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SHORT-PAPER

Wildfire@Home: Personalized Immersive Training for Household Situation Awareness

TIANYI XIAO, Swiss Federal Institute of Technology, Zurich, Zurich, ZH, Switzerland

YAN FENG, Delft University of Technology, Delft, Zuid-Holland, Netherlands

SUVODIP CHAKRABORTY, Swiss Federal Institute of Technology, Zurich, Zurich, ZH, Switzerland

PETER KIEFER, Swiss Federal Institute of Technology, Zurich, Zurich, ZH, Switzerland

PHOEBE O. TOUPS DUGAS, Monash University, Melbourne, VIC, Australia

MARTIN RAUBAL, Swiss Federal Institute of Technology, Zurich, Zurich, ZH, Switzerland

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Wildfire@Home: Personalized Immersive Training for Household Situation Awareness

Tianyi Xiao*
ETH Zürich
Zürich, Switzerland
xiaoti@ethz.ch

Peter Kiefer
ETH Zürich
Zürich, Switzerland
pekiefer@ethz.ch

Yan Feng
Delft University of Technology
Delft, Netherlands
Y.Feng@tudelft.nl

Phoebe O. Toups Dugas
Monash University
Melbourne, Australia
Phoebe.ToupsDugas@Monash.edu

Suvodip Chakraborty
ETH Zürich
Zürich, Switzerland
schakrabort@ethz.ch

Martin Raubal
ETH Zürich
Zürich, Switzerland
mraubal@ethz.ch

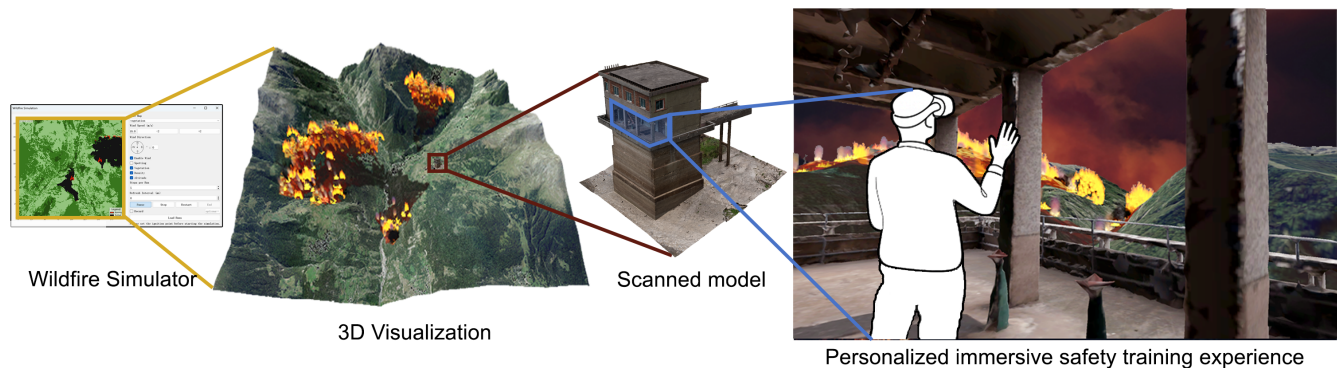


Figure 1: Overview of Wildfire@Home pipeline. A desktop wildfire simulator models fire spread behavior, which is then imported into a VR wildfire visualizer. Users scan their own homes, position them at real locations, and experience fire spread from first-person view in VR, enhancing situation awareness and decision-making within familiar surroundings.

