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A DICHOTOMY CONCERNING UNIFORM BOUNDEDNESS OF RIESZ TRANSFORMS ON RIEMANNIAN MANIFOLDS

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ABSTRACT. Given a sequence of complete Riemannian manifolds (M_n) of the same dimension, we construct a complete Riemannian manifold M such that for all $p \in (1, \infty)$ the L^p -norm of the Riesz transform on M dominates the L^p -norm of the Riesz transform on M_n for all n. Thus we establish the following dichotomy: given p and d, either there is a uniform L^p bound on the Riesz transform over all complete d-dimensional Riemannian manifolds, or there exists a complete Riemannian manifold with Riesz transform unbounded on L^p .

1. Introduction

Given a Riemannian manifold M, one can consider the Riesz transform $R := \nabla (-\Delta)^{\frac{1}{2}}$, where ∇ is the Riemannian gradient and Δ is the (negative) Laplace–Beltrami operator. In the Euclidean case $M = \mathbb{R}^n$, this can be identified with the vector of classical Riesz transforms (R_1, \ldots, R_n) , as can be seen by writing R as a Fourier multiplier (see [12, §5.1.4]).

It is easy to show that R is bounded from $L^2(M)$ to $L^2(M;TM)$, and substantially harder to determine whether R extends to a bounded map from $L^p(M)$ to $L^p(M;TM)$ for $p \neq 2$. We let

$$R_p(M) := \sup_{\|f\|_{L^p} \le 1} \|R(f)\|_{L^p}$$

denote the (possibly infinite) L^p -norm of the Riesz transform on M. Various conditions, often involving the heat kernel on M and its gradient, are known to imply finiteness of $R_p(M)$; see for example [2–9,13,14]. These results usually entail finiteness of $R_p(M)$ for all $p \in (1,2)$, or for some range of p > 2. On the other hand, there exist manifolds M for which $R_p(M)$ is known to be infinite for some (or all) p > 2; see [1,5–8,13].

Remark 1.1. When M has finite volume we abuse notation and write $L^p(M)$ to denote the space of p-integrable functions with mean zero. This modification ensures

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that $(-\Delta)^{-1/2}$ is densely defined. When M has infinite volume, $L^p(M)$ denotes the usual Lebesgue space.

The Euclidean case is now classical: for all $p \in (1, \infty)$ there is a constant $C_p < \infty$ such that $R_p(\mathbb{R}^n) \leq C_p < \infty$ for all $n \in \mathbb{N}$ ([16]). This behaviour is expected to persist for all complete Riemannian manifolds, at least for p < 2. More precisely, in [9] it is conjectured that for all $p \in (1,2)$ there exists a constant $C_p < \infty$ such that $R_p(M) \leq C_p$ for all complete Riemannian manifolds M. Such uniform bounds have been proven for all $p \in (1,\infty)$ under curvature assumptions; rather than provide an overview of the vast literature on this topic we simply point to the recent paper [10] and the references therein.

One could weaken the conjecture slightly and guess that $R_p(M)$ is finite for all M, given $p \in (1,2)$. In this article we show that this can only hold if the bound is uniform among all manifolds of a fixed dimension. This observation follows from the following dichotomy.

Theorem 1.2. Fix $d \in \mathbb{N}$ and $p \in (1, \infty)$. Then the following dichotomy holds: either

- there exists a constant $C_{p,d} < \infty$ such that $R_p(M) \leq C_{p,d}$ for all complete d-dimensional Riemannian manifolds M, or
- there exists a complete (d+1)-dimensional Riemannian manifold M such that $R_p(M) = \infty$.

This follows from the following proposition, which we prove by an explicit construction.

