

A Spatio-Temporal Method for Impact Assessment

Organic Waste Collection in Amsterdam

Roos Teeuwen, June 2018





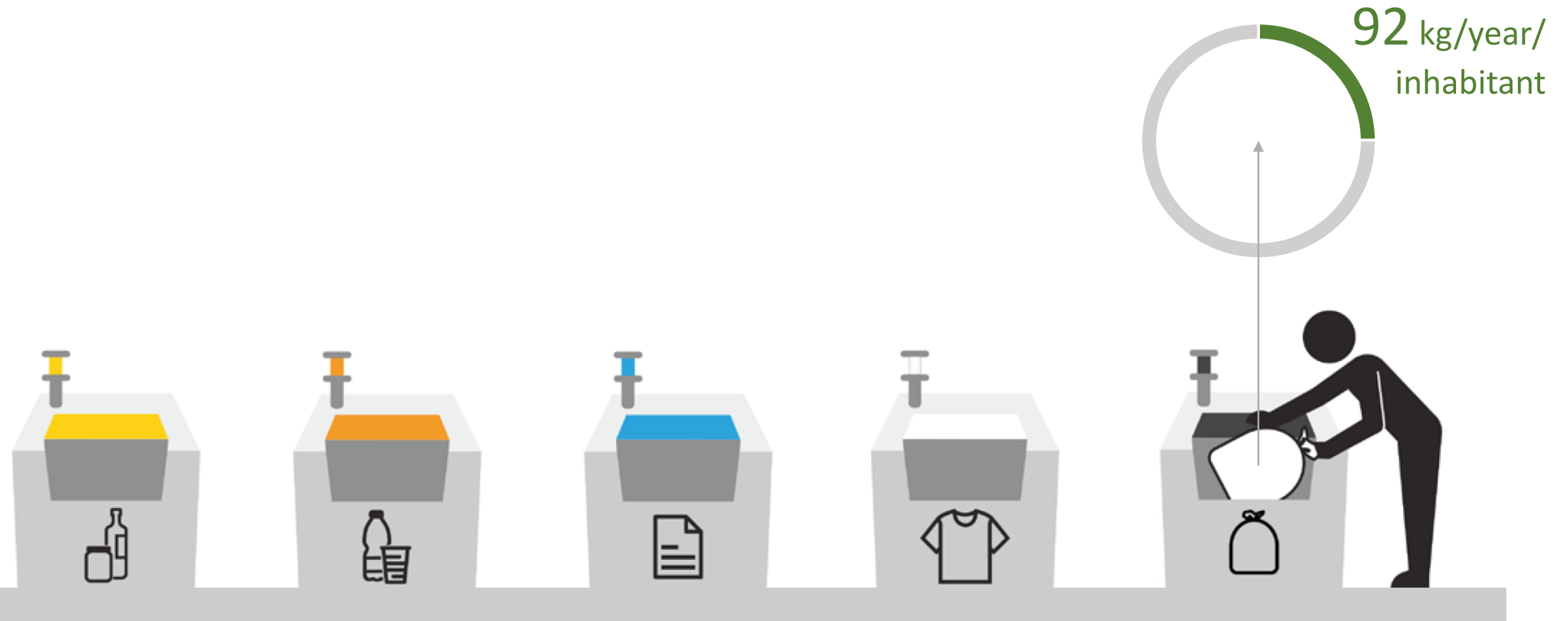


1. Introduction
2. Theoretical Background
3. Tools and Data
4. The Method
5. Conclusions
6. Discussion



1. Introduction

Garden Waste, Fruit, Vegetables...?

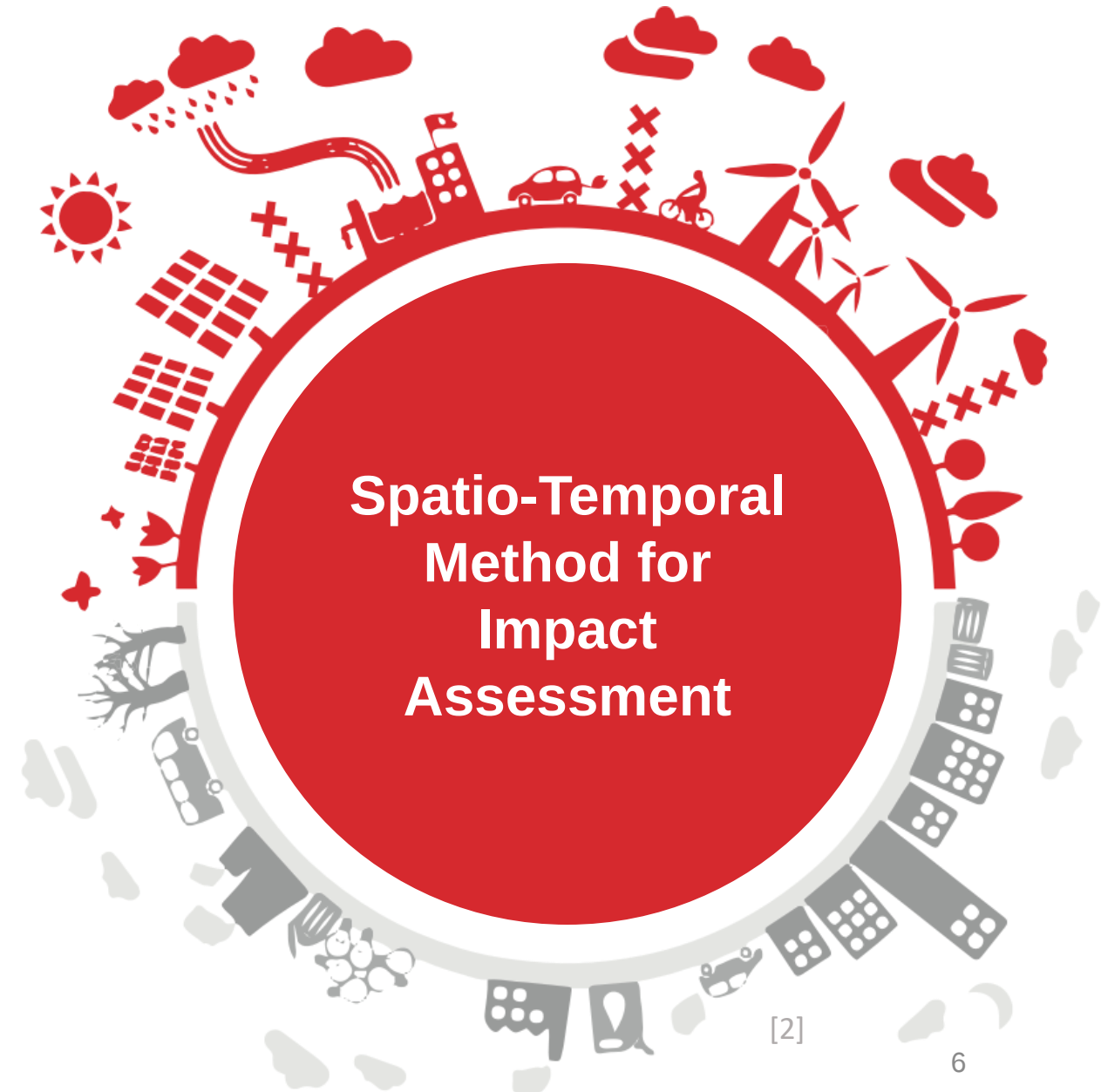


Circular Economy:
Organic Waste

Collection System
Scenarios

Impact?
Complex Question...

1. Spatially varying
2. Time dependent
3. Multiple



What **spatio-temporal method** is suitable to
assess the impacts of organic waste collection
system scenarios in Amsterdam?

Three Technical Challenges

1. Assess Impact Spatially
2. Incorporate Temporal Factors
3. Aggregation

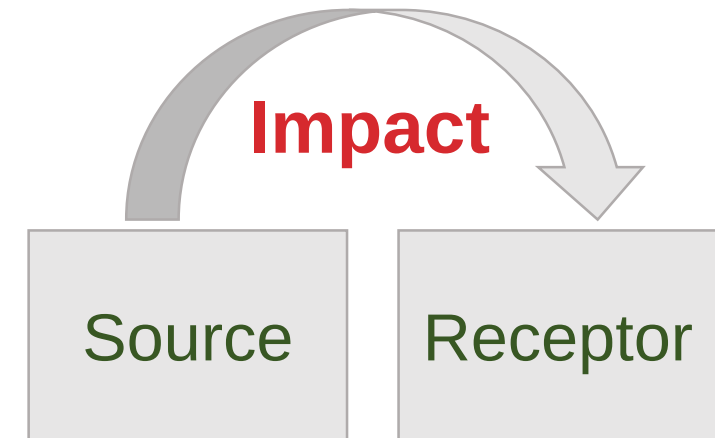


2. Theoretical Background

Definition – Impact

“ **Impact is the effect of a measure on a particular target group or situation affected** ”

[3]



Coherence



2. Theoretical Background

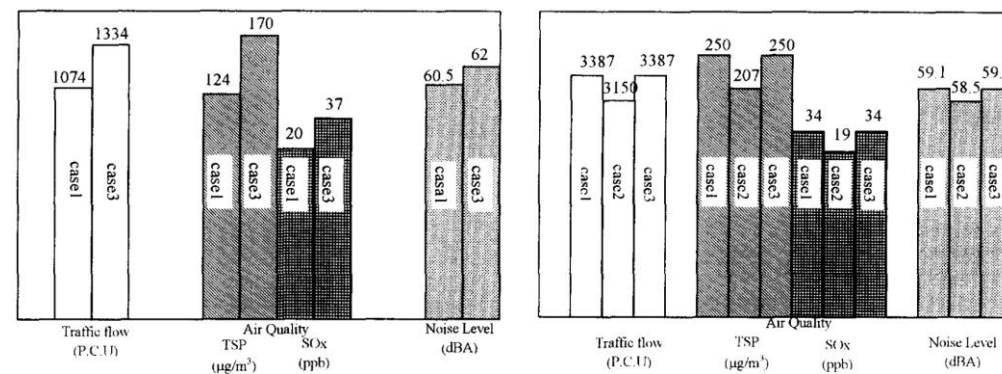
Challenge 1 – Assess Impact Spatially



2. Theoretical Background

Challenge 1 – Assess Impact Spatially

- Calculations > Outcomes



[4]

