		Dalaman	Delemen	Delawar			Sonicare	Sonicare	Spray Multi.
PARTICIPANT 1	Торіс	Weight of Criteria	Orion	Orion Detach	Orion Detach	Delorean	Roll	Delorean Opp Roll	Roll WR	Aqua trio	Komodo	+ Delorean	+ Delorean	Sonicare + Delorean
	water management water consumption	6	0	0	•		ter ter	1	1	1 0	24		2	
	energy consumption	4	0	0	1	•	1	-1		-8	1	1	1	
	heavy stains crevices	<u>8</u> 2	0			¢					3	2	3	3
	uneven surfaces	7	0		¢	Ø		ø	ø	3	3			3
	simplicity eff working time	5	0	- <u>1</u>	2	<u>-</u> 2	-2	-3 0	-3 0	<mark>в</mark> 0	-3 0	<u>2</u>	2	- <mark>-</mark> 8
			0	-5	4	5	-11	-9	-9	23	31	¥ 14	25	34
					Power							Sonicare	Spray Sonicare	Spray Multi.
				Orion	Orion		Delorean	Delorean	Delorean			+	+	Sonicare +
PARTICIPANT 2	water management	Weight of Criteria	Orion 0	Detach	Detach	Delorean	Roll	Opp Roll	Roll WR	Aqua trio	Komodo	Delorean	Delorean	Delorean
	water consumption	8	0	0	Ó	¢	0	0	¢	*	1	1	Ó	
	energy consumption heavy stains	5	0	0	_ <u>1</u>	¢ ¢	1	2	_1 _1	-8	3	<u>1</u>	1 2	2
	crevices	3	0	0	. d	ģ	0	ø	ø		2	ø	ø	0
	uneven surfaces simplicity	<u>6</u> 2	0	0 -1	¢ 2	0 -1	ф -В	1 -3	0 -B	в - В	2	¢ -2	0 -3	-8
	eff working time	4	0	¢	1	¢	-1	-2	3	-3	2		Į	
			0	5	-2	19	9	12	9	38	61	22	12 Spray	7
					Power							Sonicare	Sonicare	Spray Multi.
PARTICIPANT 3		Weight of Criteria	Orion	Orion Detach	Orion Detach	Delorean	Delorean Roll	Delorean Opp Roll	Deforean Roll WR	Aqua trio	Komodo	+ Delorean	+ Delorean	Sonicare + Delorean
	water management	7	0	¢	1	3	2	2	2	33	3	2	1	2
	water consumption energy consumption	<u>6</u> 8	0	2	• •	_1 _1	-1 -8	- <u>1</u> -3	-1 -3	- <u>2</u> -3	2 2	- <u>1</u> -2	-3 -2	-2
	heavy stains	1	0	¢.				2			2	2	3	
	crevices uneven surfaces	2 3	0		¢	¢		1	1	-59	3	3	3	3
	simplicity eff working time	5	0	-0-	2	2	- a	-3	<mark>в</mark>	а -	2	2	3	
	en working ume	!	0	ų 11	-10	-2	-27	-26	-27	-12	-2	-3	-38	-45
					Power							Sonicare	Spray Sonicare	Spray Multi.
				Orion	Orion		Delorean	Delorean	Delorean			+	+	Sonicare +
PARTICIPANT 4	water management	Weight of Criteria 3	Orion 0	Detach 0	Detach 0	Delorean 2	Roll 2	Opp Roll	Roll WR	Aqua trio	Komodo	Delorean 2	Delorean 2	Delorean 2
	water consumption	7	0	0	0	1	-2	-2	-2		-1	1	-2	-2
	energy consumption heavy stains	2 6	0	0	-3 1	-2 0	-2	-3	-2 0	-3	-3 0	-2 1	- <u>2</u> 1	-2 1
	crevices	1	0	0	0	0	0	0	0	1	1	1	1	1
	uneven surfaces simplicity	5	0	0	0	0	0	0	0	1	-3	-3	-3	-3
	eff working time	4	0	0	0	0	1	1	1	1	1	0	0	0
			0	-8	-16	-15	-36	-32	-45	-28	-28	-3	-24 Spray	-24
				Orion	Power Orion		Delorean	Delorean	Delorean			Sonicare	Sonicare +	Spray Multi. Sonicare +
	Торіс	Weight of Criteria	Orion	Detach	Detach	Delorean	Roll	Opp Roll		Aqua trio	Komodo	T Delorean	Delorean	Delorean
	water management water consumption	8	0	3	3	3	2	2	3	3	3			0
	energy consumption	3	0		1	2	2	2	2	-β	<mark>-</mark> β	2	-2	-2
	heavy stains crevices	<u> </u>	0	_ <u>1</u> _0		1	0	2	2		3	0		0
	uneven surfaces	4	0		¢	- ¢		0	0	0	¢.	0	0	Ó
	simplicity eff working time	2 1	0	3	1	0	¢ 2	- <u>2</u> 2	-8 3	- <u>2</u> 3	- <u>1</u> 3	- <u>2</u> -2	-3 -2	-B -2
			0	38	43	43	35	37	43	58	60	11	2	2
					Power							Sonicare	Spray Sonicare	Spray Multi.
	Tania	Weight of Criteri	Oriera	Orion	Orion	Delever		Delorean		Amuraturi	Komed	+	+	Sonicare +
	Topic water management	Weight of Criteria	Orion 0	Detach 0	Detach 0	Delorean 2	Roll 2	Opp Roll 2	2	2	Komodo 2	Delorean 1	2	Delorean 2
	water consumption	<u> </u>	0	0	0	0	0	0	0	1	1	1	1	1
	energy consumption heavy stains	5	0	0	2	0	2	2	2	-1	-1	2	2	2
	crevices	2 4	0	0	0	0	0	0	0	1	1	1	1	1
		4	U	U	0	U	U	U	U	U	0	1	1	1 I I
	uneven surfaces simplicity	<u> </u>	0	0	2	-2	-2	-2		-2	-2	-1	-1	-1

