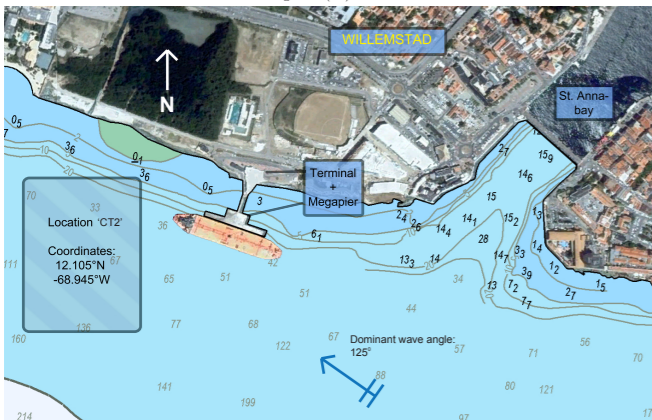
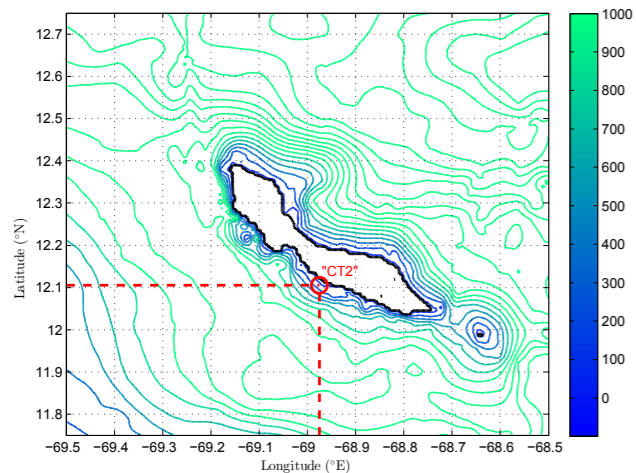


### Chapter 2: Analysis

Project Location: Port Facilities & Current Situation



Deep Sea Wave Climate

BMT ARGOS: Wind waves & Swell waves at Deep Sea

Wave Scatter Diagrams from Dataset with Wind Sea Waves:  
Significant Wave Height vs. Wave Direction

| Hs - Significant Wave Height [m] | Wave Direction [deg] |    |    |    |     |     |     |      |      |      |     |     |    |    |    |    | # | % |
|----------------------------------|----------------------|----|----|----|-----|-----|-----|------|------|------|-----|-----|----|----|----|----|---|---|
|                                  | 0                    | 3  | 6  | 9  | 12  | 15  | 18  | 21   | 24   | 27   | 30  | 33  | 36 | 39 | 42 | 45 |   |   |
| 0.3 - 0.6                        | 5                    | 19 | 15 | 43 | 103 | 205 | 504 | 1064 | 1697 | 1114 | 427 | 131 | 37 | 20 | 9  | 4  | 8 |   |

Significant Wave Height vs. Peak Wave Period

| Hs - Significant Wave Height [m] | Tp - Wave Peak Period [s] |      |      |     |     |     |     |     |     |     |     | # | % |     |      |   |
|----------------------------------|---------------------------|------|------|-----|-----|-----|-----|-----|-----|-----|-----|---|---|-----|------|---|
|                                  | 3.2                       | 3.6  | 3.9  | 4.3 | 4.7 | 5.2 | 5.7 | 6.3 | 6.9 | 7.6 | 8.4 |   |   | 9.2 | 10.2 |   |
| 0.3 - 0.6                        | 1060                      | 1480 | 1220 | 756 | 359 | 128 | 37  | 7   | 7   | 4   | -   | - | - | -   | -    | - |

### Chapter 3: Design Requirements

- Design Cruise Ship
- Structural Requirements
- Functional Requirements
- Nautical Requirements

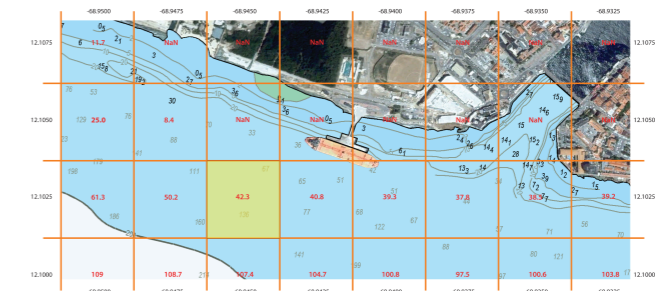
### Chapter 5: Floating Structures in General

- Theory + Background Information
- Why and why not Floating?
- Structure Types
- RAO's and Response Spectra
- Stability and Motion Criteria

### Chapter 4: Simulations with SWAN

What is the local wave climate at the suggested project location?