Abstract

As wildfires become increasingly frequent and severe worldwide, at-risk homeowners face greater responsibility in assessing the fire situation and making safety-critical decisions. This requires specific training in situational awareness (SA). However, the effectiveness of conventional wildfire response training (WRT) methods (e.g., videos, brochures) is limited, as they cannot replicate the unpredictability of wildfires nor provide real-world context. This research introduces Personalized Immersive Training (PIT), a novel paradigm designed to embed WRT in real-world contexts. We implemented PIT in Wildfire@Home, intending to increase homeowners' SA capabilities. Learners first use a desktop wildfire simulator to build mental models of how terrain, vegetation, and wind shape fire spread. Then, experience a realistic and immersive 3D rendering of the simulation in a VR wildfire visualizer. Learners can personalize the training scenario by uploading 3D models and geospatial data.

*Corresponding author.



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CCS Concepts

• **Human-centered computing** → **Virtual reality**; *User interface design*; • **Security and privacy** → *Social aspects of security and privacy*.

Keywords

Wildfire simulation, wildfire visualization, virtual reality, personalization, situation awareness

ACM Reference Format:

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1 Introduction

Wildfires are increasing in frequency and severity, threatening lives, property, and ecosystems worldwide [36, 59, 66]. Climate change, policy constraints, and urban expansion into wilderness areas have created highly vulnerable wildland-urban interfaces that threaten public safety [7, 27, 55, 56]. Although evacuation as early as possible is the safest response to wildfire threats [44], many countries reject mandatory evacuation to preserve homeowners' autonomy

and avoid economic and displacement problems [47]. This shifts responsibility to at-risk homeowners, who must dynamically assess the situation and make safety-critical decisions. However, most residents delay action, often waiting until smoke is visible or hear the fire through the news media [45, 47], increasing the death rate from radiant heat or vehicle accidents [30].

One reason for this “last-minute evacuation” phenomenon is insufficient situation awareness (SA) of wildfire. SA is the perception, comprehension, and projection of evolving conditions that enable individuals to recognize risks and choose appropriate actions [13, 21, 29, 74]. Establishing and maintaining SA requires timely and continuously updated knowledge of multiple variables in a dynamic fire environment, such as the direction and speed of the fireline [13, 29, 74]. Improving SA skills has traditionally only been available to professionals through complex drills [13, 34, 50, 75]. In contrast, wildfire response training (WRT) for public preparedness is typically based on videos, brochures, and presentations, without embodied action [24, 31, 37]. Since these training methods cannot capture wildfire behavior, residents at risk often lack exposure until a real event occurs. Limited practice leads to poor threat identification, causing delay in action and an increased death rate.

Simulation with the right level of fidelity can replicate the psychological and physiological effects of real fire drills, promoting learning [65]. VR is increasingly becoming a vital method for developing critical SA skills [17, 24, 38]. This makes VR a low-cost, low-risk training supplement for citizen response training [18, 24, 33, 41]. However, few existing tools focus on the general public or support personalized training environments. The growing accessibility of consumer-grade headsets [12, 71] and advances in 3D reconstruction technologies [40] have enabled a shift toward Personalized Immersive Training (PIT). Rooted in situated learning theory [3], PIT embeds WRT in real-world contexts featuring spatial cues (e.g., terrain, vegetation) that help users assess fire proximity and determine evacuation necessity [45, 46].

We developed Wildfire@Home based on PIT, targeting the general public, who typically lack domain expertise and cannot access fire drills. The system comprises two components: a desktop-based wildfire simulator and a VR-based wildfire visualizer. The wildfire simulator uses a cellular automata (CA) model to show how environmental factors affect fire spread; it can be accessed by users without a VR headset. The wildfire visualizer transforms CA-generated simulations into 3D experiences, offering an immersive VR experience. Unlike traditional 2D visualizations, the VR environment provides spatial depth and a more intuitive understanding of fire behavior [34]. To achieve a personalized experience, users can scan their own homes and place them within real-world terrain, then observe fire conditions against the background of familiar surroundings.

As this study represents the first exploration of a PIT system, an overarching research question emerges: Does personalized immersive training (the proposed concept) enhance SA of wildfires compared to non-personalized 2D (baseline) and immersive training? A future user study will answer this question.