TOTAL

NAME	SCORES														
NUMBER OF PARTICIPANTS	6														
TOTAL	Торіс	Average Weight of Criteria	Orion	Orion Detach	Power Orion Detach	Delorean			Delorean Roll WR		Komodo	+	+	Spray Multi. Sonicare + Delorean	Weight Criteria Order
	water management	6.5	0	0.7	0.8	2.7	20	2.0	17	2.3	23	1.7	15	1.3	8
	water consumption energy consumption	<u>6.0</u> 4.0	0	0.3	0.0	-0.0	-05	-07 -13	- <mark>0</mark> 7 -10	-03	-013	0.3	-17	-10 -18	7
	heavy stains	4.5	0	-02	02	03	05	1.5	0.8	1.8	17	17	2.0	2.0	4
	crevices	2.5	0	0.0	02	0,0	00	02	02	20	17	0.8	10	1.0	1
	uneven surfaces simplicity	4.8	0	0.0 -0 <mark>:</mark> 2	00 - <mark>0</mark> 7	00	02 -22	0.3	02 -30	17 -27	15	10 -20	10 -25	1.3	6 5
	eff working time	2.8	0	-02	-0.2	0.5	0.5	03	18	05	13	0.0	0.0	-02	2
	ļ		0	6.8	3.8	14.3	2.7	2.8	-1.2	14.8	22.0	14.2	2.5	1.5	

1.3 Proving Sonicare

For the Sonicare technology, because it would be a new application in floorcare, there is not information about its behavior. Several questions will have to be answer to optimize this system:

Does the principle work?

Get one actuator, mount it in a robot and test if it cleans.

What motion works better on heavy stains/crevices/uneven surfaces? What parameters make it perform better (amplitude, frequency, pressure, etc)?

To answer this question, a possible test is to use a piece of transparent plastic and film the behavior of the system with a slow-motion camera to see which motion is more effective dissolving the stains. Thanks to this test, other parameters such as amplitude and frequency could be partially determined.

What is the best material for the brush?

For this test, an idea is to take a piece of hard floor (wooden floor) and let the prototype work on the surface four a period of X hours and see if it damages the surface.

What amount of water is required by the system to deal with dirt?

To answer this question, first is necessary to find out which is the real impact of water in the process of removing stains from the floor together with the vibrating brush. Second, it is necessary to know how the different parameters affect the way water behaves.

How much weight can an actuator move? (mass of the brush plus the friction against the surface)

How many brushes and which size?

How many actuators do we need?

What is the optimal speed movement for the robot in order to be able to clean heavy stains in one pass?

It will be required to get a balanced solution to optimize the system and get a proper cleaning using an acceptable amount of water and energy. At the end of the process the solution should be able to deal with the stains defined on "Stains Removing" in ideally one pass.

To know if a principle works, it is necessary to test it. To do so, a fast prototype has been built using the minimum elements required to reduce the building time. Afterwards a fast test has been performed to see if the prototype is able to handle stains.

A set of stains will be created to see if the working principle has any impact on them. Any specific measurements apart from visual observations will be made at this point.



I.4 Pick Up Mop Vs Pick Up Mop + Sonicare

TESTING THE IDEAS – IMPACT OF THE DIFFERENT ELEMENTS

The stains used on the following tests were made out of coffee with one sugar and dried for at least 12 hours. The procedure followed was obtained from *"Stain Removing"*.

PICK UP MOP

The first goal is to determine the impact of each of the elements (PICK UP MOP and brush) on the system. In order to achieve it, PICK UP MOP will be tested alone to test the whole system afterwards and observe the difference in Performance.



PICK UP MOP + BRUSH LOW FREQ



LOW FREQUENCY SETTINGS: Not measured







PICK UP MOP + BRUSH MID FREQ



MID FREQUENCY SETTINGS: 100Hz







PICK UP MOP + BRUSH HIGH FREQ



TESTING THE IDEAS – IMPACT OF THE DIFFERENT ELEMENTS

The performance of medium and high frequencies is better than low frequencies. Therefore, the medium frequency setting has been tested using different speeds.