- Lumped area > Individual Entities
- Phenomenon > Impact



2. Theoretical Background

Challenge 1 – Assess Impact Spatially

Source

- Livestock Areas
- Roads

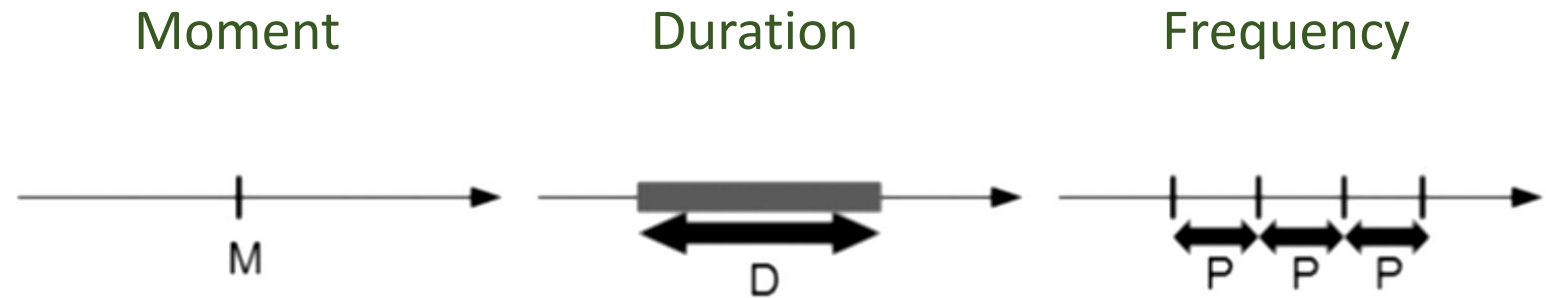
Receptor

- Population Points
- Buildings

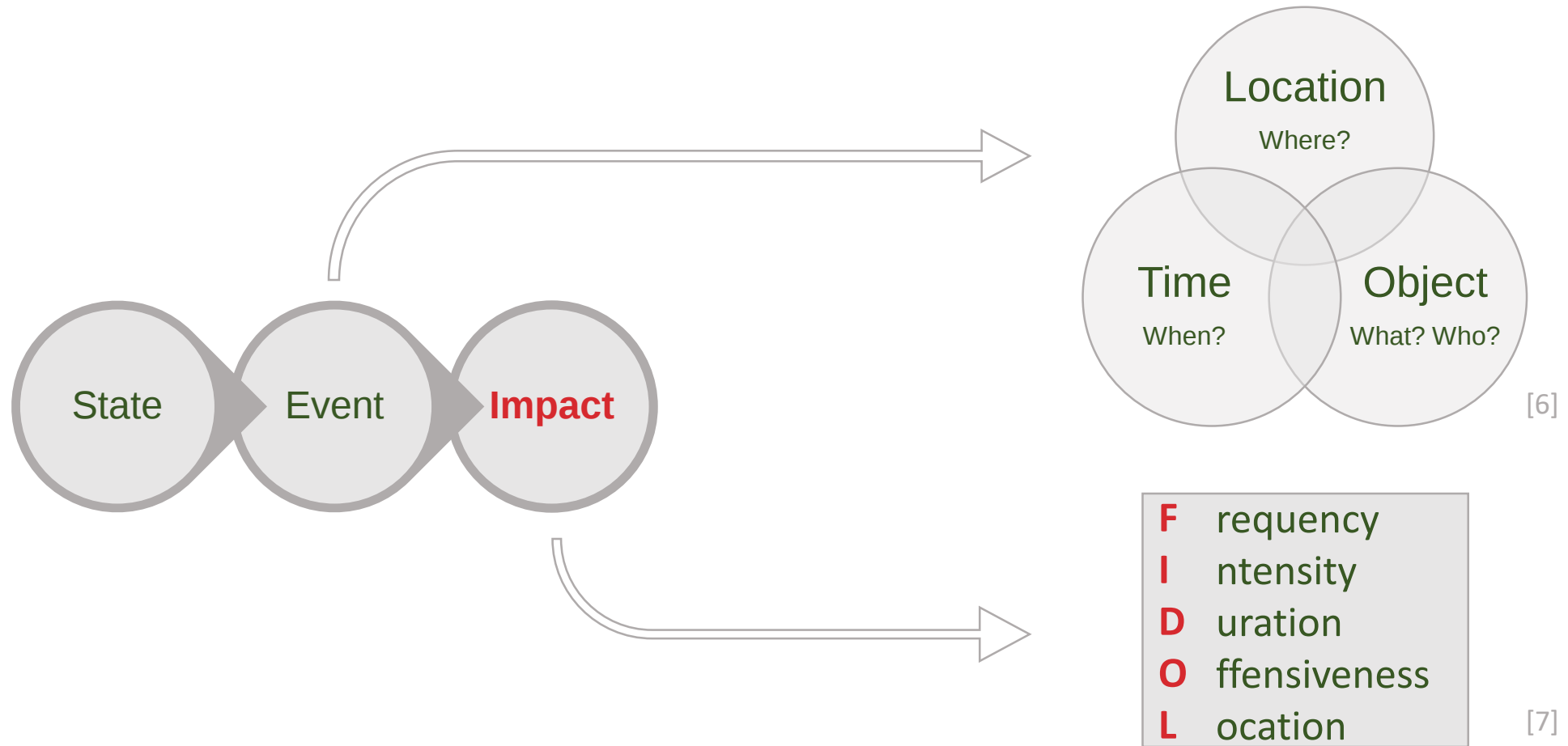
Challenge 2 – Incorporate Temporal Factors

Challenge 2 – Incorporate Temporal Factors

Temporalities of Events ^[5]



Challenge 2 – Incorporate Temporal Factors



Challenge 3 – Aggregation

Challenge 3 – Aggregation

Value Aggregation

- Compensation [8]
- *Andness* and *Orness* [9]
- Spatial Scales and Entities [10]