Computational Model + Output Location



Input scenarios for Wind Waves (& Swell):

| Wind Sea Waves |     |     |          |                   |          |            | Wave Peak Period [s] |     |     |     |     |     |     |     |     |     |
|----------------|-----|-----|----------|-------------------|----------|------------|----------------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| #              | Hs  | Tp  | $\theta$ | $\sigma_{\theta}$ | $u_{10}$ | $\theta_w$ | Wave Peak Period [s] |     |     |     |     |     |     |     |     |     |
| [-]            | [m] | [s] | [°]      | [°]               | [m/s]    | [°]        | 3.2                  | 3.6 | 3.9 | 4.3 | 4.7 | 5.2 | 5.7 | 6.3 | 6.9 | 7.6 |
| W1A            | 0.6 | 5.2 | 80       | 30                | 5.8      | 80         | *                    | *   | *   | *   | *   | *   | *   | *   | *   | *   |

Conclusion: Key Scenarios representing the local wave climate near Willemstad

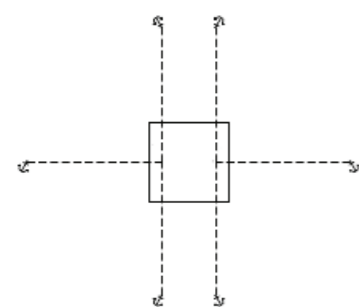
| Wind Sea Waves |     |     |                   |          |            |              | Swell Waves |     |      |                   |          |            |              |
|----------------|-----|-----|-------------------|----------|------------|--------------|-------------|-----|------|-------------------|----------|------------|--------------|
| #              | Hs  | Tp  | $\sigma_{\theta}$ | $u_{10}$ | $\theta_w$ | Pr, $\theta$ | #           | Hs  | Tp   | $\sigma_{\theta}$ | $u_{10}$ | $\theta_w$ | Pr, $\theta$ |
| [-]            | [m] | [s] | [°]               | [m/s]    | [°]        | [%]          | [-]         | [m] | [s]  | [°]               | [m/s]    | [°]        | [%]          |
| W2B            | 1.2 | 6.9 | 30                | 7.4      | 80         | 26.4         | S1C         | 0.3 | 16.3 | 15                | 5.6      | 70         | 58.6         |

### Chapter 6: General Design Considerations

Terminal Variants: Model A - 30x30m pontoon  
 Model B - 80x30m pontoon  
 Design Cruise ship: Model C - Oasis of the Seas

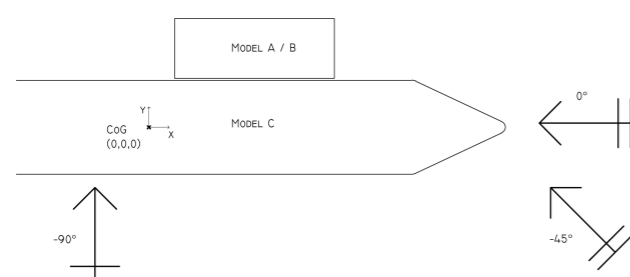
|         | Length         | Width          | Height         | Draught        | Mass           | Water Displacement  | Mass Moment of inertia            |
|---------|----------------|----------------|----------------|----------------|----------------|---------------------|-----------------------------------|
|         | L <sub>f</sub> | W <sub>f</sub> | D <sub>h</sub> | D <sub>d</sub> | m <sub>f</sub> | V <sub>w</sub>      | I <sub>xx</sub> , I <sub>yy</sub> |
|         | [m]            | [m]            | [m]            | [m]            | [m]            | [m <sup>3</sup> ]   | [t m <sup>2</sup> ]               |
| Model A | 30             | 30             | 5              | 2.53           | 2.53           | 2.3·10 <sup>3</sup> | 265021, 265021                    |
| Model B | 80             | 30             | 5              | 2.50           | 6.150          | 6.1·10 <sup>3</sup> | 639166, 3421486                   |

