Using a Space Filling Curve for the Management of Dynamic Point Cloud Data in a Relational DBMS

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TUDelft

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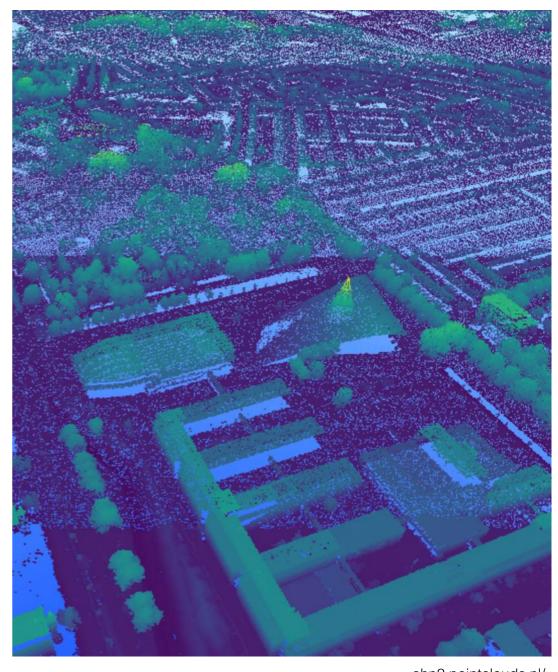
Introduction

What is a Point cloud?

Source: gisuser

Point clouds

- Rapid growth in point cloud usage
- The management of point clouds is challenging
- Typically managed using files (e.g. LAS, LAZ)
- ...But, DBMSs provide point cloud management solutions.



ahn2.pointclouds.nl/

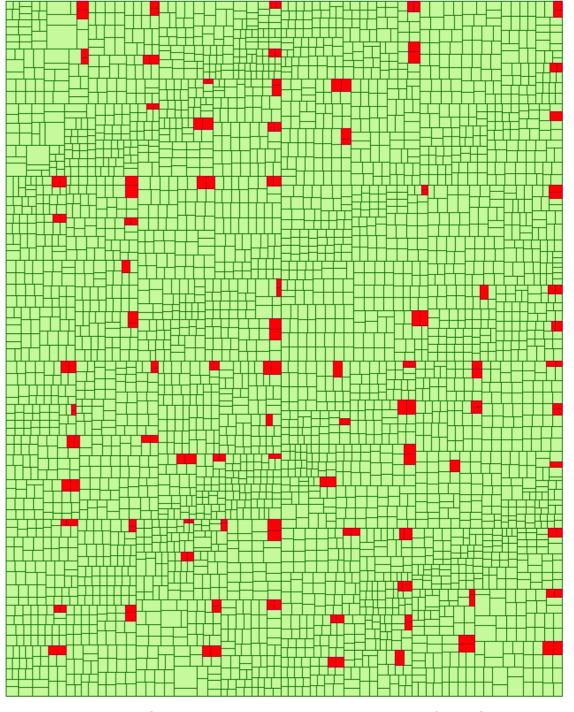
Management of PC in DBMS

Current approaches:

- Oracle SDO_PC
- PostgreSQL pgpointcloud

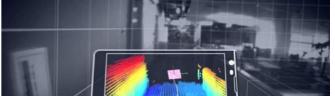
Organise points in **blocks**, meaning groups of spatially close points

...or use a normal flat table



Dynamic point clouds

- Today, developments in point cloud acquisition devices allow repeated scans of the same area
- Dynamic point clouds
 - growing datasets
 - time is an additional dimension