Challenge 3 – Aggregation

Spatial Aggregation

- Area
- Value

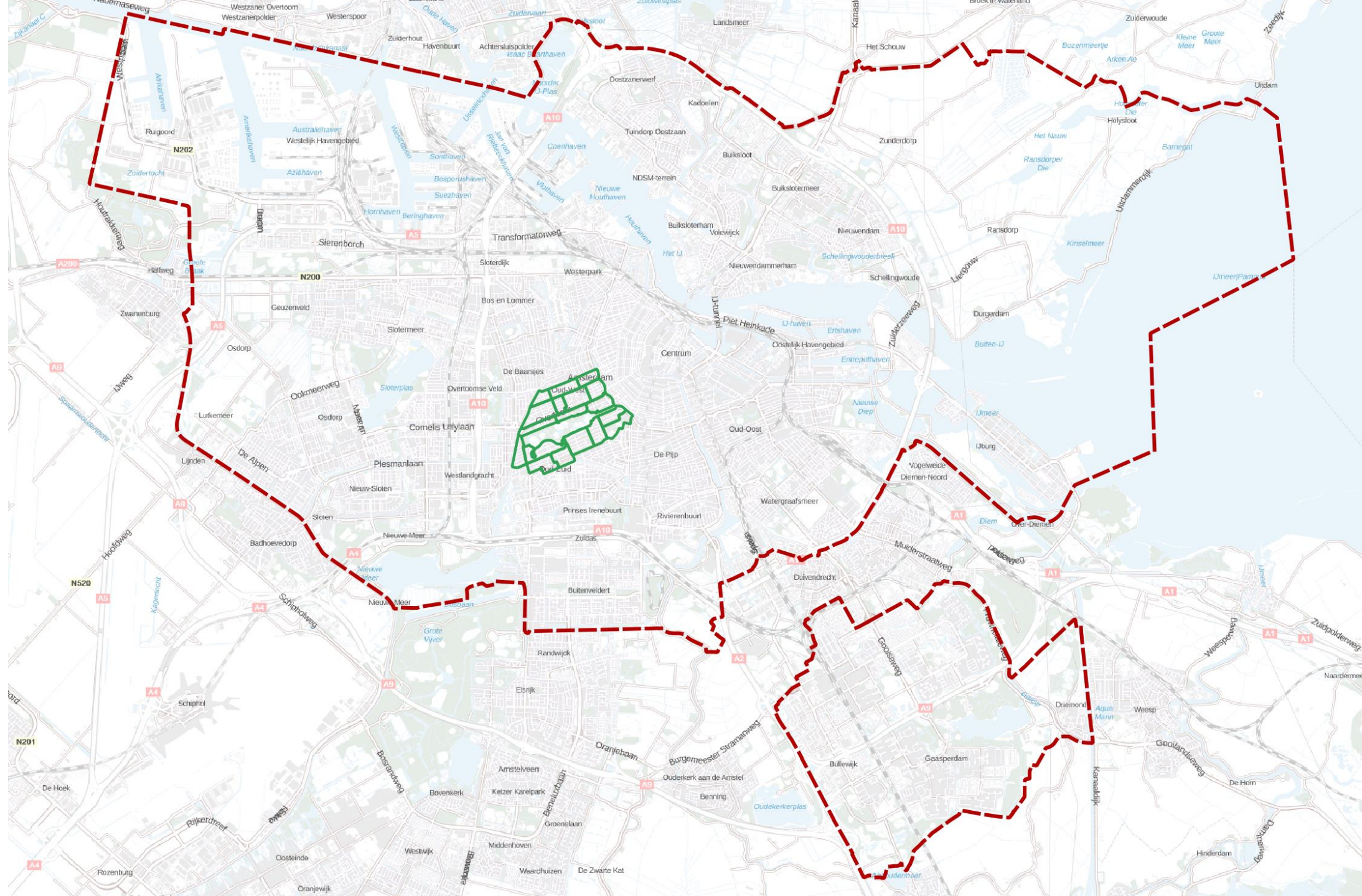


3. Tools and Data

Tools



Data



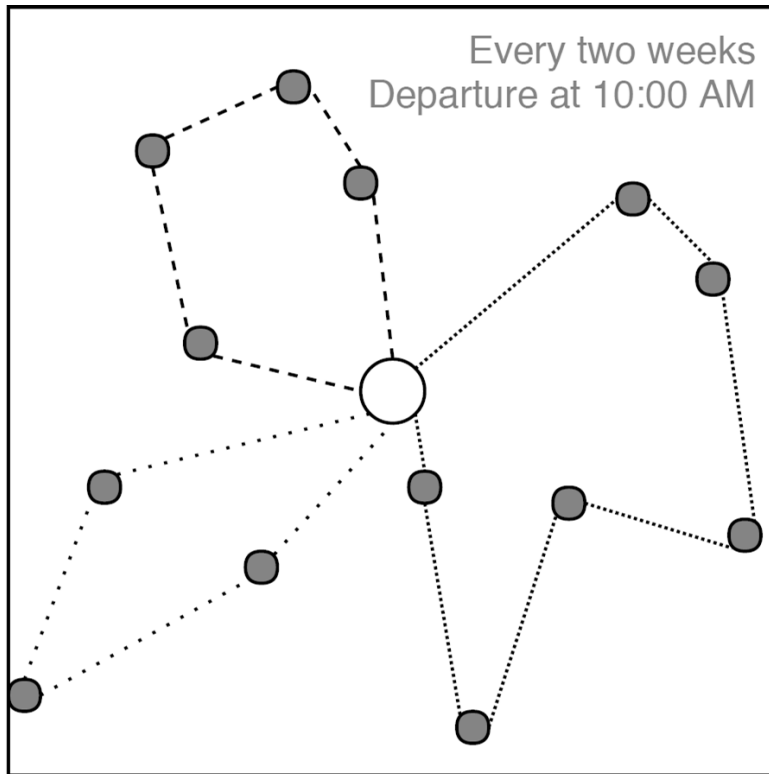
Roads

Houses

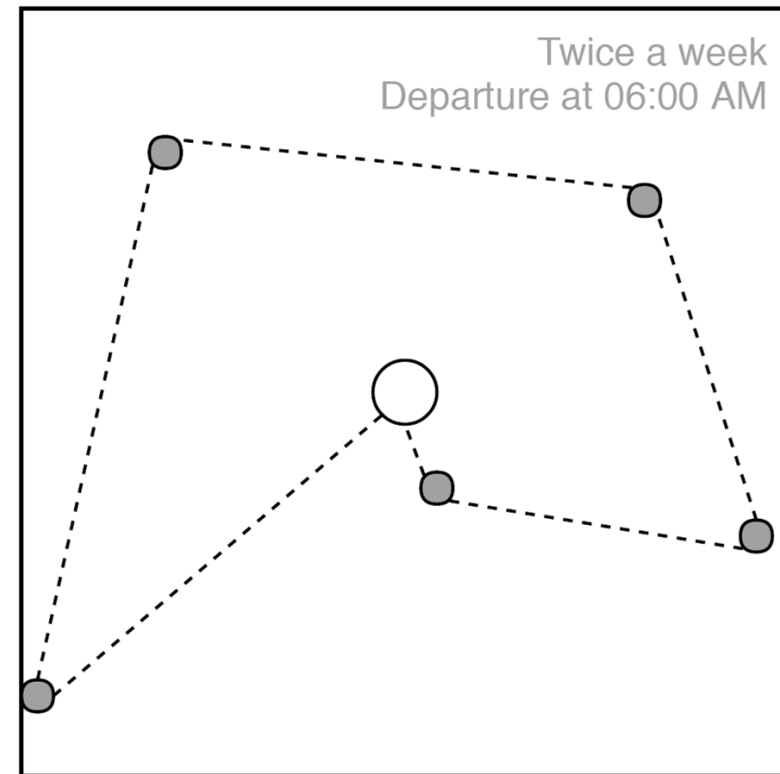


Scenarios

A



B

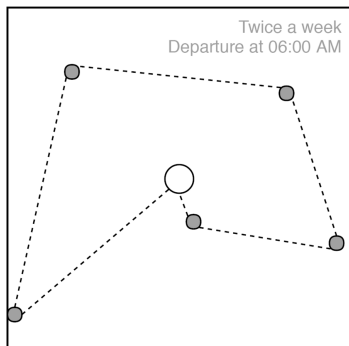


Every two weeks
Departure at 10:00 AM

- Moment
- Duration
- Frequency
- Sequence

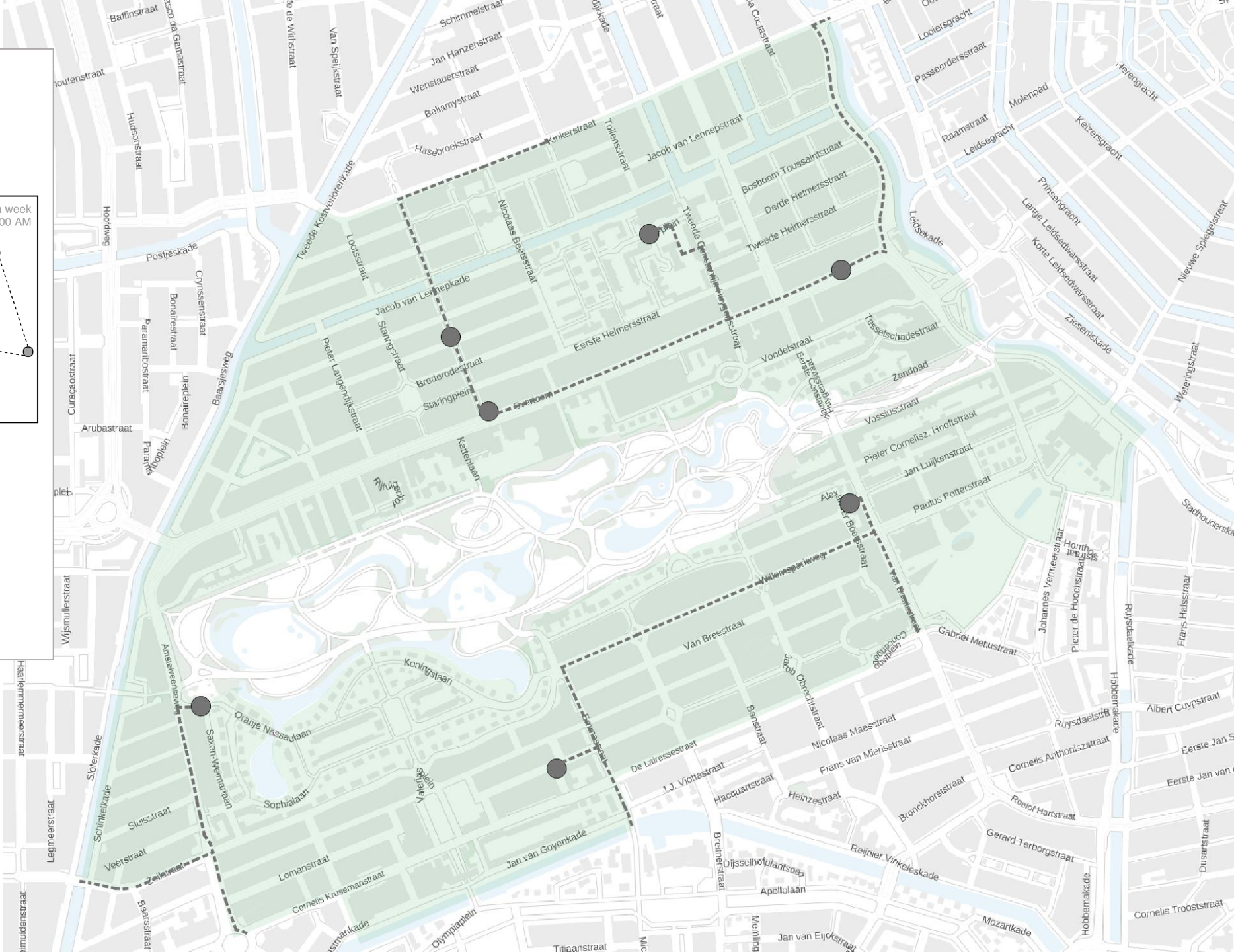


B



Attributes:

- Moment
- Duration
- Frequency
- Sequence

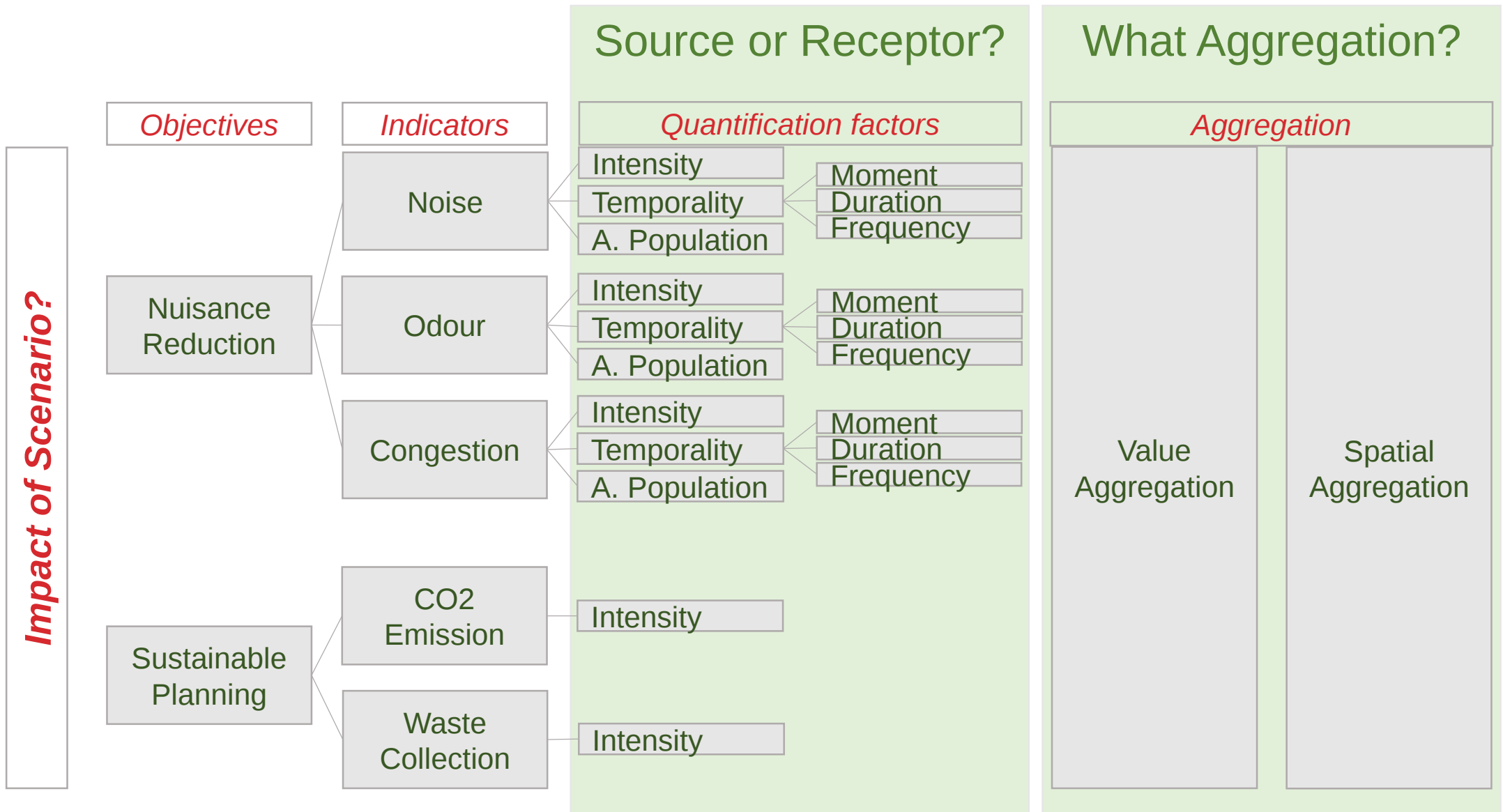


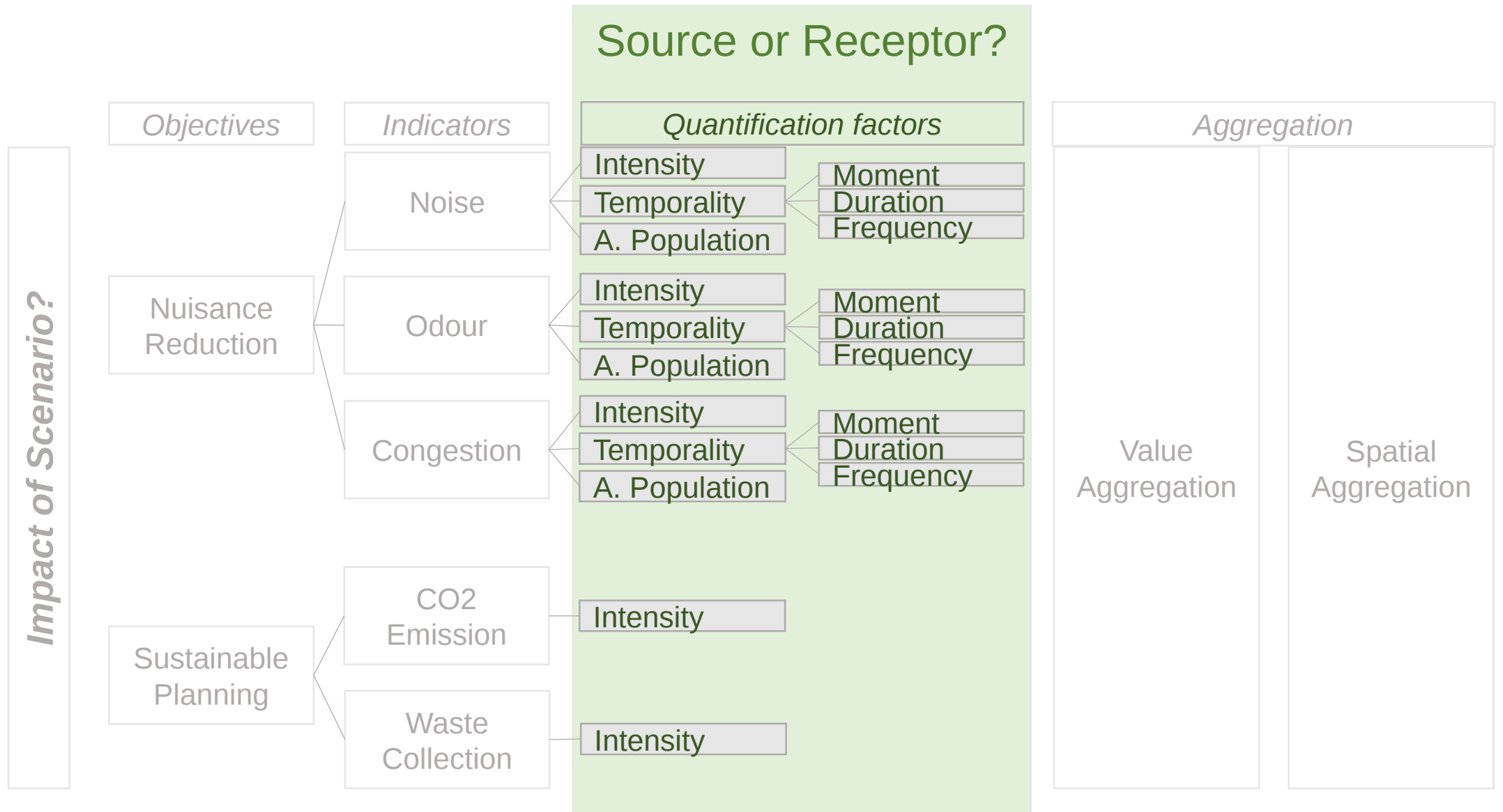


4. The Method

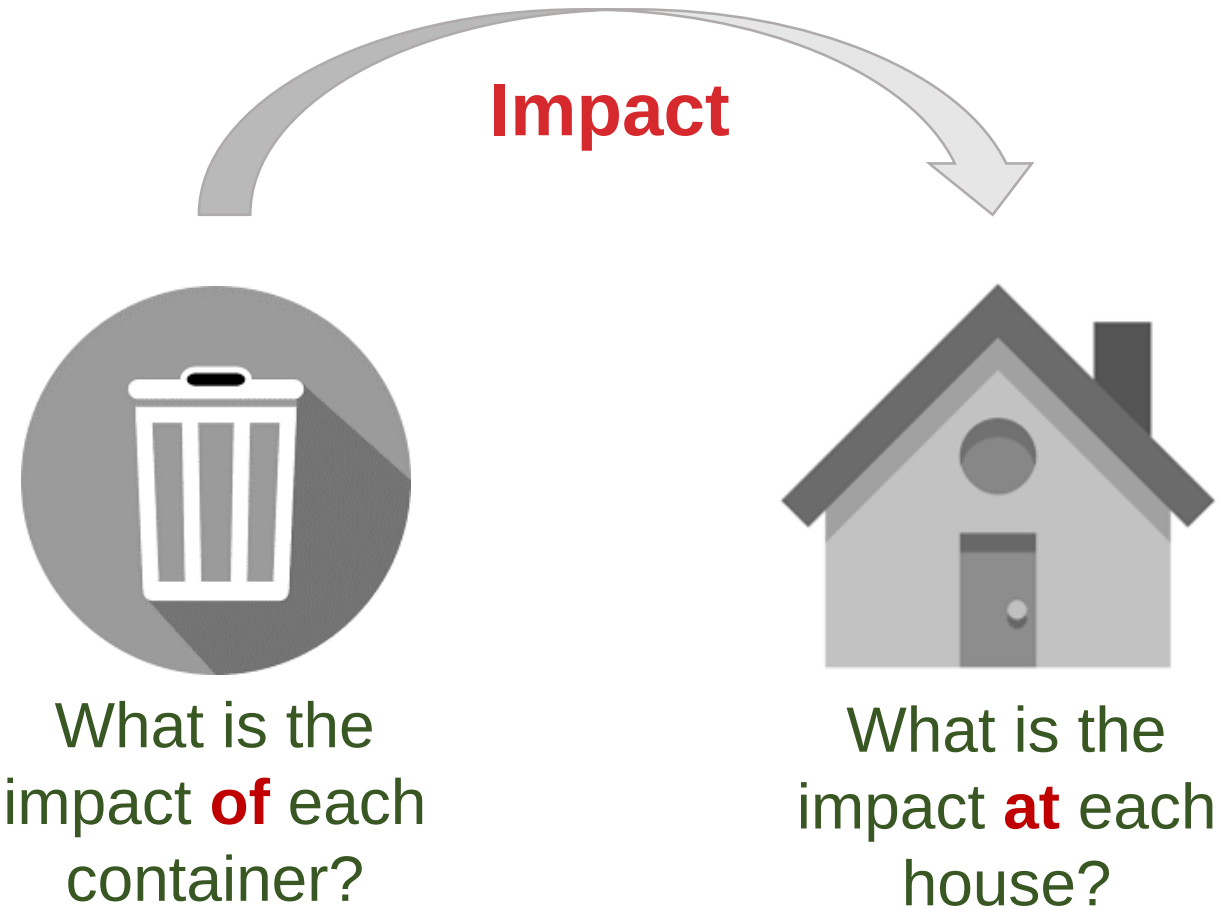
The Method Should

- **Fit the Scenarios**
 - Extent
 - Spatial Variance
 - Temporal Variance
- **Be Transparent**





Spatial Approach

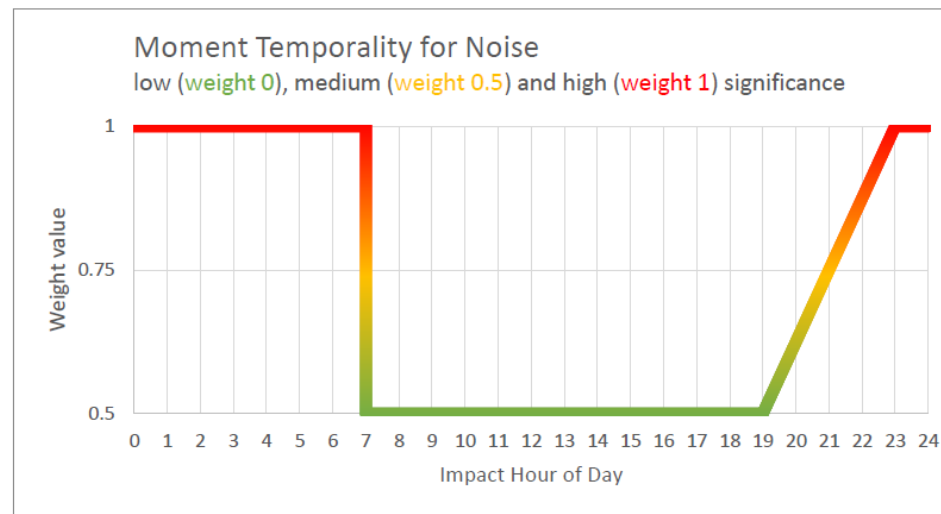


Quantification of Noise

Intensity

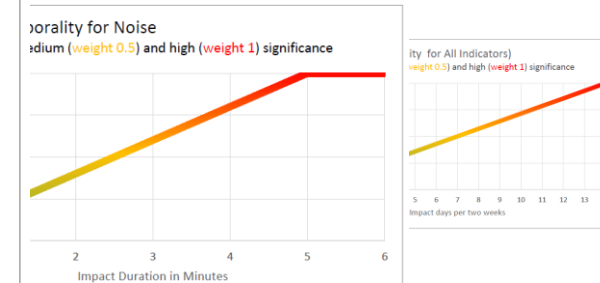
$$r = 10^{E - L - D_{\text{building}} / 10}$$

