

Landslide Detection using Random Forest classifier

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P5 Final Thesis Presentation

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Outline

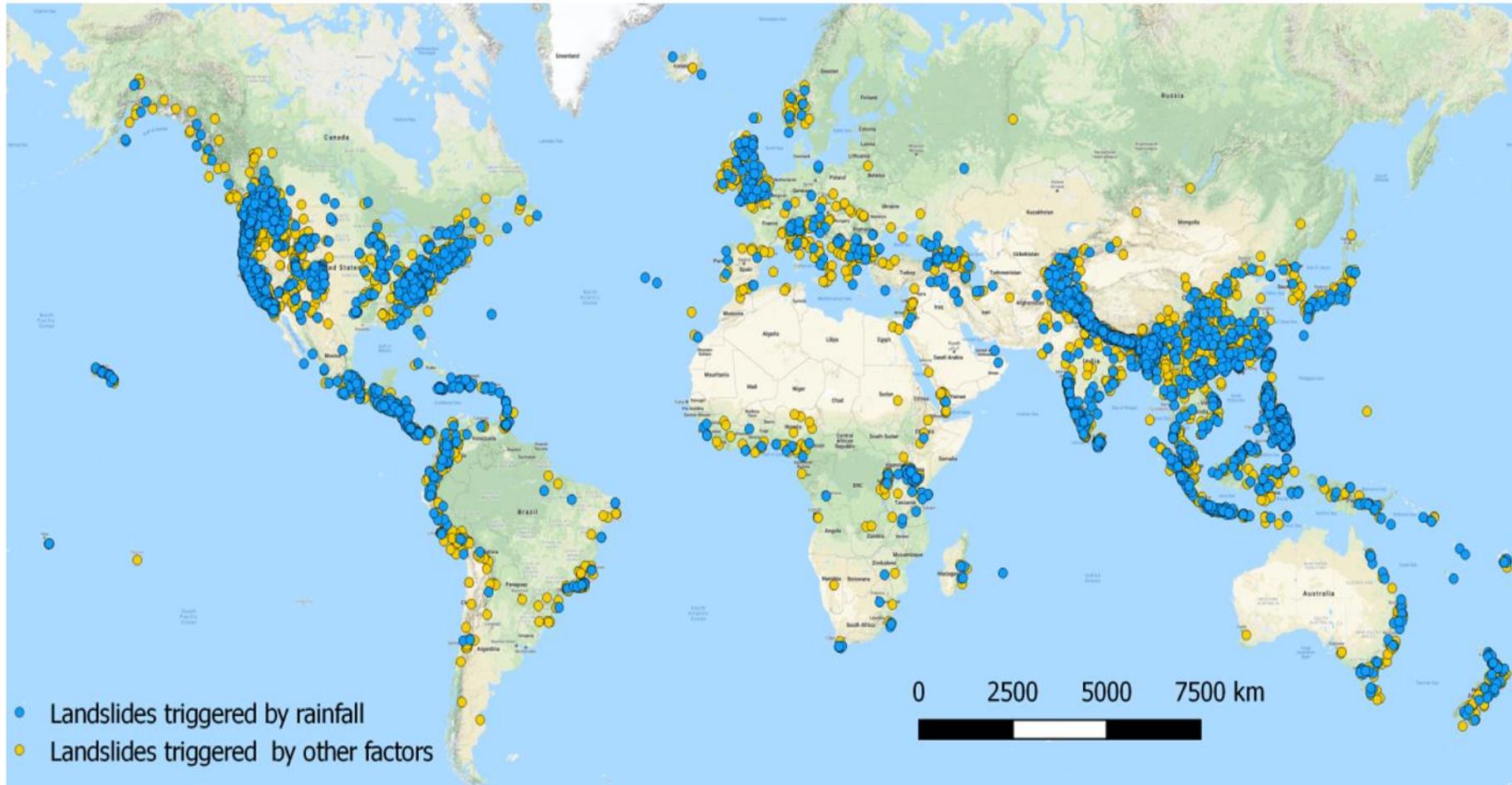
- Introduction
- Related works
- Methodology
- Results and discussions
- Conclusions and future works

Outline

- Introduction
- Related works
- Methodology
- Results and discussions
- Conclusions and future works

Motivation

NASA Global landslides Catalog (2007 – 2017)



~56.000 fatalities (2004-2016) (Froude and Petley, 2018)

Herrera, 2018

Motivation



Japan, 2018¹



New Zealand, 2016²

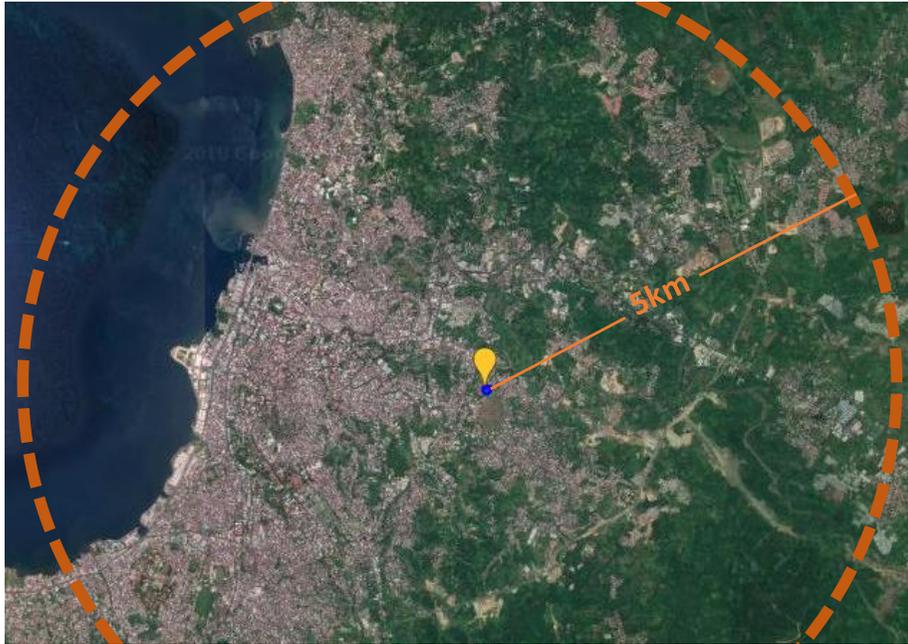


Sierra Leone, 2017³

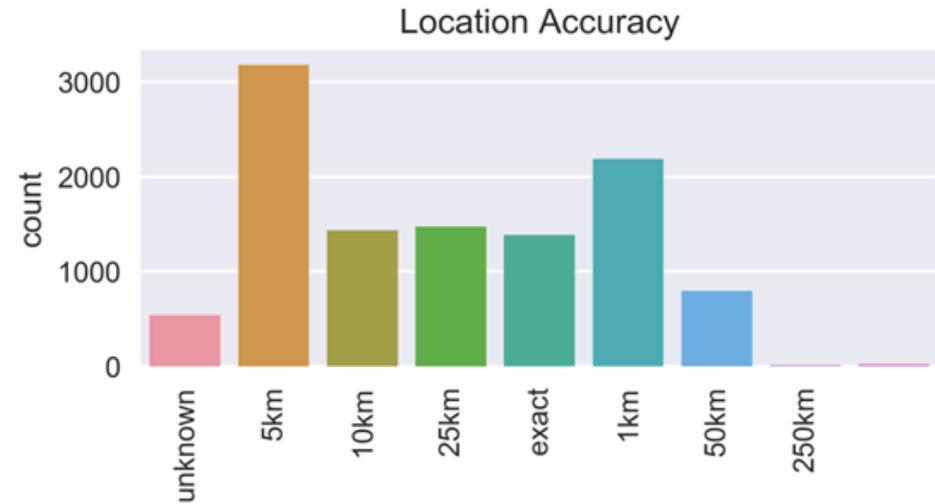


Colombia, 2017⁴

Motivation



Case study Manado-Indonesia



Landslides location accuracy (Herrera, 2018)

Main problem Landslide inventory maps (Accurate location)

Alternatives Public Earth-observation data

How? Machine Learning → automatic landslide detection

Research Questions

*How to detect landslides using
Machine Learning?*

Research Questions

- To what extent can landslides be detected using **Sentinel-2** in combination with **DEM**?
- What are the relevant **landslide diagnostic features**?
- What is the best **segmentation** strategy?
- How to exploit **features per pixels** to produce **feature per segments**?
- What is the most appropriate **Machine Learning technique**?
- What is the **accuracy** of the most appropriate Machine Learning technique?

New challenges

- Model generalization
- Multi-scale segmentation approach
- Applicability and re-usability

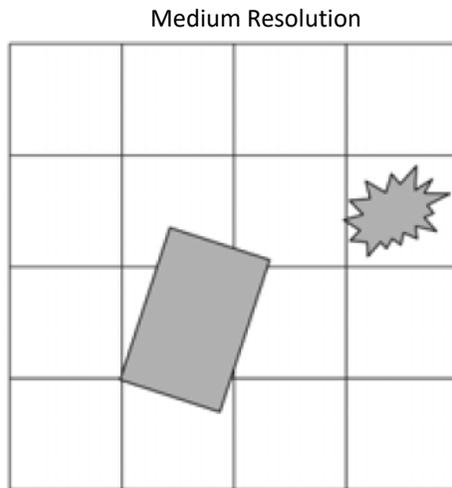
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Image classification techniques

Pixel-based

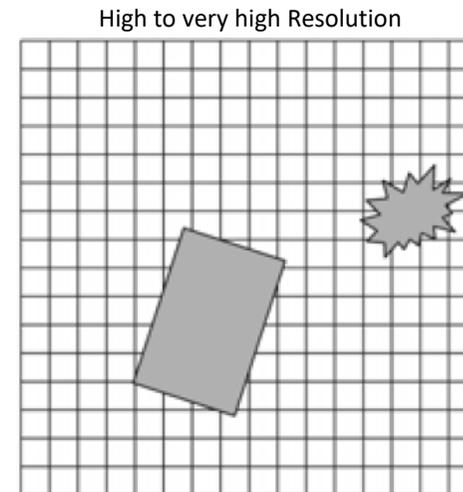
- ✓ The **pixel** is the object
- ✓ Each **pixel** belongs to a class



Blaschke (2010)

Object-based (OBIA)