Source: youtube.com

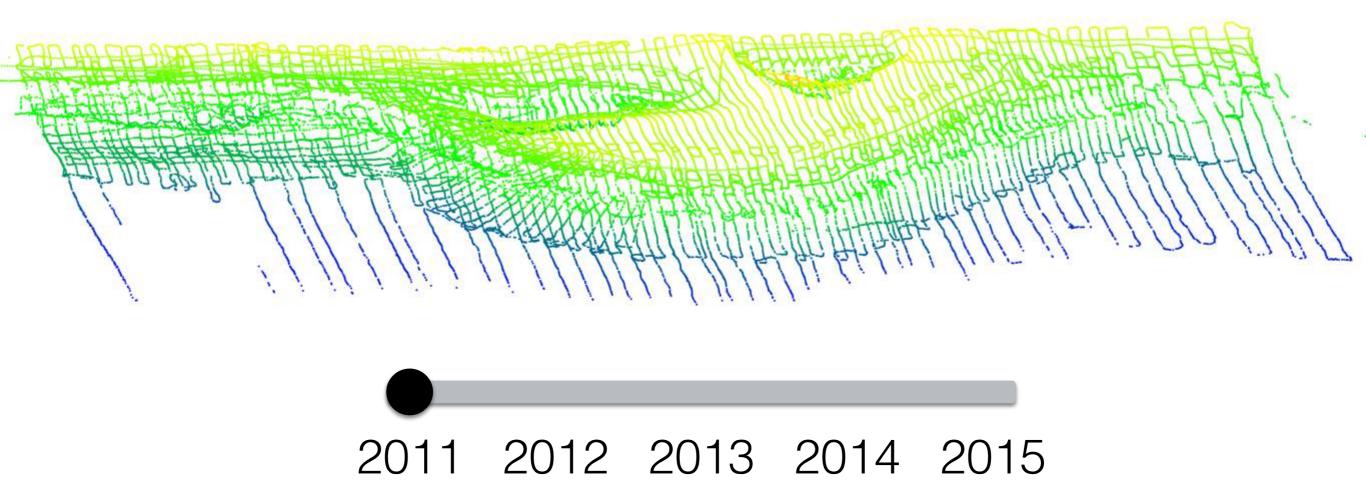




Source: TU Delft

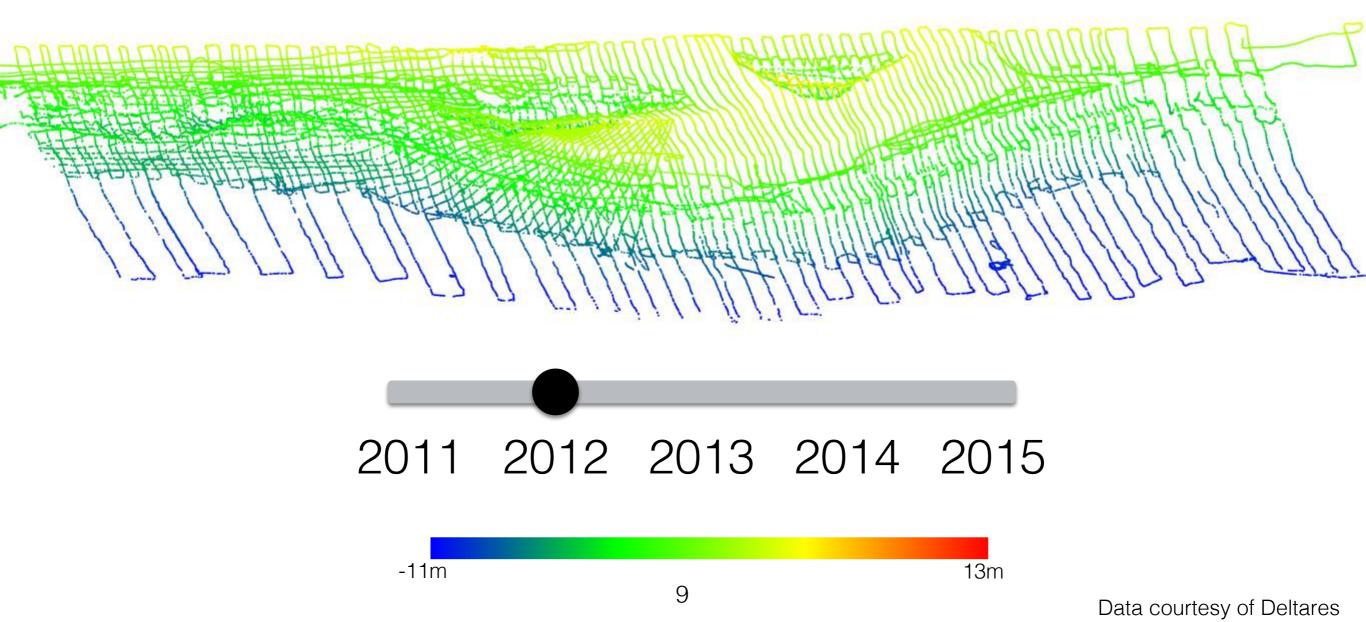


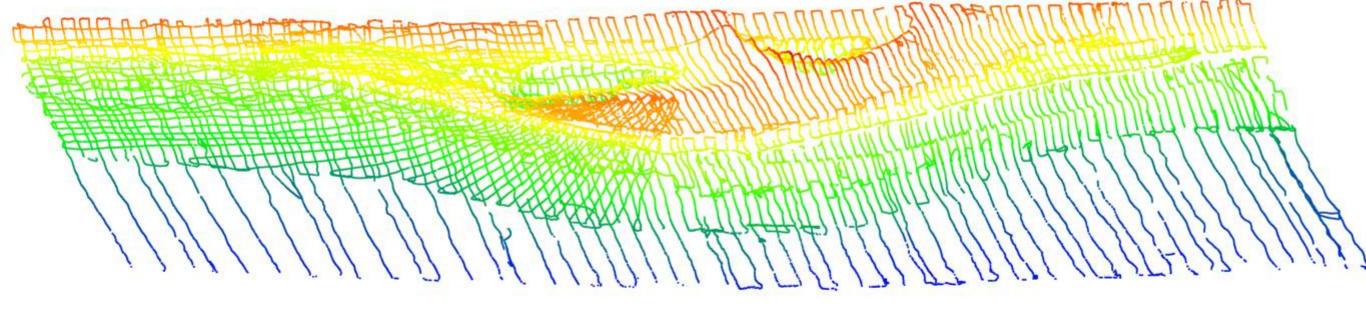
Source: Wikimedia Commons

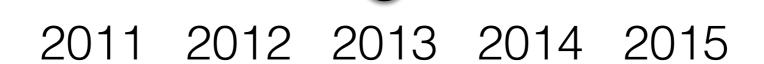


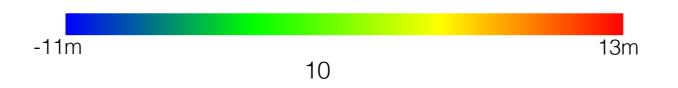
-11m

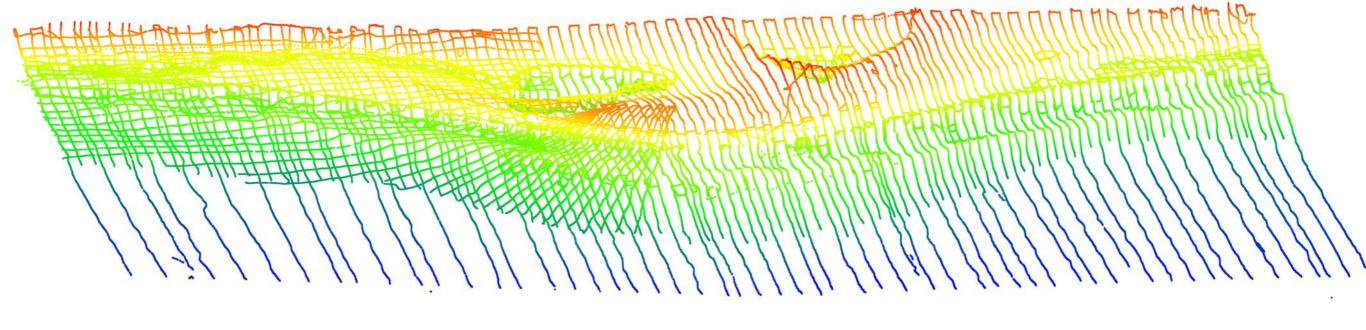
13m

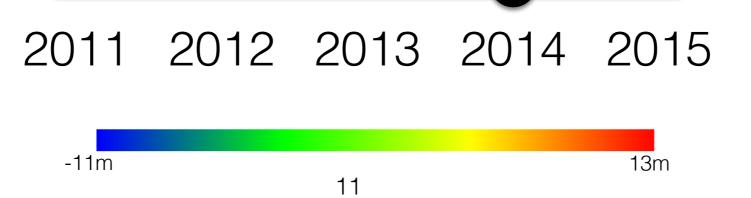


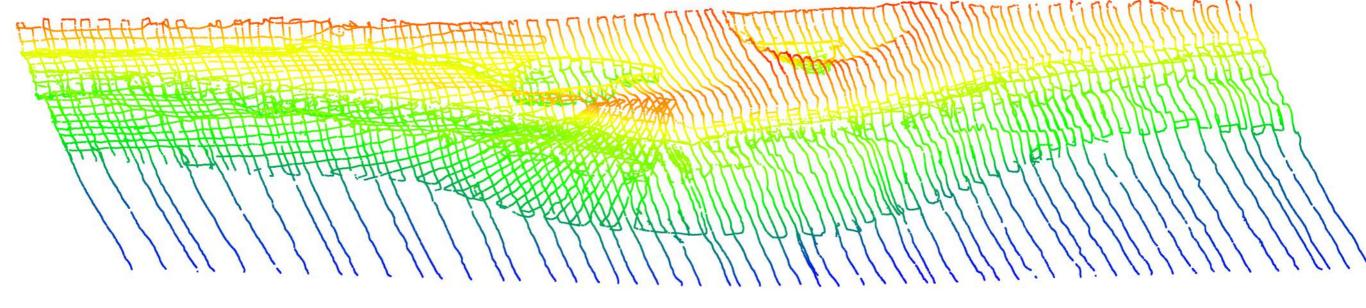












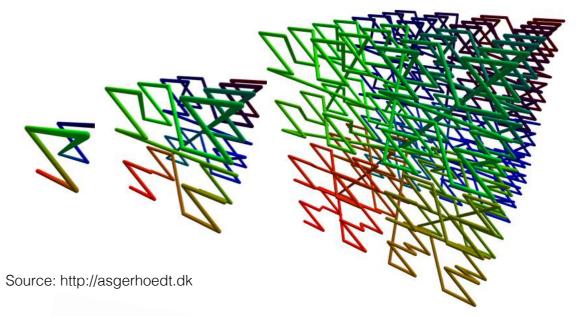


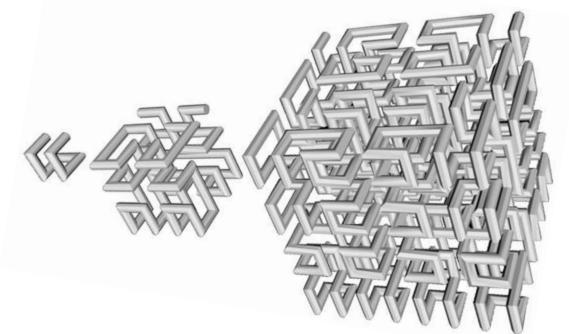
Managing dynamic PC?

