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A comprehensive toolbox for the gamma distribution: The gammadist package

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ABSTRACT

The gamma distribution is one of the most important parametric models in probability theory and statistics. Although a multitude of studies have theoretically investigated the properties of the gamma distribution in the literature, there is still a serious lack of tailored statistical tools to facilitate its practical applications. To fill the gap, this paper develops a comprehensive R package for the gamma distribution. In specific, the R package focuses on the following three important tasks: generate the gamma random variables, estimate the model parameters, and construct statistical limits, including confidence limits, prediction limits, and tolerance limits based on the gamma random variables. The proposed package encompasses the state-of-the-art methods of the gamma distribution in the literature and its usage is illustrated by a real application.

1. Introduction

The gamma distribution is an important distribution that has received considerable attention in the probability and statistics literature. For example, due to its relation with the exponential distribution, the gamma distribution is frequently the probability model for waiting times (Lee and Wang 2011; Lin and Lin 2015). In quality and reliability engineering, the gamma distribution is extensively used to fit the product lifetimes, as it could exhibit decreasing, constant, and increasing failure rates (Chen and Ye 2018; Wang and Wu 2018). Moreover, the gamma distribution has shown to be an appropriate model in many other application areas including environments (Baran and Nemoda 2016), wireless communications (Al-Ahmadi and Yanikomeroglu 2010), geoscience (Gao et al. 2017), disaster monitoring (Xiao et al. 2021), and image analysis (El-Zaart 2010).

The gamma distribution $Gam(k, \theta)$ has probability density function (pdf)

$$f(x) = \frac{1}{\Gamma(k)\theta^k} x^{k-1} e^{-x/\theta}, \ x > 0,$$

where $k > 0$ is the shape parameter and $\theta > 0$ is the scale parameter. In some applied fields, the parametrization with shape k and rate β, which is the inverse of θ, is more common. The mean and variance of $Gam(k, \theta)$ are $k\theta$ and , respectively. The gamma distribution includes the exponential distribution ($k = 1$) and the Chi-square distribution ($\theta = 2$) as its special cases, and the normal distribution ($k \to \infty$) as its limiting case. In addition, the gamma distribution is also closely related to the beta distribution, the Dirichlet distribution, and the F-distribution.

In order to successfully implement the gamma distribution in practice, some fundamental statistical issues need to be addressed. The first issue is about generating the gamma distributed random variables. In the literature, this task is often performed by considering $k \geq 1$ and $k < 1$ separately. Let $X \sim Gam(k, \theta)$. Simulating X when $k \geq 1$ is generally easy as transformations of X (e.g., $\log X$ and $X^{1/3}$) can be well approximated by a normal distribution. Using the normal distribution as the envelope, the gamma variates can be readily obtained by the acceptance-rejection method with low rejection rate (Ahrens and Dieter 1982; Marsaglia and Tsang 2000). This idea is employed by the default rgamma function in R for the $k \geq 1$ case. On the other hand, the $k < 1$ case is not easy to deal with as an adequate approximation

for X is lacking under small shape parameter and, hence, a proper envelope is difficult to construct. Some tailored envelope functions directly applied to the gamma density have been proposed in the literature, including Ahrens and Dieter (1974); Best (1983); and Kundu and Gupta (2007), with the first one being used by the rgamma function. However, these envelope functions generally do not provide an overall tight bound on the gamma density and the corresponding accept-reject algorithm could yield a high rejection rate. For example, it is well known that the rgamma function in R is relatively inaccurate and inefficient in sampling when the shape parameter k is small (Liu, Martin, and Syring 2017). In view of this fact, some more efficient sampling methods based on the limiting distribution of $\log X$ as $k \to 0$ have been proposed during recent years (Liu, Martin, and Syring 2017; Xi, Tan, and Liu 2013). In the proposed R package, a gamma random variable generator that suffices for all ranges of k will be developed.

The second important issue is how to estimate the gamma parameters based on the gamma distributed data. It is well known that the maximum likelihood (ML) estimators of the gamma parameters do not have closed-form expressions, and they have to be numerically obtained by algorithms such as the quasi-Newton method. However, these algorithms could easily fail to converge when the shape parameter k is small (Ye and Chen 2017). On the other hand, although the moment estimators of the gamma parameters have the closed forms, they are not efficient under either small or large samples. Recently, Ye and Chen (2017) proposed the ML-like closed-form estimators for the gamma parameters deriving from the generalized gamma distribution. The proposed estimators are shown to perform almost identically to the ML estimators in both finite and large samples. In addition, the proposed estimators are consistent and asymptotically normally distributed. Louzada, Ramos, and Ramos (2019) further improved the performance of the estimators in finite samples by considering bias correction, and these estimators will be integrated in the gammadist package.

The third task accomplished by the package is to construct some important statistical limits (intervals) of the gamma distribution, including the confidence limits, prediction limits, and tolerance limits (see, e.g., Hayter and Kiatsupaibul 2014). The confidence limits construction is undoubtedly a classical topic in statistics, as it quantifies uncertainties during point estimation. On the other hand, the prediction and tolerance limits are critical in knowing the properties of the future observations, which play fundamental roles in quality control and environment monitoring applications where the gamma distribution is a popular model. In the literature, there have been a multitude of methods of constructing these statistical limits for the gamma distribution. For example, the large-sample approximation or the bootstrap are often used to construct the confidence limits (see, e.g., Bhaumik, Kapur, and Gibbons 2009), while the normal-based method (see, e.g., Krishnamoorthy, Mathew, and Mukherjee 2008) and some complex analytical approximations (see, e.g., Bhaumik and Gibbons 2006) have been proposed for the other two statistical limits. One drawback of these methods is that their performance is not uniformly satisfactory in practice. For instance, the large-sample approximation and bootstrap only work well in large samples, and the normal-based method does not perform satisfactorily when the shape parameters are small. Until recently, the new paradigm of the generalized pivotal quantity (GPQ) has been developed for construing the statistical limits of the gamma distribution, and its uniformly outstanding performance has been verified by many studies (Chen and Ye 2017a, 2018; Wang and Wu 2018). In the gammadist package, the GPQ method will be implemented.