PICK UP MOP + BRUSH MID FREQ 30% & 50% SPEED

50% SPEED (LEGO NXT SETTINGS)











5 strokes

16

30% SPEED (LEGO NXT SETTINGS) -





1 stroke

2 strokes

The speed has a big impact on the performance of the working principle. From now on, the speed used for the tests will be 30% and the frequency will vary between mid and high freq to determine the impact of the variable.

start

1.5 Test On Different Stains

TESTING THE IDEAS – COFFEE



The stains used on the following tests were made out of coffee with one sugar and one creamer. Afterwards, they dried for at least 12 hours. The procedure followed was obtained from "Stain Removing".

PICK UP MOP + BRUSH 30% SPEED





1 stroke

2 strokes

3 strokes





PICK UP MOP + BRUSH MID FREQ 30% SPEED ON HEAVY STAINS



PICK UP MOP + BRUSH HIGH FREQ 30% SPEED ON HEAVY STAINS



AQUA TRIO USING ITS OWN WATER SUPPLY 50% SPEED





AQUA TRIO 30% & 50% SPEED WITH SPRAY WATER SUPPLY



WATER TANK+MOP 30% & 50% SPEED WITH SPRAY WATER SUPPLY





start


AQUA TRIO WITH 30% SPEED ON HEAVY STAINS



AQUA TRIO WITH 50% SPEED ON HEAVY STAINS



start



1 stroke





2 strokes

0

2 strokes

3 str

3 strokes



4 strokes

5 strokes



WATER TANK+MOP 30% SPEED ON HEAVY STAINS





1 stroke





3 strokes





4 strokes



WATER TANK+MOP 50% SPEED ON HEAVY STAINS



WATER TANK+MOP+BRUSH MID & HIGH FREQ WITH SPRAY WATER SUPPLY





WATER TANK+MOP +BRUSH MID & HIGH FREQ ON HEAVY STAINS

MID FREQ









HIGH FREQ





1 stroke



2 strokes



TESTING THE IDEAS - TEA



The stains used on the following tests were made out of tea from the machine in the corridor with one sugar and dried for at least 12 hours. The procedure followed to create the stain was obtained from *"Stain Removing"*.







WATER TANK+MOP+BRUSH MID & HIGH FREQ WITH SPRAY WATER SUPPLY



TESTING THE IDEAS – SPREAD SOY



Stains of soy sauce were generated by applying 20-25 drops with a syringe to a piece of laminate and spreading them with the fingers along the laminate. The stains dried for at least 12 hours.

PICK UP MOP+BRUSH MID & HIGH FREQ 30% SPEED





AQUA TRIO 30% & 50% SPEED







TESTING THE IDEAS – HEAVY SOY STAINS



Heavy stains of soy sauce were generated by applying 2.4 ml of soy per stain with a syringe to a piece of laminate. The stains dried for at least 12 hours.







AQUA TRIO 30% & 50% SPEED



10

10 stroke

11 strokes 12 strokes

13 strokes

14 strokes

15 strokes



WATER TANK+MOP 30% & 50% SPEED WITH SPRAY WATER SUPPLY









11 strokes











9 strokes

10 stroke

12 strokes

13 strokes

14 strokes

15 strokes



9 strokes

8 strokes

6 strokes

TESTING THE IDEAS – SWEET SOY



Stains of sweet soy were generated by putting 4 ml in a syringe and generating drops along the laminate. The stains dried for at least 12 hours.









WATER TANK+MOP 30% & 50% SPEED



52

start

1 stroke

2 strokes

3 strokes

2. APPENDIX

Motion Analysis-Visual Cleaning - 2.1 Water Supply Analysis-Visual Cleaning - 2.2





APPENDIX

2.1 Motion Analysis Visual Cleaning

MOTION ANALYSIS – Visual Cleaning

A first test has been performed in order to get some insights about the behavior and connections of the different parameters. On this test, no special setup was used focusing more on observation and understanding. The test consisted on generating a soy sauce stain on a piece of laminate and use the different motions while the whole process was recorded. The water left on the laminate will be dried using a window cleaner. A pressure of 1,5 Kg will be applied to the brushes and different soaking times will be used. It has been observed that long bristles tend to bend when the product moves.









11 stroke











*The rest of pictures related to circular oscillation have not been found. Probably due to the use of the shared camera or hard drives of the lab.The data about the number of strokes was registered after every test so the information is still relevant.