- Blocks
 - compact storage with better scalability, less overhead, better compression
 - overlapping blocks, adding new data not trivial
- Flat
 - ☑ flexible, insertions trivial, Use a SFC to improve the organisation (van Oosterom et. al., 2015)
 - large storage requirements, overhead

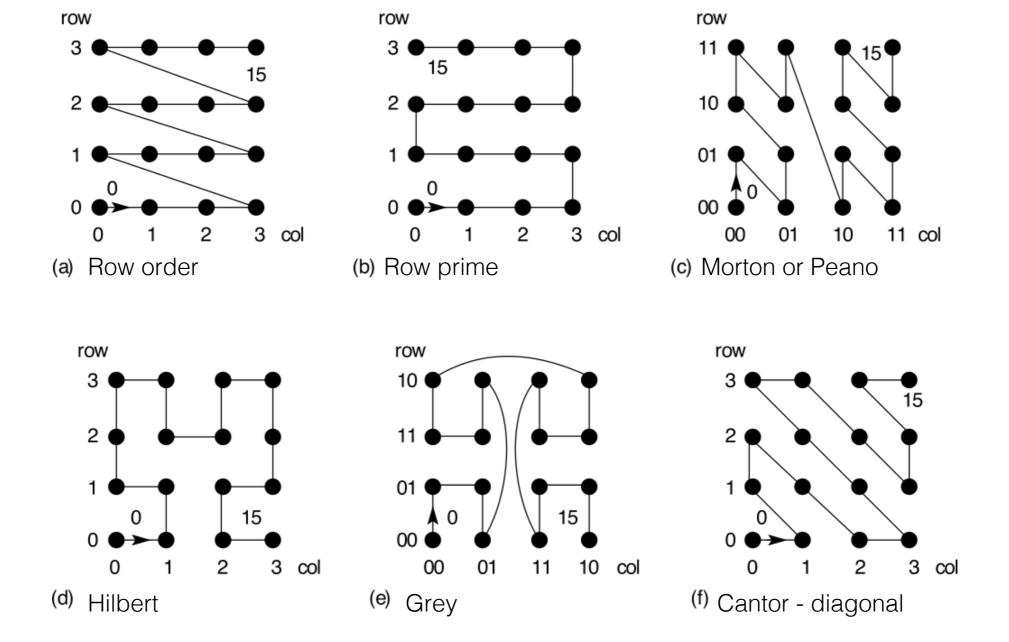
Space Filling Curves

- Apply a linear ordering to a multidimensional domain
- Why?
 - Dimensionality reduction
 - Full resolution curve
 - Clustering of points





Space Filling Curves



Space Filling Curves

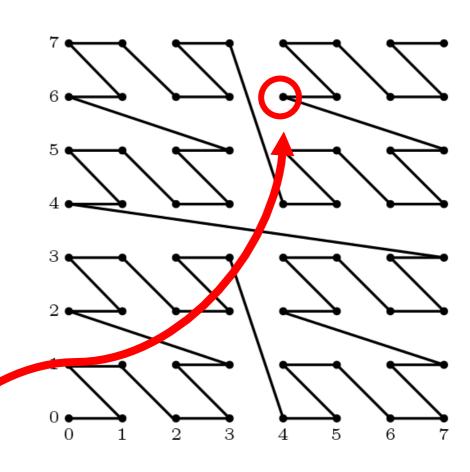
- Morton Curve
- Bitwise interleaving

Example:

x = 4 or 0100 in binary

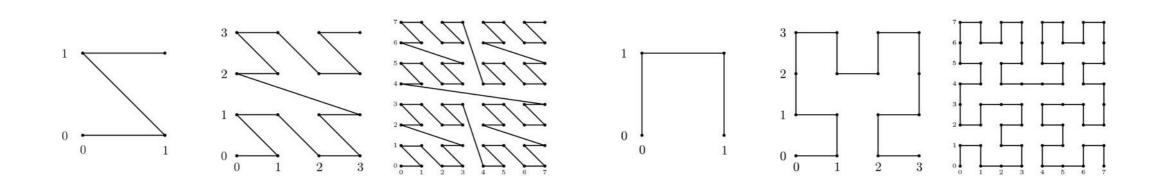
y = 6 or 0110 in binary

morton = 00111000 or 56



Research Question

Is a Space Filling Curve (SFC) approach an appropriate method for integrating the space and time components of point clouds in order to support efficient management and querying (use) in a DBMS?



Methodology: A Space Filling Curve approach

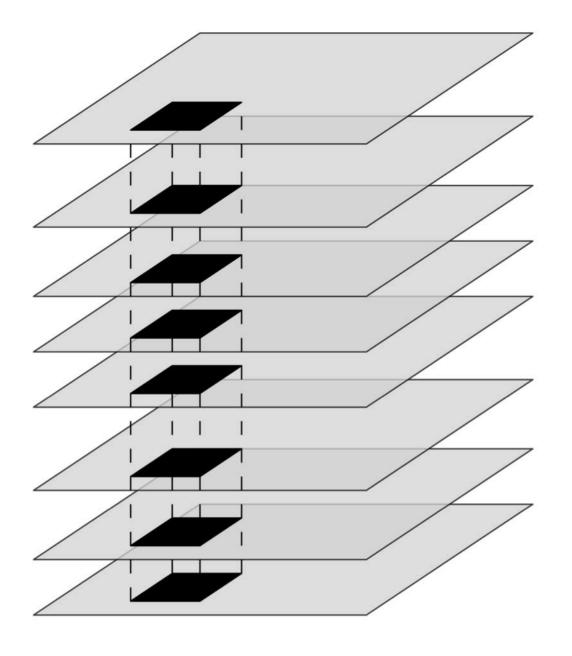
Requirements

Requirements for spatio-temporal data management [Adapted from Gaede and Gunther, 1998]:

- Should support operations other than just retrieval of the data.
- Should be *dynamic*: support insertions
- Should be scalable: adapt to growing database.
- Should be *efficient* in terms of time (and space): minimise as much as possible the number of disk accesses

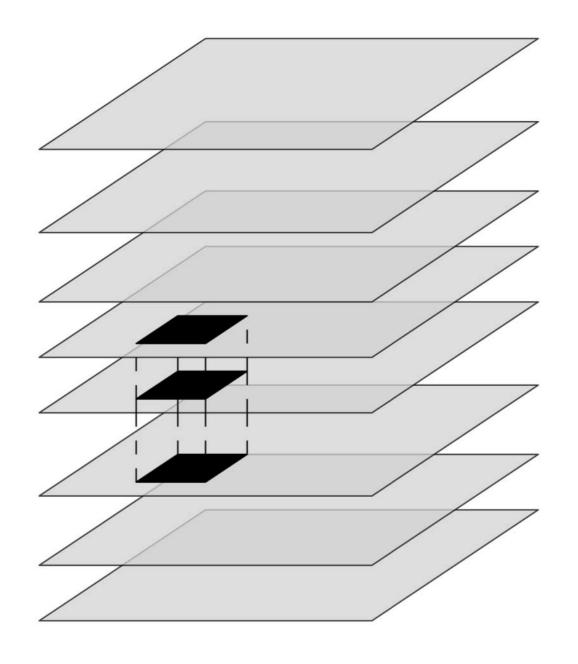
Important queries

 Space queries: all points located in a specific area over the complete time range



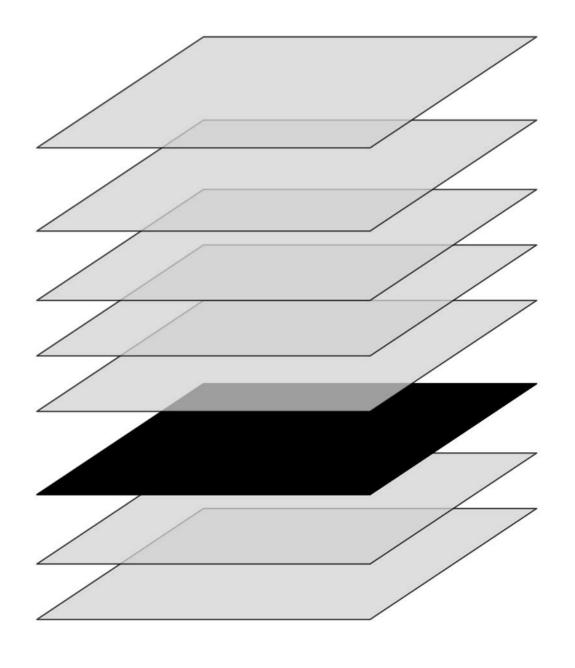
Important queries

Space - time
 queries: all points
 located in a specific
 area during a
 specific time range



Important queries

 Time queries: all points of a specific time moment or range, for the whole spatial domain



A SFC approach

Structuring space and time is not a trivial problem. Contradiction:

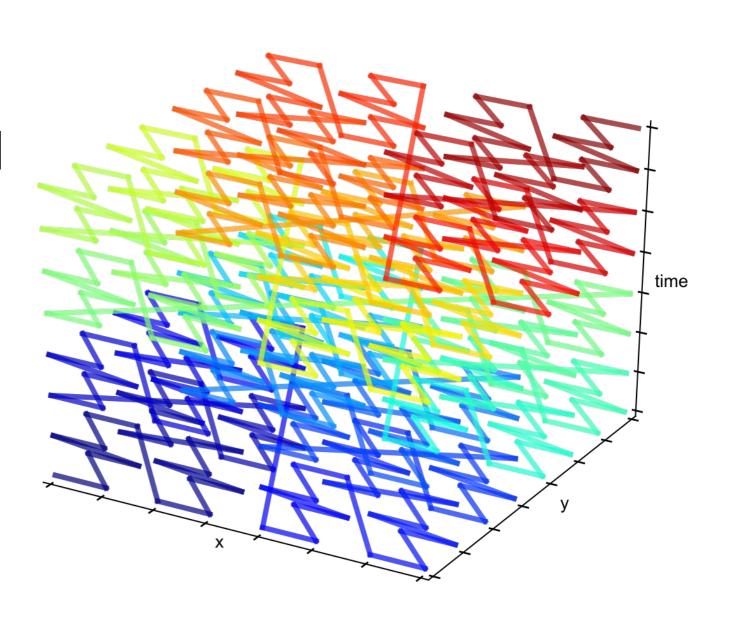
- Points close in space and time should be stored (up to a certain extent) in contiguous blocks in disk, for *fast* spatio-temporal retrieval.
- Already organised points should not be reorganised when inserting new data, for fast loading.

A SFC approach

Integrated space and time approach: all dimensions have equal part in SFC.

Two treatments of z:

- 1. as an attribute.
- 2. as part of the SFC key.

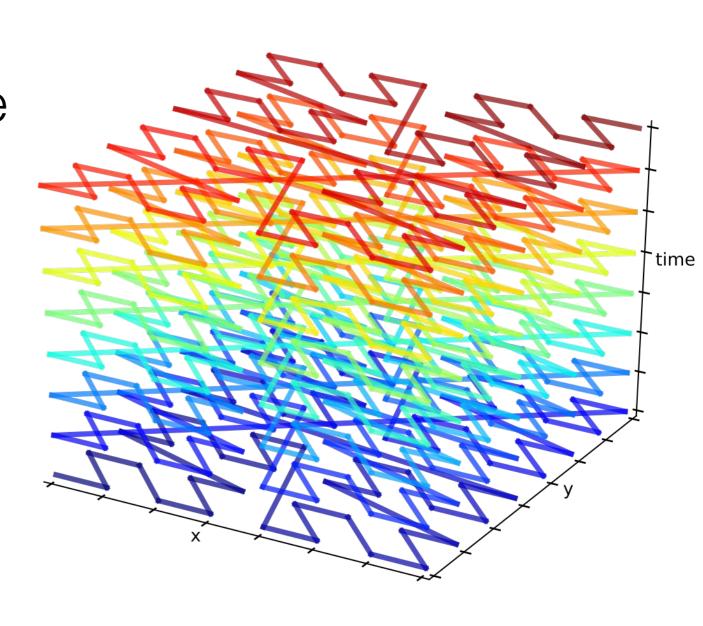


A SFC approach

Non-integrated space and time approach: time dominates over space.

Two treatments of z:

- 1. as an attribute.
- 2. as part of the SFC key.



A SFC approach - Loading

Two step approach:

- Preparation: Read files and convert to SFC key, according to
 - integration of space and time,
 - treatment of z and
 - scaling of time

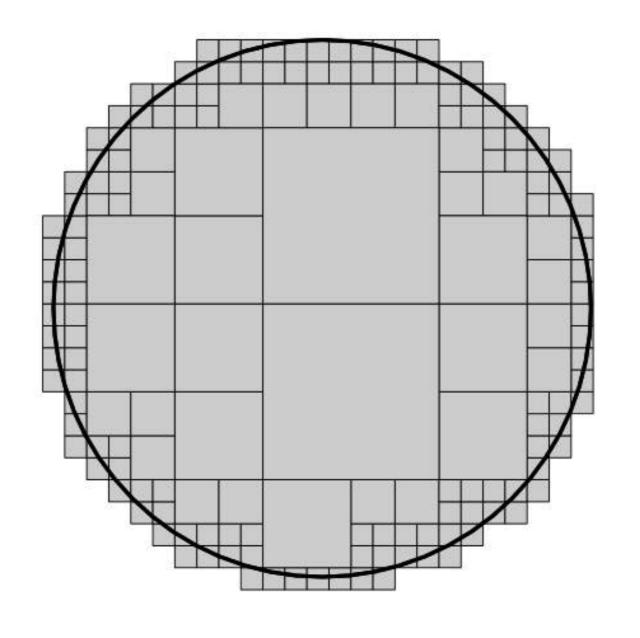
The data are bulk loaded into a normal heap table

- **Loading**: Sort the data based on the key into an Index Organised Table (data stored in the B-Tree index)

- Translation of the n-D query geometry into a number of continuous runs on the curve.
- Take advantage of the quadrant recursive characteristic of Morton curve: Use a Quadtree/ Octree/ 2ⁿ-tree
- The maximum depth of the tree affects:
 - the number of ranges
 - the approximation of the query geometry

Multi-step query procedure

- Filter step: approximate query geometry using the 2ⁿ-tree
- Fetch the approximated data and decode back to the original dimensions
- Refinement step: Detect the false hits using a Point in Polygon operation, or time and z refinement.



Identify Tree Cells

Direct neighbour merging

Reduce the number of ranges without affecting the approximation, by merging neighbouring ranges.

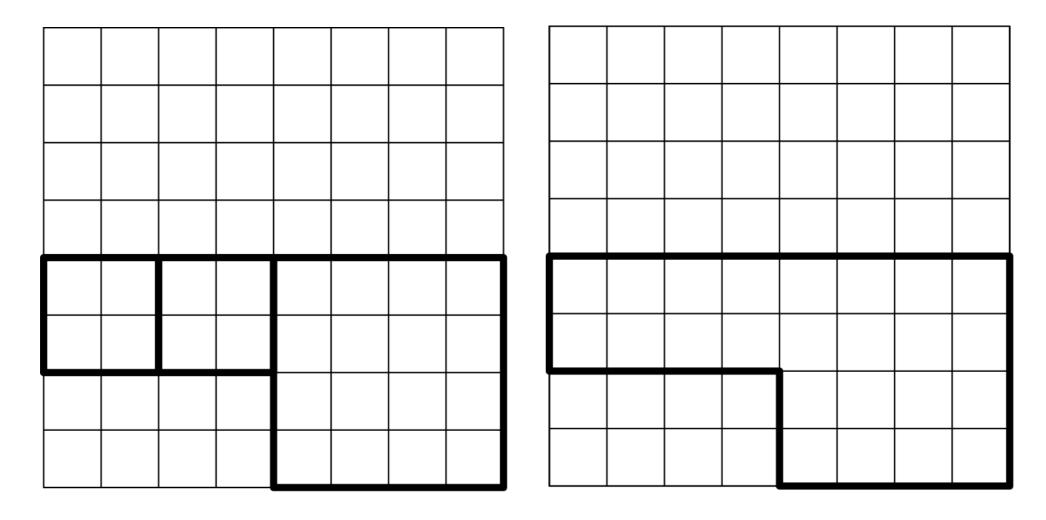
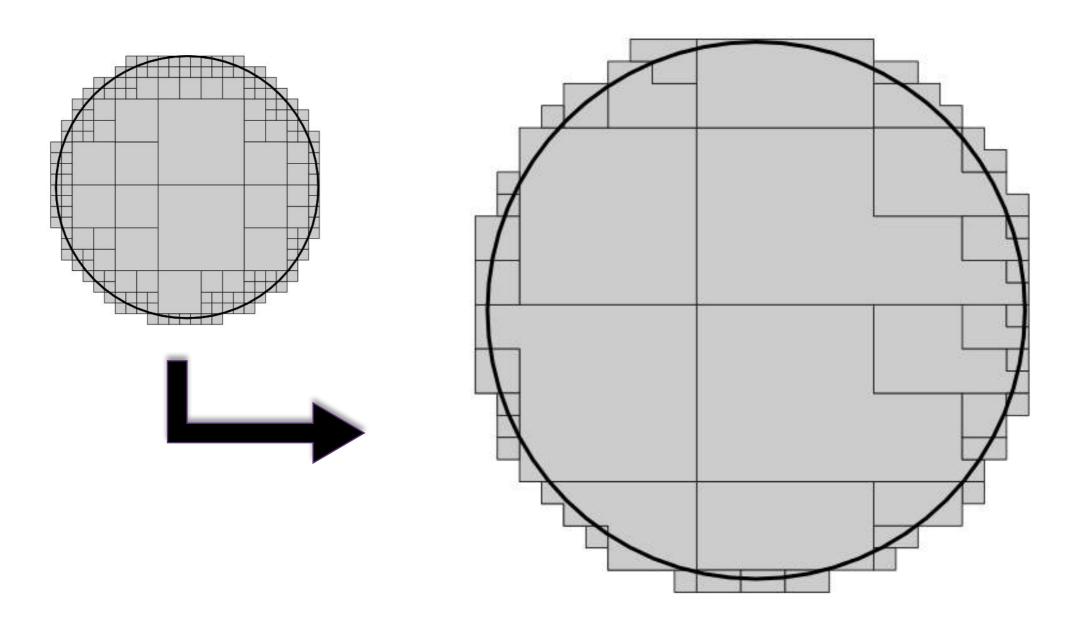