The remainder of the article will be organized as follows. Section 2 introduces the underlying methodologies used in the package, including random variable generation, parameter estimation, and statistical limits construction. Section 3 presents the gammadist package, which consists of six functions. For each function, its arguments and outputs are explicitly stated and its demos are shown in R code. Section 4 illustrates the package by a groundwater monitoring application. At last, Section 5 concludes the article and discusses some potential directions of extending the package.

2. Technical details

This section introduces the underlying technical details used in the gammadist package. The methods of generating random variables, estimating parameters, and constructing statistical limits will be discussed in the following subsections.

2.1. Random variable generation

As argued, we focus on generating gamma random variables when $0 < k < 1$, as the default rgamma function in R is efficient when $k \geq 1$. We only need to consider the random variable $Y \sim \text{Gam}(k, 1)$ as the scale parameter could be multiplied afterwards, that is, $X = \theta Y \sim \text{Gam}(k, \theta)$. Liu, Martin, and Syring (2017) considered the transformation $Z = -k \log(Y)$ and observed that $Z \to \text{Exp}(1)$ in distribution as $k \to$

0, where Exp (1) denotes the unit-rate exponential distribution. In specific, the density function $h(z)$ of Z is

$$h(z) = ce^{-z-e^{-z/k}}, \; z \in (-\infty, \infty),$$

where $c = 1/\Gamma(k+1)$ is the normalization constant. It is easy to see that $h(z)$ is log-concave, and it is ideally suited to acceptance-rejection sampling with two exponential envelopes oriented in opposite directions from the mode $m = 0$. This is because any line tangent to $\log h(z)$ lies above $\log h(z)$, while the log exponential density is a straight line. Thus, the aim is to find the two exponential envelopes that minimize the rejection rate. Toward this end, Liu, Martin, and Syring (2017) obtained the optimal envelop function as follows:

$$\eta(z) = \begin{cases} ce^{-z}, & \text{if } z \geq 0, \\ cw\lambda e^{\lambda z}, & \text{if } z < 0, \end{cases}$$

where $w \equiv w(k) = k/[e(1-k)]$ and $\lambda \equiv \lambda(k) = (1/k) - 1$. Thus, the two exponential distributions are Exp(1) and -Exp(λ), respectively. In addition, the ratio of sampling from Exp(1) and -Exp(λ) is $1/w$. Therefore, we only need to sample from the following mixture of two exponential distributions:

$$\frac{1}{1+w} \text{Exp}(1) + \frac{w}{1+w}[-\text{Exp}(\lambda)], \quad [1]$$

which can be easily achieved by the uniform random variable generators such as the runif function in R. Once a z is sampled from Eq. [1], it is accepted only if $h(z)/\eta(z) > u$, where u is a realization of Unif(0, 1), that is, the standard uniform distribution. The gamma random variable can then be obtained based on the transformation relation $Z = -k \log(Y)$. To summarize, Algorithm 1 shows the pseudo-code for generating the gamma random variables for all the range of $k > 0$.

Algorithm 1: Generation of the gamma random variables.

Input: Shape parameter k and scale parameter θ
Output: Gamma random variable $X \sim \text{Gam}(k, \theta)$

```
1  do
2    if k ≥ 1 then
3      X ← rgamma(k, θ) // rgamma is the
         default function in R that gener-
         ates gamma random variable with
         shape parameter k and scale param-
         eter θ
4    end
5    else
6      w ← k/e/(1 − k); λ ← 1/k − 1; r ← 1/(1 + w)
7      U₁ ← runif(0, 1) // runif(0,1) gener-
         ates the standard uniform ran-
         dom variable
8      if U₁ ≤ r then
9        z ← rexp(1) // rexp(λ) generates
           the exponential random variable
           with rate λ
10     end
11     else
12       z ← −rexp(λ)
13     end
14     U₂ ← runif(0, 1)
15     if h(z)/η(z) > U₂ then
16       Z ← z
17       Y ← exp(−Z/k)
18       X ← θY
19     end
20   end
21 until X is generated
```

2.2. Parameter estimation

The closed-form estimators proposed in Ye and Chen (2017) and Louzada, Ramos, and Ramos (2019) are used for parameter estimation. The underlying idea is to use the generalized gamma distribution GGam(k, θ, b), which has pdf

$$g(x) = \frac{b}{\Gamma(k)\theta^{bk}} x^{bk-1} e^{-(x/\theta)^b}, \; x > 0.$$

When $b = 1$, the generalized gamma distribution degenerates to the gamma distribution. Let $X \sim$ GGam(k, θ, b) and $X_1, ..., X_n$ be independent and identically distributed copies of X. Thus, the score equations are

$$-\psi(k) - b \log \theta + \frac{b}{n} \sum_i \log X_i = 0,$$

$$-k + \frac{1}{n} \sum_i (X_i/\theta)^b = 0,$$

$$\frac{1}{b} + \frac{k}{n} \sum_i \log(X_i/\theta) - \frac{1}{n} \sum_i (X_i/\theta)^b \log(X_i/\theta) = 0.$$

By setting $b = 1$ in the above equations and noting $\beta = 1/\theta$, the closed-form estimators for k, θ, and β could then be obtained as

$$\hat{k} = \frac{n \sum_i X_i}{n \sum_i Xi \log X_i - \sum_i \log X_i \sum_i X_i},$$
$$\hat{\theta} = \frac{n \sum_i X_i \log X_i - \sum_i \log X_i \sum_i X_i}{n^2}, \quad [2]$$
$$\hat{\beta} = \frac{n^2}{n \sum_i X_i \log X_i - \sum_i \log X_i \sum_i X_i}.$$

Ye and Chen (2017) numerically showed that these estimators perform almost identically to the ML

estimators in finite samples and they are nearly efficient in large samples. To facilitate small-sample applications, the authors further proposed the bias-corrected estimators for the parameters. Because the estimator of k is based on an asymptotic argument and it still has systematic biases in finite samples, Louzada, Ramos, and Ramos (2019) further proposed an improved version. The idea is to subtract the second-order bias of the ML estimator, and a useful approximation was proposed by the authors; see Louzada, Ramos, and Ramos (2019) for more technical details.