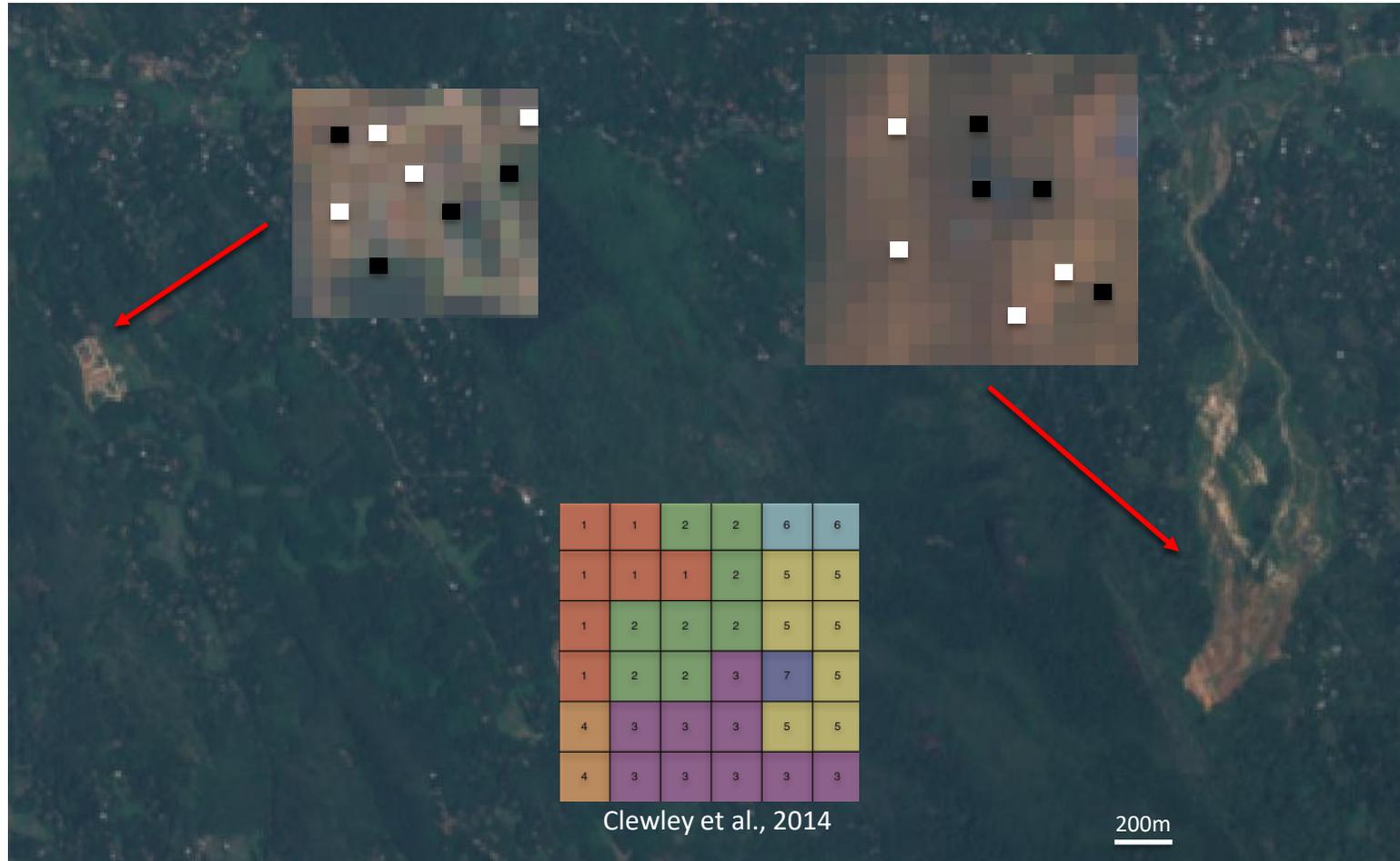
- ✓ The **segment** is the object
- ✓ Each **segment** belongs to a class



Blaschke (2010)

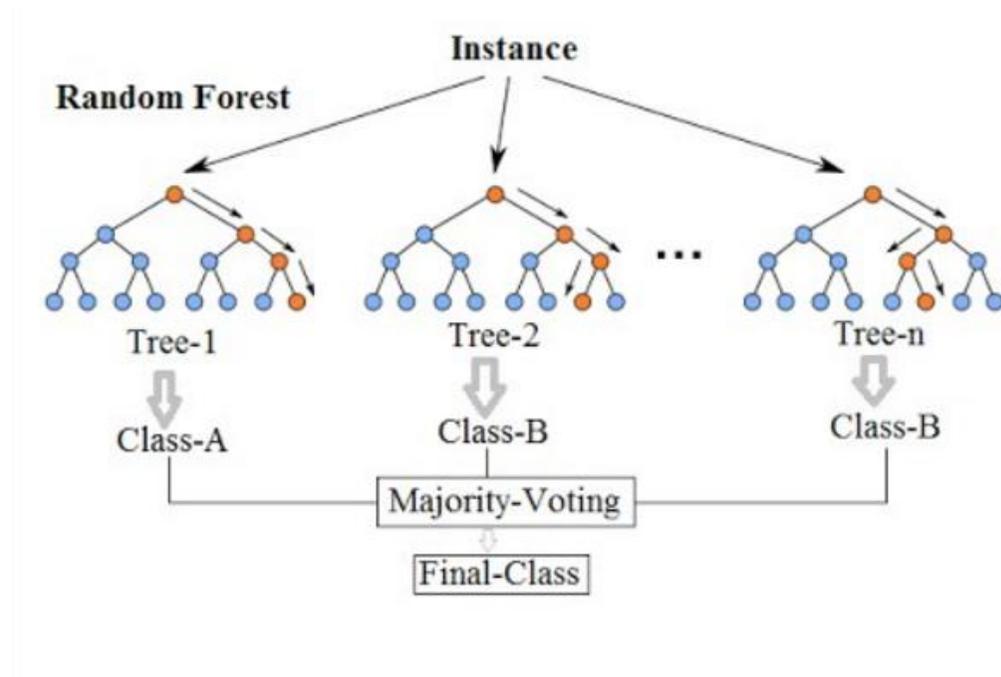
Why OBIA?

Spectral + spatial + contextual



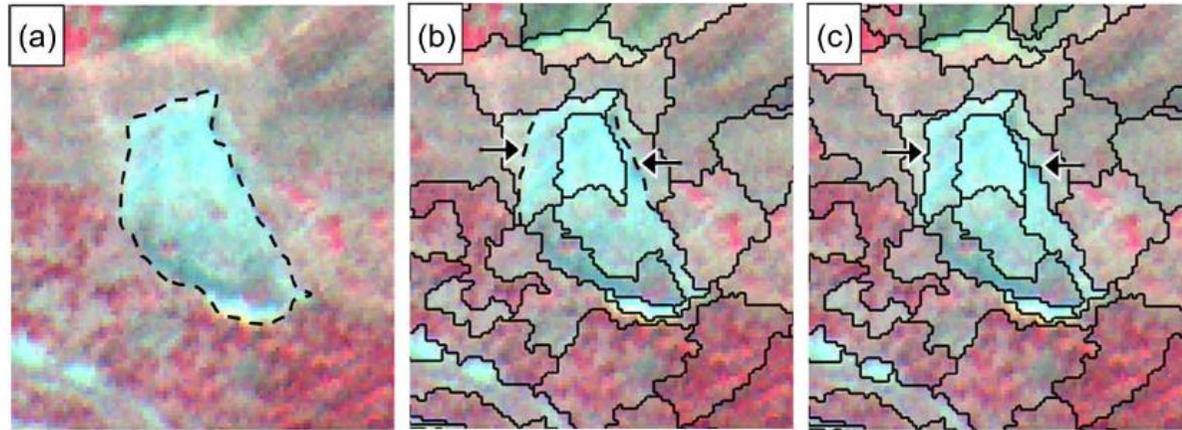
Supervised classification

Random Forest



Source image: <https://community.tibco.com/wiki/random-forest-template-tibco-spotfirer-wiki-page>

OBIA in the context of landslides



Martha et al. (2011)

Object-based classification

- Rule-based
- Rule-based
- Rule-based
- Machine Learning
- Machine Learning

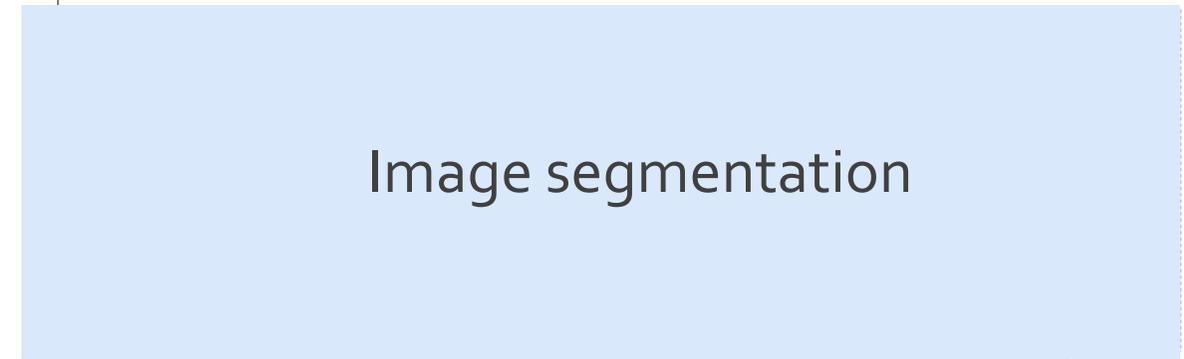
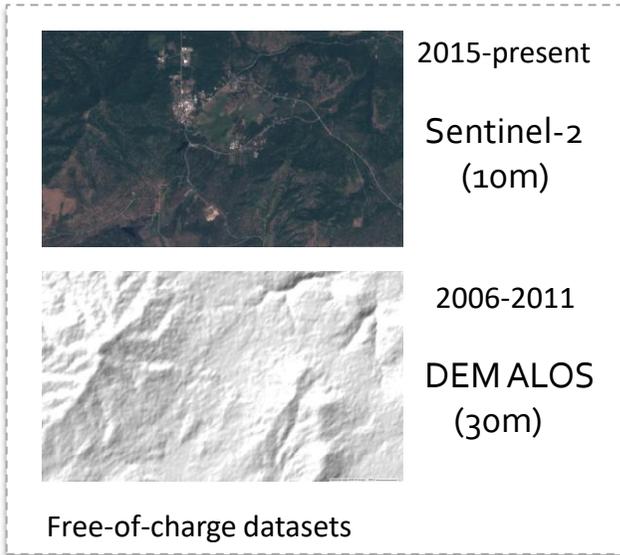
Author

- Martha et al. (2011)
- Blaschke et al. (2014)
- Holbling et al. (2015)
- Stumpf and Kerle (2011)
- Parker (2013)

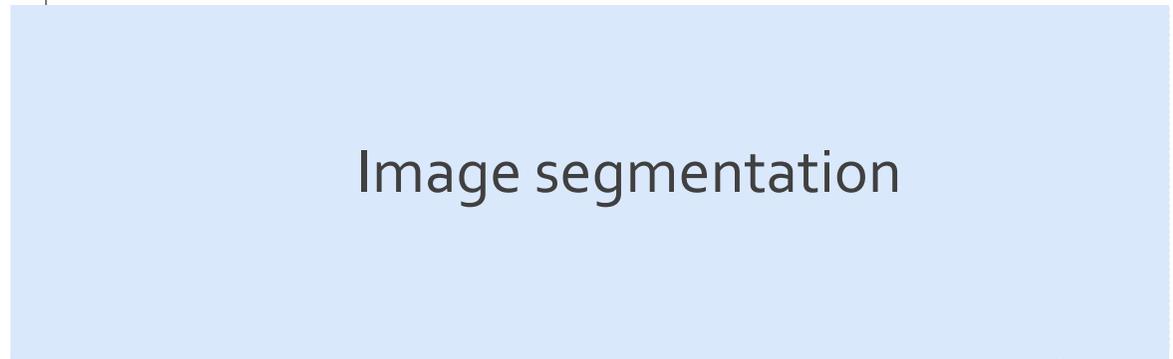
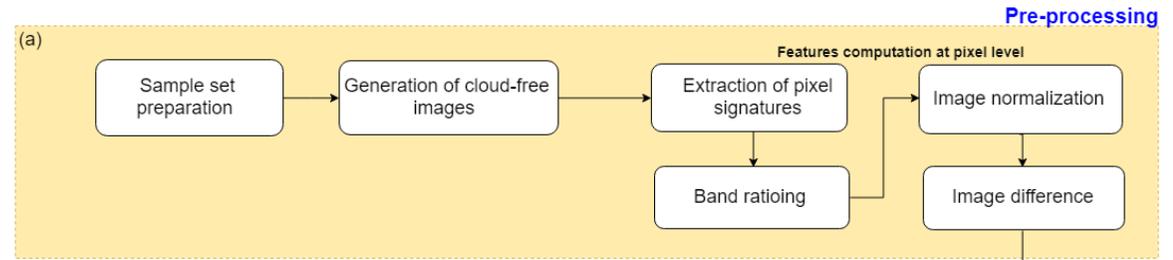
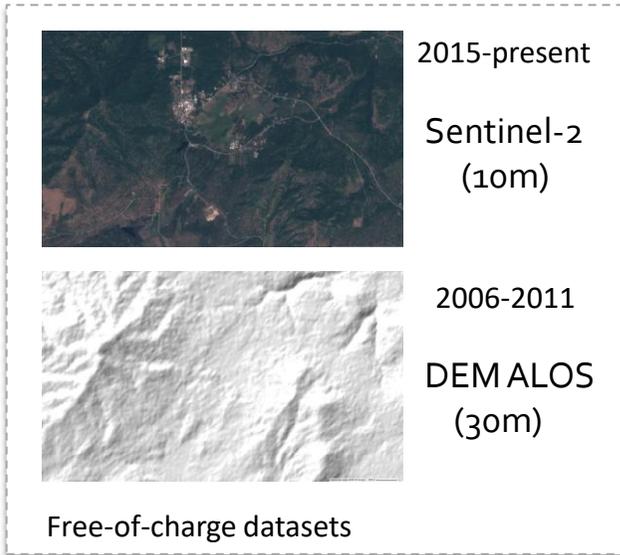
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Methodology overview



