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Single-molecule protein sequencing through fingerprinting: computational assessment

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Abstract

Proteins are vital in all biological systems as they constitute the main structural and functional components of cells. Recent advances in mass spectrometry have brought the promise of complete proteomics by helping draft the human proteome. Yet, this commonly used protein sequencing technique has fundamental limitations in sensitivity. Here we propose a method for single-molecule (SM) protein sequencing. A major challenge lies in the fact that proteins are composed of 20 different amino acids, which demands 20 molecular reporters. We computationally demonstrate that it suffices to measure only two types of amino acids to identify proteins and suggest an experimental scheme using SM fluorescence. When achieved, this highly sensitive approach will result in a paradigm shift in proteomics, with major impact in the biological and medical sciences.
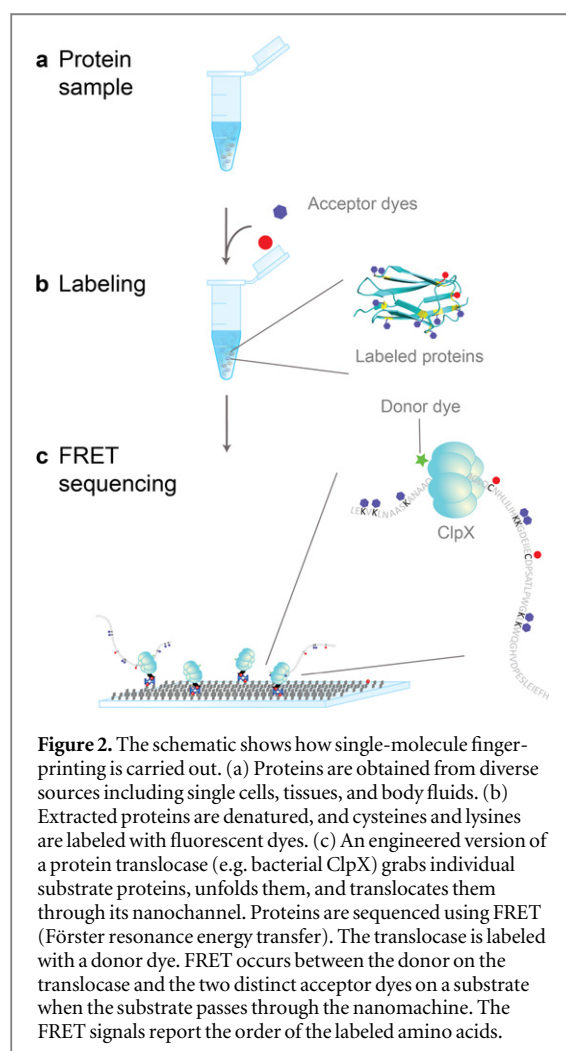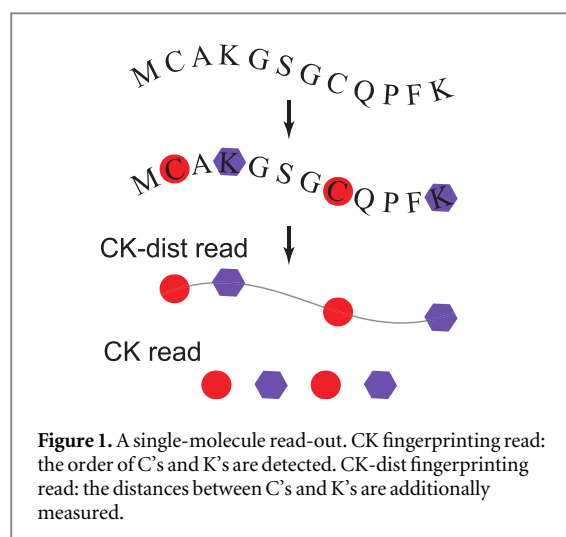
In 2014 two international teams produced the first draft of the human proteome, using mass spectrometry (MS) [1, 2]. By opening a new chapter in proteomics, these large scale studies will help us understand complex cellular processes. Yet, MS—the most widely used protein sequencing technology—requires a large amount of sample. This hampers quantification, precludes detecting many proteins of interest that are present only in low concentrations in the cell, and renders single-cell analysis impossible.