In summary, the bias-corrected estimators for $k, \theta,$ and β are, respectively, given by

$$
\tilde{k} = \hat{k} - \frac{1}{n}\left[3\hat{k} - \frac{2\hat{k}}{3(1+\hat{k})} - \frac{4\hat{k}}{5(1+\hat{k})^2}\right],
$$
$$
\tilde{\theta} = \frac{n}{n-1}\hat{\theta} = \frac{n\sum_i X_i \log X_i - \sum_i \log X_i \sum_i X_i}{n(n-1)},
$$
$$
\tilde{\beta} = \frac{n-1}{n+2}\hat{\beta} = \frac{n^2(n-1)}{(n+2)(n\sum_i X_i \log X_i - \sum_i \log X_i \sum_i X_i)},
$$
[3]

where the closed-form expressions of $\hat{k}, \hat{\theta}$ and $\hat{\beta}$ are given in Eq. [2]. Algorithm 2 illustrates the overall estimation procedures.

Algorithm 2: Estimation of the parameters of a gamma distribution.

    Input: n observations $x_1, ..., x_n$.
    Output: Estimates of k, θ and β.
1 Compute the closed-form estimators $\hat{k}, \hat{\theta}$ and $\hat{\beta}$ by using Eq. [2]
2 Compute the bias-corrected closed-form estimators $\tilde{k}, \tilde{\theta}$ and $\tilde{\beta}$ by using Eq. [3]

2.3. Construction of statistical limits

In this section, the GPQ method will be implemented for constructing the statistical limits of the gamma distribution. We first give a brief introduction of the GPQ method. As its name stands for, GPQ is a generalization of the classical pivotal quantity, and it is particularly useful in constructing statistical limits in the presence of nuisance parameters. Since its first introduction by Weerahandi (1993), the GQP method has received significant attention in the literature for its

outstanding performance in interval estimation; successful applications can be found in Krishnamoorthy, Mallick, and Mathew (2011), Chen and Ye (2017b), and Wang et al. (2021a), to name a few. Suppose that we are interested in making inference of one unknown parameter $\theta \in \boldsymbol{\theta}$, where $\boldsymbol{\theta}$ is the vector of all the unknown parameters. Then, $\mathcal{G}_\theta(\mathbf{X}, \mathbf{x}, \boldsymbol{\theta})$, which is a function of the random sample $\mathbf{X} = (X_1, ..., X_n)$, the observed data $\mathbf{x} = (x_1, ..., x_n)$ and the unknown parameters $\boldsymbol{\theta}$, are a GPQ for θ if it satisfies the following two conditions:

C1. $\mathcal{G}_\theta(\mathbf{X}, \mathbf{x}, \boldsymbol{\theta})$ has a probability distribution that is free of unknown parameters $\boldsymbol{\theta}$.
C2. The observed pivotal, defined as $\mathcal{G}_\theta(\mathbf{x}, \mathbf{x}, \boldsymbol{\theta})$, only depends on θ, that is, it does not depend on the nuisance parameters.

Based on the distribution of $\mathcal{G}_\theta(\mathbf{X}, \mathbf{x}, \boldsymbol{\theta})$, the confidence interval for θ can be constructed, which is known as the generalized confidence interval (GCI). Asymptotically, the GCI achieves the exact coverage under some mild conditions (Hannig, Iyer, and Patterson 2006). Moreover, numerous studies in the literature showed the excellent performance of the GCI under small and moderate sample sizes (see, e.g., Krishnamoorthy, Lee, and Zhang 2017; Wang et al. 2021b).

2.3.1. GPQs for the gamma parameters
GPQs for the parameters of the gamma distribution were first developed in Chen and Ye (2017a, 2017b), and later the GPQ for the shape parameter k was improved by Wang and Wu (2018). In the R package, the GPQs proposed by Wang and Wu (2018) are used as they yield better performance in terms of the coverage probabilities. In specific, let $T = \log(\tilde{X}/\bar{X})$ where $\tilde{X} = \prod_i X_i^{1/n}$ and $\bar{X} = \sum_i X_i/n$. Iliopoulos (2016) showed the distribution of T only depends on the shape parameter k. Let $F(T|k)$ be the cumulative distribution function (cdf) of T and then $F(T|k) \sim U_k$, where U_k follows the standard uniform distribution. In other words, $T = Q(U_k|k)$, where $Q(p|k)$ represents the pth quantile of T and it depends on k only. On the other hand, the quantiles could be approximated by the Cornish-Fisher expansion, that is,

$$
Q(p|k) = z_p + \frac{1}{6}\tilde{c}_3(z_p^2 - 1) + \frac{1}{24}\tilde{c}_4(z_p^3 - 3z_p) - \frac{1}{36}(\tilde{c}_3)^2(2z_p^3 - 5z_p)
$$
$$
+ \frac{1}{120}\tilde{c}_5(z_p^4 - 6z_p^2 + 3) - \frac{1}{24}\tilde{c}_3\tilde{c}_4(z_p^4 - 5z_p^2 + 2) + \frac{1}{324}(\tilde{c}_3)^3(12z_p^4 - 53z_p^2 + 17),
$$

where c_i is the ith cumulant of T, $\tilde{c}_i = c_i/(c_2)^{i/2}$ and z_p is the pth quantile of a standard normal distribution. The expressions of c_i's are derived in Wang and Wu (2018) and they are given by