Methodology overview



Sample set preparation

Landslides events: 110

Satellite Images: 96 (32 post-event / 32 pre-event / 32 image difference)



Sample set preparation

Quality assessment

id	event_date	longitude	latitude	location_accuracy	landslide_trigger	size	country	# events	quality	land cover	Source
L0	2017-03-25	-76.66247976	1.169677465	exact	downpour	very large	Colombia	1	M1	Vegetated areas/ Urban	NASA Catalog
L1	2017-06-27	103.6529857	32.06849057	exact	continuous_rain	catastrophic	China	1	H1	Vegetated	NASA Catalog
L2	2017-08-14	-13.22985664	8.436115153	exact	unknown	very large	Sierra Leone	1	M1	Vegetated areas /Urban	Web resources
L3	2017-01-10	-65.46772261	-23.9134425	approximated	downpour	very large	Argentina	1	S1	Bare-lands	NASA Catalog
L4	2016-05-18	80.4319754	7.16080832	exact	monsoon	very large	Sri Lanka	2	M1	Vegetated areas	NASA Catalog
L5	2016-06-15	-117.2679	56.2246	approximated	downpour	large	Canada	1	S3	Croplands	NASA Catalog
L7	2016-11-27	101.613538	3.366921	exact	rain	large	Malasia	1	M2	Urban	NASA Catalog
L12	2017-02-09	-43.42657247	-20.24799736	exact	mining	very large	Brasil	1	H3	Wetlands	NASA Catalog
L17	2017-01-18	13.77821597	42.42921449	exact	earthquake	large	Italy	2	H3	Vegetated area	NASA Catalog
L25	2017-07-06	130.8207411	33.40312701	exact (major landslide)	tropical_cyclone	various	Japan	3	M2	Vegetated areas	Time series GEE
L41	2018-04-11	130.8966053	33.43075427	exact	unknown	large	Japan	1	H3	Vegetated areas	Web Resources
L55	2016-11-15	173.8168708	-42.20224732	bbox center	earthquake	large	New Zealand	2	H3	Vegetated areas	Web Resources

Description	C or S <15%	15%< (C or S) <40%	Scale
GL validated / catastrophic landslides/vegetated areas	H1	H3	H1
GL validated / very large landslides/vegetated areas	H2	M1	H2
GL validated / large landslides/vegetated areas	H3	M2	H3
GL validated / catastrophic landslides/ wetlands or croplands	H2	M1	M1
GL validated / very large landslides/wetlands or croplands	H3	M2	M2
GL validated / large landslides/wetlands or croplands	M1	M3	M3
GL validated / catastrophic landslides/vegetated areas and urban	H3	M2	S1
GL validated / very large landslides/vegetated areas and urban	M1	M3	S2
GL validated / large landslides/vegetated areas and urban	M2	S1	S3
GL validated /various size/barelands	S2	S2	
Uncertain Geographical Location + any of the above options	S3	S3	

Image set preparation

Processed images (GEE) > 1,500
~1TB

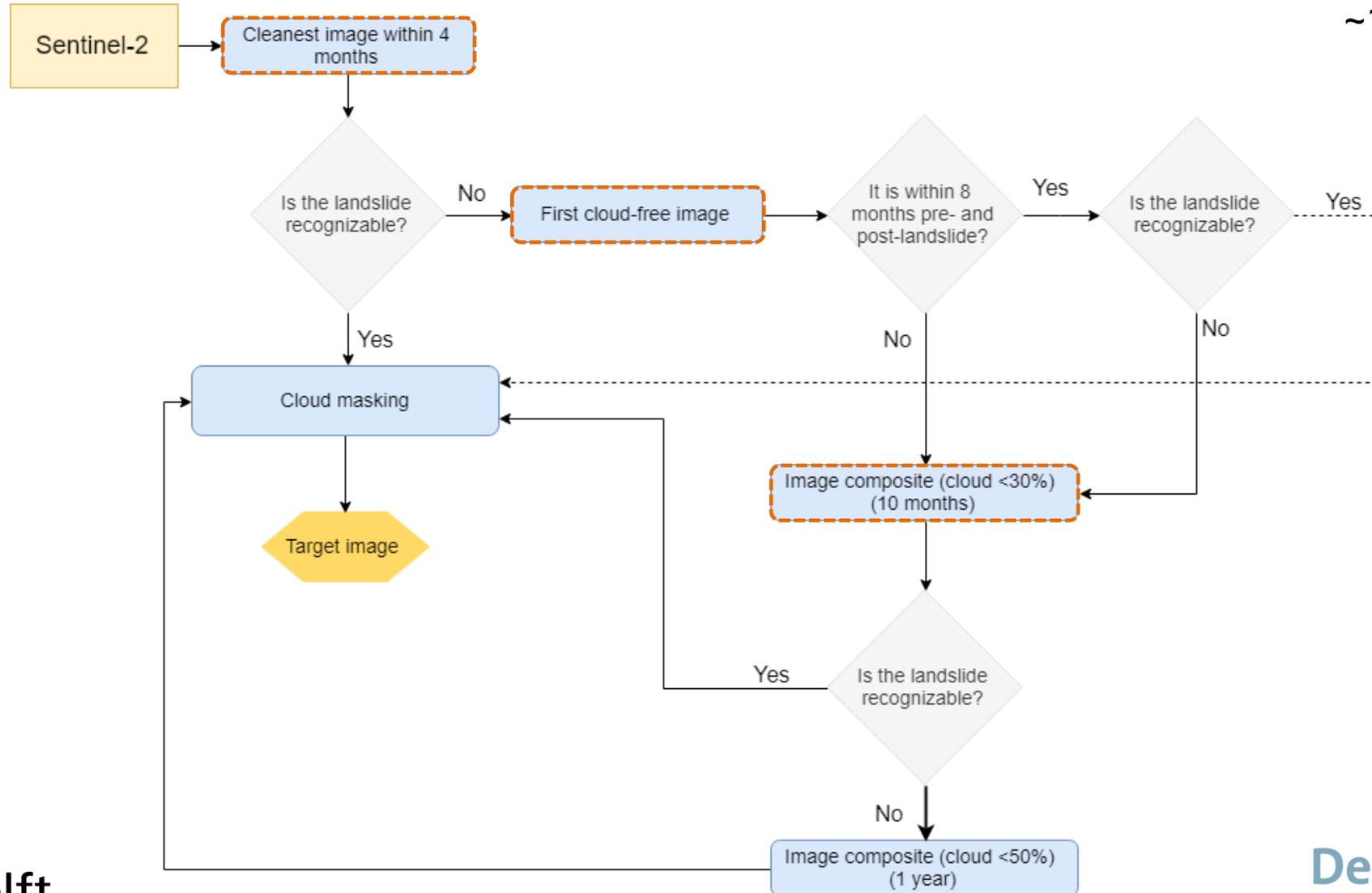
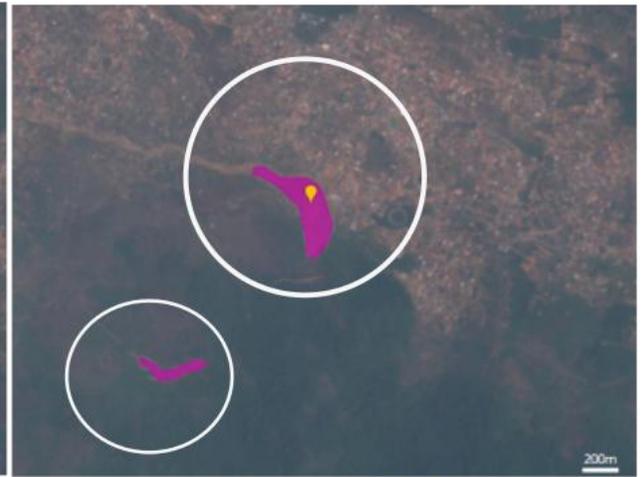
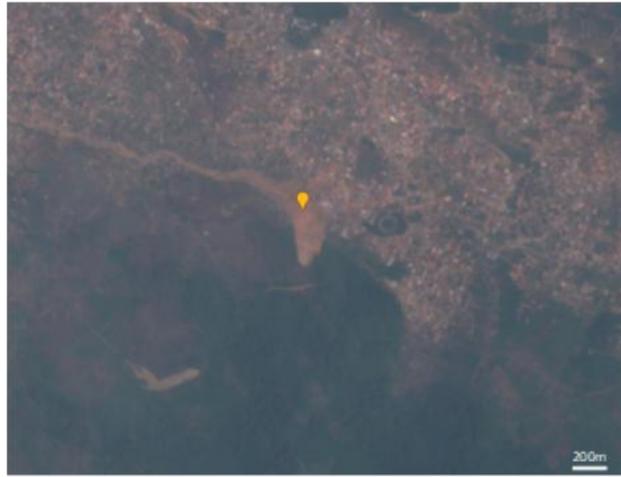
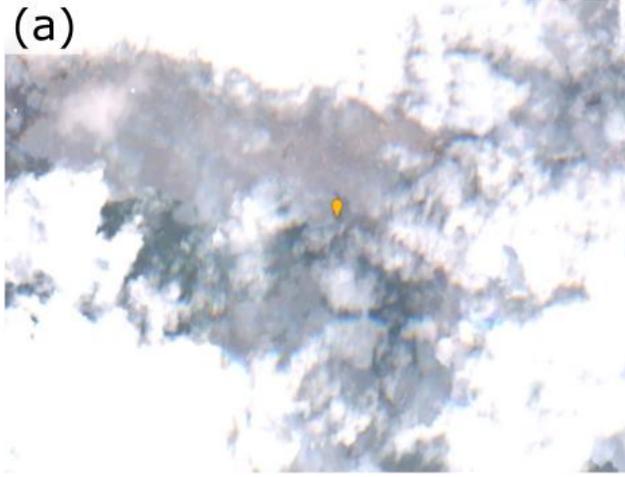
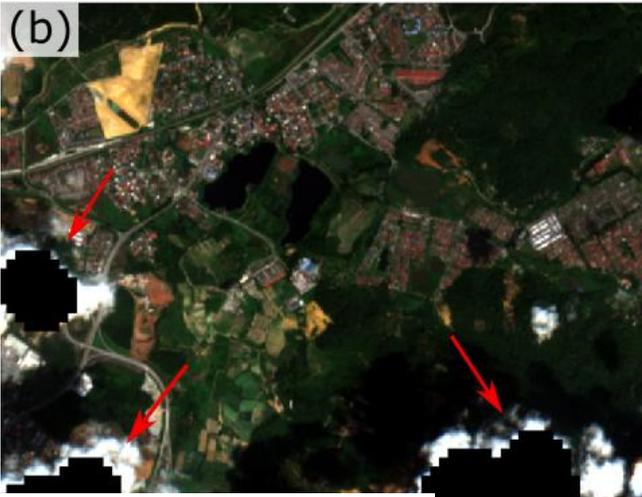


Image set preparation

(a)