Single-molecule (SM) protein sequencing would bring about 'protein deep sequencing' [3–5]. However, unlike DNA sequencing that needs to read out only four nucleotides, protein sequencing demands differentiation of 20 amino acids, far beyond what current SM techniques can offer [3]. SM protein sequencing has therefore not followed up SM DNA sequencing that uses fluorescence and nanopores [6–8]. Here we propose a novel SM protein sequencing method that overcomes this challenge and assess its feasibility using computational analysis.

Unique to protein sequencing is that a protein can be identified using incomplete information with reference to proteomic databases. Consider a 2 bit fingerprinting scheme in which only two types of amino acids are labeled (figure 1). A consecutive read of 15 labeled amino acids is sufficient to identify up to $2^{15} = 32\,768$ unique protein sequences. This exceeds the number of (major isoform) protein species that most organisms express. As the median length of a protein ranges from 270 (bacteria) to 350 amino acids (eukaryotes), it is not difficult to choose two amino acid types that appear more than 15 times in each protein (supplementary figure 1, stacks.iop.org/PB/12/055003/mmedia).

Figure 2 describes a SM protein fingerprinting scheme using fluorescence. We chose to label two highly nucleophilic amino acids, lysine (K) and cysteine (C) as they are frequent (supplementary figure 2) and can be labeled both efficiently and orthogonally (NHS–ester coupling with lysine and maleimide coupling with cysteine) [9]. A similar idea using lysine and arginine for monitoring protein synthesis inside a living cell was patented by *Anima Cell Metrology* [10]. Recently, Swaminathan *et al* discussed fingerprinting schemes that are based on

Figure 1. A single-molecule read-out. CK fingerprinting read: the order of C's and K's are detected. CK-dist fingerprinting read: the distances between C's and K's are additionally measured.

Figure 2. The schematic shows how single-molecule fingerprinting is carried out. (a) Proteins are obtained from diverse sources including single cells, tissues, and body fluids. (b) Extracted proteins are denatured, and cysteines and lysines are labeled with fluorescent dyes. (c) An engineered version of a protein translocase (e.g. bacterial ClpX) grabs individual substrate proteins, unfolds them, and translocates them through its nanochannel. Proteins are sequenced using FRET (Förster resonance energy transfer). The translocase is labeled with a donor dye. FRET occurs between the donor on the translocase and the two distinct acceptor dyes on a substrate when the substrate passes through the nanomachine. The FRET signals report the order of the labeled amino acids.

multiple labels, including two labels [3]. Separately, a work published in 2013 shows how our fingerprinting approach might be implemented using nanopores [4].

To assess the predictive power of fingerprinting, we developed a dedicated search algorithm. In brief, we search CK (cysteine–lysine) fingerprints by combining a filtering strategy to decrease computation time with a dynamic programming-based alignment