Temporality

# people within r

Receptor

$$L = E - D_{\text{distance}} - D_{\text{building}}$$



people in house

Quantification of Odour

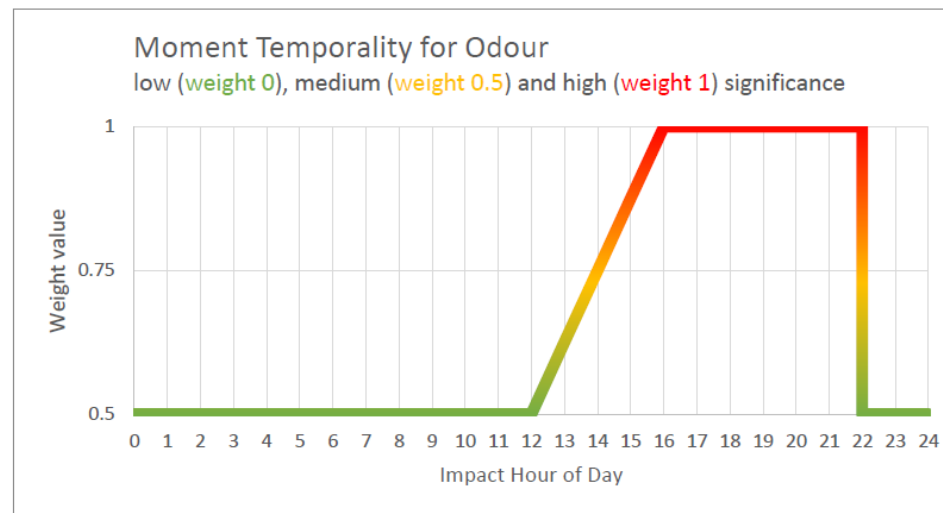
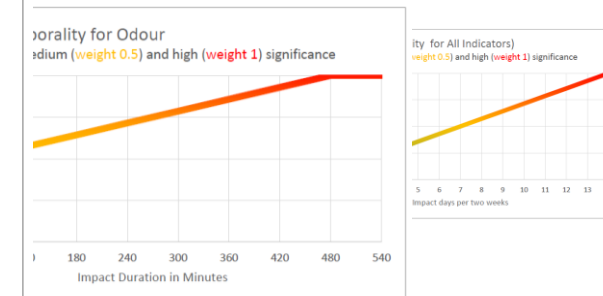
Intensity

$$r = (E / (C * \pi * u * 0.04))^{0.64}$$

Receptor

$$C = E / (\pi * 0.04 * d^{1.56} * u)$$

Temporality

# people within r 

people in house

Affected
Population

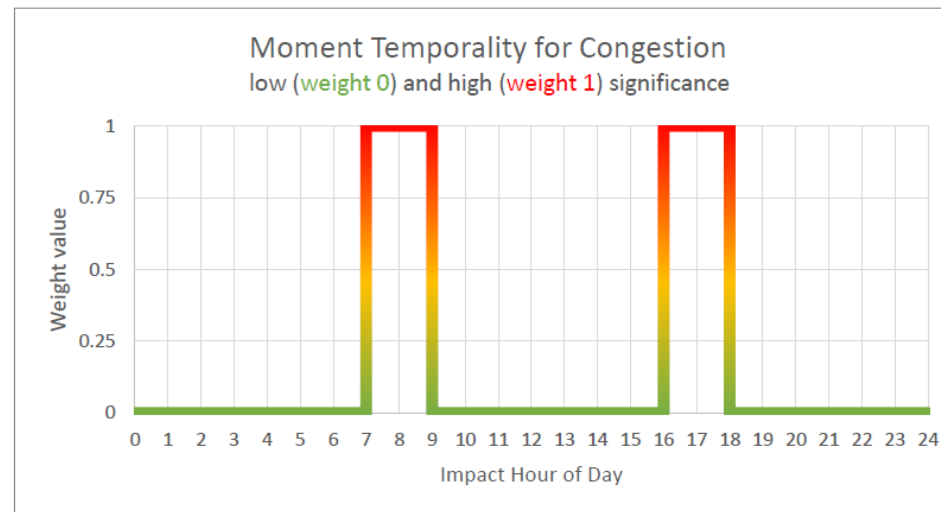
Quantification of Congestion

Intensity

Temporality

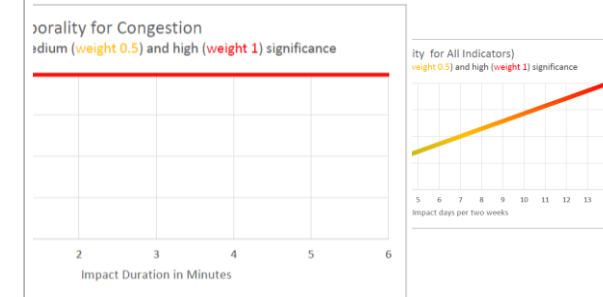
Affected
Population

Source

maximum C in proximity*maximum L in proximity*

Receptor

$$C = (L_{car} + 2 L_{truck}) / c_{car}$$



$$(L_{car} + L_{truck}) * 1.4 \frac{2}{60}$$

Quantification of CO2 Emission

Intensity

Source

$$M = d * f_{load} * f_{speed} * 2.63 * \text{frequency}$$

Quantification of Waste Collection

Intensity

Source

$$r = 140m$$

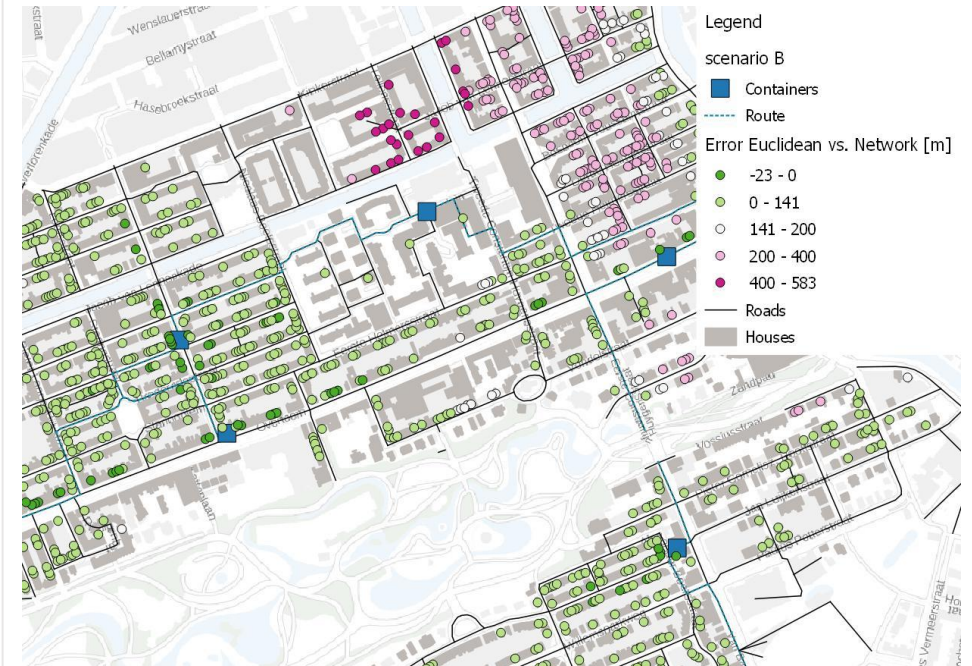
$$M = 92 * n_{people} * f_{willingness}$$