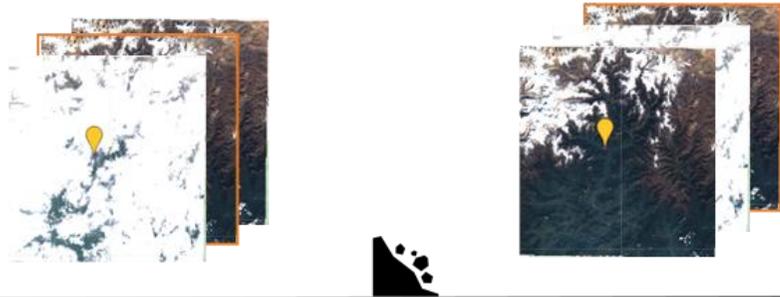


(b)



Features computation (RGD)

Cloud-free images



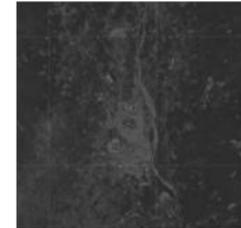
Pre-event

Post-event

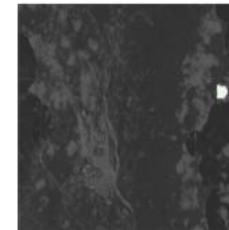


Band ratioing

$$rg(i, j) = \frac{gk(i, j)}{gl(i, j)} \quad (i, j) : i = 1, \dots, n; j = 1, \dots, m$$



Pre-event



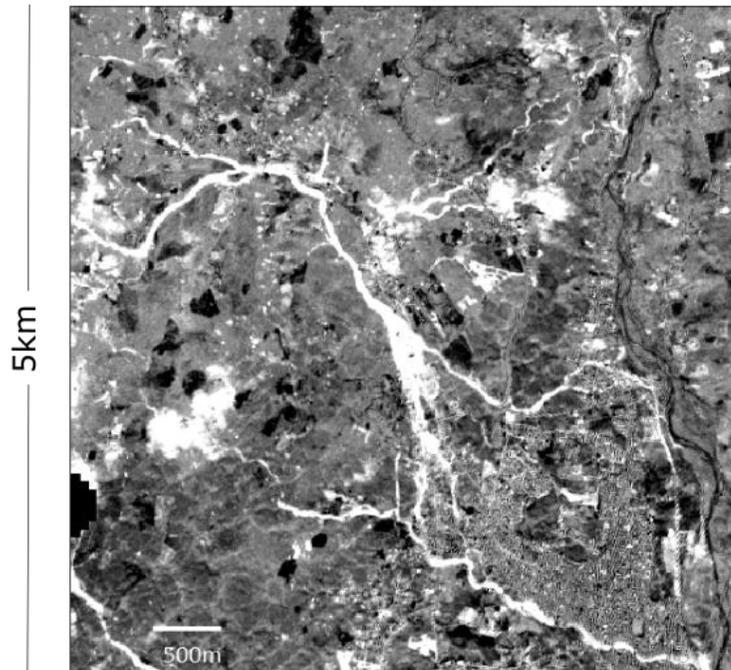
Post-event



Image difference

$$rgd(i, j) = rg(i, j)_{t_2} - rg(i, j)_{t_1} + c$$

$$(i, j) : i = 1, \dots, n; j = 1, \dots, m$$



5km

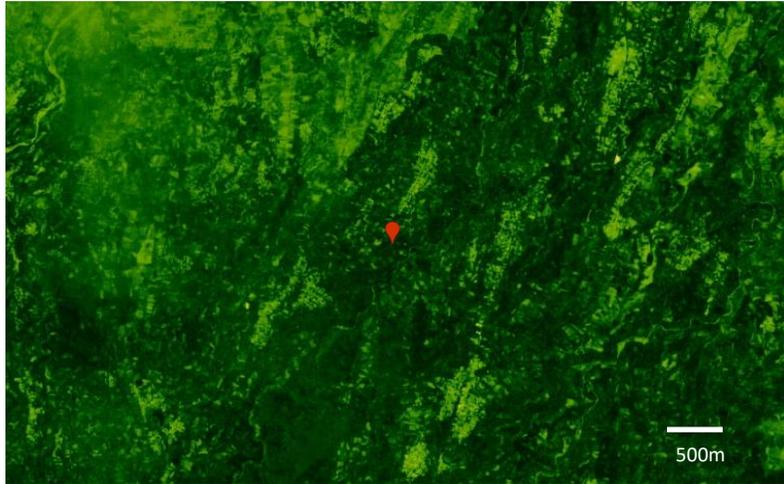
Feature:

Red/Green Difference (RGD)

Features computation (VID)

Image normalization

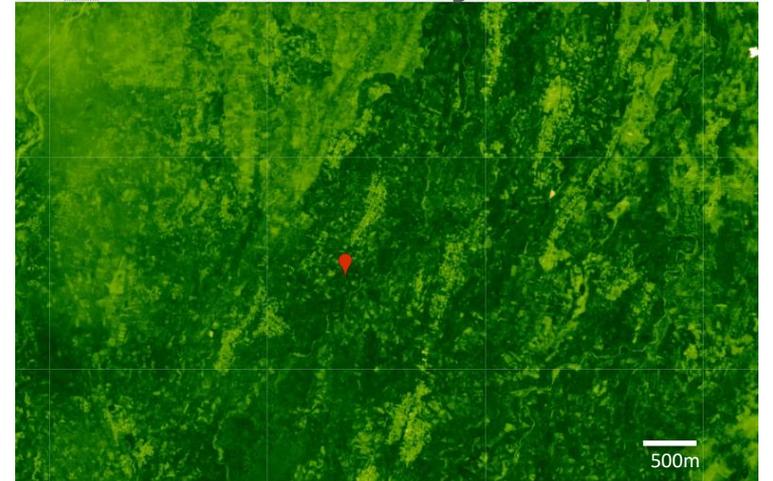
Original image (pre-event)



normalization



Image normalized (pre-event)



Original image (post-event)

Feature:

Vegetation index difference (VID)

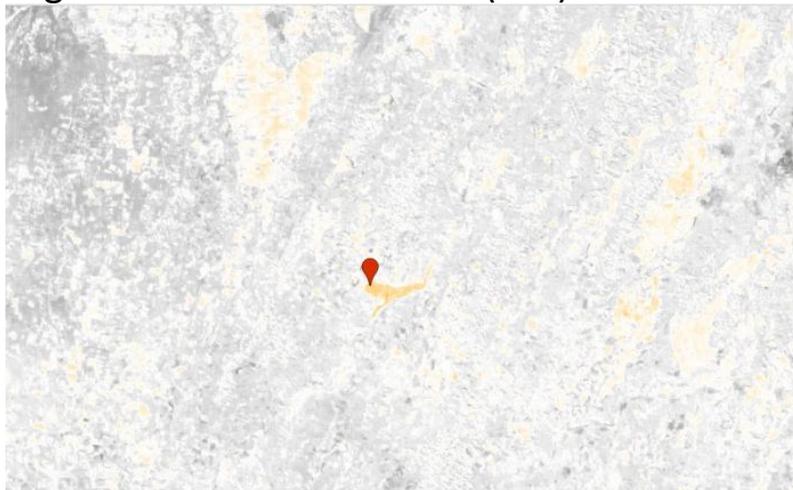
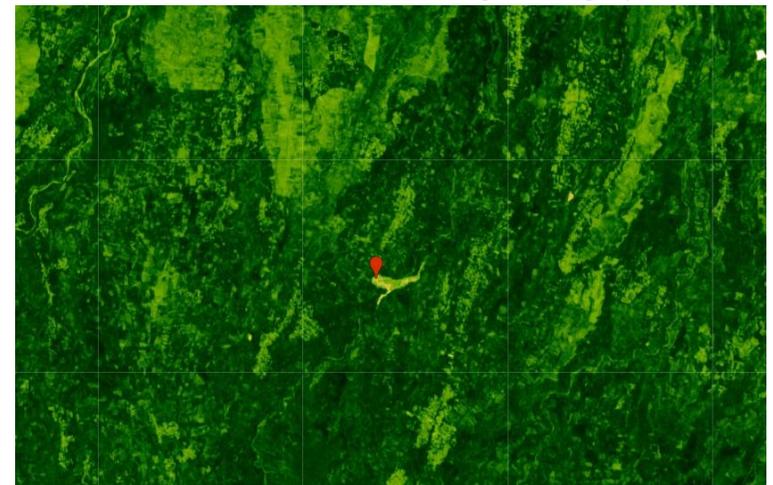
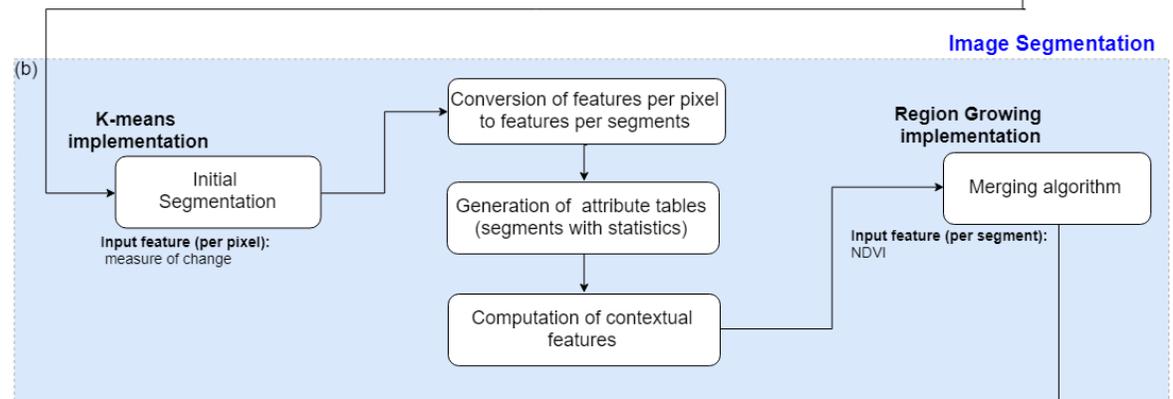
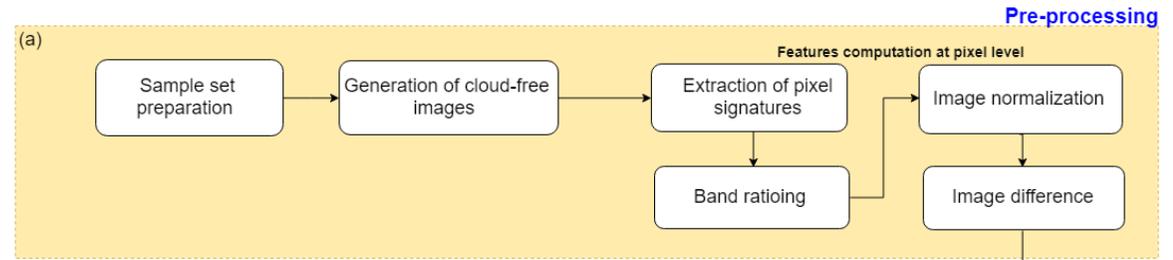
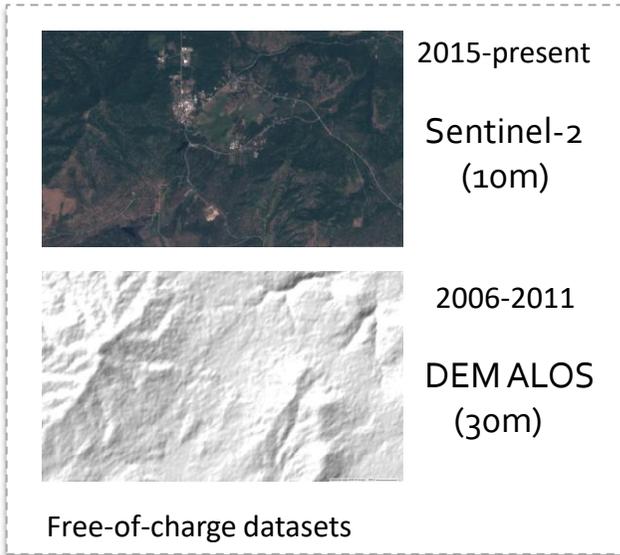