2 Related Work

We first address the importance of SA in responding to wildfires. We then consider simulation algorithms for wildfires, a necessary

technology for our interface. Finally, we review prior approaches to immersive training.

2.1 Situation Awareness in Wildfire Response

Numerous studies have highlighted the importance of SA in fire-fighting operations, improving responders’ chances of successfully managing the fire and, more importantly, safety and survival [46, 60, 64, 74]. Endsley’s [21] three-level model indicates SA encompasses the perception of relevant environmental elements (Level 1), the comprehension of their meaning (Level 2), and the projection of their future status (Level 3). In the context of wildfires, these levels correspond to: (1) perceiving environmental and fire-related cues (e.g., nearby building numbers and locations, terrain features, fire origin); (2) comprehending the current fire situation (e.g., estimating fire size and identifying threatened areas); and (3) projecting future developments, such as the fire’s likely trajectory or the potential need for evacuation [13, 20, 60].

Effective SA training requires more than the acquisition of factual knowledge; it also depends on perceptual learning, the ability to recognize critical environmental cues, and the development of mental models that accurately encode fire dynamics and progression [15]. VR has been shown to be an effective training method to increase SA skills [53]. For example, trainees can be placed within the visual, auditory, and even thermal/smoke environments of a virtual fire scene, activating their sensory and emotional capabilities to foster the development of SA behaviors [22]. The critical role of SA in fire prevention prompted this study to pose a research question aimed at comparing the impact of the PIT method versus non-personalized approaches for cultivating SA capabilities.

2.2 Wildfire Simulation Algorithms

Wildfire spread simulation algorithms can be grouped into four paradigms: empirical models, physics-based, raster-based, and machine learning (ML) approaches. Empirical models approximate fire behavior through parameterized formulas derived from historical data and controlled experiments; the most widely used is the mathematical model proposed by Rothermel [58], which underpins simulators such as FARSITE [43]. Physics-based approaches (e.g., WFDS [49], WRF-Fire [14]) solve fluid dynamics and combustion processes, offering high-fidelity insights into fire-atmosphere interactions, but they demand prohibitive computational resources and run orders of magnitude slower than real time [5, 25]. Raster-based approaches, such as CA models [1], simulate fire spread through cell-based state-transition rules, integrate efficiently with geographic information systems (GIS), and are computationally efficient, yet often produce unrealistic fire perimeters due to directional constraints [6]. ML approaches (e.g., decision trees, random forests [9]) capture complex non-linear relationships among environmental factors [8, 26], but require large datasets from remote sensing and meteorological records, and are difficult to interpret [73].

While low-fidelity simulations can be effective for learning, the goal of the present research is to help participants gain a better understanding of how a wildfire near their home might actually unfold. For this, we seek an algorithm of wildfire simulation within the constraints of an interactive, real-time, and context-rich method. Therefore, our system adopts a widely used CA model proposed by

Alexandridis et al. [1], as it provides rapid feedback and simulates terrain, wind, and vegetation effects on wildfire spread.

2.3 Immersive Wildfire Response Training

WRT aims to convey the characteristics, causes, effects, and prevention measures of wildfires to help individuals and professionals learn how to respond [15]. Recently, the growing evolution of immersive technology allows users to observe and explore fire events with a high degree of presence [13, 63]. For example, VFire enables users to modify fuel and weather conditions, and test firefighting strategies from a first-person perspective [35]. Vega et al. [66] developed a VR campfire game that guides users through building and extinguishing a campfire, using gamification to promote SA and safe behavior. However, compared to small-scale and enclosed fire scenarios, such as hospitals [23], coal mines [54], and train stations [68], there are relatively few immersive training interfaces specifically designed for wildfires.