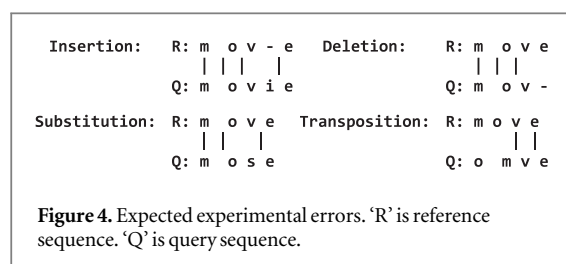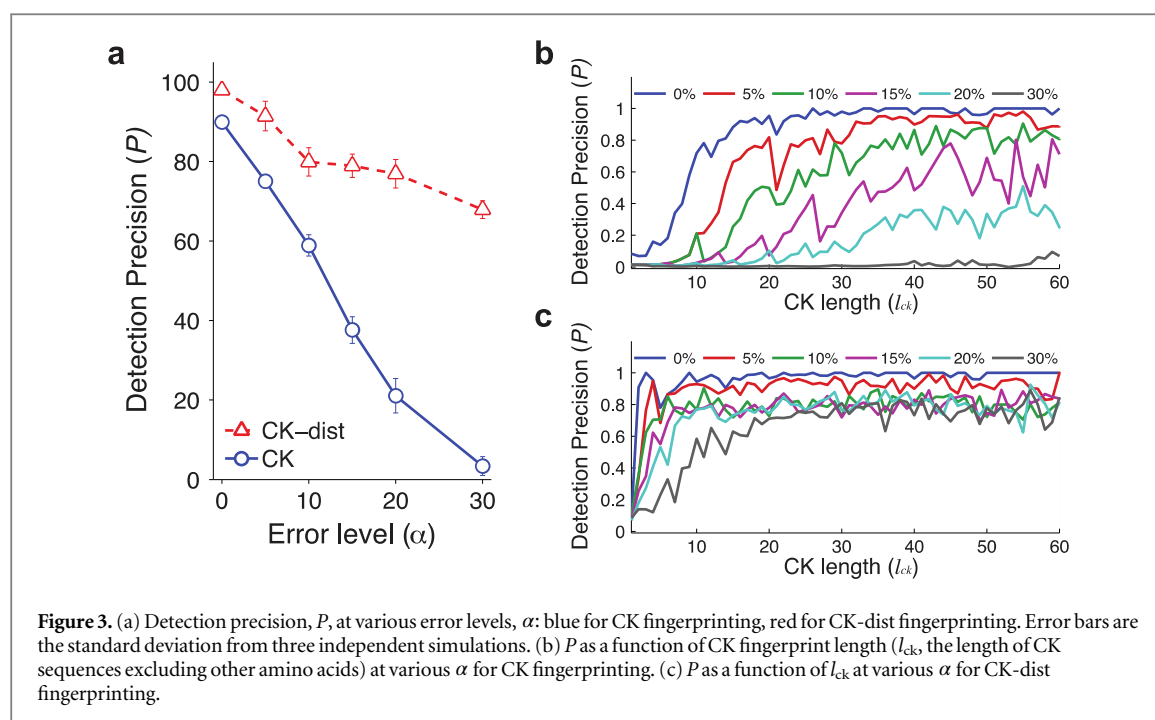step, considering a specific set of potential experimental errors (see methods).

For our analysis, we used a canonical human proteome database based on Uniprot release 2014.04 [11]. We simulated 2000 different read-outs, searched for each of them in the database and measured the detection precision (P), i.e. the probability of retrieving the correct sequence. In an ideal situation with no experimental error, P is 90% (figure 3(a), blue). Next, we assessed the robustness of the method against inaccuracies that are expected from actual experiments, by iteratively introducing errors into each fingerprint at random (see *error simulation* in *methods* for details) up to a specified error level (α, a number of errors (k) divided by a CK fingerprint length (l_{ck}, the length of CK sequences excluding other amino acids). Figure 3 reports P of these computations. As expected, P drops when α increases. For example, at $\alpha = 10\%$, half of the sequences are correctly and uniquely retrieved (figure 3(a), blue).

To improve performance, we considered other information: the distance between C's and K's (figure 3(a), red). At any α, P was dramatically higher with the distance included: at $\alpha = 10\%$, P increased to 85%. In general, P increases when l_{ck} becomes longer (figures 3(b)–(c)). At any l_{ck}, P for CK fingerprinting with distance information (named 'CK-dist fingerprinting') is higher than or equal to P for CK fingerprinting. A similar observation was made when different additional information was considered (supplementary figure 5). Taken together, these demonstrate the feasibility of the technique for identifying primary protein sequences.

Another application area could be clinical diagnostics. As an example of detecting infections, we chose human respiratory syncytial virus (HRSV) and tuberculosis (TB). We determined that a set of HRSV and TB proteins contain a unique CK fingerprint and thus can be detected at α as high as 15–20% and be potentially used as markers for HRSV and TB (supplementary figure 6).

The CK fingerprinting technique will also enable us to detect post-translational modifications of proteins when it is expanded to a three-color fluorescence measurement. For example, glycosylated amino acids can be labeled with a third acceptor dye using hydrazide–aldehyde coupling chemistry, which is orthogonal to the labeling methods for lysine and cysteine residues. Phosphorylated serine and threonine can be labeled with a third acceptor using another coupling scheme [12]. This will advance the proof-of-principle of detecting a post-translationally modified peptide using a nanopore that was reported in 2014 [5].