$$c_1 \equiv c_1(k) = \log(n) + \psi(k) - \psi(nk),$$
$$c_i \equiv c_i(k) = \frac{1}{n^{i-1}}\psi_{i-1}(k) - \psi_{i-1}(nk), \quad i = 2, 3, ...,$$

where $\psi(k) = \Gamma'(k)/\Gamma(k)$ is the digamma function and $\psi_i(\cdot)$ is the ith derivative of $\psi(\cdot)$. With all these treatments, the GPQ $\mathcal{G}_k$ for k can be readily obtained by solving

$$\log(\tilde{x}/\bar{x}) = c_1(\mathcal{G}_k) + [c_2(\mathcal{G}_k)]^{1/2}Q(U_k|\mathcal{G}_k), \qquad [4]$$

where $\tilde{x}$ and $\bar{x}$ are the observed geometric and arithmetic means, respectively. As seen, the distribution of $\mathcal{G}_k$ only depends on the standard uniform distribution U_k, so the first condition (C1) is satisfied. In addition, the observed pivotal, where U_k is replaced by its observed value, is equal to k, so the second condition (C2) also holds. Therefore, $\mathcal{G}_k$ is a valid GPQ for k. Because T is stochastically strictly increasing in k (Iliopoulos 2016), the above equation can be easily solved by bisection search given a realization of U_k. As for the scale parameter θ, observe that $2n\bar{X}/\theta \sim \chi^2(2nk)$, a χ^2 distribution with $2nk$ degrees of freedom. Conditional on $\mathcal{G}_k$, the GPQ for θ can be constructed as

$$\mathcal{G}_\theta = 2n\bar{x}/U_\theta,$$

where $U_\theta \sim \chi^2(2n\mathcal{G}_k)$. It is easy to check that $\mathcal{G}_\theta$ is independent of k and θ and its observed value is equal to θ. Therefore, $\mathcal{G}_\theta$ is a valid GPQ for θ. Consequently, the GPQ for the rate parameter β is $\mathcal{G}_\beta = 1/\mathcal{G}_\theta$.

The exact distributions of the GPQs are difficult to derive. Nevertheless, their realizations can be readily generated by using the Monte Carlo simulation, and the procedures are summarized in Algorithm 3.

Algorithm 3: Generation of the realizations of the GPQs of the gamma parameters.

    Input: n observations $x_1, ..., x_n$ and the number of realizations B.

    Output: B realizations of the GPQs of k, θ, and β.

1   $\tilde{x} \leftarrow \prod_i x_i^{1/n}$; $\bar{x} \leftarrow \sum_i x_i/n$

2 for i in $1:B$ **do**

3     $U_k \leftarrow$ runif$(0,1)$ // runif(0,1) generates the standard uniform random variable

4     $\mathcal{G}_k \leftarrow$ solution of Eq. [4]

5     $U_\theta \leftarrow$ rchisq$(2n\mathcal{G}_k)$ // rchisq(a) generates the χ^2 random variable with a degrees of freedom

6     $\mathcal{G}_\theta \leftarrow 2n\bar{x}/U_\theta$

7     $\mathcal{G}_\beta \leftarrow 1/\mathcal{G}_\theta$

8 end

2.3.2. Confidence limits

One direct application of the derived GPQs is to construct the confidence intervals of the parameters. Mathematically, for a parameter θ, we want to construct two statistics, $L(\mathbf{X})$ and $U(\mathbf{X})$, such that the coverage probability

$$P[L(\mathbf{X}) \leq \theta \leq U(\mathbf{X})] = 1 - \alpha,$$

where $1 - \alpha$ is the pre-determined confidence level. Common values of α include 0.01, 0.05, and 0.1. Once the observed data $\mathbf{x}$ is available, the confidence interval for θ is $[L(\mathbf{x}), U(\mathbf{x})]$. The one-sided confidence limits are defined by taking $L(\mathbf{x}) = -\infty$ (upper confidence limit) and $U(\mathbf{x}) = \infty$ (lower confidence limit). Similar to the use of classical pivotal quantities, the quantiles of the GPQs can be treated as the confidence intervals of the parameters, which can be well approximated by the empirical percentiles of the GPQ realizations. The detailed procedures of constructing confidence intervals of the gamma parameters are illustrated in Algorithm 4.

Algorithm 4: Construction of confidence limits of the gamma parameters.

    Input: n observations $x_1, ..., x_n$, the number of realizations B, and the confidence level $1 - \alpha$.

    Output: confidence interval, lower confidence limit, and upper confidence limit of k, θ and β.

1 Obtain B realizations of GPQs for the parameters by using Algorithm 3

2 Use the $\alpha/2$ th and $(1 - \alpha/2)$ th empirical percentiles as the $1 - \alpha$ confidence interval, the αth empirical percentile as the $1 - \alpha$ lower confidence limit, and the $(1 - \alpha)$ th empirical percentile as the $1 - \alpha$ upper confidence limit

---

2.3.3. Prediction limits

The prediction interval is another important statistical interval, which predicts the range of a future observation with a certain probability. Consider two statistics $PL(\mathbf{X})$ and $PU(\mathbf{X})$, and the next sample variable X_{n+1}. A $1 - \alpha$ prediction interval $[PL(\mathbf{X}), PU(\mathbf{X})]$ satisfies

$$P[L(\mathbf{X}) \leq X_{n+1} \leq U(\mathbf{X})] = 1 - \alpha,$$

where $1 - \alpha$ is the confidence level. The one-sided prediction limits can be easily constructed as the open-ended version of the prediction interval. Regarding the gamma distribution, its prediction limits construction plays an important role in

applications such as environment monitoring and quality control (Chen and Ye 2017a; Wang and Wu 2018). The GQP method can again be invoked. In specific, for each pair of realizations $(\mathcal{G}_k, \mathcal{G}_\theta)$, a gamma variable is generated. Afterwards, B gamma variables will be generated based on B realizations of $(\mathcal{G}_k, \mathcal{G}_\theta)$, whose empirical percentiles can be used as the prediction limits. The detailed procedures are summarized in Algorithm 5.