Immersive WRT interfaces show a superior training experience and performance over traditional methods. For example, research shows that 360° immersive wildfire videos increased presence, risk perception, and emotional arousal compared to reading articles and watching videos [48]. VR training also simulates higher motivation and interest [69], yielding task performance comparable to real-world training, with both significantly outperforming the untrained condition [57]. Calandra et al. [10] integrated VR training with passive haptic feedback into a forest firefighting training course, finding that compared to video instruction alone, this approach significantly enhanced trainees’ learning outcomes, motivation, and perceived quality of training.

Despite their innovation, most existing VR-based WRT systems rely on predefined scenarios [18, 19] and are designed primarily for professionals [16, 33, 39, 65, 67, 69]. While these approaches raise general awareness of wildfire hazards, they provide limited guidance on property-specific risks and tailored safety measures, making it difficult for users to apply what they learn to their own contexts. Recent advances in personalized VR experiences (e.g., healthcare [51], exhibitions [4], workspace [11]) inspired us to adapt this idea into the WRT system, Wildfire@Home, to address these gaps—particularly for the general public.

3 Formative Study

The present article is concerned with the technical design of Wildfire@Home, in particular, its simulation implementation. We briefly describe the light, formative study that we used to develop this novel system. The IRB board of ETH Zürich approved this study.

3.1 Methods

We conducted semi-structured interviews with nine experts in firefighting (E1–9; 6 men and 3 women), recruited through professional and social networks. Participants were selected based on a screening survey that collected demographic and professional information, as shown in Appendix B.1. They reported 2 to 15 years of working experience ($M = 6.0$, $SD = 3.9$). Roles included six field responders and three participants with both command/field experience (E2, E5, E7). More details appear in Appendix A: Table 1. All participants were compensated at local wage rates.

The interviews mainly covered their firefighting experiences, training methods, tools used in training, limitations of these tools, requests for improvements, and vision for future immersive training tools for citizens. A complete interview protocol is shown in Appendix B.2. The interview was conducted in Chinese and subsequently translated into English by the first author. Interview recordings were reviewed by the first author to gather insights, and findings were summarized using descriptive coding.

3.2 Results

All experts express a strong interest in VR-based training tools. They acknowledge its effectiveness and usefulness, but also indicate several limitations of the current VR experience. These insights directly informed the design of Wildfire@Home.

3.2.1 Visualization. Experts mentioned that current training approaches rely mainly on static 2D or 2.5D maps. These representations force users to mentally reconstruct terrain and cannot represent dynamic fire behavior. In contrast, E2 highlighted that immersive visualization “lets you see it directly from a first-person view,” reducing cognitive load in interpreting elevation and slope.

3.2.2 Fidelity. Experts emphasized the importance of simulation fidelity in training knowledge transfer, providing trainees with enhanced immersion and situation awareness. They noted that VR technology has significant potential to induce real-world stressors, allowing participants to make sound decisions under high-pressure conditions. For example, E6 argued that lifelike visuals increase applicability to real-world action, while E1 emphasized that “people take more reasonable reactions about when to leave, where to go, and what to take in a realistic environment.”

3.2.3 Scenarios. E7 noted that “training in people’s own neighborhoods would be taken more seriously”—a reflection of how several experts envisioned placing fire scenarios on the users’ own properties. Existing systems only simulated small-scale, enclosed, and highly predictable scenarios. While such simulations are suitable for enclosed-space fire response training, they fail to prepare firefighters for the complex, multidirectional, and unpredictable nature of wildfire. The experts reported that current immersive training systems largely replicate outdated drills and practices, highlighting an urgent need for modernization. Unpredictable wildfires are viewed as exceptional and rare occurrences—though they are more common than ever—and thus excluded from most training exercises.

3.2.4 Interactivity. Immersive systems allow users to observe both the external impacts of wildfire spread and the internal dynamics between wildfire variables. Experts stressed the value of active engagement. Instead of passively observing scenarios, users should be able to manipulate key parameters and observe the resulting changes in fire spread. Such interactive experimentation deepens understanding of fire spread.