We described SM protein fingerprinting, a technique that will provide proteomics with high sensitivity and a large dynamic range. Our computational assessment indicated that, even if we read only two amino acid types, we could correctly identify proteins with reference to proteomic databases. When this entirely

Figure 3. (a) Detection precision, *P*, at various error levels, α: blue for CK fingerprinting, red for CK-dist fingerprinting. Error bars are the standard deviation from three independent simulations. (b) *P* as a function of CK fingerprint length (l_{ck}, the length of CK sequences excluding other amino acids) at various α for CK fingerprinting. (c) *P* as a function of l_{ck} at various α for CK-dist fingerprinting.

Figure 4. Expected experimental errors. 'R' is reference sequence. 'Q' is query sequence.

new SM protein sequencing approach is achieved, it will become a proteomics tool that complements MS and opens up new avenues in global, high-throughput protein analysis.

Methods

Here we describe the approaches that we used to simulate errors and find protein fingerprints that match a given query fingerprint pattern.

Error simulation

We simulated 2000 read-outs, each for a different protein. The proteins are randomly picked from the database and thus contain random amino acids and fingerprint lengths. Next, to assess the robustness of the method against inaccuracies that are expected from actual experiments, errors are iteratively introduced for each read-out up to the error level we want to investigate.

We expect that actual data will be convoluted with poor dye-labeling, photoblinking and photobleaching of dyes, local structures of a substrate protein, non-uniform speed of substrate translocation, proximity between dyes etc. The poor labeling, photoblinking,

and photobleaching of acceptor dyes will appear as deletion errors (figure 4). The non-uniform speed of translocation will introduce insertion and deletion errors to CK-dist fingerprinting. The proximity of acceptor dyes will bring deletion and transposition/ substitution errors. If a donor dye is photobleached during a measurement, it will appear as a truncation error. We do not consider this error for fingerprinting analysis since donor photobleaching can be determined from SM time traces and thus can be easily excluded from further analysis. Other complications, such as aggregation of denatured proteins, may also be expected but are not considered in our analysis. See a pseudo-code for simulating these errors (supplementary information).

In figure 3, we investigated one combination of errors (70% deletions, 20% insertions, 10% transpositions) for CK fingerprinting, in which we assigned the largest percentage to deletions since this error is the most likely to occur (poor labeling of acceptors due to incomplete denaturation of proteins, photoblinking/ photobleaching of acceptors, and presence of consecutive identical acceptor fluorophores). For CK-dist fingerprinting analysis, we considered the same combination of errors as for CK fingerprinting but with errors at CK residues and errors of the distance between CK residues equally likely to occur. In supplementary figure 3, we expanded the error space that we explored and obtained trends nearly identical to that found in figure 3(a).

Overview of the CK fingerprinting

The 2000 simulated readouts are searched for in the database, and the numbers of true positives and the number of matches are recorded. To examine the

performance variability of our algorithm in retrieving proteins using fingerprints, three independent repetitions are executed. In each repetition, detection precision (*P*) (figure 3) and detection recall (*R*) (supplementary figure 4) are calculated based on the outputs. *P* is defined as the number of true positives divided by the number of read-outs returned by the algorithm. *R* is the number of true positives divided by the number of conditional matches.

The inputs to our method are a reference database *R* containing fingerprint representations of protein sequences, a query fingerprint *Q* and an error level α. The alphabet is $\Sigma = \{C, K\}$, since we only compare fingerprints of these two amino acids. Let L_Q be the query length and $R_x \in R$ denote the *x*th reference sequence in the database *R* with length L_x^R. The distance $S(R_x, Q)$ between a reference fingerprint R_x and a query *Q* is the minimal number of steps required to transform *Q* into R_x. Formally, given *Q*, *R*, and α, the problem is to find all $R_x \in R$ for which $S(R_x, Q)$ is smaller than $k = \alpha \times L_Q$.

Given the inputs, the algorithm takes two steps to retrieve matches: (1) a filtration strategy is applied to identify candidate sequences in *R*; and (2) a verification method is employed to examine all candidates for possible matches.