Receptor

$$A = (140 - d) / 140$$

$$M = A * 92 * n_{people} * f_{willingness}$$



First Outcomes: Noise at Receptor

Intensity

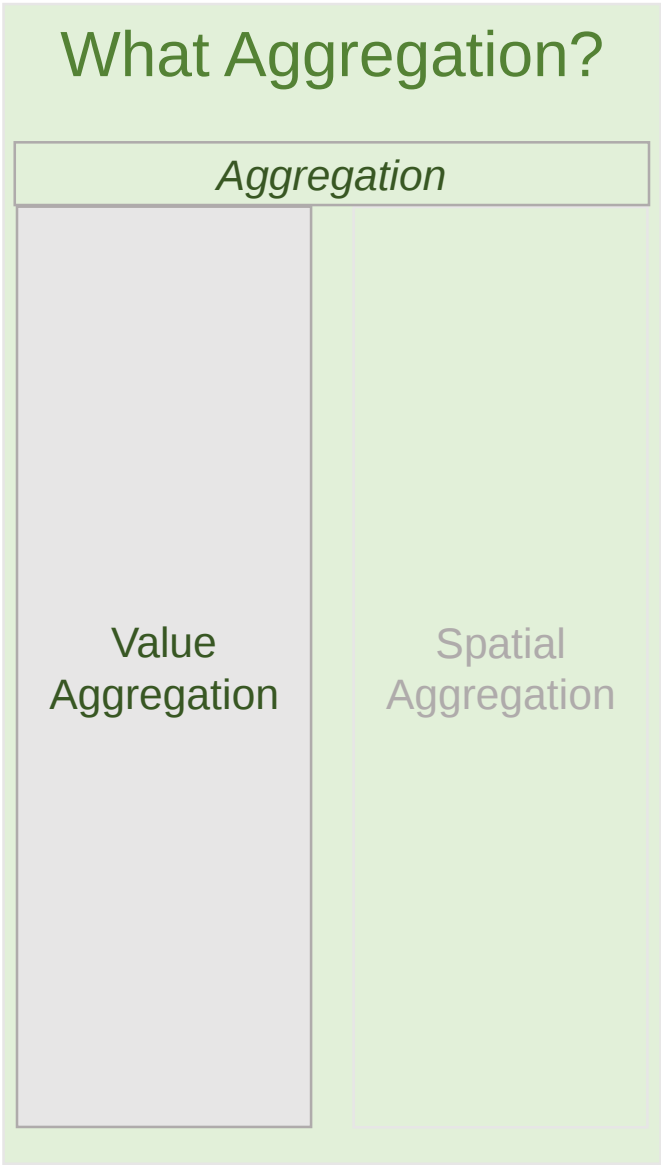
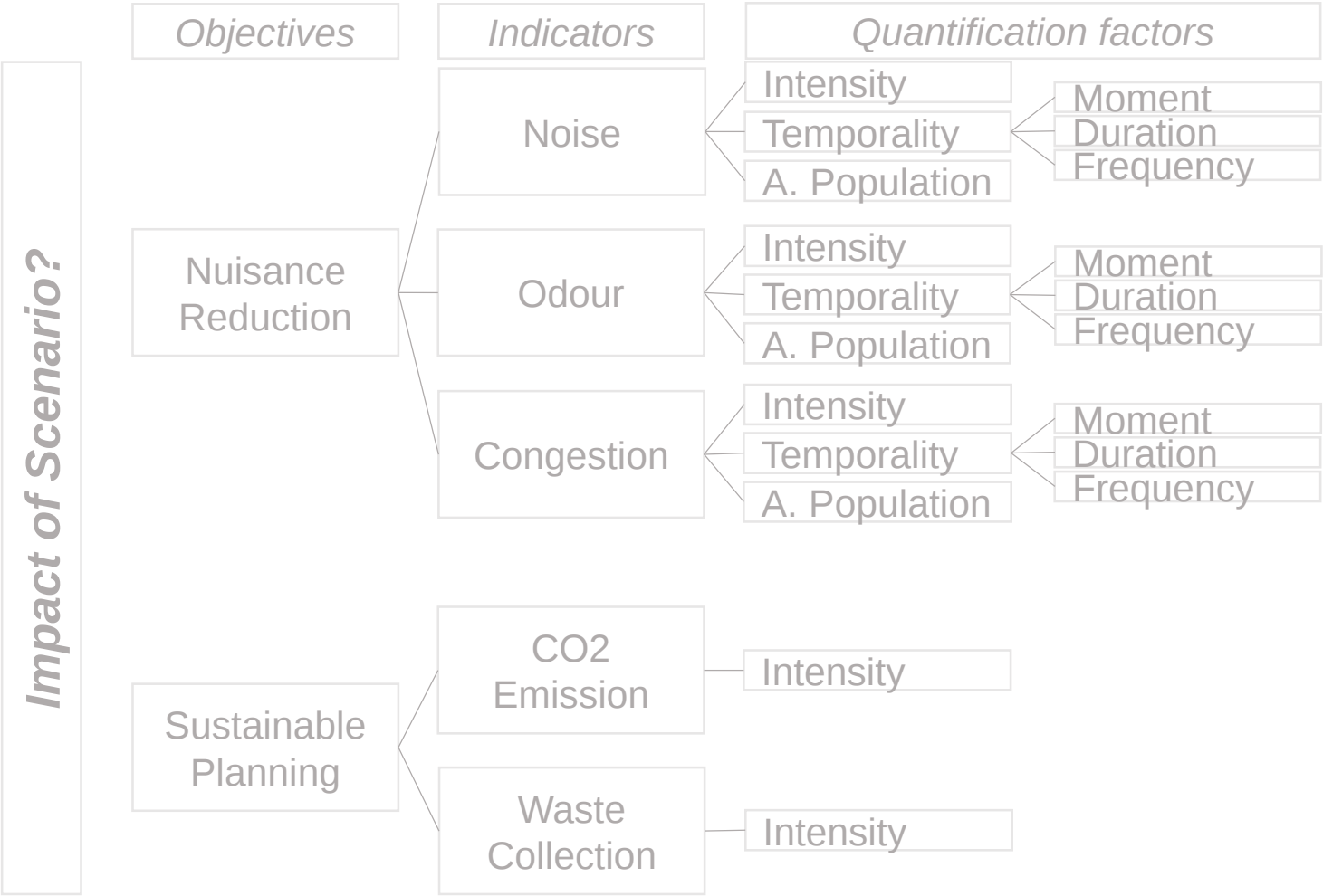


Temporality



*Affected
Population*





Value Aggregation

- Normalisation
- Aggregation: **andness**
 - Product
 - Boolean & Average
 - Boolean & Maximum

Value Aggregation

Intensity



Temporality



Affected Population



Product



Value Aggregation

Intensity



Temporality



Affected Population



Boolean & Average



Value Aggregation

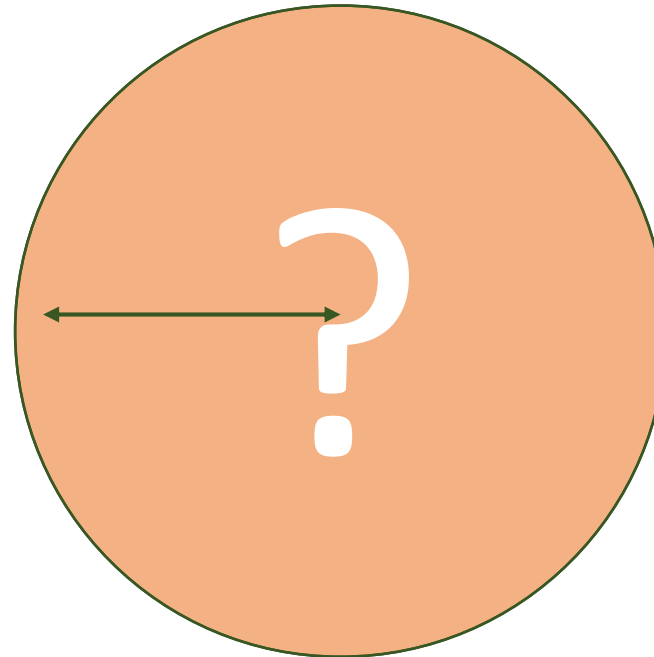
Intensity*Temporality**Affected Population*