Proposition 1.3. Fix $d \geq 1$, and let $(M_n)_{n \in \mathbb{N}}$ be a sequence of complete d-dimensional Riemannian manifolds. Then there exists a complete Riemannian manifold M of dimension d+1 such that for all $p \in (1, \infty)$,

$$R_p(M) \ge \sup_{n \in \mathbb{N}} R_p(M_n).$$

The main implication of Theorem 1.2 is as follows: to construct a manifold M for which $R_p(M) = \infty$ for some $p \in (1,2)$, it suffices to construct a sequence $(M_n)_{n \in \mathbb{N}}$ of manifolds of equal dimension such that $R_p(M_n) \to \infty$ as $n \to \infty$. Thus one is led to consider lower bounds for L^p -norms of Riesz transforms. These seem not to have been considered in the literature, excluding of course the well-known computation of the L^p -norm of the Hilbert transform (the Riesz transform on \mathbb{R}) [15]. We hope that our contribution will provoke further interest in such lower bounds.

2. Preliminary Lemmas

We begin with some basic lemmas. The first says that the range of the Laplace-Beltrami operator is dense in L^p , and the second relates the Riesz transform on a manifold M with that on the M-cylinder $M \times \mathbb{R}$. These cylinders play a key role in the proof of our main theorem.

Lemma 2.1. Let M be a complete Riemannian manifold. Then the set $S := \Delta(C_c^{\infty}(M))$ is dense in $L^p(M)$ for all $p \in (1, \infty)$ (recalling that we write $L^p(M)$ for the space of p-integrable mean zero functions when M has finite volume).

Proof. Let $H \in L^{p'}(M)$ be such that $\langle H, F \rangle = 0$ for every $F \in S$. Then $\langle H, \Delta G \rangle = 0$ for every test function G, so H is harmonic. By [17, Theorem 3], it follows that H is constant, and the result follows.

Lemma 2.2. Let M be a complete Riemannian manifold. Then

$$R_p(M \times \mathbb{R}) \ge R_p(M)$$
.

Proof. Consider the following modification of the Riesz transform on $M \times \mathbb{R}$:

$$\tilde{R} := \nabla_M (-\Delta_{M \times \mathbb{R}})^{-\frac{1}{2}} = \nabla_M (-\Delta_M - \partial_t^2)^{-\frac{1}{2}}.$$

This is just the projection of R onto the first summand of the tangent bundle $T(M \times \mathbb{R}) = TM \oplus T\mathbb{R}$, so we have that

(1)
$$\|\tilde{R}F\|_{L^p} \le \|RF\|_{L^p}.$$

Let $F \in C_c^{\infty}(M \times \mathbb{R})$, and for all $\lambda > 0$ consider the function

$$F_{\lambda}(x,t) := \lambda^{\frac{1}{p}} F(x,\lambda t),$$

which satisfies $\|F_{\lambda}\|_{L^p(M\times\mathbb{R})} = \|F\|_{L^p(M\times\mathbb{R})}$. Rescaling the operator \tilde{R} in the variable t, we define

$$\tilde{R}_{\lambda} := \nabla_{M} (-\Delta_{M} - \lambda^{2} \partial_{t}^{2})^{-\frac{1}{2}},$$

so that

(2)
$$\|\tilde{R}F_{\lambda}\|_{L^{p}} = \|\tilde{R}_{\lambda}F\|_{L^{p}}.$$

Now take $f \in C_c^{\infty}(M) \cap D((-\Delta_M)^{-\frac{1}{2}})$ and $\rho \in C_c^{\infty}(\mathbb{R})$ such that $\|\rho\|_{L^p(\mathbb{R})} = 1$, and consider the function $F(x,t) = f(x)\rho(t)$. Since Δ_M and ∂_t^2 commute, and the function

$$G_{\lambda}(x,y) = \left(\frac{x}{x+\lambda^2 y}\right)^{\frac{1}{2}}$$

is bounded by 1 for (x,y) > 0, and $G_{\lambda} \to 1$ pointwise as $\lambda \to 0$, we have

$$\lim_{\lambda \to 0} (-\Delta_M - \lambda^2 \partial_t^2)^{-\frac{1}{2}} F = \lim_{\lambda \to 0} G_\lambda(-\Delta_M, -\partial_t^2) (-\Delta_M)^{-\frac{1}{2}} f \otimes \rho = (-\Delta_M)^{-\frac{1}{2}} f \otimes \rho$$

in L^2 , and thus also as distributions. Therefore $\tilde{R}_{\lambda}F \to Rf \otimes \rho$ as distributions, and so

$$\liminf_{\lambda \to 0} \|\tilde{R}_{\lambda} F\|_{L^p(M \times \mathbb{R})} \ge \|Rf \otimes \rho\|_{L^p(M \times \mathbb{R})} = \|Rf\|_{L^p(M)}.$$

Combining this with (2) and (1), and the fact that $C_c^{\infty}(M) \cap D((-\Delta_M)^{-\frac{1}{2}})$ is dense in $L^p(M)$, l yields $R_p(M \times \mathbb{R}) \geq R_p(M)$.