Algorithm 5: Construction of prediction limits of the gamma distribution.

> **Input:** n observations $x_1, ..., x_n$, the number of realizations B, and the confidence level $1 - \alpha$.
> **Output:** prediction interval, lower prediction limit and upper prediction limit.

1 Obtain B realizations of $(\mathcal{G}_k, \mathcal{G}_\theta)$ by using Algorithm 3
2 For each realization of $(\mathcal{G}_k, \mathcal{G}_\theta)$, generate a gamma variable by using Algorithm 1
3 Use the $\alpha/2$ th and $(1 - \alpha/2)$ th empirical percentiles of the generated B gamma variables in the last step as the $1 - \alpha$ prediction interval, the αth empirical percentile as the $1 - \alpha$ lower prediction limit, and the $(1 - \alpha)$ th empirical percentile as the $1 - \alpha$ upper prediction limit

---

2.3.4. Tolerance limits

When the number of future measurements is either large or unknown, the appropriate statistical limits to quantify the range of future observations are the tolerance limits. Consider two statistics $TL(\mathbf{X})$ and $TU(\mathbf{X})$, and $[TL(\mathbf{X}), TU(\mathbf{X})]$ is the $(\gamma, 1 - \alpha)$ tolerance interval if it contains at least a proportion γ of the population with confidence level $1 - \alpha$, that is,

$$P[(F_X(TU(\mathbf{X})) - F_X(TL(\mathbf{X}))) \geq \gamma] = 1 - \alpha,$$

where $F_X(\cdot)$ is the cdf of the random variable X. If we set $TL(\mathbf{X}) = -\infty$ and $TU(\mathbf{X}) = \infty$, we get the $(\gamma, 1 - \alpha)$ upper and lower tolerance limits, respectively.

In terms of the gamma distribution, the one-sided tolerance limits can be readily obtained based on their relationship with the confidence limits for the quantiles of the gamma distribution. In specific, the $(\gamma, 1 - \alpha)$ upper tolerance limit is equal to the $1 - \alpha$ upper confidence limit for the γth quantile and the $(\gamma, 1 - \alpha)$ lower tolerance limit is equal to the $1 - \alpha$ lower confidence limit for the $(1 - \gamma)$ th quantile. Because the gamma quantiles are functions of the gamma parameters, their one-sided confidence limits can be obtained by using the GPQ realizations of the parameters.

Algorithm 6 summarizes the procedures to obtain the one-sided tolerance limits.

Algorithm 6: Construction of one-sided tolerance limits of the gamma distribution.

> **Input:** n observations $x_1, ..., x_n$, the number of realizations B, the proportion of population γ, and the confidence level $1 - \alpha$.
> **Output:** lower tolerance limit and upper tolerance limit.

1 Obtain B realizations of $(\mathcal{G}_k, \mathcal{G}_\theta)$ by using Algorithm 3
2 For each realization of $(\mathcal{G}_k, \mathcal{G}_\theta)$, generate the gamma quantile by using qgamma$(\gamma, \mathcal{G}_k, \mathcal{G}_\theta)$
3 Use the $(1 - \alpha)$ th empirical percentile of the generated B gamma quantiles in the last step as the $(\gamma, 1 - \alpha)$ upper tolerance limit
4 For each realization of $(\mathcal{G}_k, \mathcal{G}_\theta)$, generate the gamma quantile by using qgamma$(1 - \gamma, \mathcal{G}_k, \mathcal{G}_\theta)$
5 Use the αth empirical percentile of the generated B gamma quantiles in the last step as the $(\gamma, 1 - \alpha)$ lower tolerance limit

---

On the other hand, the GPQ method is not directly applicable to construct the two-sided tolerance intervals, as there is no unique mapping between the tolerance interval and the gamma quantile. Based on the investigation from Chen and Ye (2017a), the normal-based method, proposed by Krishnamoorthy, Mathew, and Mukherjee (2008), is more straightforward to implement in terms of constructing the tolerance intervals of the gamma distribution. The underlying idea of the normal-based method is that the cube root of the gamma random variable $R = X^{1/3}$ is approximately normally distributed due to the famous Wilson-Hilferty approximation (Krishnamoorthy, Mathew, and Mukherjee 2008). In the literature, constructing tolerance intervals for the normal distribution has been well studied. Let $\bar{R}$ and S_R^2 be the sample mean and sample variance based on the transformed variables $R_1, R_2, ..., R_n$. The tolerance interval $[TL_R, TU_R]$ regarding R has the form of $\bar{R} \pm v S_R$, where v is the tolerance factor. Exact values of v can be obtained by solving an equation involving the integral and many satisfactory approximations have been proposed in the literature. The approximation used in the package is

$$v = \left(\frac{(n-1)\chi^2_{1,\gamma}(1/n)}{\chi^2_{n-1,\alpha}} \right)^{1/2}, \qquad [5]$$

where $\chi^2_{1,\gamma}(1/n)$ represents the γth quantile of a non-central χ^2 distribution with 1 degree of freedom and noncentrality parameter $1/n$, and $\chi^2_{n-1,\alpha}$ represents the αth quantile of a χ^2 distribution with $n - 1$

degrees of freedom. The outstanding performance of this approximation even under small sample sizes has been verified by the numerical studies in Krishnamoorthy and Mathew (2009, sec 2.3). Once $[TL_R, TU_R]$ is available, the tolerance interval for the gamma distribution can be computed as $[TL, TU] = [TL_R^3, TU_R^3]$. For illustration, the procedure of constructing tolerance intervals for the gamma distribution is narrated in Algorithm 7.

Algorithm 7: Construction of two-sided tolerance intervals of the gamma distribution.