APPENDIX

2.2 Water Supply Analysis Visual Cleaning





Rotational Mop



Droplets



Atomiser







APPENDIX

2.3 Stain Prototcol Creation Stain Images




2.4 DoE Combinations

DOE RAW DATA

StdOrder	RunOrder	PRESSURE (KG)	SPEED ROBOT (CM/S)	SPEED ROTATION (RPM)	SIZE OF BRUSH (CM)	AMOUNT OF WATER (ML/MIN)		NUMBERS OF STROKES	TEMPERATURE	HUMIDITY
13	1	0.5	10	1500	5.4	10	BRISTLES (MM)	7	24.2	51.5
31	2	0.5	25	1500	5.4	40	3	9	24.2	51.5
9	3	0.5	10	0	5.4	10	8	10	24.2	51.5
24	4	2.5	25	1500	3.8	40	3	8	24.2	51.5
21	5	0.5	10	1500	3.8	40	3	6	24.2	51.5
34	6	1.5	17.5	750	4.6	25	5.5	7	24.2	51.5
7	7	0.5	25	1500	3.8	10	3	9	22	41
1	8	0.5	10	0	3.8	10	3	12	22	41.5
27	9	0.5	25	0	5.4	40	8	11	22	41.5
11	10	0.5	25	0	5.4	10	3	14	22	41.5
6	11	2.5	10	1500	3.8	10	3	9	22	41.5
16	12	2.5	25	1500	5.4	10	3	11	22	41.5
30	13	2.5	10	1500	5.4	40	3	8	22	41.5
25	14	0.5	10	0	5.4	40	3	11	22	41.5
19	15	0.5	25	0	3.8	40	3	13	22	41
12	16	2.5	25	0	5.4	10	8	11	22.6	40
15	17	0.5	25	1500	5.4	10	8	11	22.6	40
5	18	0.5	10	1500	3.8	10	8	10	22.3	50.5
22	19	2.5	10	1500	3.8	40	8	8	22.3	50.5
18	20	2.5	10	0	3.8	40	3	10	22.65	40.5
4	21	2.5	25	0	3.8	10	3	12	21.8	53.5
14	22	2.5	10	1500	5.4	10	8	8	21.8	53.5
2	23	2.5	10	0	3.8	10	8	9	22	46
10	24	2.5	10	0	5.4	10	3	10	22	46
26	25	2.5	10	0	5.4	40	8	7	22	46
8	26	2.5	25	1500	3.8	10	8	10	22	46
23	27	0.5	25	1500	3.8	40	8	10	22.5	49.5
35	28	1.5	17.5	750	4.6	25	5.5	11	22.5	49.5
33	29	1.5	17.5	750	4.6	25	5.5	9	22.5	49.5
20	30	2.5	25	0	3.8	40	8	11	22.5	49.5
28	31	2.5	25	0	5.4	40	3	9	22.5	49.5
17	32	0.5	10	0	3.8	40	8	9	22.5	49.5
29	33	0.5	10	1500	5.4	40	8	8	22.5	49.5
32	34	2.5	25	1500	5.4	40	8	10	22.5	49.5
3	35	0.5	25	0	3.8	10	8	10	22.5	49.5





COMBINATION 19



COMBINATION 19



3. APPENDIX

- Ideas Presentation 3.1

 - Comments 3.2 Ranks Papers 3.3 Ranks Scores 3.4



3.1 Ideas Presentation



IN THE LAST DECADE, A LOT OF COMPANIES HAVE ENTERED INTO THE ROBOT VACUUM CLEANERS MARKET



PHILIPS

NUMEROUS FUCTIONS AND ELEMENTS HAVE BEEN DEVELOPED TO MAKE ROBOTS MORE EFFICIENT

Slides to introduce the topic: Wet robot vacuum cleaners



THESE INNOVATIONS HAVE ALLOWED **ROBOTS TO REACH EVERY SPOT**



HILIPS

VACUUMING THE DUST FROM EVERY SURFACE OF YOUR HOUSE AND IN THE LAST FEW YEARS THE NEXT STEP STARTED, WITH ROBOTS THAT NOT ONLY VACUUM BUT ALSO



MOP YOUR FLOOR FOR YOU !!!

A LOT OF TECHNOLOGIES HAVE BEEN DEVELOPED TO MAKE THESE PRODUCTS SMARTER



oyson 300 eye





--β3





















3.2 Comments

Comments Paper

PROPOSITION Comments	PROPOSITION Comments
Positive Comments	Positive Comments
Negative Comments	Negative Comments
Improvements/Observations	Improvements/Observations

The participants had to fill a paper like the one above for every proposition. The idea with this paper was to collect the different thoughts about each idea in a way that they could be analyze afterwadrs. After conducting both focus groups the comments were translated by one of my colleagues at the office. Once all the comments were translated a serie of mind maps were created to look at the different topics covered by those comments. In the following pages the mind maps are going to be presented.





ç







3.3 Ranking Papaers





3.4 Ranking Scores

In this activity the participants had to order the ideas in position from 1 to 5 being the position number 1 the best score possible. Afterwards a numerical score was assign to each position in order to process the data. In the following pages the scores given by the participants are going to be presented.