3. Proof of the main theorem

In this section we carry out the construction that proves Proposition 1.3, which implies Theorem 1.2.

Consider a sequence $(M_n)_{n\in\mathbb{N}}$ of complete d-dimensional Riemannian manifolds. We will connect the M_n -cylinders $(M_n \times \mathbb{R})_{n\in\mathbb{N}}$ along a \mathbb{T}^d -cylinder $\mathbb{T}^d \times \mathbb{R}$ as follows.² For each $n \in \mathbb{N}$ fix a coordinate chart $U_n \subset M_n \times (-1/2, 1/2)$ and a small ball $B_n \subset U_n$. Similarly, for each $n \in \mathbb{N}$ choose a small coordinate chart $U'_n \subset \mathbb{T}^n \times \mathbb{R}$ such that the charts $(U'_n)_{n\in\mathbb{N}}$ are pairwise disjoint, and a small ball $B'_n \subset U'_n$. For each $n \in \mathbb{N}$, glue the manifold $(M_n \times \mathbb{R}) \setminus B_n$ to $(\mathbb{T}^n \times \mathbb{R}) \setminus B'_n$ along the boundaries

¹This follows from the inclusion $D((-\Delta_M)^{-\frac{1}{2}}) \supseteq D((-\Delta_M)^{-1}) \supseteq \Delta_M(C_c^{\infty}(M))$, which is dense by Lemma 2.1. See also [11, Lemma 2.2]. Again, recall that $L^p(M)$ denotes the corresponding space of mean zero functions when M has finite volume.

²Of course, one could connect the M_n -cylinders to each other directly, without needing the \mathbb{T}^d -cylinder. This would work just as well.

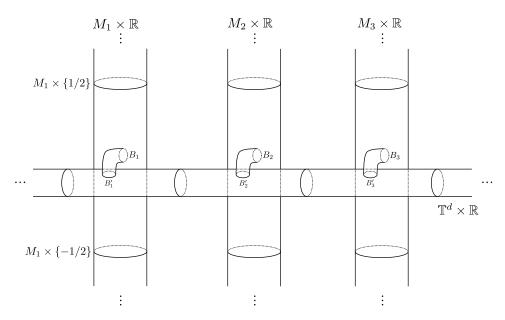


FIGURE 1. Construction of M from $(M_n)_{n\in\mathbb{N}}$.

of B_n and B'_n ; this is possible since both these balls are "Euclidean" balls sitting inside coordinate charts. This results in a C^0 -Riemannian manifold (M,g'), which is C^∞ away from the set $\Sigma = \bigcup_n \partial B_n$ on which we glued the manifolds together. Mollify the metric to get a C^∞ -Riemannian manifold (M,g) such that g=g' away from the ε -neighbourhood of Σ for some very small ε . An artist's impression of this construction, with $M_n = S^1$ for each n, is shown in Figure 1.

For each $n \in \mathbb{N}$ we have an inclusion map

$$i_n \colon M_n \times (1, \infty) \to M$$

which is an isometry. From here on we fix n and just write $i=i_n$. Functions on M can be pulled back to $M_n \times (1,\infty)$; the pullback map is denoted i^* , so that for $f: M \to \mathbb{R}$ the function $i^*f: M_n \times (1,\infty) \to \mathbb{R}$ is defined by

$$i^* f(x,t) = f(i(x,t)).$$

On the other hand, for $g \colon M_n \times (1, \infty) \to \mathbb{R}$ we can define a pushforward $i_*g \colon M \to \mathbb{R}$ by setting $i_*g(i(x,t)) := g(x,t)$ on $i(M_n \times (1,\infty))$ and extending by zero to the rest of M. For a function $g \colon M_n \times \mathbb{R} \to \mathbb{R}$ and for $s \in \mathbb{R}$ we let $\tau_s g \colon M_n \times \mathbb{R} \to \mathbb{R}$ be the translated function $\tau_s g(x,t) := g(x,t-s)$. Similarly if $g \colon M_n \times (1,\infty) \to \mathbb{R}$ we can define $\tau_s g \colon M_n \times (1+s,\infty) \to \mathbb{R}$. These concepts apply equally well to vector fields in place of functions.