Anchorage:  
 - Catenaries  
 - Weight Blocks



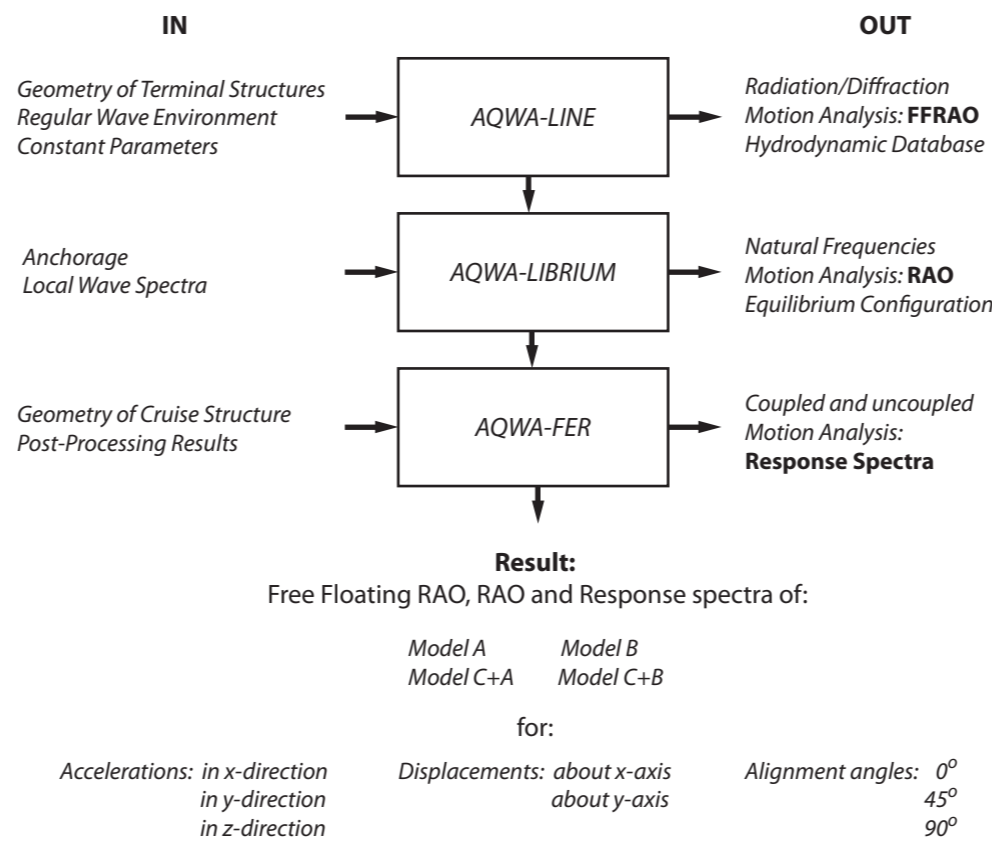
Alignment Angles:

- 0 degrees
- 45 degrees
- 90 degrees



### Chapter 7: Simulations with AQWA

What is the motion response of Models A and B?  
 What is the influence of a cruise ship next to the terminal?



### Chapter 8: Downtime Assessment

Do the models exceed motion criteria?  
 What is the downtime of the models?

| Acceleration in Z-Direction | 0 deg   |         |         | 45 deg  |         |         | 90 deg  |         |         |
|-----------------------------|---------|---------|---------|---------|---------|---------|---------|---------|---------|
|                             | S1C     | S2E     | S3A     | S1C     | S2E     | S3A     | S1C     | S2E     | S3A     |
| W2B                         | 3,0E-03 | 1,1E-02 | 1,0E-01 | 1,7E-03 | 5,3E-03 | 4,6E-02 | 6,9E-03 | 3,2E-01 | 1,9E-01 |

- Calculated RMS-values for the indicated motions and wave angles
- Compared with the Nordforsk Criteria for:  
 - Cruise Liners (= Green)  
 - Transit Passengers (= Orange)

### Chapter 9: Conclusion

For these specific floating terminals studied, the realisation is only feasible in specific cases:

- Model C+B leads to the lowest downtimes:  
 - at most 0.1% for swell wave scenarios,  
 - at most 1.4% for wind sea wave scenarios,
- in case of an alignment angle of 45° relative to the dominant wave angle.
- Heave accelerations are in all cases the limiting factor that results in downtime.
- Recommendation: Optimizing the pontoon geometry and the mooring system will most likely lead to a reduction of heave accelerations, greatly improving the potential of this concept.