Figure a: Original 3 ranges

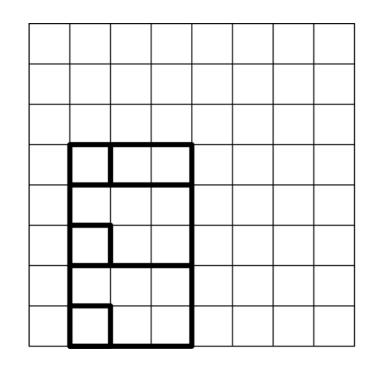
Figure b: Direct neighbour merging (1 range)

Direct neighbour merging

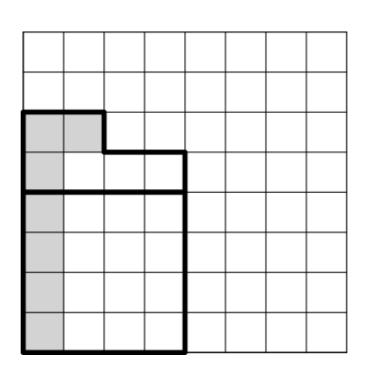


Merge of direct neighbours

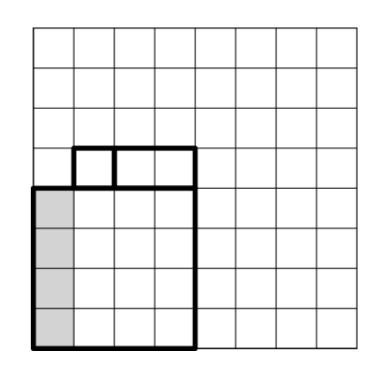
- Impose upper limit to the number of ranges
- Approximation gets slightly worse
- More false hits fetched during the filter step