Participants in the focus group 1

Participant I: woman

POSITION	EASY TO USE	DURABILITY	IN STATE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE
1	5	5	5	4	5	5
2	4	1	4	5	4	4
3	1	2	3	3	3	3
4	3	4	2	2	2	2
5	2	3	1	1	1	1
5	-	5	-	-	-	-

Participant 2: woman

POSITION	EASY TO USE	DURABILITY	IN STATE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE
1	4	4	4	4	4	3
2	5	5	3	3	3	4
3	1	1	2	2	1	2
4	2	2	1	1	2	1
5	3	3	5	5	5	5

Participant 3: woman

POSITION	EASY TO USE	DURABILITY	IN STATE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE
1	4	4	3	3	3	3
2	1	1	4	4	4	0
3	5	3	2	2	2	0
4	2	2	1	1	1	0
5	3	5	5	5	5	1

Participant 4: man

POSITION	EASY TO USE	DURABILITY	IN STATE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE
1	5	5	5	5	5	3
2	4	1	4	4	2	0
3	2	2	3	3	3	0
4	1	4	2	2	4	0
5	3	3	1	1	1	1

Participant 5: woman

POSITION	EASY TO USE	DURABILITY	IN STATE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE
1	4	4	3	3	4	3
2	1	1	4	4	2	4
3	5	2	5	5	5	5
4	3	3	2	2	3	2
5	2	5	1	1	1	1

Participant 6: man

POSITION	EASY TO USE	DURABILITY	IN STATE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE
1	5	5	3	3	5	3
2	4	4	4	5	4	4
3	3	3	5	4	3	5
4	1	1	2	2	1	2
5	2	2	1	1	2	1

Participant 7: woman

POSITION	EASY TO USE	DURABILITY	IN STATE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE
1	4	3	5	5	5	5
2	3	4	4	4	4	2
3	5	5	2	2	2	3
4	1	1	1	1	1	4
5	2	2	3	3	3	5

Participant 8: woman

POSITION	EASY TO USE	DURABILITY	IN STATE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE
1	4	4	4	3	4	4
2	1	5	3	5	3	5
3	5	1	5	4	1	3
4	2	2	2	2	2	2
5	3	3	1	1	5	1

Participants in the focus group 2

Participant I: woman

POSITION	EASY TO USE	DURABILITY	IN STATE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE
1	2	4	4	4	3	4
2	1	3	3	3	4	5
3	4	5	5	5	5	3
4	5	2	2	2	2	2
5	3	1	1	1	1	1

Participant 2: man

POSITION	EASY TO USE	DURABILITY	IN STATE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE
1	4	4	3	3	3	3
2	1	5	5	5	2	5
3	2	2	4	4	1	4
4	5	3	1	1	5	2
5	3	1	2	2	4	1

Participant 3: woman

POSITION	EASY TO USE	DURABILITY	IN STATE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE
1	1	4	1	4	1	4
2	4	1	4	5	2	5
3	5	5	5	3	4	3
4	2	2	3	2	5	2
5	3	3	2	1	3	1

Participant 4: man

POSITION	EASY TO USE	DURABILITY	IN STATE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE
1	4	4	1	3	3	5
2	5	1	4	4	4	4
3	1	2	5	2	2	3
4	2	3	3	5	5	2
5	3	5	2	1	1	1

Participant 5: man

POSITION	EASY TO USE	DURABILITY	IN STATE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE
1	1	1	3	3	3	3
2	4	2	2	2	1	2
3	2	4	1	4	2	5
4	3	5	4	1	4	4
5	5	3	5	5	5	1

Participant 6: woman

POSITION	EASY TO USE	DURABILITY	IN STATE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE
restrict	2/01/10/032	DONADIEITT	TOORTEOOR	51015	THE OBILITE	ESTIMATED TRICE
1	1	4	4	4	2	5
2	2	1	5	5	1	2
3	3	2	3	3	5	4
4	5	5	2	2	3	3
5	4	3	1	1	4	1

Total Scores

Averaged Scores

PROPOSITION	EASY TO USE	DURABILITY	ABLE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE	AVERAGE
IDEA 1	2.43	2.79	4.00	4.64	3.50	4.92	3.71
IDEA 2	3.71	3.57	3.86	3.64	3.00	3.42	3.53
IDEA 3	4.29	4.00	2.50	2.00	2.57	2.50	2.98
IDEA 4	1.79	1.71	1.93	1.93	2.57	2.33	2.04
IDEA 5	2.79	3.00	2.86	2.79	3.21	1.83	2.75

Now, the reversed averaged scores are going to be introduced. In order to generate a logical spider graph the following operation has been performed:

Highest possible score "5"+1-Averaged scored

By doing this operation the spider graphs are turn over showing those points with a lower averaged, which means the product was in better positions, as a higher score.