Image difference



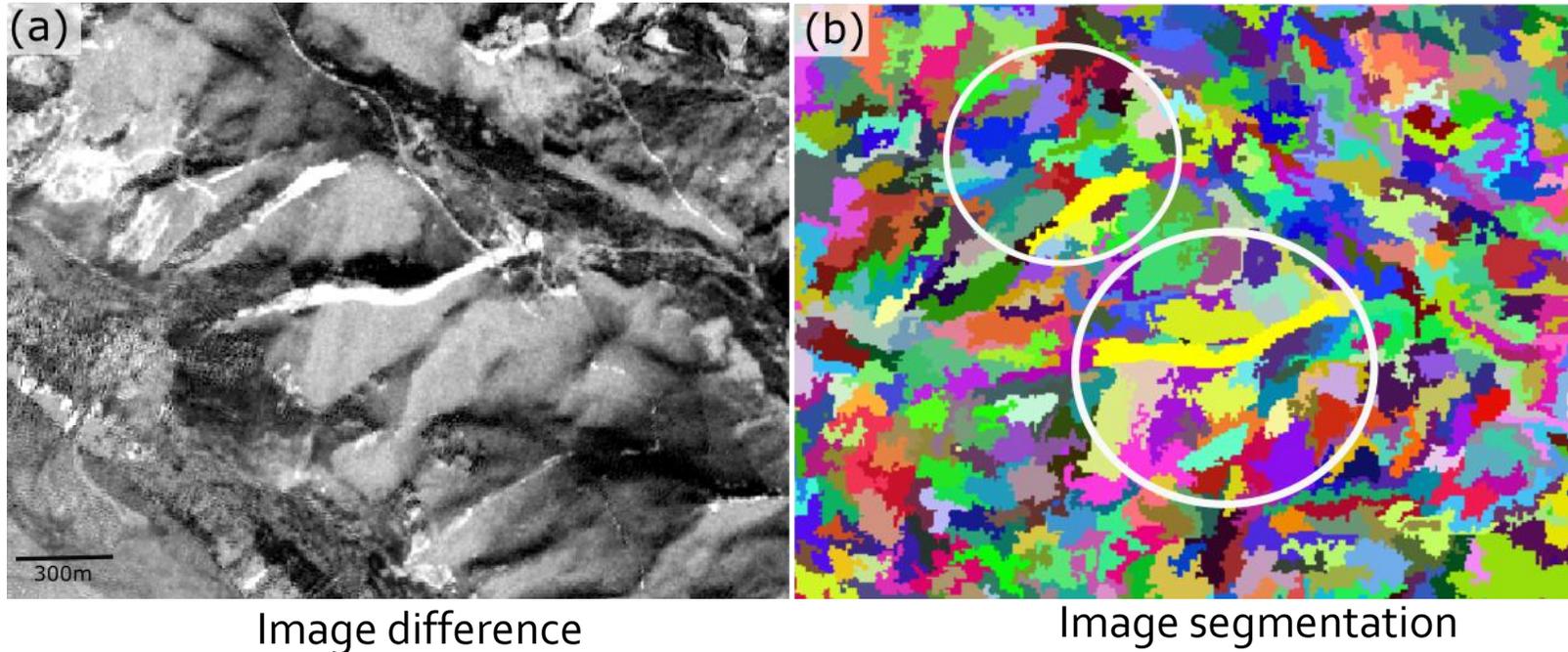
Methodology overview



Initial Segmentation

Feature: Red/Green Difference (RGD)

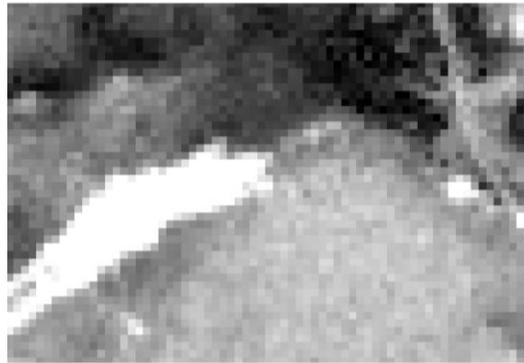
Segmentation algorithm: k-means Implementation (Shepherd et al. 2019)



To ensure segmentation of smallest landslides
(~100m x 100m)

- Initial K estimated using the Elbow method ($k = 8$)
- A unique K (for all images) adjusted to a higher value ($K=19$)
- Minimum number of pixels is fixed to $80px$

Pixels to Segments



Pixels



Segments

	NDVI	RGD	VID	BrightnessD	Slope_max	Slope_mean	Class	Class_name
518	0.23	0.66	0.09	-0.24	20.07	16.12	0	no_landslide
519	0.64	0.60	0.13	-0.23	33.86	23.62	0	no_landslide
520	0.51	0.54	0.09	-0.24	7.21	5.11	0	no_landslide
521	0.67	0.44	0.03	-0.09	38.45	33.62	0	no_landslide
522	0.54	0.62	0.17	-0.28	8.73	5.96	0	no_landslide
523	0.68	0.37	-0.08	-0.09	5.62	5.62	0	no_landslide
524	0.61	0.39	0.01	-0.03	7.44	4.85	0	no_landslide
525	0.61	0.49	0.03	-0.14	16.55	9.48	0	no_landslide
526	0.66	0.44	0.00	-0.23	11.14	7.94	0	no_landslide
527	0.20	0.85	0.49	-1.13	20.28	6.31	1	landslide
528	0.56	0.30	-0.05	0.05	7.44	5.97	0	no_landslide
529	0.60	0.54	0.06	-0.15	27.11	22.16	0	no_landslide
530	0.67	0.56	0.06	-0.20	4.98	2.55	0	no_landslide
531	0.67	0.42	-0.01	-0.12	16.15	7.37	0	no_landslide
532	0.31	0.81	0.30	-0.47	16.62	13.85	0	no_landslide
533	0.61	0.48	0.04	-0.15	33.58	15.74	0	no_landslide
534	0.60	0.51	0.05	-0.20	11.89	9.74	0	no_landslide
535	0.37	0.39	0.23	0.06	7.03	3.44	0	no_landslide
536	0.63	0.52	0.04	-0.21	31.36	13.93	0	no_landslide
537	0.61	0.36	-0.15	-0.07	4.98	4.98	0	no_landslide

Features at segment level

Segment level

Feature nature	Feature	Statistics per segment
Spectral	NDVI	mean
Spectral	GNDVI	mean
Spectral	Brightness	mean
Spectral	RGD	mean
Spectral	VID	mean
Spectral	BrightnessD	mean
Textural	NDVI _{texture}	mean
Spatial	Slope	mean, maximum
Spatial	Relative relief	mean
Contextual	RGD _{deviation}	mean
Contextual	VID _{deviation}	mean
Contextual	BrightnessD _{deviation}	mean

Final landslides diagnostic features

Initial Segmentation

Challenge → multi-scale objects

- ✓ Over-segmentation of *non-landslides* cases
- ✓ Extremely imbalanced dataset
- ✓ Classifier biased toward the majority class
- ✓ Poor performance for the landslide case

Merging algorithm

Merging algorithm: region growing at segment level

Key Considerations:

- ✓ Criteria for **seed** selection
- ✓ **Feature** to define homogeneity
- ✓ **Threshold** of homogeneity

Homogeneity criterion

Feature: NDVI

$$Sm = | \overline{ndvi}_{ws} - ndvi_{nb} |$$

If $Sm < t$, segments are merged



Post-event image



Image difference



Initial segmentation

Homogeneity criterion

Challenge

Different


Images

Types of landslides

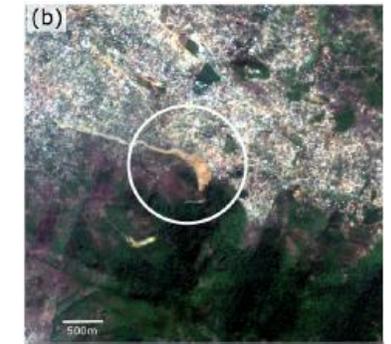
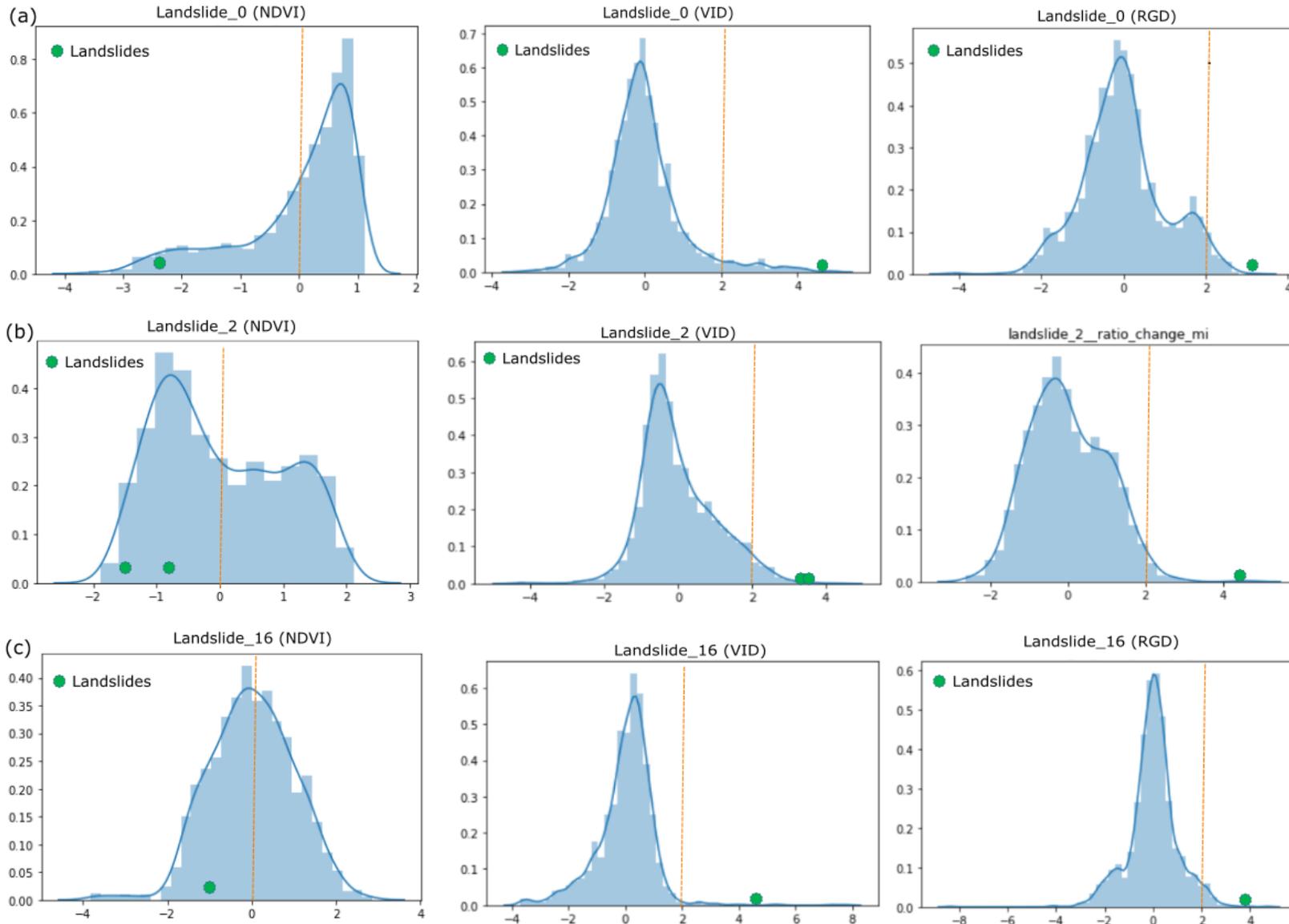
Geomorphological settings