Filtration: eliminating uninteresting sequences

Dynamic programming is computationally costly, prohibiting direct application on large databases in a high-throughput setting [13]. In order to reduce the running time without affecting sensitivity, we use filtration to remove those references that definitely cannot match the query fingerprint *Q* with distance smaller than or equal to *k*. Filtration exploits the fact that it is easier to tell a reference fingerprint that does not match a query fingerprint than to tell one that does match. Typically, it uses a simple and highly efficient filter criterion to analyze the reference sequences, leaving only a small number of R_x's for further (more expensive) analysis. We devised a new filtration method combining two existing algorithms, partial exact matching and *n*−gram counting.

In partial exact matching, the query fingerprint *Q* is divided into (*k* + 1) pieces $q^0, q^1, \ldots, q^k$, where *k* equals $\alpha \times L_Q$. For a match to be possible, there must be at least one piece that appears exactly in a reference sequence R_x [15]. If this is not the case, R_x is discarded.

A faster filtration method is *n*−gram counting, which compares the *n*−grams of two fingerprints. An *n*−gram [16] on the alphabet set $\Sigma = \{C, K\}$ is any string in Σ^n, where Σ^n is the set of all possible strings of length *n* over Σ. For example, the 2−grams for $\Sigma = \{C, K\}$ are CC, CK, KC and KK. The *n*−gram distance is defined as the sum of the absolute differences between the numbers of occurrences of each *n*−gram. If the *n*−gram distance exceeds 2*nk*, R_x is discarded [16].
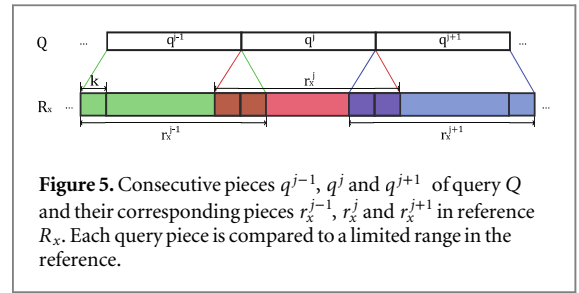
Figure 5. Consecutive pieces q^{j-1}, q^j and q^{j+1} of query *Q* and their corresponding pieces r_x^{j-1}, r_x^j and r_x^{j+1} in reference R_x. Each query piece is compared to a limited range in the reference.

We combined the partial exact matching and *n*−gram counting approaches to decide whether there exists at least one piece in *Q* that appears with a limited amount of errors as a piece of R_x [17]. The distance function between two pieces of *Q* and R_x, q^j and r_x^j, based on their *n*−grams was defined as:

$$S_{npm}\left(r_x^j, q^j\right) = \sum_{\nu \in \Sigma^n} \max\left(G\left(q^j\right)[\nu] \right.$$
$$\left. - G\left(r_x^j\right)[\nu], 0\right),$$

where $[\nu]$ is an *n*−gram and $G\left(q^j\right)[\nu]$ and $G\left(r_x^j\right)[\nu]$ denote the total number of times $[\nu]$ occurs in q^j and r_x^j, respectively.

For each piece q^j in the query, the corresponding piece r_x^j contains the same letters in the reference sequence with an additional *k* letters on both sides, as shown in figure 5. It is sufficient to compare the r_x^j in the reference with the q^j in the query to determine whether the piece q^j appears in the reference R_x, since *k* errors cannot alter more than *k* positions. Since a query piece is searched in a limited range in the reference, it can discard more entries in the reference database than the partial exact matching method, in which the q^j is compared with the entire reference sequence.

The distance between a piece q^j in query *Q* and the corresponding piece r_x^j in R_x is computed to determine whether R_x is a candidate match. For each q^j and its corresponding r_x^j, we check whether any *n*−gram occurs more often in q^j than in r_x^j. If not, the $S_{npm}(r_x^j, q^j)$ is zero, i.e. the *n*-grams in q^j appear exactly in r_x^j. Only if for at least one q^j, $S_{npm}(r_x^j, q^j)$ is zero, R_x is kept as a candidate.

Verification: finding matches

The remaining candidate matches are examined by a global alignment dynamic programming approach considering a number of possible error types. In our analysis, four types of error may occur: deletion, insertion, mismatching an amino acid with another one (substitution), and swapping (transposition).