Reversed Averaged Scores

	EASY TO USE	DURABILITY	ABLE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE	AVERAGE
IDEA 1	3.57	3.21	2.00	1.36	2.50	1.08	2.29
IDEA 2	2.29	2.43	2.14	2.36	3.00	2.58	2.47
IDEA 3	1.71	2.00	3.50	4.00	3.43	3.50	3.02
IDEA 4	4.21	4.29	4.07	4.07	3.43	3.67	3.96
IDEA 5	3.21	3.00	3.14	3.21	2.79	4.17	3.25

Reversed Men Averaged Scores

	EASY TO USE	DURABILITY	ABLE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE	AVERAGE
IDEA 1	3.57	3.21	2.00	1.36	2.50	1.08	2.29
IDEA 2	2.29	2.43	2.14	2.36	3.00	2.58	2.47
IDEA 3	1.71	2.00	3.50	4.00	3.43	3.50	3.02
IDEA 4	4.21	4.29	4.07	4.07	3.43	3.67	3.96
IDEA 5	3.21	3.00	3.14	3.21	2.79	4.17	3.25

Reversed Women Averaged Scores

	EASY TO USE	DURABILITY	ABLE TO CLEAN YOUR FLOOR	BEST RESULTS ON HARD SPOTS	FAVOURITE	ESTIMATED PRICE	AVERAGE
IDEA 1	3.78	3.22	1.78	1.33	2.67	1.13	2.32
IDEA 2	2.22	2.22	2.22	2.33	3.00	2.63	2.44
IDEA 3	1.78	2.11	3.22	3.67	3.00	2.67	2.74
IDEA 4	4.11	4.56	4.44	4.44	3.89	4.33	4.30
IDEA 5	3.11	2.78	3.11	3.22	2.67	4.33	3.20

4. APPENDIX

Holistic Experience Scan Papers - 4.1 Holistic Experience Scores - 4.2 Holistic Experience Scan Papers - 4.3




APPENDIX

4.1 Holistic Experience Scan Papers





USE STAGES EVALUATION : Maintenance

Participant Number :



APPENDIX

4.2 Holistic Experience Scan Scores

MAINTENANCE	Detach mopping pad and brushes	Ļ	Ļ	m	o	ċ	1.5	0	m	2	0.61111111
	Remove & clean water tank	m	2	2	o	1	2.5	ω	Ņ	1	1.38888889
	Remove&dea n filter	m	m	m	o	m	m	m	m	Ļ	2.44444444
	Remove dustbin	'n	'n	m	2	ĸ	'n	m	'n	m	2.88888889
WET CLEANING	Remove mop	2-	1	m	1	m	1.5	Ļ	m	m	1.3888889
	Remove mopping module	m	m	m	o	2	m	m	m	2	2.44444444
	Empty water tank	m	2	2	ή	2	2	0	'n	Ļ	0.44444444
	Empty dustbin	ო	ო	m	7	2	1	ŵ	ო	Ļ	1.44444444
	Select Cleaning mode	ო	m	m	7	2	m	'n	o	ო	1.7777778
	Attach water tank	ო	m	m	1	2	2.5	2	2	ო	2.38888889
	attach mopping pad	ო	ო	m	0	0	2.5	Ļ	ო	ო	1.83333333
	Fill the water tank	ċ	2	m	4	2	1.5	ŵ	ŵ	Ļ	-0.16666667
DRY CLEANING	Empty Dustbin	ო	ო	m	m	m	1	2	ო	2	2.5555556
	Select Cleaning Mode	ო	2	m	1	2	2	ŵ	Ļ	2	AVERAGE 1.22222222 2.55555556 -0.166666667 1.83333333 2.38888889 1.77777778 1.444444444 0.44444444 2.44444444 1.388888889 2.44444444 1.38888889 2.44444444 1.38888889 0.6111111
	Participa nt	ст Г	2	m	4	ъ	و	2	ø	ŋ	AVERAGE

APPENDIX

4.3 Interviews Notes

PI Broke her nail

- Blue handle DB easy to understand
- Water tank: add sign for clean and dirty water
- o Too small now
- Nail broke when pushing brushes
- Nice button
- Likes opening DB on top
- Very easy to empty DB
- Difficult: mop
- o How to disassemble?
- o Pushing brushes difficult: takes force
- o Detaching mop with the rubber is easy
- Brushes and mop in different color? Yes good idea
- When you see the screws, you think you cannot remove it
- The drawing fermi made was a good idea
- Write 'remove' on he brushes part

P2 (has robot)

- Gonna lose the ramp
- Vinegar in water tank
- Mop never gets dry, where to put it so it doesn't drip
- Wants to rinse the DB with soapy water
- Throws away filter in trash
- Likes when it clicks, otherwise not sure it's connected
- Dirt gets in ridges on top
- Likes to turn it around on its back. Doesn't like when the button is sticking out. Now uses towel so robot lies soft.
- Many holes where dust can accumulate
- Impossible to get wheels out, wants to take out to clean
- Understands front side
- Bumper should be longer
- Square shape looks faster
- Make it balck, looks smaller
- Shape is aerodynamic
- Different colors for dirty and clean water lids
- Needs to look fancy
- Likes to see robot in the room
- Attached her dock with duct tape to floor
- Suction cap to secure dock?
- Uses the 'buttons' to remove the brush
- Doesn't like to push hard
- Doesn't want to choose modes, just clean everything, but doormat extra
- Carries her iRobot to doormat for spot clean. Thinks it knows when it is finished.
- Brushes renew your doormat
- When you have wet hand you don't want to touch the button anymore
- (she's careful of damaging the robot, needs to look nice)