Input: n observations $x_1, ..., x_n$, the number of realizations B, the proportion of population γ, and the confidence level $1 - \alpha$.

Output: two-sided tolerance interval.

1 Cube-root transform $x_1, ..., x_n$ to $r_1, ..., r_n$ where $r_i = x_i^{1/3}$

2 Compute the normal $(\gamma, 1 - \alpha)$ tolerance interval $[TL_R, TU_R]$ by $\bar{r} \pm v s_r$, where the tolerance factor v can be computed by Eq. [5]

3 The $(\gamma, 1 - \alpha)$ tolerance interval of the gamma distribution is $[TL_R^3, TU_R^3]$

---

3. The gammadist package

The algorithms in Section 2 will be realized as R functions in the gammadist package to facilitate the use of gamma distribution in practice. A summary of the functions is given as follows:

- rGamma: generate the gamma random variables based on Algorithm 1.
- parest: estimate the parameters of a gamma distribution based on Algorithm 2.
- pargpq: generate realizations of GPQs of the gamma parameters based on Algorithm 3.
- conflimits: construct confidence limits of the gamma parameters based on Algorithm 4.
- predlimits: construct prediction limits of the gamma distribution based on Algorithm 5.
- tollimits: construct tolerance limits of the gamma distribution based on Algorithms 6 and 7.

Detailed description and demos of these functions will be presented in the following subsections. All demos are coded using R (version 4.0.4) on a computer with a standard Intel i7 processor and a Windows 10 system.

3.1. rGamma function

Similar to the default rgamma function, the rGamma function has the following four arguments:

- n: number of observations, which is a positive integer.
- shape: shape parameter of the gamma distribution, which is a positive real number.
- rate: rate parameter of the gamma distribution, which is a positive real number. The default value is 1.
- scale: scale parameter of the gamma distribution, which is the inverse of the rate.

Some examples of using the rGamma function are as follows:

```
# generate 10 gamma variates with shape-
=0.5 and scale=2
R>set.seed(1)
R>gamma.rv1 <- rGamma(10, shape=0.5,
scale=2)
R>gamma.rv1
[1]  0.18822102  3.80508508  0.03421693
0.17101963  1.09029916  0.16829112
0.04693821  0.61642892  0.13760850
0.64494911
# generate 10 gamma variates with shape-
=2 and scale=1
# this is essentially generated by the
default rgamma function
R>set.seed(2)
R>gamma.rv2 <- rGamma(10, shape=2)
R>gamma.rv2
[1]  0.6026224  0.5532367  0.4350155
1.6577979  0.7565759  1.2207949
0.7198031  2.0551237  2.9433563
1.0576008
```

3.2. parest function

The argument of the parest function is simply

- x: observations from a gamma distribution.

In addition, the function returns the estimation results as a list with components

- shape: estimate of the shape parameter.
- scale: estimate of the scale parameter.
- rate: estimate of the rate parameter.

Some examples of using the parest function are as follows:

```
R>set.seed(3)
R>x <- rGamma(10, shape=0.5)
```

```
# return a list that contains all the
estimates of the three parameters
R > est.all <- parest(x)
R > est.all
$rate
[1] 1.054187
$scale
[1] 0.7904987
# return the estimate of the shape par-
ameter
R > est.shape <- est.all$shape
R > est.shape
[1] 0.3624244
```

3.3. pargpq function

The use of the pargpq function is straightforward, that is, it uses the observed data as the input and generates the realizations of the GPQs of the gamma parameters as the output. In specific, the arguments are

- x: observations from a gamma distribution.
- B: number of realizations of the GPQs. If B is not specified, the default value is 2000,

and the returned data frame is a list of three variables

- shape: B realizations of the GPQ of the shape parameter.
- scale: B realizations of the GPQ of the scale parameter.
- rate: B realizations of the GPQ of the rate parameter.

An example of using the pargpq function is as follows:

```
R > set.seed(4)
R > x <- rGamma(20, shape=0.5)
# return a dataframe which contains the
10 realizations of the GPQs of the
parameters
R > set.seed(5)
R > gpq.all <- pargpq(x, B=10)
R > gpq.all
          shape   scale    rate
1 0.6255108 1.4501426 0.6895873
2 0.4401840 1.6614775 0.6018739
3 0.3396037 3.3207661 0.3011353
4 0.5836404 1.2473648 0.8016901
5 0.6936647 0.7959861 1.2563034
6 0.4347012 2.3959141 0.4173772
7 0.4928774 1.5773779 0.6339635
```

```
8 0.3945214 3.0475248 0.3281352
9 0.3078740 2.1524749 0.4645815
10 0.6883403 0.8667913 1.1536802
# return the 10 realizations of the GPQ
of the shape parameter
R > gpq.shape <- gpq.all$shape
R > gpq.shape
 [1]  0.6255108  0.4401840  0.3396037
0.5836404  0.6936647
0.4347012  0.4928774  0.3945214
0.3078740  0.6883403
```

3.4. conflimits function

As illustrated in Algorithm 4, the conflimits function has the following arguments:

- x: observations from a gamma distribution.
- α: $1 - \alpha$ is the nominal confidence level. If α is not specified, the default value is 0.05.
- B: number of realizations of the GPQs. If B is not specified, the default value is 2,000,

and it returns a data frame consisting of three variables

- shape: $1 - \alpha$ confidence interval, lower confidence limit, and upper confidence limit for the shape parameter.
- scale: $1 - \alpha$ confidence interval, lower confidence limit, and upper confidence limit for the scale parameter.
- rate: $1 - \alpha$ confidence interval, lower confidence limit, and upper confidence limit for the rate parameter.