Boolean & Maximum

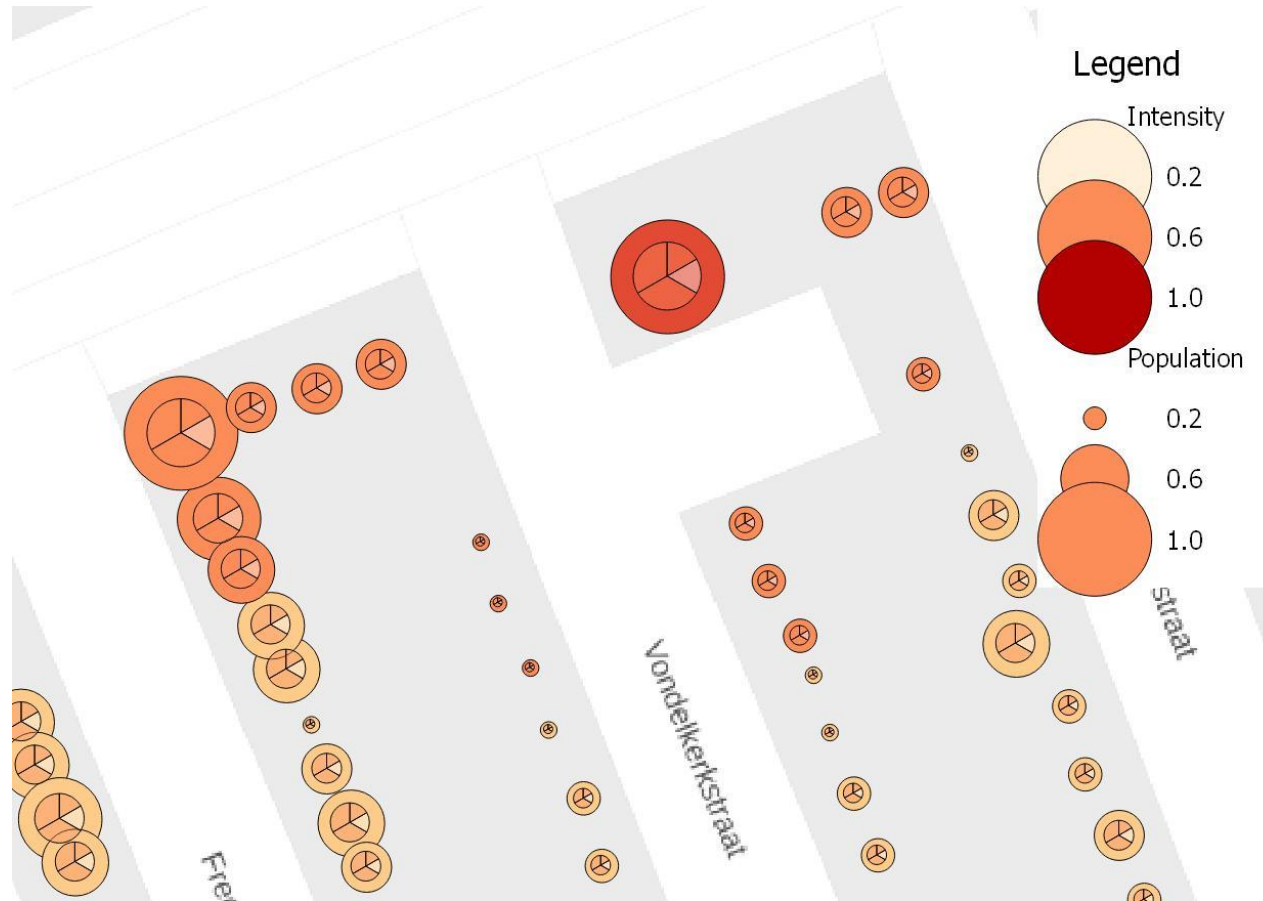


Visual Aggregation

- Affected Population
- Intensity
- 3 Temporalities
 - Diagram
 - Clock



Value Aggregation: Visual



Moment factor 1.0
Duration factor 0
Frequency factor 0



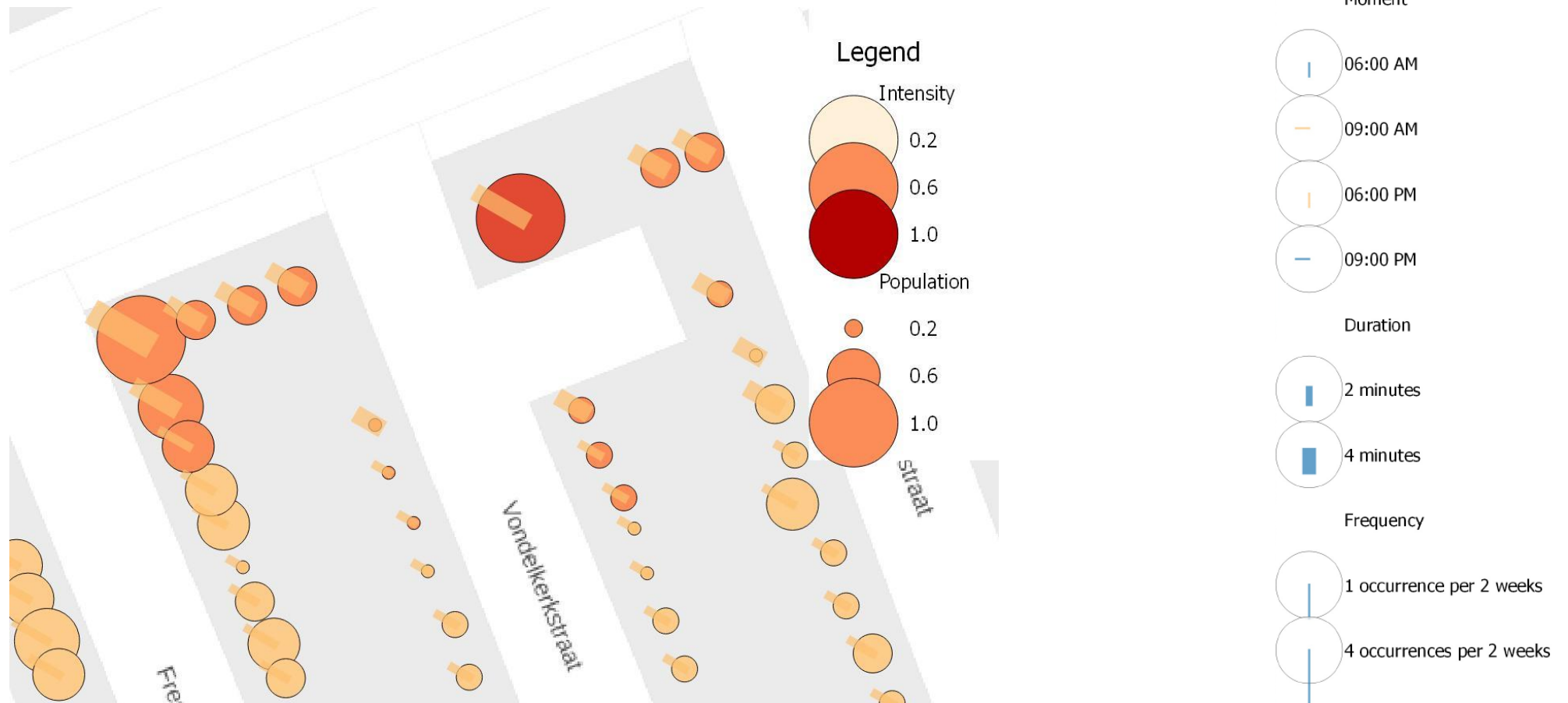
Moment factor 0
Duration factor 1.0
Frequency factor 0



Moment factor 0
Duration factor 0
Frequency factor 1.0



Value Aggregation: Visual



Outcomes: Individual Spatial Entities

Of Source

Scenario A

Noise



Odour



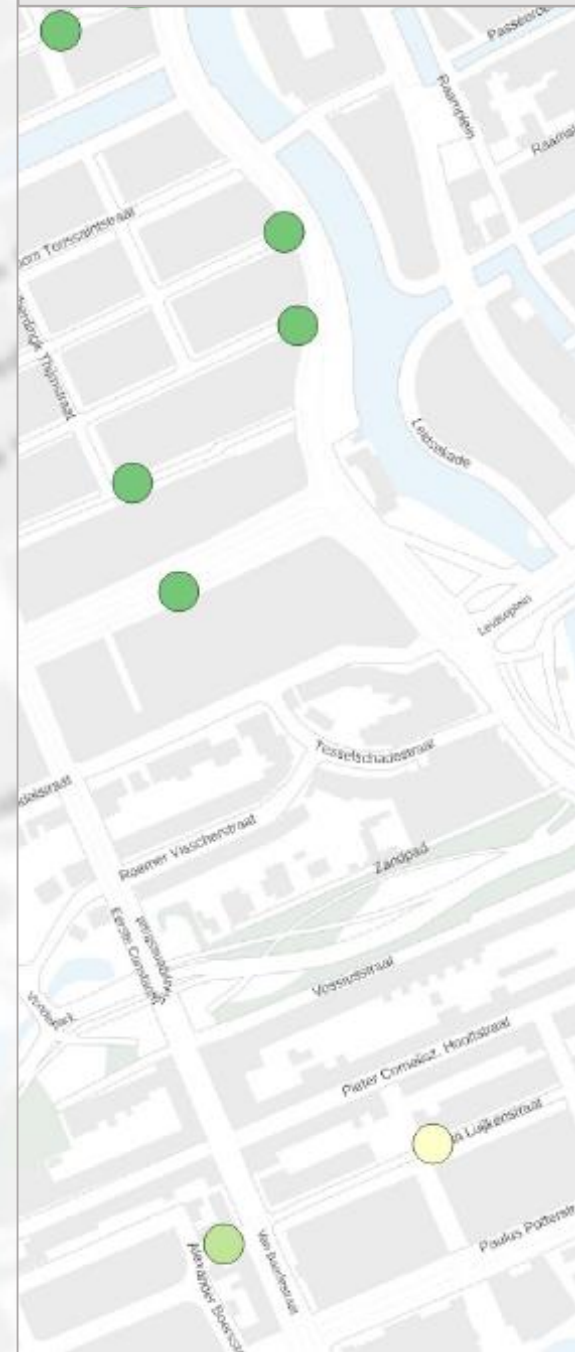
Congestion



CO2



Waste

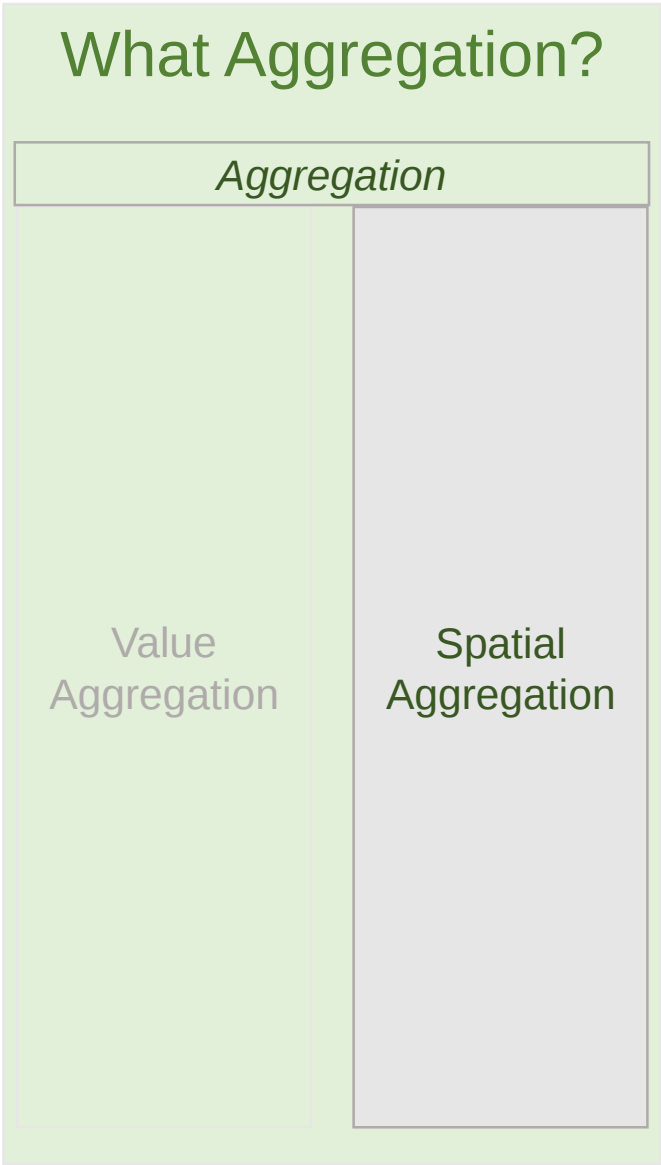
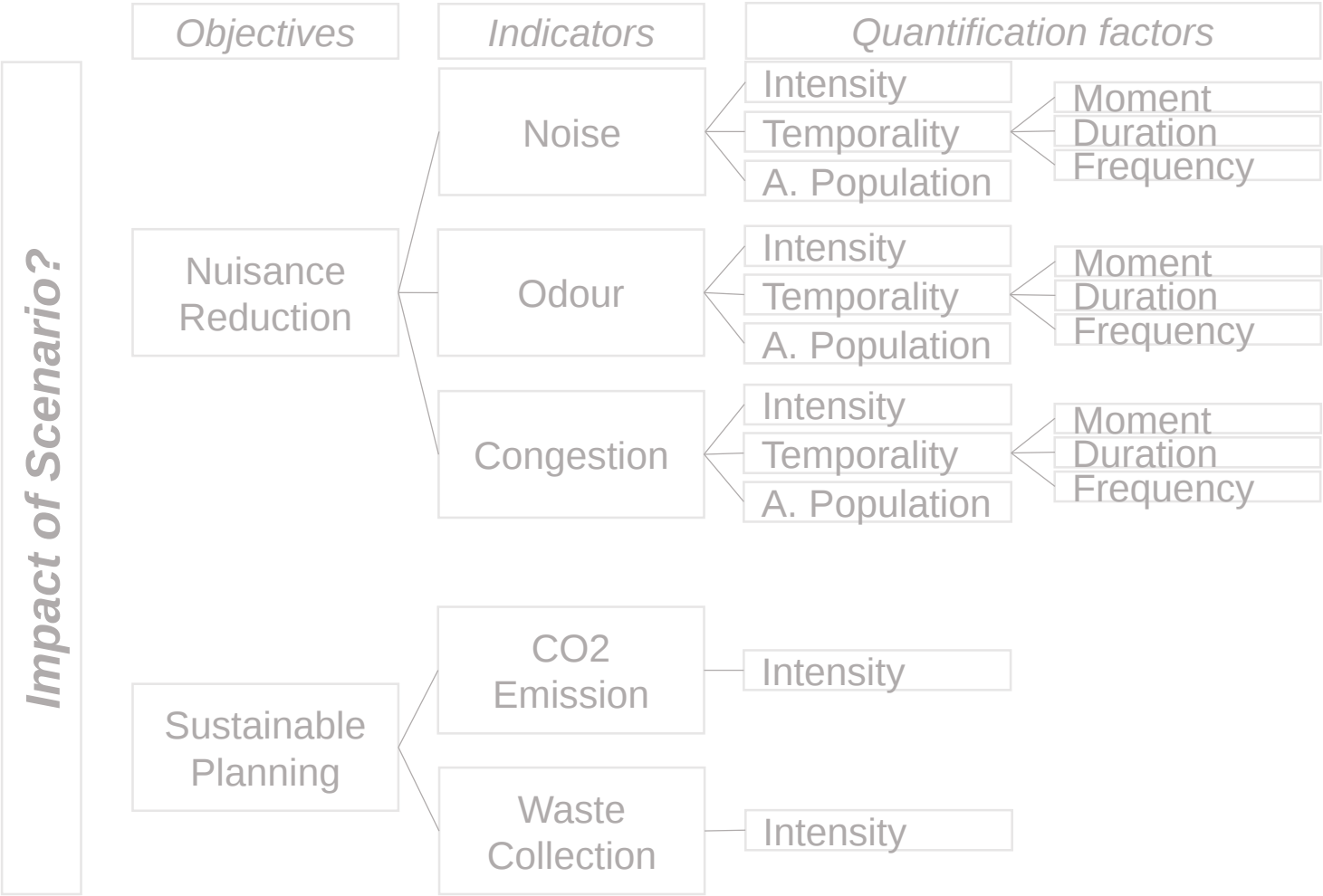