Original 6 ranges

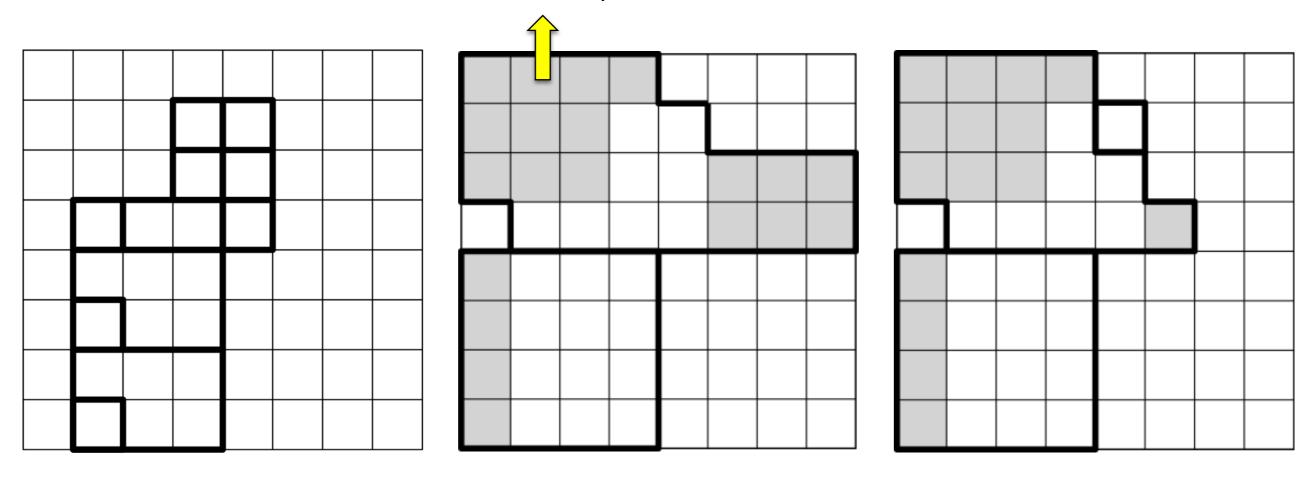


maximum 2 ranges



maximum 3 ranges

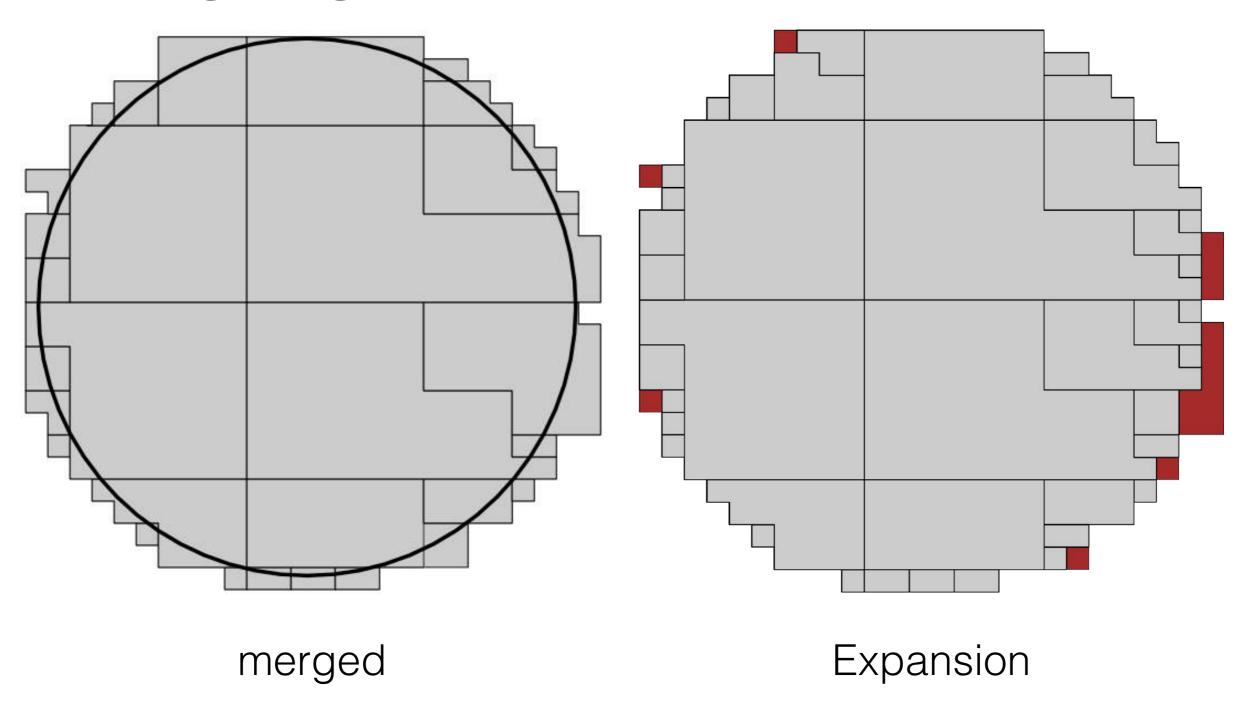
Additional space



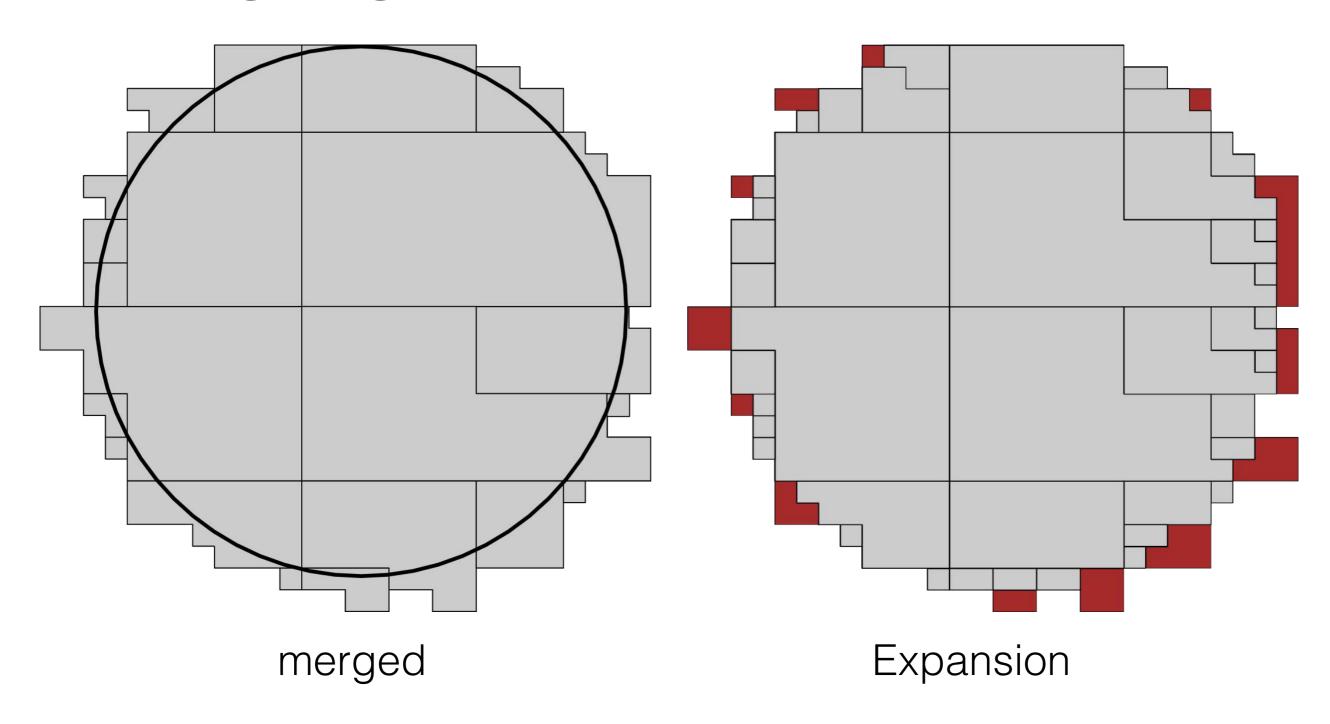
Original 11 ranges

maximum 2 ranges

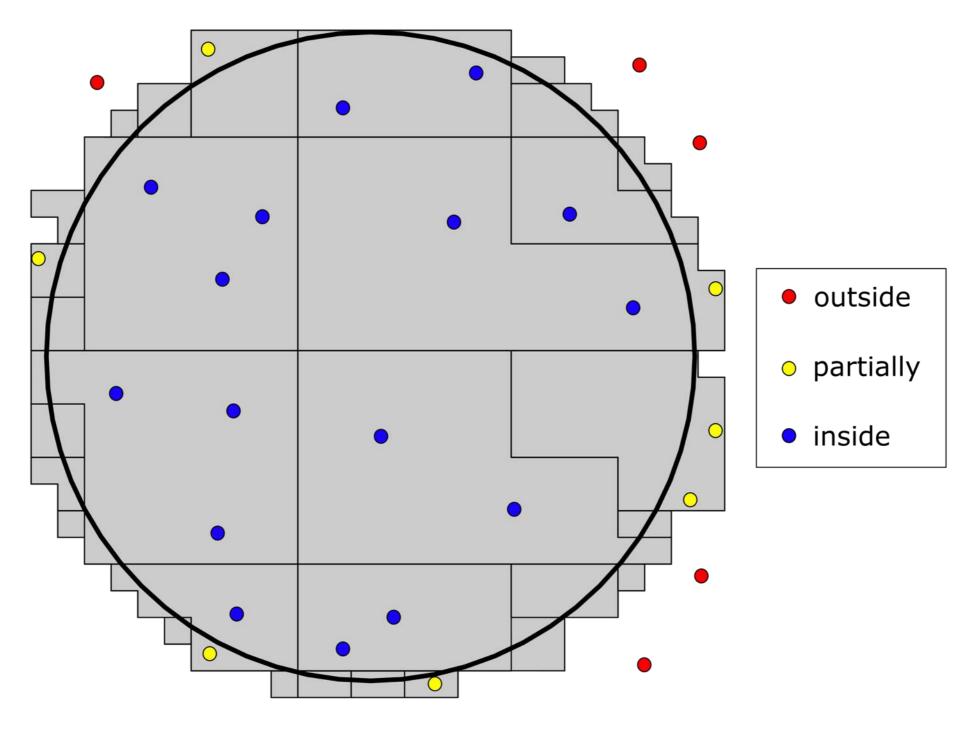
maximum 3 ranges

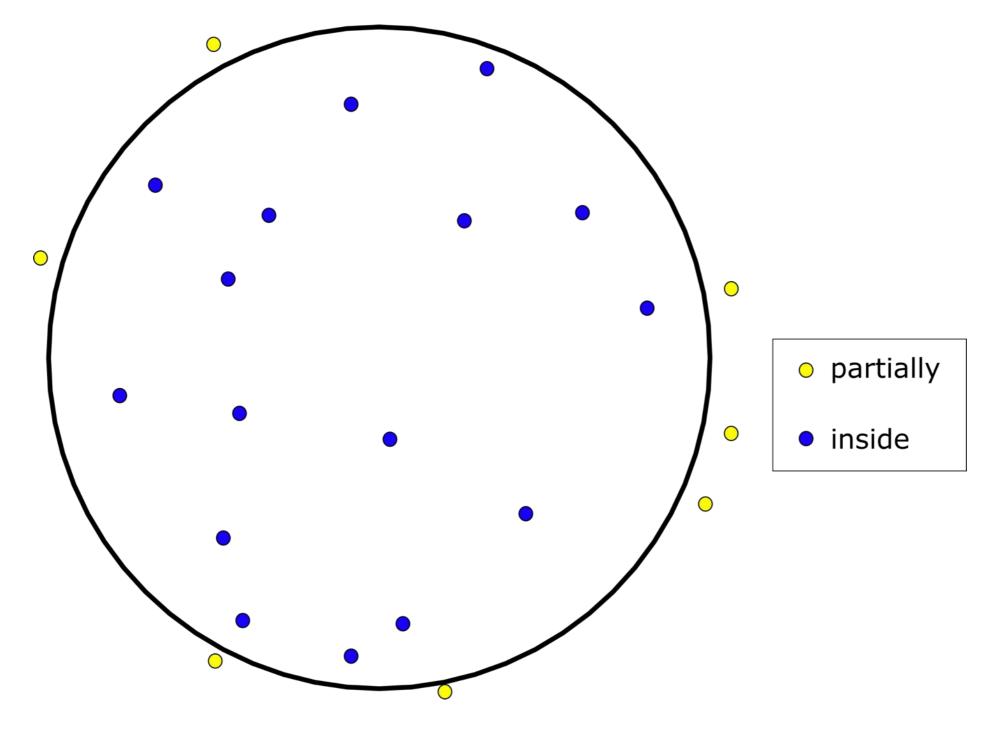


Merge to max. number (30)