Below is an example of using the conflimits function.

```
R > set.seed(6)
R > x <- rGamma (10, shape = 3, rate = 2)
# return a dataframe that contains 95%
two-sided confidence interval and 95%
one-sided confidence limits for the
gamma parameters
R > set.seed(7)
R > conf.all <- conflimits(x)
R > conf.all
                 shape    scale    rate
low-int 0.6694231 0.2952957 0.4024307
up-int 3.9122894 2.4849002 3.3864400
low-lim 0.8201190 0.3304748 0.5453553
up-lim 3.4827415 1.8336673 3.0259501
# return 95% two-sided confidence
```

interval and 95% one-sided confidence limits for the shape parameter
```
R > shape.conf <- conf.all$shape
R > shape.conf
[1]  0.6694231  3.9122894  0.8201190
3.4827415
```

3.5. predlimits function

The predlimits function has the following three arguments

- x: observations from a gamma distribution.
- α: $1 - \alpha$ is the nominal level. If α is not specified, the default value is 0.05.
- B: number of realizations of the GPQs. If B is not specified, the default value is 2,000,

and it returns a data frame containing one vector, where the first two elements are the $1 - \alpha$ prediction interval, the third element is the $1 - \alpha$ lower prediction limit, and the last element is the $1 - \alpha$ upper prediction limit. Below is an example of using the predlimits function.
```
R > set.seed(8)
R > x <- rGamma(20, shape = 0.5)
# return a vector that contains the 90%
two-sided prediction interval and 90%
one-sided prediction limits
R > set.seed(9)
R > pred.limit <- predlimits(x, alpha =
0.1, B = 5000)
R > pred.limit
                pred
low-int 0.002399023
up-int  1.327799978
low-lim 0.008398397
up-lim  0.930562341
```

3.6. Tollimits function

The arguments of the tollimits function are as follows:

- x: observations from a gamma distribution.
- α: $1 - \alpha$ is the nominal level. If α is not specified, the default value is 0.05.
- γ: proportion of population. If γ is not specified, the default value is 0.99.
- B: number of realizations of the GPQs. If B is not specified, the default value is 2,000,

and it returns a data frame containing one vector, where the first two elements are the $(\gamma, 1 - \alpha)$ tolerance interval, the third element is the $(\gamma, 1 - \alpha)$ lower tolerance limit, and the last element is the $(\gamma, 1 - \alpha)$ upper tolerance limit. Examples of tollimits are as follows:
```
R > set.seed(10)
R > x <- rGamma(20, shape = 2)
# return a vector that contains the
(99%,95%) two-sided tolerance interval
and (99%,95%) one-sided tolerance limits
R > set.seed(11)
R > tol.limit <- tollimits(x)
R > tol.limit
                tol
low-int 0.04020652
up-int  7.09049988
low-lim 0.09236501
up-lim  6.25695963
```

4. Real application

In this section, a real groundwater monitoring application will be used to illustrate the gammadist package. The leakage from waste disposal facilities could be potentially harmful to human health and the environment, and it is of critical importance to detect the earliest possible leakage. Toward this purpose, a common practice is to monitor the groundwater at the disposal facilities by regularly measuring concentrations of quality indices including alkalinity, organic carbon, Kjeldahl nitrogen, and biochemical oxygen demand. A sudden change of the measurements indicates a potential occurrence of the hazardous leakage.

The groundwater monitoring can be formulated as a statistical prediction problem. As an example, Table 1 shows the 27 measurements of alkalinity concentration in a groundwater obtained from a facility in which no disposal of waste has yet occurred. Given a future measurement, if its value is larger than the upper prediction limit (with a pre-fixed confidence level) computed from the data set, it indicates a possible contamination of the groundwater. A similar comparison can be made between a large number of future measurements and the upper tolerance limit.

The alkalinity concentrations data in Table 1 have been well analyzed in the literature (Chen and Ye 2017a; Krishnamoorthy, Mathew, and Mukherjee 2008; Krishnamoorthy and Wang 2016; Wang and

Table 1. Alkalinity concentrations (mg/L) in groundwater.

58	82	42	28	118	96	49	54	42	39	40	60	63	59
51	66	89	40	51	54	55	59	42	70	32	52	79	

Wu 2018), and the gamma distribution is assumed in all these studies. The estimates of the gamma parameters can be obtained by using the parest function. The so-obtained estimates $(\tilde{k}, \tilde{\beta}) = (8.171, 0.141)$ are slightly different from the ML estimates $(\hat{k}_{ML}, \hat{\beta}_{ML}) = (9.372, 0.161)$. To check the accuracy, two simulations are conducted. The first simulation generates samples using rGamma (27, 8.171, 0.141) and the second using rGamma (27, 9.372, 0.161). Under each setting, 10,000 replications are used to estimate biases and root mean square errors (RMSEs) of the estimators by the two methods, and the results are reported in Table 2. As seen, the estimators by parest clearly outperform the ML estimators under the two settings, indicating that $(\tilde{k}, \tilde{\beta}) = (8.171, 0.141)$ should be more appropriate for this dataset. In addition, the conflimits function is used to construct the 90% confidence intervals for k and β, and the results are $(5.352, 13.55)$ and $(0.091, 0.235)$, respectively. This is consistent with the confidence interval developed in Krishnamoorthy and Wang (2016).

Based on the estimates of the parameters, we could assess the goodness-of-fit of the gamma distribution to this dataset. One way is to use graphical tools such as probability-probability (P-P) plot and quantile-quantile (Q-Q) plot. As seen from Figure 1, the blue data points are reasonably close to the red straight line, indicating an adequate fit of the gamma distribution. Alternatively, we could use quantitative tools such as the Kolmogorov–Smirnov statistics and the Cramér–von Mises statistics for the goodness-of-fit test. For example, the Kolmogorov–Smirnov test gives

a p-value of 0.8178, supporting the use of the gamma distribution. Other tests all yield the same conclusion. At last, we could use the predlimits and tollimits to compute the upper prediction limits and the upper tolerance limits, respectively. The statistical limits under different confidence levels are shown in Table 3, which tally well with the results in Krishnamoorthy, Mathew, and Mukherjee (2008); Chen and Ye (2017a); and Wang and Wu (2018). The detailed R codes used in this section are provided in the Appendix.