We will need the following lemma, which relates the heat flow on $M_n \times \mathbb{R}$ to the one on M.

Lemma 3.1. Let $F: M_n \times \mathbb{R} \to \mathbb{R}$ be smooth and compactly supported, and fix $\sigma > 0$. Then for every $(x,t) \in M_n \times \mathbb{R}$,

$$\lim_{s \to +\infty} (e^{\sigma \Delta_M} i_* \tau_s F)(i(x, t+s)) = (e^{\sigma \Delta_{M_n \times \mathbb{R}}} F)(x, t).$$

Proof. Let $W_{x,t}(\sigma)$ be a Brownian motion on $M_n \times \mathbb{R}$ at time σ starting from the point (x,t). Since the generator $\frac{1}{2}\Delta_{M_n \times \mathbb{R}}$ satisfies $\frac{1}{2}i_* \circ \Delta_{M \times \mathbb{R}}|_{i(M_n \times (1,+\infty))} = \frac{1}{2}\Delta_M|_{i(M_n \times (1,+\infty))}$, defining the stopping time

$$T(x,t) := \inf \{ s : W_{x,t}(s) \in M_n \times (-\infty,1) \},$$

we have that $i(W_{x,t}(\sigma))$ is a Brownian motion on M for $\sigma < T(x,t)$. Therefore there exists a Brownian motion $\tilde{W}_{i(x,t)}(\sigma)$ on M such that $\tilde{W}(\sigma) = i(W(\sigma))$ for $\sigma < T$; if \overline{W} is a Brownian motion on M, we can take for example

$$\tilde{W}_{i(x,t)}(\sigma) = \begin{cases} i(W_{x,t}(\sigma)) & \text{if } \sigma < T, \\ \overline{W}_{i(W_{x,t}(T))}(\sigma - T) & \text{if } \sigma \ge T. \end{cases}$$

We have that

$$\begin{split} &(e^{\sigma\Delta_{M}}i_{*}\tau_{s}F)(i(x,t+s))\\ &=\mathbb{E}[(i_{*}\tau_{s}F)(\tilde{W}_{i(x,t+s)}(2\sigma))]\\ &=\mathbb{E}[(i_{*}\tau_{s}F)(\tilde{W}_{i(x,t+s)}(2\sigma))\mathbb{1}_{2\sigma< T}]+\mathbb{E}[(i_{*}\tau_{s}F)(\tilde{W}_{i(x,t+s)}(2\sigma))\mathbb{1}_{2\sigma\geq T}]\\ &=\mathbb{E}[(\tau_{s}F)(W_{x,t+s}(2\sigma))\mathbb{1}_{2\sigma< T}]+\mathbb{E}[(i_{*}\tau_{s}F)(\tilde{W}_{i(x,t+s)}(2\sigma))\mathbb{1}_{2\sigma\geq T}]\\ &=\mathbb{E}[(\tau_{s}F)(W_{x,t+s}(2\sigma))]\\ &-\mathbb{E}[(\tau_{s}F)(W_{x,t+s}(2\sigma))\mathbb{1}_{2\sigma\geq T}]+\mathbb{E}[(i_{*}\tau_{s}F)(\tilde{W}_{i(x,t+s)}(2\sigma))\mathbb{1}_{2\sigma\geq T}]\\ &=(e^{\sigma\Delta_{M_{n}}\times\mathbb{R}}\tau_{s}F)(x,t+s)\\ &-\mathbb{E}[(\tau_{s}F)(W_{x,t+s}(2\sigma))\mathbb{1}_{2\sigma> T}]+\mathbb{E}[(i_{*}\tau_{s}F)(\tilde{W}_{i(x,t+s)}(2\sigma))\mathbb{1}_{2\sigma> T}]. \end{split}$$