Seasons

Atmospheric conditions

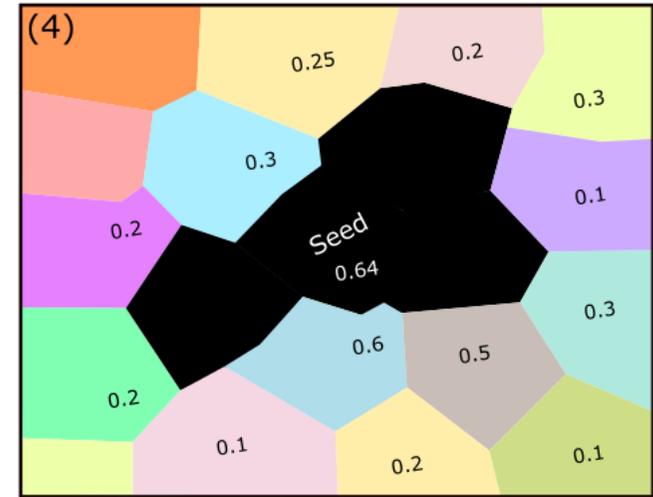
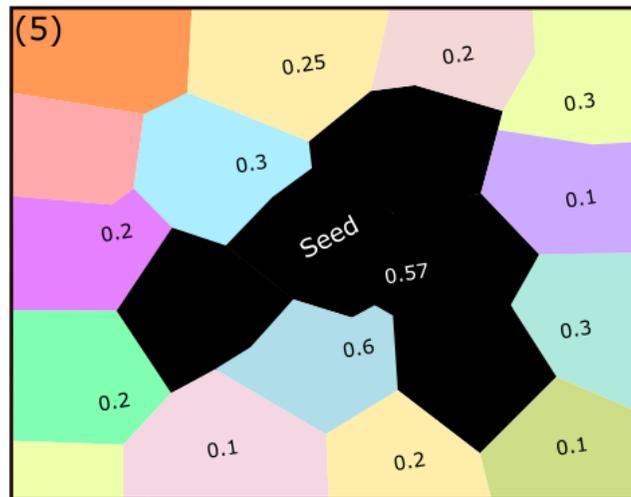
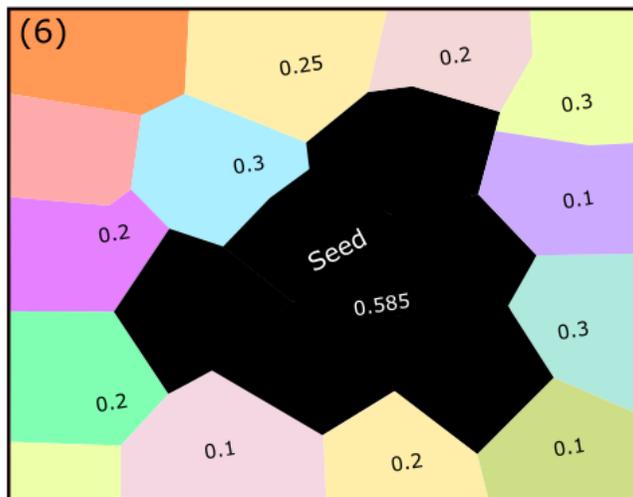
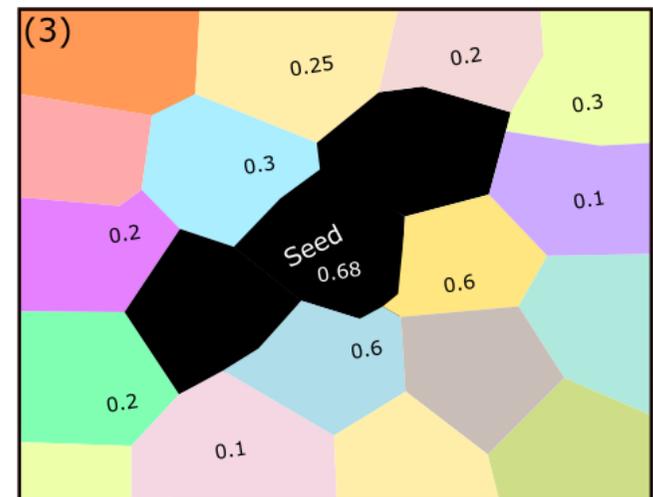
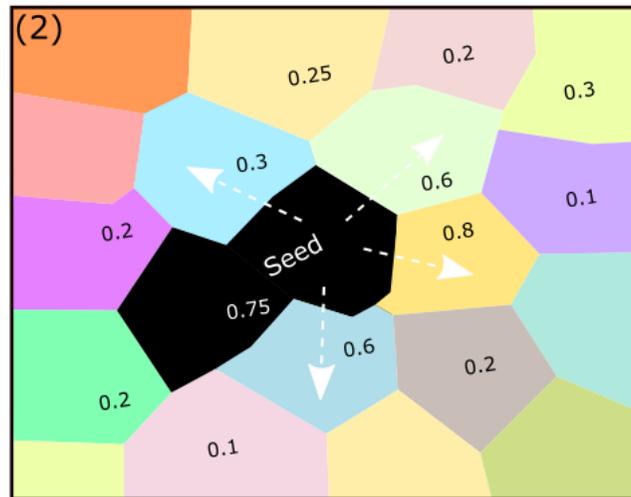
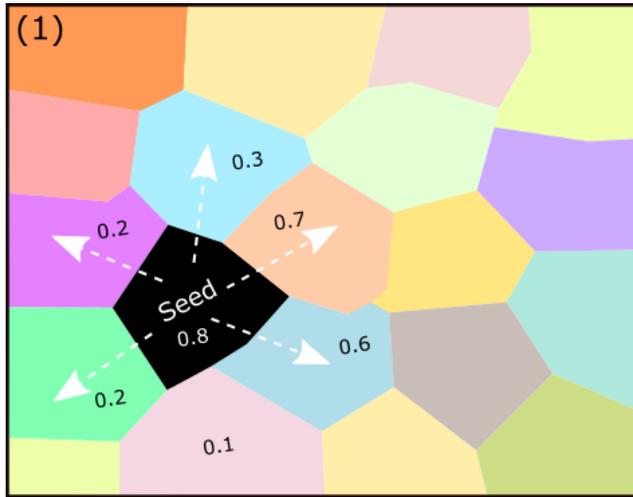
How to define a threshold of similarity for all images ?

Homogeneity criterion



Region growing

Input Data: List of the Segments
Output Data: List of Regions

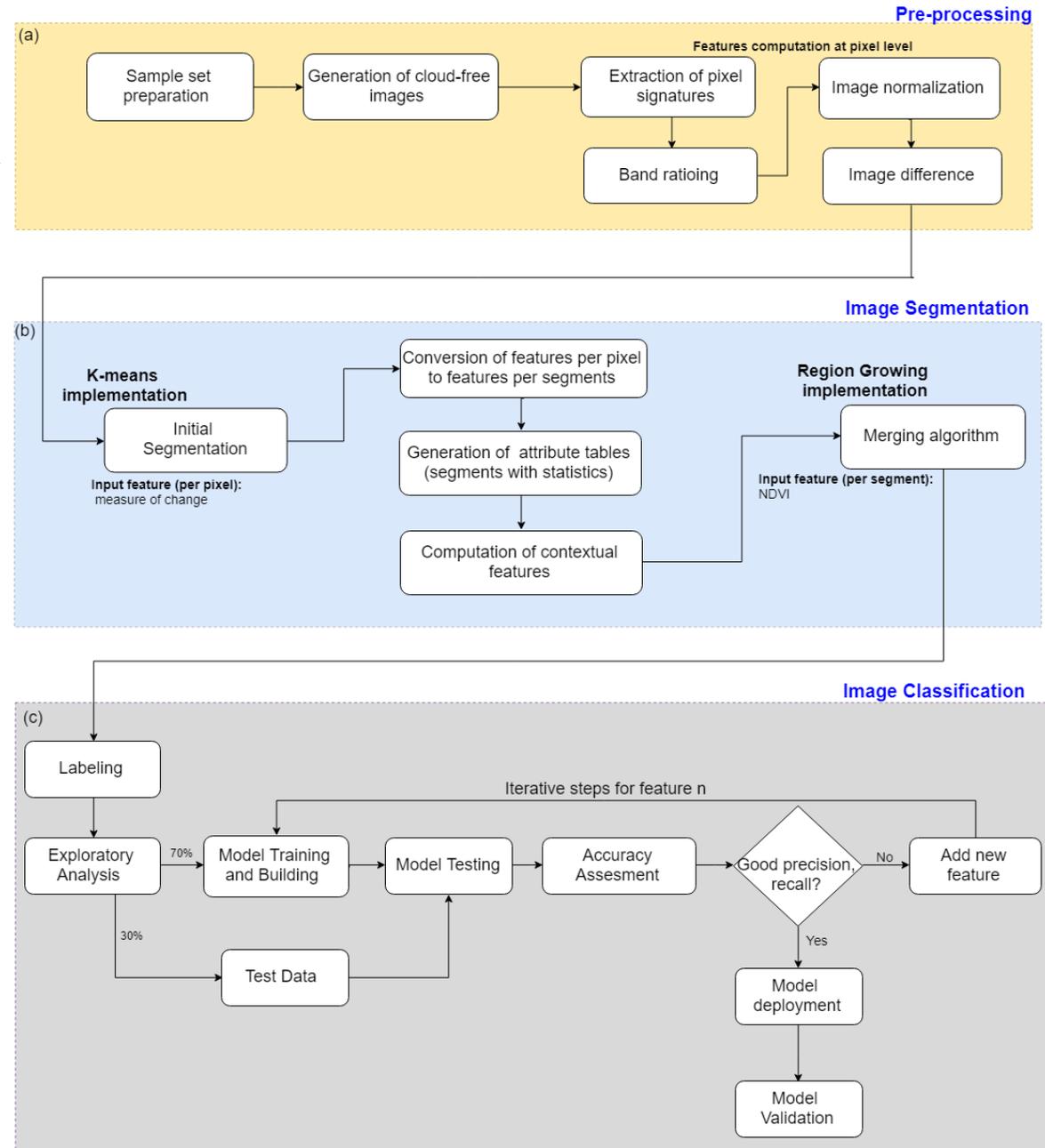


Methodology overview

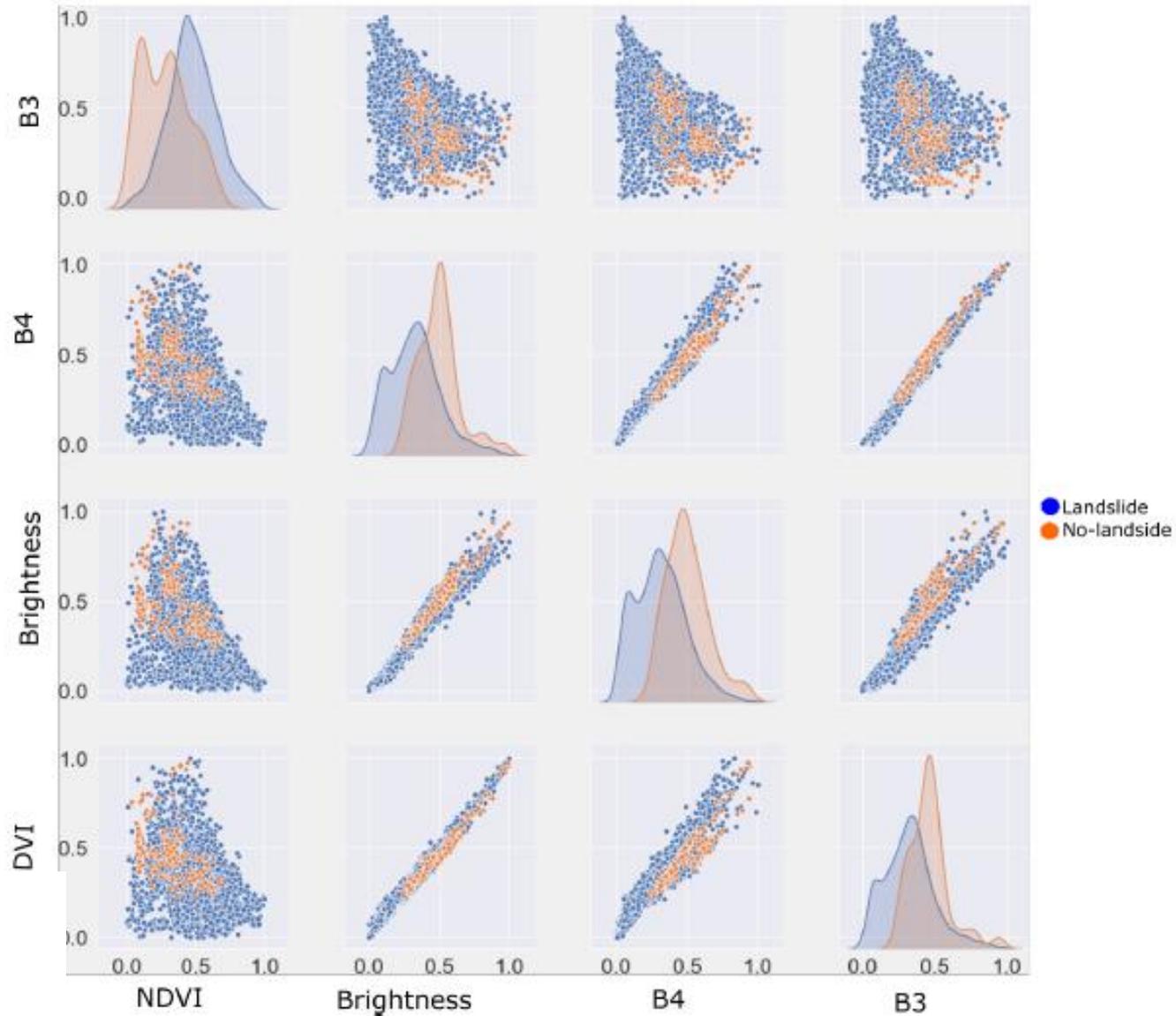
2015-present
Sentinel-2
(10m)