5. Conclusion

This article introduces the gammadist package, which implements the up-to-date statistical methods for the gamma distribution. In specific, the rGamma function efficiently generates the gamma variates for all ranges of the parameter values, the parest function provides the closed-form estimators for the gamma parameters, and the conflimits, the predlimits, and the tollimits functions, respectively, construct the confidence limits, prediction limits, and tolerance limits with an accurate coverage for the gamma distribution. All these functions essentially deal with the fundamental statistical problems of applying the gamma distribution in practice. For each function, its associated methods have been introduced and its demo codes have been provided. A real environment monitoring application has demonstrated the usefulness of the package. The package is available on https://github.com/statcp/gammadist.

Further development of the package could focus on incorporating more functions related to the gamma distribution. For example, goodness-of-fit test of the gamma distribution is a premise to implement the model in practice. We show in Section 4 that the use of the parest function could be the first step to facilitate graphical assessments or some commonly used tests. Nevertheless, the uncertainties in the estimators may weaken the power of those tests. If more accurate

Table 2. Estimated biases and RMSEs for the estimators by parest and ML estimators.

Setting		$\tilde{k}$	$\tilde{b}$	$\hat{k}_{ML}$	$\hat{b}_{ML}$
$(k, \beta) =$	Bias	0.066	0.002	1.025	0.018
(8.171, 0.141)	RMSE	2.393	0.043	2.855	0.051
$(k, \beta) =$	Bias	0.300	0.006	1.430	0.026
(9.372, 0.161)	RMSE	3.035	0.054	3.643	0.065

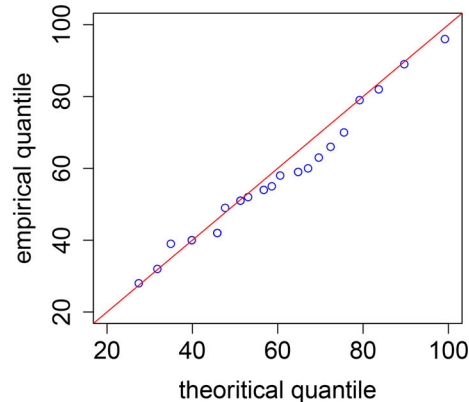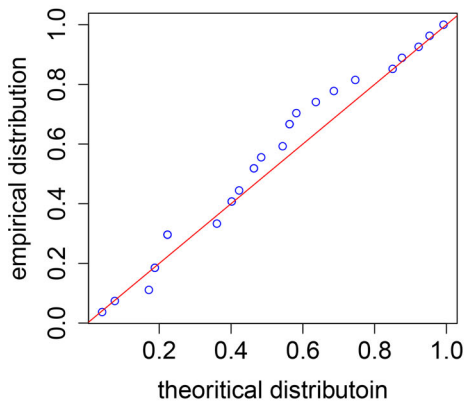**Figure 1.** P-P plot (left) and Q-Q plot (right) based on the fitted gamma distribution to the alkalinity data.

Table 3. Upper prediction limits (UPL) and upper tolerance limits (UTL) by predlimits and tollimits.

α	0.1	0.05	0.01
UPL	85.88	92.20	121.5
(γ, α)	(0.9, 0.05)	(0.95, 0.05)	(0.99, 0.05)
UTL	97.67	110.1	138.0

and advanced methods of testing goodness-of-fit of the gamma distribution become available, they could be integrated to the gammadist package as a separate function. As another example, the three-parameter gamma distribution with an additional scale parameter is often used to fit lifetimes of products/units that cannot fail below a threshold (see, e.g., Ye, Hong, and Xie 2013). The rGamma function can be naturally extended to generate random variables from a three-parameter gamma distribution. However, estimation of parameters is a difficult research problem, let alone construction of the statistical limits. Substantial efforts are needed in order to include the three-parameter gamma distribution in our package. At last, the package may be further extended to deal with the gamma process, which is a commonly used stochastic model. Although the gamma distribution and the gamma process have a close relationship, some fundamental issues for the gamma process, such as accurate estimation and prediction, have not been completely addressed in the literature. The authors will pay special attention to the methodology development of the gamma process and are willing to enrich the gammadist package once these methods become available.

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No potential conflict of interest was reported by the authors.

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Appendix: R codes for real application

```
## Load package and alkalinity concentra-
tions data
library(gammadist)
x   <-  c(58,82,42,28,118,96,49,54,42,39,
40,60,63,59,51,66,89,40,51,54,55,59,42,70,
32,52,79)
## Point estimates and confidence intervals
of parameters
est.all <- parest(x)
est.shape <- est.all$shape
est.rate <- est.all$rate
conf.all <- conflimits(x,alpha=0.1)
## Graphical goodness-of-fit test
# compute the empirical cdf
```

```
Fn <- ecdf(x)
# P-P plot
plot(pgamma(x,est.shape,est.rate),Fn(x),
col='blue',cex.main=1.5,cex.lab=1.5,ce-
x.axis=1.5,
xlab='theoritical  distributoin',  ylab=
'empirical distribution')
abline(0,1,col = 'red')
# Q-Q plot
plot(qgamma(Fn(x),est.shape,est.rate),x,-
xlim=c(20,100),ylim=c(20,100),
col='blue',cex.main=1.5,cex.lab=1.5,ce-
x.axis=1.5,
```

```
xlab='theoritical quantile',ylab='empiri-
cal quantile')
abline(0,1,col='red')
## K-S test
ks.test(x,"pgamma",est.shape,est.rate)
## Upper prediction limits
predlimits(x,0.1)$pred[4]
predlimits(x,0.05)$pred[4]
predlimits(x,0.01)$pred[4]
## Upper tolerance limits
tollimits(x,0.05,0.9)$tol[4]
tollimits(x,0.05,0.95)$tol[4]
tollimits(x,0.05,0.99)$tol[4]
```