3.3 Design Strategies

We derived four design strategies from these insights for Wildfire@Home, which support PIT and help us answer our research question: (1) provide immersive 3D visualization to reduce cognitive load; (2) render high-fidelity and realistic fire, smoke, and

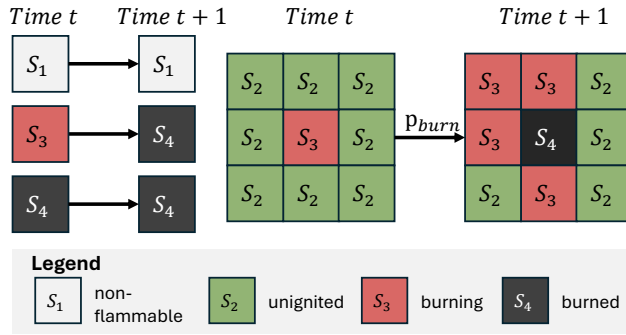


Figure 2: CA model state evolution rules: (1) S_1 remains S_1 ; (2) S_2 may ignite and transition to the burning state (S_3) if at least one neighboring cell is burning, with probability p_{burn} ; (3) S_3 transitions to the burned state (S_4); (4) S_4 remains S_4 .

terrain to enhance presence and SA; (3) support scenario personalization using user-specific and public geospatial data; and (4) allow parameter manipulation to reveal the underlying mechanisms of fire spread, thereby facilitating the construction of mental models.

4 Wildfire@Home

Wildfire@Home is designed for public preparedness and comprises a desktop-based wildfire simulator and a VR-based visualizer.

4.1 Desktop-Based Wildfire Simulator

The wildfire simulator component adopts a CA model [1]. The simulator can function independently, enabling users without VR equipment to engage with the tool. It allows intuitive manipulation of key parameters to explore how various factors influence wildfire spread, thereby supporting basic learning about wildfire dynamics.

4.1.1 Simulation Algorithm. The area is discretized into grid cells, each in one of four possible states (S): non-flammable (S_1), unignited (S_2), burning (S_3), or burned (S_4). The evolution rules between states are shown in Figure 2.

Fire propagates stochastically from burning to neighboring cells with a spread probability p_{burn} that integrates vegetation type, fuel density, wind, slope, and a baseline ignition probability:

$$p_{burn} = p_h(1 + p_{veg})(1 + p_{den})p_w p_s. \quad (1)$$

Baseline ignition probability (p_h). p_h represents the inherent likelihood of ignition under neutral conditions (e.g., flat terrain, no wind, average vegetation). It serves as a scaling factor and is typically calibrated in the range $[0, 1]$ based on empirical fire records or expert judgment.

Vegetation type (p_{veg}). Vegetation type influences combustibility. In the model, p_{veg} is discretized into categorical values (e.g., grasslands, shrublands, forests). Higher flammability vegetation is assigned larger p_{veg} values, whereas low-flammability vegetation (e.g., grasslands) receives smaller values.

Fuel density (p_{den}). p_{den} is likewise categorized into categorical values (e.g., sparse, normal, dense) corresponding to land-cover data.

The spread probability is increased by denser fuels and decreased by sparser fuels.

Wind (p_w). Wind is modeled according to empirical wind-fire relations: $p_w = \exp(c_1 V) \cdot \exp(V c_2 (\cos \theta - 1))$,

where V is wind speed, θ is the angle between the wind direction and fire spread direction, and c_1, c_2 are constants. Spread rate is maximized when fire moves with the wind ($\theta = 0$) and minimized against the wind ($\theta = \pi$). Parameters c_1 and c_2 can be fitted by minimizing the difference between the simulated and observed burned areas.

Slope (p_s). Uphill increases the spread rate uphill due to the convective and radiative heating of unburned vegetation ahead of the fire front [32]. This effect is modeled as: $p_s = \exp(a \theta_s)$, where θ_s is the slope angle and a is an empirical constant. The positive slope increases p_s as the flames are closer to the surface, while the spread of the fire on the slope is reduced.