Therefore

$$\left| (e^{\sigma \Delta_M} i_* \tau_s F)(i(x,t+s)) - (e^{\sigma \Delta_{M_n \times \mathbb{R}}} \tau_s F)(x,t+s) \right| \le 2 \|F\|_{L^{\infty}} \mathbb{P}(T(x,t+s) \le 2\sigma).$$

Since $\Delta_{M_n \times \mathbb{R}}$ is translation invariant in the \mathbb{R} coordinate, we have that

$$\mathbb{P}(T(x,t+s) \le 2\sigma) \le \mathbb{P}(\{W_{x,t+s}(\sigma') \in M_n \times (-\infty,1) \text{ for some } \sigma' \le 2\sigma + 1\})$$
$$= \mathbb{P}(\{W_{x,t}(\sigma') \in M_n \times (-\infty,1-s) \text{ for some } \sigma' \le 2\sigma + 1\})$$

and by continuity of $W_{x,t}(\cdot)$, this tends to 0 as $s\to\infty$. Thus we find that

$$\lim_{s\to +\infty} \left((e^{\sigma\Delta_M} i_* \tau_s F) (i(x,t+s)) - (e^{\sigma\Delta_{M_n\times \mathbb{R}}} \tau_s F) (x,t+s) \right) = 0.$$

The conclusion follows from translation invariance of $\Delta_{M_n \times \mathbb{R}}$ in \mathbb{R} .

We return to the proof of Proposition 1.3. Fix $\varepsilon > 0$, and choose $F = \Delta_{M_n \times \mathbb{R}} H$ for some $H \in C_c^{\infty}(M_n \times \mathbb{R})$ with $||F||_{L^p} = 1$ such that

$$||R_{M_n \times \mathbb{R}} F||_{L^p} \ge (R_p(M_n) - \varepsilon) \wedge \varepsilon^{-1}.$$

Such a function exists by Lemmas 2.1 and 2.2. We claim that

(3)
$$\lim_{s \to +\infty} \tau_{-s} i^* R_M(i_* \tau_s F) = R_{M_n \times \mathbb{R}} F$$

as distributions. Assuming (3) for the moment, we have

$$\begin{split} \limsup_{s \to \infty} \|R_M(i_*\tau_s F)\|_{L^p(M)} &\geq \limsup_{s \to \infty} \|i^* R_M(i_*\tau_s F)\|_{L^p(M_n \times \mathbb{R})} \\ &= \limsup_{s \to \infty} \|\tau_{-s} i^* R_M(i_*\tau_s F)\|_{L^p(M_n \times \mathbb{R})} \\ &\geq \|R_{M_n \times \mathbb{R}} F\|_{L^p(M_n \times \mathbb{R})} \geq R_p(M_n) - \varepsilon, \end{split}$$

while for all $s \in \mathbb{R}$

$$||i_*\tau_s F||_{L^p(M)} \le ||\tau_s F||_{L^p(M_n \times \mathbb{R})} = ||F||_{L^p(M_n \times \mathbb{R})} \le 1.$$

The result follows, so it remains to prove (3).

For s sufficiently large, we have that

$$i_*\tau_s F = i_*\tau_s(\Delta_{M_n \times \mathbb{R}} H) = i_*(\Delta_{M_n \times \mathbb{R}} \tau_s H) = \Delta_M i_*\tau_s H,$$

therefore $i_*\tau_s F \in D(\Delta_M^{-1}) \subseteq D((-\Delta_M)^{-\frac{1}{2}})$, and hence

$$R(i_*\tau_s F) = \nabla \left((-\Delta)_M^{-\frac{1}{2}} i_* \tau_s F \right)$$

as a distribution. To test the distributional convergence, let X be a smooth compactly supported vector field in $M_n \times \mathbb{R}$. For large s we have that

$$\begin{split} \langle \tau_{-s} i^* R_M(i_* \tau_s F), X \rangle &= \langle R_M(i_* \tau_s F), i_* \tau_s X \rangle \\ &= \left\langle (-\Delta)_M^{-\frac{1}{2}} i_* \tau_s F, \operatorname{div}(i_* \tau_s X) \right\rangle \\ &= \left\langle (-\Delta)_M^{-\frac{1}{2}} i_* \tau_s F, i_* \tau_s \operatorname{div}(X) \right\rangle. \end{split}$$