Outcomes: Individual Spatial Entities

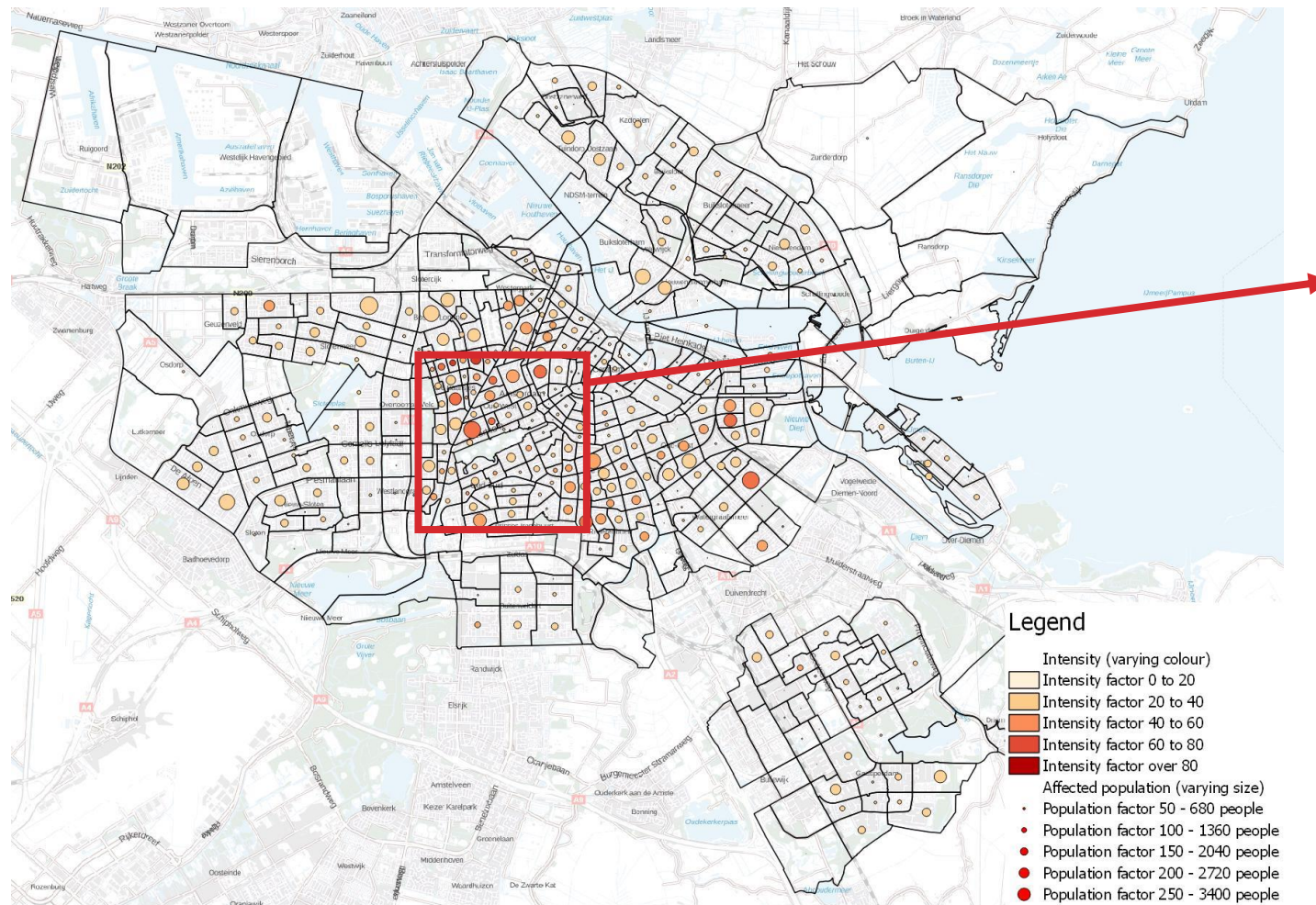
At Receptor

Scenario A

[illegible]



Spatial Aggregation

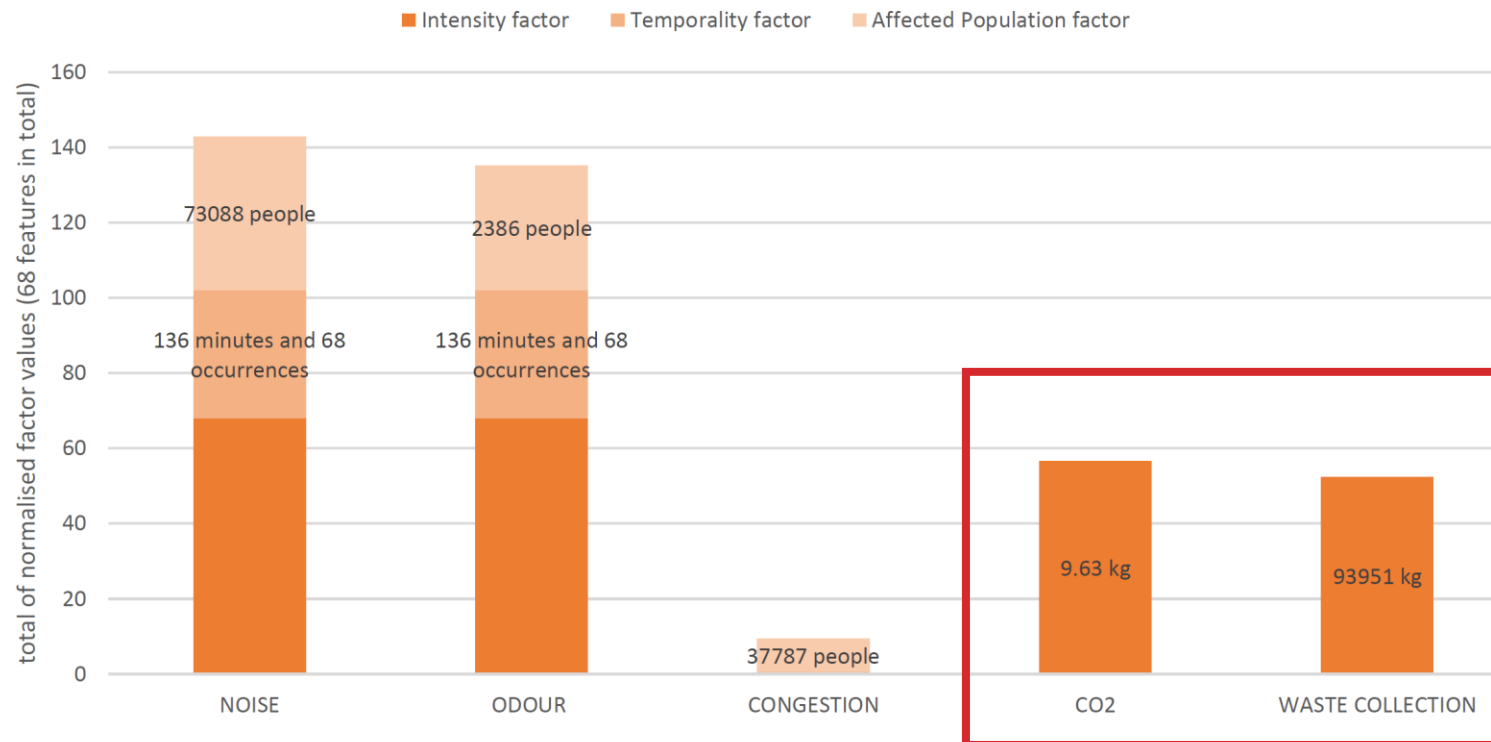


Validation: a Non-Spatial Chart

Source modelled Impact of Scenario A (testset)

totals of normalised factor values

labels with meaningful values





5. Conclusions

A Spatio-Temporal Impact Assessment Method...

Approaches Impact from **both**

- Source
- and Receptor

A Spatio-Temporal Impact Assessment Method...

Divides Impact into

- Objectives
 - Indicators
 - Factors

A Spatio-Temporal Impact Assessment Method...

Uses Nuisance Indicators

- Noise
- Odour
- Congestion

Quantified in **3 Factors**

- Intensity
 - Temporality
 - Affected Population
- Moment, Duration, Frequency

A Spatio-Temporal Impact Assessment Method...

Uses Sustainability Indicators

- CO₂
- Waste Collection

Quantified in **1 Factor**

- Intensity

A Spatio-Temporal Impact Assessment Method...

Presents Outcomes **Spatially** for

- Noise, Odour, Congestion and Waste

As Individual Entities

and Neighbourhood Totals

A Spatio-Temporal Impact Assessment Method...

Does not aggregate into values

But into **a marker**

A Spatio-Temporal Impact Assessment Method...

Presents Outcomes **also** Non-Spatially for

- CO2 & Waste Collection



6. Discussion

Critical Notes

- Assumptions
- Verification and Calibration
- Readability and Transparency

Recommendations

1. Verification and Calibration
2. Accuracy
3. User tests

What Else?

- Other Impacts
- Other Indicators
- Other Areas

Festivals, Markets?

Light Pollution?

Questions?

Roos Teeuwen, June 2018



References

Theme picture

- [2] Missouri Organic Recycling via <https://www.missouriorganic.com/food-waste-recycling>
- [3] Circular Amsterdam via <https://amsterdamsmartcity.com/circularamsterdam>
- [4] Rooijen & Nesterova (2013); Cambridge University Press (2017)
- [5] Chang & Wang (1997)
- [6] Arnaud & Davoine (2009); Gautier et al. (2017)
- [7] Peuquet (2005)
- [8] Freeman & Cudmore (2002)
- [9] Ferreti & Montibeller (2016); Antunes et al. (2001)
- [10] Yager (1988)
- [10] Antunes et al. (2001)