4.1.2 Simulation Data. The data used for wildfire simulation includes vegetation and digital elevation model (DEM) data (Figure 4). User can import datasets corresponding to their household location, using publicly available geospatial resources such as swissALTI3D [52]. Wind data may be obtained from local meteorological agencies' measurements of wind speed and direction.

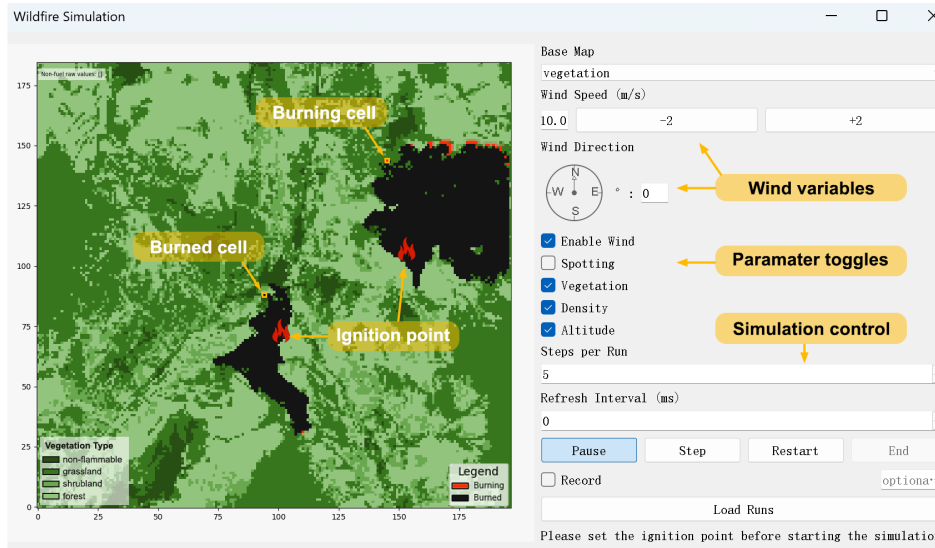
4.1.3 Interface Design. The user interface (Figure 3) is designed to support novice users' interactive exploration of wildfire dynamics. The left panel displays the base map, which users can configure to show either a DEM, a vegetation map, or a binary map indicating flammable and non-flammable areas. The right panel allows users to manipulate key environmental parameters, such as *wind speed* and *wind direction*, and to toggle simulation factors including *wind*, *spotting*, *vegetation type*, *vegetation density*, and *altitude*. These toggles activate corresponding terms in the CA model [1] (see Equation 1), thereby directly influencing the probability of fire propagation p_{burn} . Simulation control panel includes *pause*, *step*, *restart*, and *end*, alongside adjustable parameters for *steps per run* and *refresh interval*. Users can also record simulation sessions as binary files that can be imported into the wildfire visualizer (Section 4.2) for an immersive training experience.

4.2 VR-Based Wildfire Visualizer

When combined with the wildfire simulator, the wildfire visualizer offers an immersive, first-person experience of the simulated fire, which is expected to enhance users' SA skills (Figure 5(a)).

4.2.1 Visualization Data. The visualization of the environment integrates personalized input data (Figure 4). User-scanned 3D models are captured with free applications such as Metaroom [2]. A 3D terrain model and building models were generated using the GIS Terrain Loader Pro plugin in Unity [28]. The terrain model was created based on DEM data and textured with satellite imagery, while the building models were constructed using vector building boundary data. A realistic rendering system is used to transform wildfire simulation generated from the wildfire simulator (Section 4.1) into an animation of fire's progression from ignition to extinction.