2006-2011
DEM ALOS
(30m)

Free-of-charge datasets



Exploratory analysis



Model training and building

Landslide diagnostic features

Ranking	Feature
1	NDVI
2	RGD _{deviation}
3	BrightnessD _{deviation}
4	VID _{deviation}
5	Brightness
6	Slope_mean
7	GNDVI _{deviation}
8	Slope_max
9	NDVI _{texture}
10	Relative_relief

Initial ranking of features

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Segments optimization

Coarse threshold	Segments	Reduction	missed	Error
0.1	7296	82%	11	5%
0.2	2749	93.3%	16	8%
0.3	1653	96.3%	24	13%

+ fine threshold = 0.05

K-means

non-landslides segments: 56,563

Ratio 1:225

Merging algorithm

non-landslides segments: 2,749

93.3 %

Ratio 1:14

Model training and building

Total segments = 2,905

landslides = 199

non-landslides = 2,706

Ratio 1:14

Training (70%)

non-landslides = 1,899

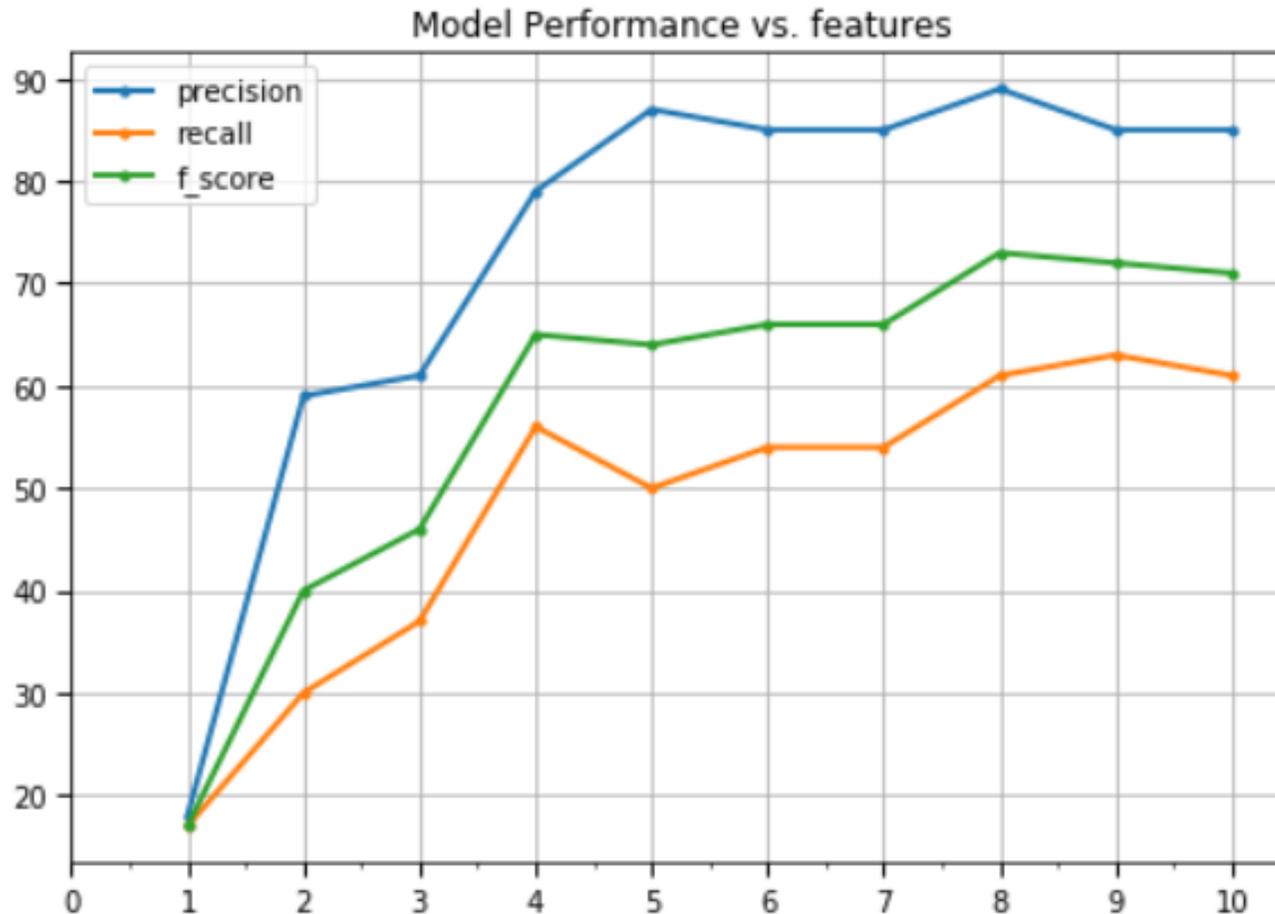
landslides = 134

Testing (30%)

non-landslides = 807

landslides = 65

Model performance

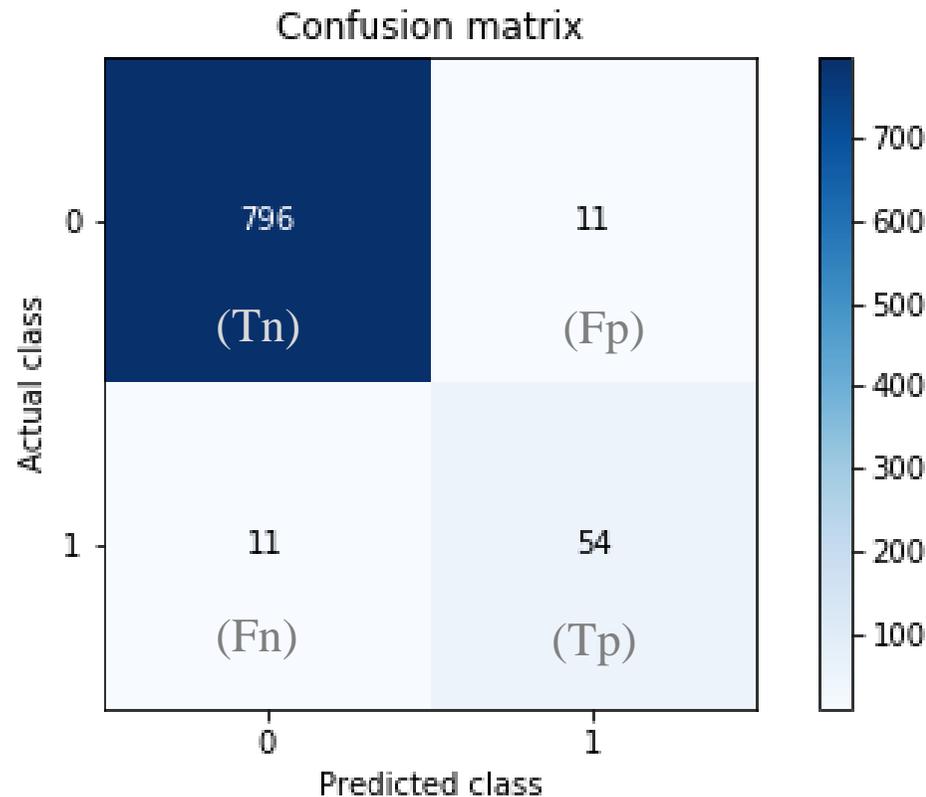


Ranking	Feature
1	NDVI
2	RGD _{deviation}
3	BrightnessD _{deviation}
4	VID _{deviation}
5	Brightness
6	Slope_mean
7	GNDVI _{deviation}
8	Slope_max
9	NDVI _{texture}
10	Relative_relief

Model performance

landslide = 1

non-landslide = 0



Target class: *landslide*

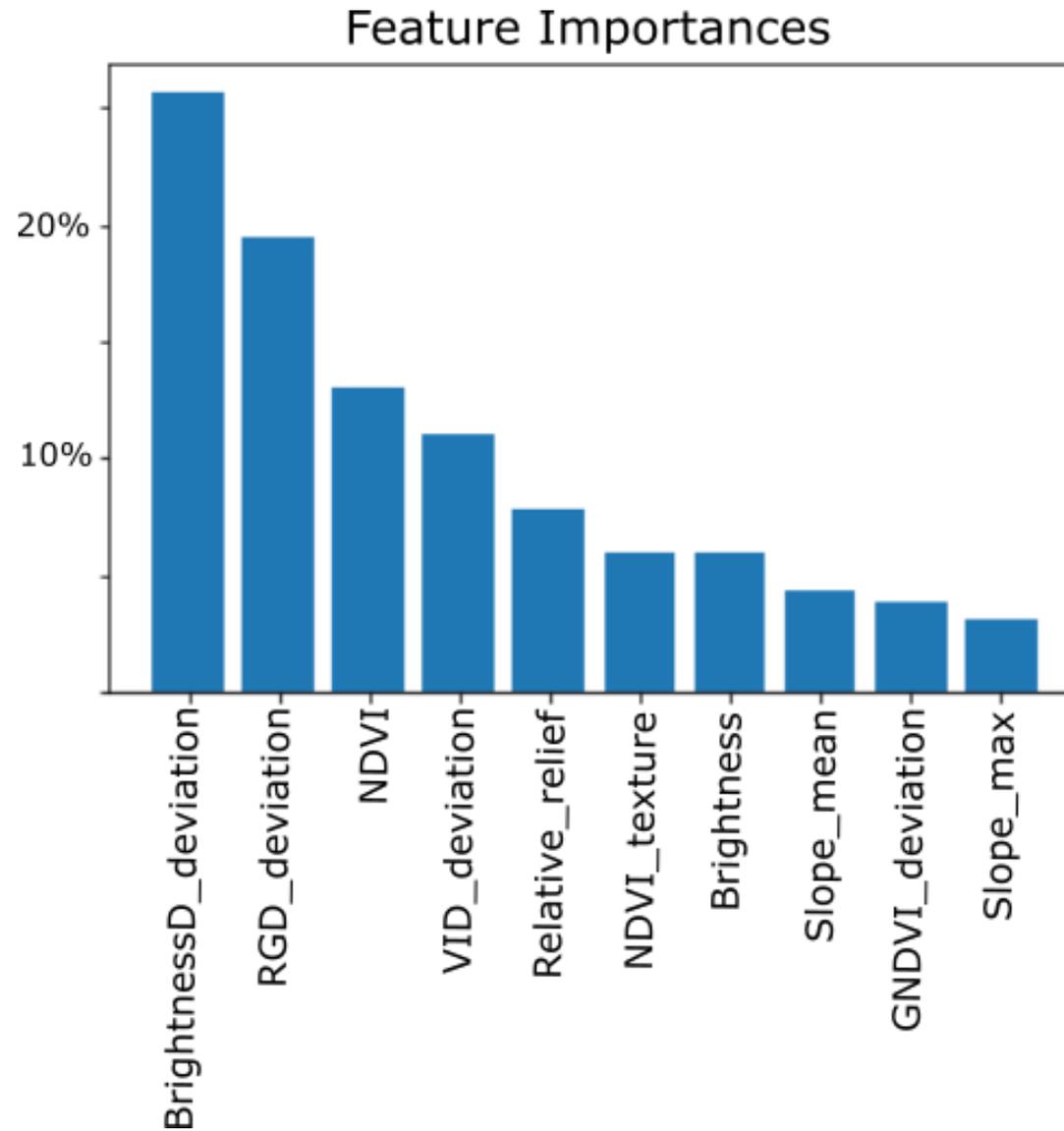
$$Precision = \frac{\mathcal{T}_p}{\mathcal{T}_p + F_p} = 0.83$$

$$Recall = \frac{\mathcal{T}_p}{\mathcal{T}_p + F_n} = 0.83$$

$$\mathcal{F}1 = 2 \cdot \frac{precision \cdot recall}{precision + recall} = 0.83$$