Merge to max. number (20)



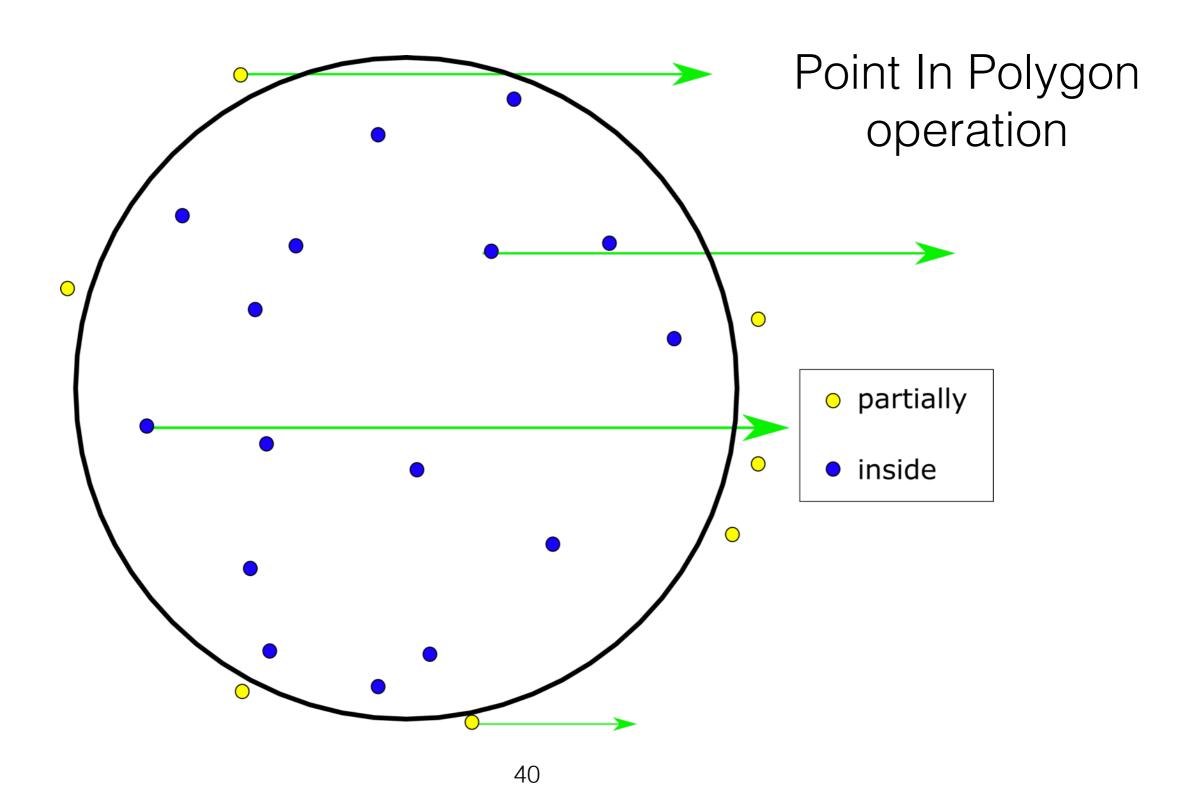


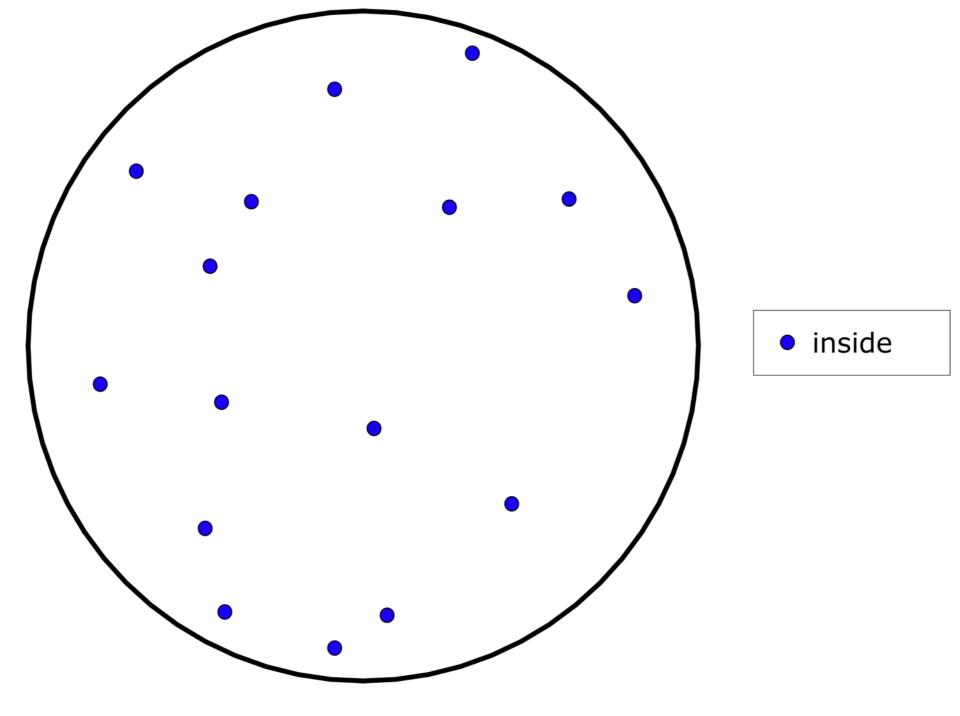
Multi-step query procedure

- Filter step: approximate query geometry using the 2ⁿ-tree
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Multi-step query procedure

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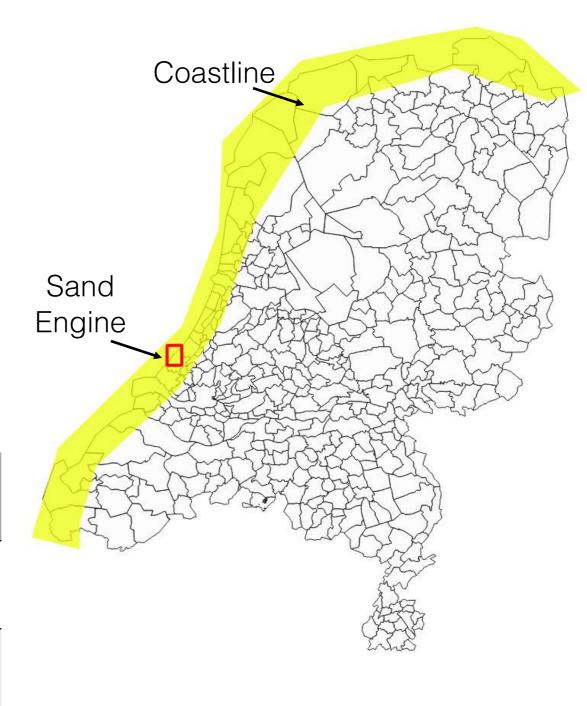


Results

Benchmark design

- Measure performance of storage space, loading time and query response time
- Datasets
 - Sand Engine
 - Coastline of the NL

Dataset	Time resolution	Spatial resolution	Points
Sand Engine	day	mm	100,000 pts/day
Coastline	year	cm	500 million pts/year 43