(a) Wildfire Simulation Interface



(b) Simulation Screenshots

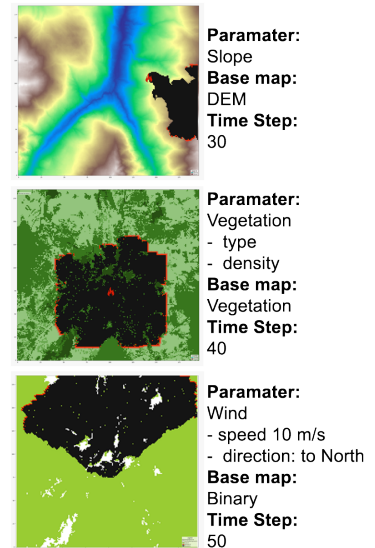


Figure 3: A Swiss town, Stalden, was selected as our example location for its high wildfire risk. (a) The left panel presents fire progression dynamically on the base map, with actively burning cells shown in red and burned cells shown in black. Ignition points are marked with fire icons on the map and are interactively defined by the user. The right panel contains buttons and text input fields that allow users to configure simulation parameters. (b) shows the simulation results under different setups.

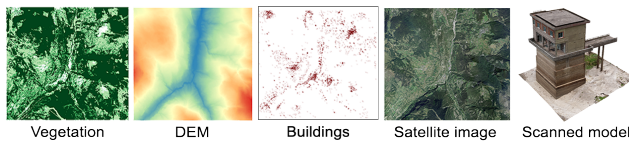


Figure 4: Wildfire simulation and visualization data.

4.2.2 Realistic Rendering System. We use a hybrid method combining 2D textures as a base with 3D particles in Unity [62]. We support performance optimization through level-of-detail and selective rendering. The visualization and the wildfire spread process are shown in Figure 5(c)–(d).

The texture system applies color gradients based on the cells’ states (Figure 5(c)), illustrating the fire lifecycle from bright flames (ignition) to dim embers (extinction). To reduce the blocky appearance caused by grid-based data, we apply a convolution kernel to smooth the texture. Simultaneously, a Gaussian filter is employed for temporal smoothing across time steps for better frame transition. To achieve a more natural flame appearance, subtle variations are introduced through Perlin noise and controlled randomness.

The 3D particle system and the texture data are correlated, synchronizing fire effects. The generation of particles is controlled by probability rules and spacing constraints to maintain visual density without overloading the system. Particle types include flames, explosions, dust, smoke, and ashes. Each particle undergoes three distinct phases: a vibrant flame stage with bright yellow colors, a transitional phase where hues gradually shift to deep red, and a final ember stage featuring towards black. Different particles will

be randomly selected to fit the phase. The particle size and behavior evolve through a Gaussian distribution, lending the flames a more natural and lifelike appearance.

5 Planned User Study

We plan a between-subjects study with three WRT methods: non-personalized 2D training (C1, baseline), non-personalized immersive training (C2), and personalized immersive training (C3, proposed concept). The interface in C1 is limited to the wildfire simulator, while C2 and C3 offer the complete set of Wildfire@Home features. The dependent variables will be SA acquisition. Participants will be randomly assigned to one condition. Target participants are homeowners residing in high wildfire risk areas who possess traditional wildfire management experience.

The procedure is designed as follows: Participants will receive a digital consent form by email and, upon agreement, will sign and return it. Participants in the C3 condition will provide their homes’ location and use a free mobile app to scan their homes. The experiment will be conducted in a controlled lab environment at the ETH Zürich, Chair of Geoinformation Engineering. When arriving at the lab, the participants will complete a demonstration questionnaire. The participants will then receive a 10-minute tutorial on the assigned interface. After the tutorial, the participants will follow 20 minutes of step-by-step, pre-defined standardized instruction to manipulate the parameters and learn how they affect the spread of the wildfire. The experimenter will assist them if any problem occurs. For C1 and C2, the experimenter will load a pre-defined location for the participant that they are not familiar with, while for C3, the experimenter will load the participant’s home