- Bumper can look softer, so doesn't damage furniture. Rest glossy.
- Like a car, also nice color

P3 Guy with robot

- Water tank is DB
- Saw DB and thought no this is DB
- Recognized on /off button
- Would rinse DB
- Turns robot upside down for attaching mop
- Doesn't understand ramp, does attach correctly
- Thinks DB not used when wet cleaning
- Expected a main brush
- Clean filter every 1 or 2 weeks
- He cleans the wheels
- Identifies bumper as front part
- He cleans sensors too
- Ridges will get dirty, the smoother the robot, the better
- No brush in this, not as good as Roomba
- Will not clean edges, not wide enough (vacuum nozzle)
- Thinks side brush is useful to clean edges
- Recognizes wetting and drying part of mop
- More focused on wet clean this design
- Doesn't know if useful to combine wet and dry
- Mopping would be nice, but should avoid his carpet
- Doesn't see problem with square back. Round front useful when turning
- Doesn't use spot clean mode. Uses handheld small vac for small stuff
- Uses robot at night
- Has robot > 5 years, 3 batteries replaced
- Bounce and Z-mode he likes, doesn't understand why to have other modes
- One button is better, easier to understand, certainly with screen
- Wet cleaning not every day, dry every day
- Letting the robot attach / detach mop by itself would be too expensive, only wet cleans once in a while
- Adjusted his house for the robot, cables and such. Needs to be tidy for robot to work
- Robot is visible, for docking purposes
- Uses robot upstairs, needs to find it there after use. Doesn't bother him
- Would he set a timer for cleaning? He wouldn't know how to estimate required time. Like now is fine. Maybe light and hard clean, but keep it simple.
- If you clean every day already, it is not that dirty. Doesn't expect dirt in his house
- Thinks wet cleaning brushes will clean a lot
- At least 2 mops so you can exchange them
- Because you use it so much, don't make it glossy. Best to stay nice, but few scratches won't matter
- Idea: add a handle for going upstairs

P4 (Has aqua trio)

- Water tank is home base? No
- Hope DB does not have to empty all the time. Will wait for feedback light
- Does not understand how to fil water tank
- Water tank too small (compared to aquatrio)
- No problem if water gets in DB.Why not put dirty water and dust in I
- Always residue of sand in water tank
- Prefers cleaning wet + dry at same time
- Should clean itself like aquatrio
- Change mop every 6 months
- Hairs gonna be stuck in brushes
- Hopes she can store it when it is still wet, Should not smell
- Trouble w/ disassembling mop. Lot of work. Doesn't want to do every time
- Now says cloth needs to be changed every time
- Thinks ramp is unnecessary
- Trouble attaching ramp
- Easier if ramp was integrated

MAINTENANCE

- Should clean itself every time
- Put mop in washing machine
- "Vacuum cleaners have more than I filter", where is other filter
- Filter should be rinsable
- Know front and back
- Cannot clean carpet
- Can replace her mop, but not along edges
- W/ aquatrio you sometimes need 6 strokes to clean something
- Robot should clean so I don't have to myself
- In Aquatrio she sees visual feedback dirty water
- Add detergent to water

INTERFACE

- Click wheel is complicated
- Prefers to use app
- Wants the option to choose for cleaning mode; in case robot does not clean well
- Robot should decide himself as much as possible
- Water tank will pollute itself
- Does not want to show robot, prefers to hide
- Less dirty upstairs, living room more important
- Doesn't care how it looks, doesn't want to see it, should work without you
- Water tank: prefers to have no movable wall, saves cleaning step, more robust
- Should not damage walls. Should have rubber protection.

P5

- Looks at water tank and ramp, doesn't know what for
- Tries putting ramp in front of nozzle
- Tries to 'click' robot on mop from the top. Mop positioned correctly though
- Idea: put arrow on mop slide in piece
- Does not understand ramp at all
- Thinks squeegee make everything dry
- Mop components stuck together, do not come loose

DISCUSSION

- Cleans very well
- Every time you should clean the mop, but you don't want to do that every time
- Cleaning after I month would be good
- Brushes do not have to be cleaned as often as mop
- Would use in entire house, apart from stairs
- Obvious what front is due to sensors
- Would hide the robot
- Dock downstairs
- Water on left part of tank

P6

- Squeegee is for wet cleaning
- Understands product well
- Not clear where to put clean water, expects left
- Brushes look fixed to mop module
- Space in between brushes, so stripes on floor
- Successfully dismantled mopping module
- Thinks sensors are lights, later knows they are sensors
- Dustbin lid is symmetrical, dustbin too. Better to do asymmetrical.
- Cleaning power
- o Wil keep house quite clean if you use 1x / week
- o But have to clean yourself every 6 months
- o Will handle footprints
- o Will not handle
 - Beer stain
 - 🗆 Cola
 - 🗆 Food
- Hair gets stuck in brush, e.g. when turning. Would be better if vacuuming part is closer to mop part
- Shape confusing, front and back. Thought front is flat, like millennium falcon
- Water vacuumed no big problem, but annoying when soggy/muddy
- Clean mop: once every 2 weeks, after 3 times use
- Brushes and mop last a year. Then buy new one
- Every night dry cleaning
- Wet I-2 times per week
- Trusts dry clean