The dynamic programming algorithm is designed to provide the optimal gapped alignment between two sequences, i.e. an alignment with long regions of identical amino acid pairs and very few mismatches and gaps [14]. As the sequences become more dissimilar, more mismatched amino acid pairs and gaps should

appear. To find the optimal alignment, a dynamic programming matrix M first needs to be calculated. Each element $M_{i,j}$ represents the maximum score of aligning the substrings $Q[1\ldots i]$ and $R_x[1\ldots j]$. Let c denote the scores of the four operations. The base cases, $M_{0,j}$ and $M_{i,0}$, are defined as $(c_{\mathrm{del}} \times j)$ and $(c_{\mathrm{ins}} \times i)$ for all $1 \leqslant j \leqslant L_x^R$ (length of R_x) and $1 \leqslant i \leqslant L_Q$ (length of Q) respectively. Then, considering the four possibilities, M is updated using the following recursive relation

$$M_{i,j} = \max \begin{cases} M_{i-1,j-1} + c_{\mathrm{sub}}, \\ M_{i-1,j} + c_{\mathrm{ins}}, \\ M_{i,j-1} + c_{\mathrm{del}}, \\ M_{i-2,j-2} + c_{\mathrm{swap}}. \end{cases}$$

The score for each operation is set based on the estimation of how likely each error is to occur in our measurements. Currently, deletions caused by low labeling efficiency are the dominating errors, followed by insertions, transpositions and substitutions (i.e. matching C to K or vice versa) (see error simulation). Hence we choose a relatively low penalty (negative) for deletions and higher penalties (negative) for transpositions and substitutions. For the matching positions, the score is positive (see supplementary table 2).

By memorizing the solutions to the subproblems for $1 \leqslant j \leqslant L_x^R$ and $1 \leqslant i \leqslant L_Q$ stored in the dynamic matrix, we can recursively compute the maximum score of aligning R_x and Q. Therefore we find the score of the optimal alignment of the two sequences starting from the maximum value in the last row or last column. We maintain a matrix of traceback pointers in the recursion, so that we remember which case was used to calculate every cell $M_{i,j}$, allowing to reconstruct the optimal alignment.

From this alignment the numbers of errors for different types as well as the total number of errors can be calculated. The distance between the query and the reference $S(R_x, Q)$ is defined as the total number of errors. If this distance is smaller than k, the reference sequence R_x is considered as a *match*. Otherwise, it is not a match of the query sequence within the error bound k. A match is considered a *true positive match* when the match is the exact query protein. If a match has the same fingerprint but a different amino acid sequence, it is not considered to be a true positive match. In our analysis, this is determined by checking the protein accession codes.

Additional information, such as the distance between two read-outs, can be deduced from the measurements. This distance is the space between two labeled amino acids, which is the number of non-labeled amino acids in between, which show a different pattern in the measurement. For this to be estimated reliably, proteins will have to be sequenced at a relatively constant speed, an assumption which is not

a priori valid. From the sequencing signals, we cannot easily determine the start or the end of proteins in the time trace if they do not correspond to a labeled amino acid. Thus, the starting and ending non-labeled amino acids are not included when we construct the fingerprint with distance information.

This distance information is added to the original CK fingerprints using an additional symbol (say, 'o'), occurring multiple times (representing the length of distance). Next, two distances between query and reference are calculated to examine whether a reference sequence is a match. One is the $S(R_x, Q)$ between fingerprints with distance information, the other the $S'(R_x, Q)$ between CK fingerprints only. Reference sequence R_x is considered a match if and only if $S'(R_x, Q)$ is smaller than $k' = (\alpha \times L_Q')$ and $S(R_x, Q)$ is smaller than $k = \alpha \times L_Q$, where L_Q is the length of the query CK fingerprint, L_Q' is the length of the query fingerprint with distance information and k' and k represent the numbers of errors allowed. Experimental error on the distance information is also taken into consideration.

Note: Supplementary information is available in the online version of the paper. An animated experimental scheme is available at https://youtube.com/watch?v=YpWCCWO5q10.

Acknowledgments

Author contributions

C J conceived the study. Y Y, M D, and D R conducted the computational analysis. Y Y, M D, J G, D R and C J discussed the data and wrote the manuscript.

Competing financial interests

C J and J G filed a patent (WO2014014347).

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