Figure 5: (a) Training takes place from a first-person perspective in VR. (b) A third-person view shows the relations between the user, the scanned model, and the surroundings in the wildfire scene. (c) Wildfire visualization combines particles (flames, embers) with terrain textures indicating different fire states. (d) The wildfire spread process is simulated over time.

location and import the scanned home model into the wildfire visualizer. After completion of the training, participants will answer an SART Questionnaire [61]. Then, the experimenter will conduct a semi-structured interview to investigate general feedback on training effectiveness, perceived efficacy, and usability, while soliciting suggestions for interface design improvements. Data analysis will compare quantitative and qualitative metrics across conditions.

6 Limitations & Future Work

Our work primarily focused on Wildfire@Home’s interface design. We have conducted internal testing, but have not yet validated it through real user evaluation. Moreover, current wildfire visualizations remain limited in realism. Future work could improve simulation fidelity in terms of physical, functional, psychological, and social aspects, as suggested in [42].

Another key direction for future work is to integrate eye tracking within VR for enhanced personalization. Unlike traditional methods, VR allows seamless capture of gaze data in 3D environments, providing insights into SA and cognitive load. This capability could enable personalized training by detecting gaze patterns and delivering adaptive feedback, such as highlighting overlooked hazards or reinforcing attention to critical areas. Metrics such as fixation duration, scanpath entropy, and pupil dilation could indicate whether trainees attend to critical uncertainty zones or are distracted by non-essential stimuli.

Embedding uncertainty maps and sketch mapping functions into VR simulations is another direction. Ensemble-based fire spread predictions or probabilistic exposure risks could be visualized as

heatmaps, contour bands, or region opacity shifts, enhancing environmental literacy. When combined with eye tracking, these visualizations can reveal suboptimal behavior, such as avoidance of high-risk areas. VR-based sketch mapping technologies [70–72] can also be used to evaluate users’ spatial understanding of the fire situation by indicating the fire perimeter and elements’ location.

7 Conclusion

This paper introduced PIT, a paradigm that integrates wildfire simulation with immersive VR visualization for personalized WRT. We implemented PIT with Wildfire@Home, a system that enables users to explore cause-and-effect relationships between environmental conditions and fire behavior through direct manipulation and personalized immersive feedback.

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A Characteristics of Experts

Table 1: Characteristics of experts involved in the semi-structured interviews. Abbreviations: F = field responder; C = commander; M = man; W = woman.

ID	Service Years	Role	Gender	Age
E1	7	F	M	41
E2	3	C/F	M	30
E3	4	F	M	29
E4	4	F	W	36
E5	10	C/F	M	50
E6	6	F	W	32
E7	15	C/F	M	36
E8	2	F	W	32
E9	3	F	M	25

B Formative Study Materials

B.1 Screening Survey

Part 1 – Participants Information and Firefighting Expertise

SS-1 Contact: _____; Gender: _____; Age: _____

SS-2 Role: [Commander / Field Responder / Both / Other]

SS-3 Service years: _____

Part 2 – Availability

SS-4 What times are you typically available for an interview?

SS-5 Do you have any additional comments?

B.2 Interview Protocol

This interview served to generate our design strategists (Section 3).

- IP-1 Can you briefly describe your primary responsibilities?
- IP-2 What types of firefighting missions have you been involved in?
- IP-3 Have you received fire response training? What content was covered? What tools were used?
- IP-4 What challenges have you faced during training?
- IP-5 How could tools be improved to better support fire response training?

- IP-6 Do you see the potential for immersive technology to support (public) fire response training?
- IP-7 Compared to traditional tools, what are the strengths and limitations of this system?
- IP-8 In what scenarios would immersive technology be more useful than traditional methods?
- IP-9 What features or capabilities would you expect in an immersive fire response training tool?
- IP-10 Do you have any concerns about using such tools in practice?
- IP-11 Is there anything else you would like to share?