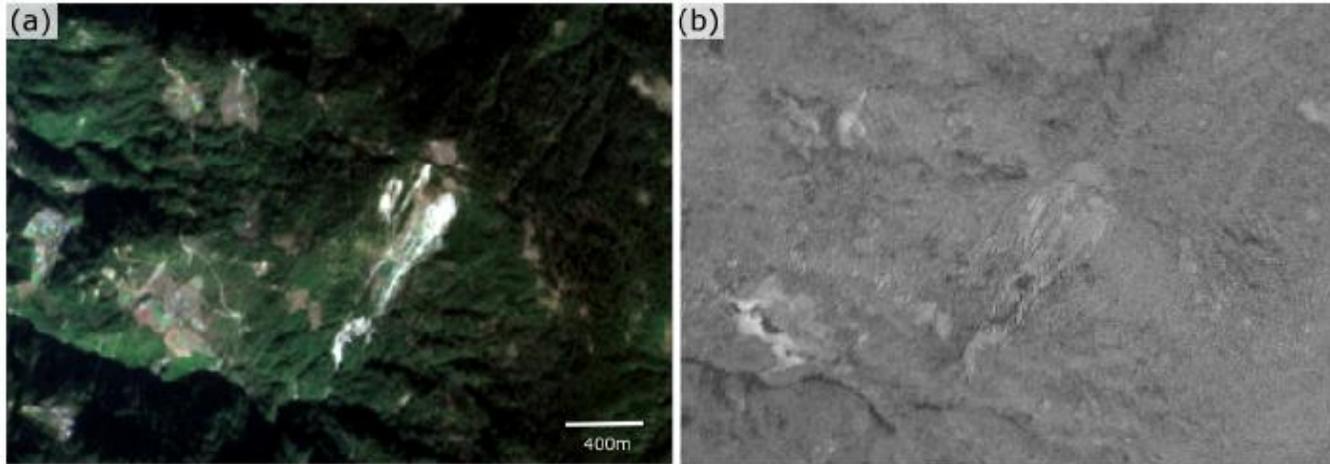
Model performance

Final ranking of features

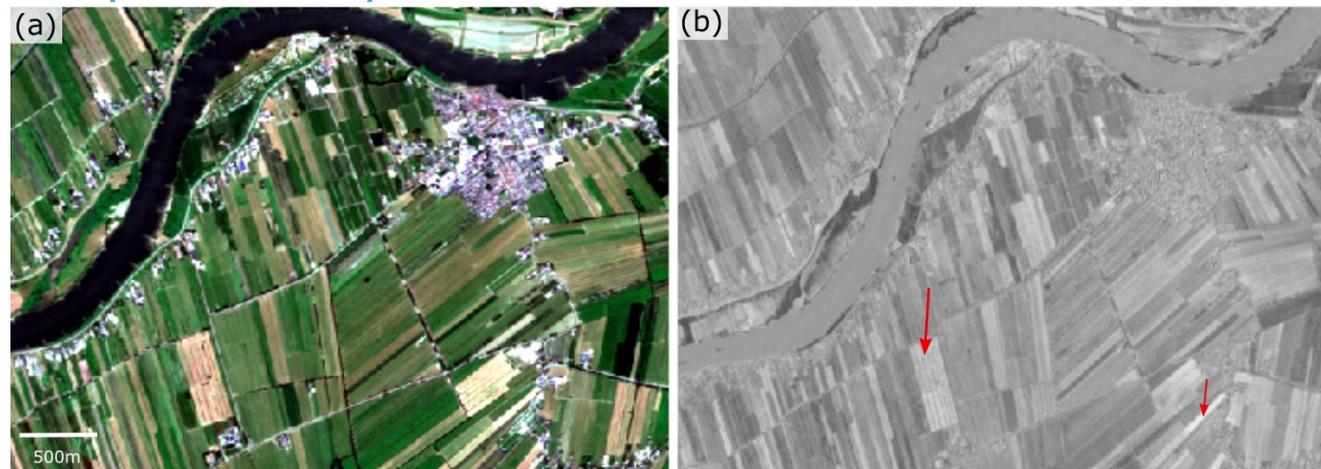


Model validation

(1) Ancient landslides

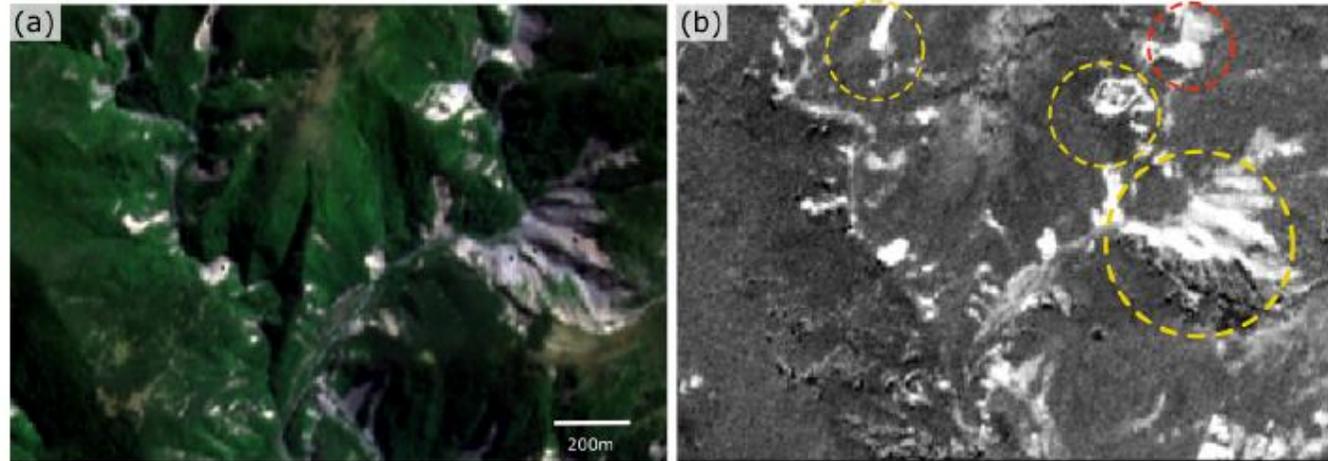


(2) Area with non probability of landslides

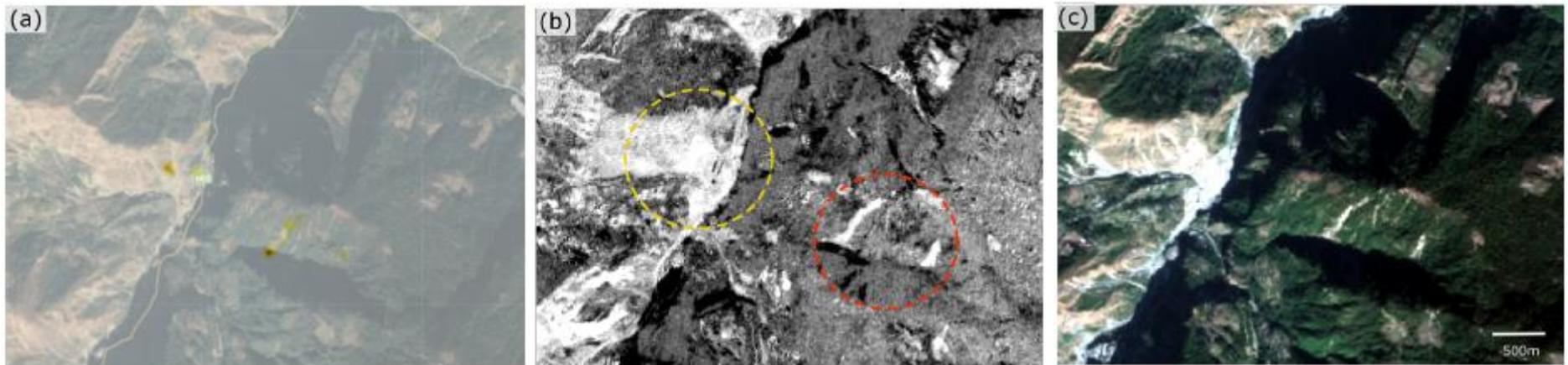


Model validation

(3) Fresh landslides



(4) Nepal case study



NASA tool

Our tool

Out tool

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- Introduction
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Conclusions

How to detect and locate landslides using Machine Learning?

- To what extent can landslides be detected using Sentinel-2 in combination with DEM?

Landslides **can be detected** using features derived from the spectral information of Sentinel-2 and topographic features from global DEM.

Conclusions

- What are the relevant landslide diagnostic features?

1. BrightnessD <i>deviation</i>	26%
2. RGD <i>deviation</i>	19%
3. NDVI	13%
4. VID <i>deviation</i>	12%
5...10 Rest of the features	<10% each

Conclusions

- What is the best segmentation strategy?

Initial Segmentation
(Red/Green difference)



Detailed segmentation of landslides

Merging algorithm
(NDVI)



To balance the dataset (reduce the number of non-landslides cases)

Conclusions

- How to exploit features per pixels to produce features per segments?
 - ✓ Features at **pixel level** are grouped into **segments**
 - ✓ Statistical measures: mean and maximum

Mean  all features

Maximum  slope

Conclusions

- What is the most appropriate Machine Learning technique?

Random Forest

- ✓ Non-parametric
- ✓ Best performance in OBIA
- ✓ Non-complex implementation
- ✓ Few tuning parameters
- ✓ Can handle imbalanced datasets

Conclusions

- What is the accuracy of most appropriate Machine Learning technique?
 - ✓ Precision = 83%
 - ✓ Recall= 83%
 - ✓ F1-score= 83%

Conclusions

- First attempt of a general method to detect landslides
- Semi-automatic method
- Applicable and re-usable
- Able to work with mixed-landcover (urban-vegetated)
- Limitations in areas with perennial snow, high sedimentation rates, regions with non-vegetation.

Future works

- Increase the number of training samples
- Remove redundant information
- Apply similar methodology to extract features from SAR images
- Explore an strategy to include automatic derived thresholds

Thanks for your attention!

Questions ?

Tools

Storage

PostgreSQL



Google fusion tables

Pre-processing

Google Earth Engine



Processing



GDAL



NumPy



scikit learn



RSGISLib



Visualization



Source code: https://github.com/mhscience/landslides_detection