Therefore it is enough to show that for every $G \in C_c^{\infty}(M_n \times \mathbb{R})$,

(4)
$$\lim_{s \to \infty} \left\langle (-\Delta)_M^{-\frac{1}{2}} i_* \tau_s F, i_* \tau_s G \right\rangle = \left\langle (-\Delta)_{M_n \times \mathbb{R}}^{-\frac{1}{2}} F, G \right\rangle.$$

By the well-known formula

$$(-\Delta)^{-\frac{1}{2}} = \pi^{-\frac{1}{2}} \int_0^{+\infty} \sigma^{-\frac{1}{2}} e^{\sigma \Delta} d\sigma,$$

(4) is equivalent to showing that

$$(5) \qquad \lim_{s \to \infty} \int_{0}^{+\infty} \sigma^{-\frac{1}{2}} \left\langle e^{\sigma \Delta_{M}} i_{*} \tau_{s} F, i_{*} \tau_{s} G \right\rangle \, d\sigma = \int_{0}^{+\infty} \sigma^{-\frac{1}{2}} \left\langle e^{\sigma \Delta_{M_{n} \times \mathbb{R}}} F, G \right\rangle \, d\sigma.$$

Note that

$$\left| \sigma^{-\frac{1}{2}} \left\langle e^{\sigma \Delta_M} i_* \tau_s F, i_* \tau_s G \right\rangle \right| \leq \sigma^{-\frac{1}{2}} \left\| i_* \tau_s F \right\|_{L^2} \left\| i_* \tau_s G \right\|_{L^2} \leq \sigma^{-\frac{1}{2}} \left\| F \right\|_{L^2} \left\| G \right\|_{L^2}$$

and

$$\left|\sigma^{-\frac{1}{2}}\left\langle e^{\sigma\Delta_{M}}i_{*}\tau_{s}F,i_{*}\tau_{s}G\right\rangle\right|=\left|\sigma^{-\frac{3}{2}}\left\langle e^{\sigma\Delta_{M}}\sigma\Delta_{M}i_{*}\tau_{s}H,i_{*}\tau_{s}G\right\rangle\right|\lesssim\sigma^{-\frac{3}{2}}\left\|H\right\|_{L^{2}}\left\|G\right\|_{L^{2}}.$$

Since the function $\min(\sigma^{-\frac{1}{2}}, \sigma^{-\frac{3}{2}})$ is integrable, by dominated convergence (5) will be proved if we show

(6)
$$\lim_{M \to \infty} \left\langle e^{\sigma \Delta_M} i_* \tau_s F, i_* \tau_s G \right\rangle = \left\langle e^{\sigma \Delta_{M_n \times \mathbb{R}}} F, G \right\rangle$$

for every $\sigma > 0$. We show (6) by writing

$$\begin{split} \lim_{s \to \infty} \left\langle e^{\sigma \Delta_M} i_* \tau_s F, i_* \tau_s G \right\rangle &= \lim_{s \to \infty} \left\langle \tau_{-s} i^* e^{\sigma \Delta_M} i_* \tau_s F, G \right\rangle \\ &= \lim_{s \to \infty} \int_{1-s}^{+\infty} \int_{M_n} (e^{\sigma \Delta_M} i_* \tau_s F) (i(x,t+s)) G(x,t) \, dx \, dt \\ &= \int_{\mathbb{R}} \int_{M_n} (e^{\sigma \Delta_{M_n \times \mathbb{R}}} F) (x,t) G(x,t) \, dx \, dt \\ &= \left\langle e^{\sigma \Delta_{M_n \times \mathbb{R}}} F, G \right\rangle, \end{split}$$

using Lemma 3.1 and dominated convergence (by $||F||_{L^{\infty}} |G(x,t)|$). This completes the proof of Proposition 1.3, and hence establishes Theorem 1.2.

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