• Wants more control over wet clean

INTERFACE

- Blue/green colors good
- Don't rotate 360 degrees. Hand will be in way. Keep finger in one place and then stroke to turn
- Buttons better than circular knob
- Prefers LCD
- Dock not in sight but accessible
- Would not carry robot upstairs
- Dock in lower floor, gets dirtiest there. Upstairs not as needed
- Does not want to have to attach the (BLANK) (I think mop)
- Doesn't matter how long it takes, as long as it is clean
- Just wants to say go to the robot, nothing else
- Not worth putting in function to clean specific rooms, not worth money
- Mopping stripes in same direction would be nice
- Would like access to programming
- Other functionalities: serving beer

P7 hannie

- Thinks sensor is start button, after that pushes the actual start button
- Thinks water tank is battery
- Thinks ramp is to put on nozzle squeegee
- Robot upside down, tries to attach ramp. Knows it is for the mop though.
- Thinks it does only mopping or vacuum cleaning
- Clean wtare on left side
- Pushes brushes part correctly (on the motor connections though)
- Mop clean every time
- Filter is replaceable
- If possible dry and wet at the same time
- Mop replace every half year
- Store in kitchen
- Would use upstairs
- Would keep out of sight
- Integrate ramp
- 7x / week dry clean. 1x/ week
- Interface: described it right, so it is intuitive to her. Easy to use one button

P8

- Immediately presses on button
- Brushes could be used for dry cleaning to brush dust
- Ramp is wall mount, to store mop on
- Doesn't know what water tank is, thinks it is a battery because it is heavy
- Button on top may be a sensor?
- Sensors are on front, shape is aerodynamic

- Water tank: soap and water compartments
- Should notify when DB full
- Does not recognize to detach dustbin lid at corner
- Thinks filter is disposable
- Possible to put filter in upside down
- Dock should be flat and small, under couch maybe
- Clean water on left side
- Use indicators on water tank for the separation part; where to put it
- Cleans downstairs more often than upstairs, also no visitors (with shoes) upstairs
- Should be able to control mode: dry, dry + wet, wet
- Cleaning mopping module seems a lot of work
- Understands how to disassemble mopping module
- Wants to take out brushes individually
- 'click' missing when pushing brushes in
- Take off wheels to clean
- Would put cloth in washing machine, but distrusts attachment to silicon frame
- Would pre-clean brush before putting it in dishwasher. No problem to mix with spoons, forks and

what not. Hot cleaning program though.

- Integrate ramp
- Cleaning power depends on force being applied on the mop, while still being able to move
- Add soap
- Tubes inside robot will get dirty

• "cleaning the robot more like a nice puzzle, better than cleaning your house". She likes maintaining her motorcycle also for instance.

- Button interface is intuitive
- Keep water tank attached always, even when dry cleaning only

P9

- Identifies button correctly
- Ramp unclear
- Thinks you can wet clean without mop
- Squeegee for wet cleaning, water comes out nozzle
- Really misunderstands everything
- Understands front and back
- Puts ramp upside down on mop, cannot attach ramp
- Right side for clean water, does not know why
- Only tries to pull the brushes out, does not try to push from other side
- Very slow
- Tries to assemble all parts of the mopping module at the same time

MAINTENANCE

- Does use corner of DB lid. Recognizes the filter
- This on also thought the dust was collected above the filter, and all the dirty water below the filter
- Replaces filter every 2-4 weeks, based on daily dry clean

DISCUSSION

- Hide robot in washing machine room
- Dry 3 times / week
- Wet I time / week
- Can clean almost everything, except stains like wine
- Wants to be there when it is used
- Is not bothered if it would make as much sounds as a vacuum cleaner
- Wet clean ground floor more often
- Would carry robot upstairs to use it there
- No real preference for wet + dry or separate

MOST IMPORTANT TOPICS:

- Likes when it clicks, otherwise not sure it's connected XX
- Water on left part of tank XXXX
- Many holes where dust can accumulate
- Impossible to get wheels out, wants to take out to clean XXX
- Doesn't want to choose modes XXX
- Recognized on /off button XXXXXX
- Expected a main brush
- Mopping would be nice, but should avoid his carpet
- Uses robot at night (DRY) XX
- Thinks wet cleaning brushes will clean a lot XXX
- Idea: add a handle for going upstairs
- Letting the robot attach / detach mop by itself would be too expensive, only wet cleans once in a while
- Should clean itself like aquatrio
- Hairs gonna be stuck in brushes XX
- Extra functions like auto attach detach mop may not be worth the money XX
- Brushes could be used for dry cleaning to brush dust