Benchmark design

Benchmark stages

Table 1. The benchmark stages of the Sand Engine dataset

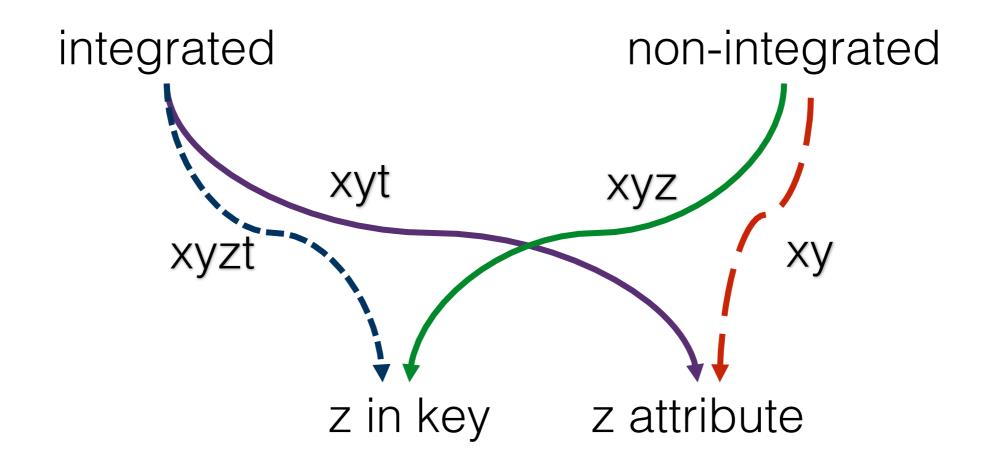
Benchmark	Points	Days	Size (MB)	Description
Small	18 M	230	347	2000 - 2002
Medium	44 M	554	836	2000 - 2006
Large	74 M	931	1414	2000 - 2015

Table 2. The benchmark stages of the Coastline dataset

Benchmark	Points	Years	Size (GB)	Description
Small	500 M	1	9.4	2012
Medium	995 M	2	18.7	2012 - 2013
Large	2020 M	4	37.9	2013 - 2015

Benchmark design

4 combinations



	1
Sand Engine	

	Time (s)			Size	Points	
Approach	conversion	Load heap	Load IOT	(MB)	Heap	IOT
xy - S	105.43	11.79	13.60	471	18,147,709	18,147,709
xy - M	145.14	16.56	49.65	1130	25,561,106	43,708,815
xy - L	167.75	19.72	78.00	1897	30,205,111	73,913,926
xyz - S	352.37	9.91	10.5	368	18,147,709	18,147,709
xyz - M	498.79	14.24	34.07	885	25,561,106	43,708,815
xyz - L	590.00	16.77	61.71	1495	30,205,111	73,913,926
xyt - S	349.68	11.79	13.09	471	18,147,709	18,147,709
xyt - M	492.29	16.56	40.39	1130	25,561,106	43,708,815
xyt - L	594.10	19.72	74.11	1897	30,205,111	73,913,926
xyzt - S	435.48	11.79	10.78	386	18,147,709	18,147,709
xyzt - M	604.27	16.56	33.21	927	25,561,106	43,708,815
xyzt - L	722.08	19.72	57.96	1566	30,205,111	73,913,926

- The SFC
 conversion is the
 most expensive
 phase.
- Adding one more dimension in the key decreases the performance of the conversion.

8	Time (s)			Size	Points	
Approach	conversion	Load heap	Load IOT	(MB)	Heap	IOT
xy - S	105.43	11.79	13.60	471	18,147,709	18,147,709
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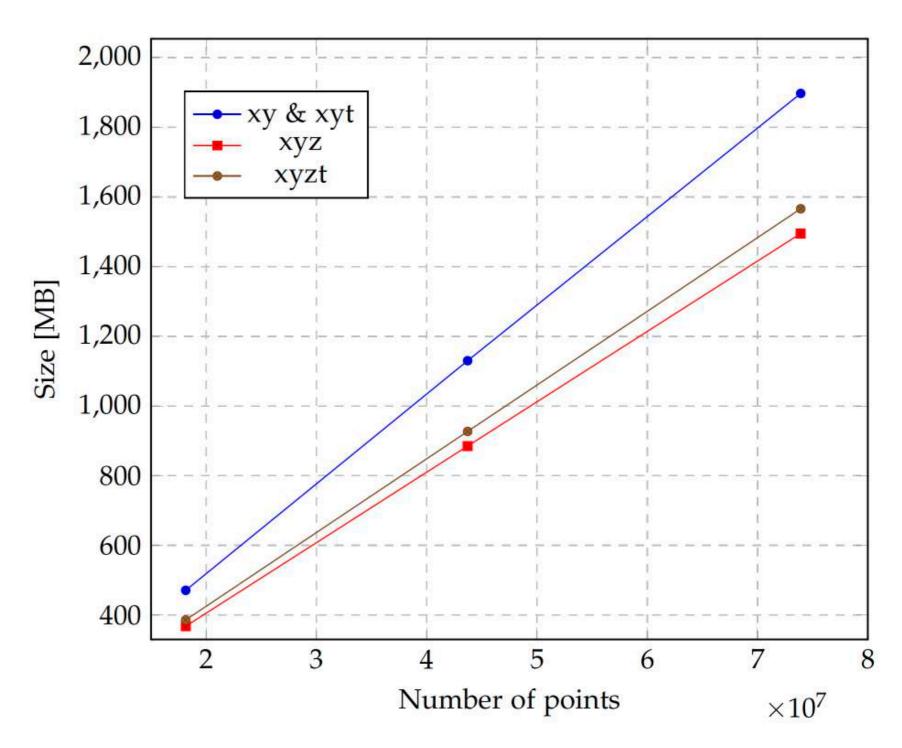
 Loading into the heap table is not affected by the benchmark case used.

Approach	Time (s)			Size	Points	
	conversio	Load heap	Load IOT	(MB)	Heap	ЮТ
xy - S	105.43	11.79	13.60	471	18,147,709	18,147,709
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- The creation of the IOT is dependent only on the treatment of z used.
- The IOT is created faster when treating z as part of the key.

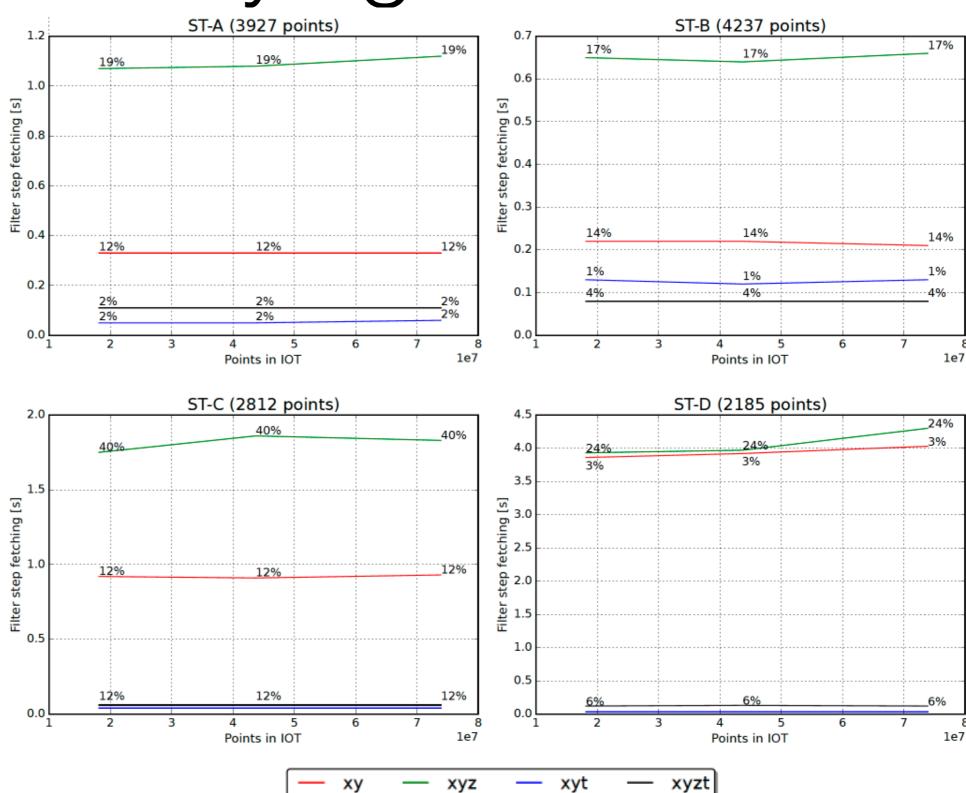
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- The storage requirements are affected only by the treatment of z.
- Treating z as an attribute increases the storage.

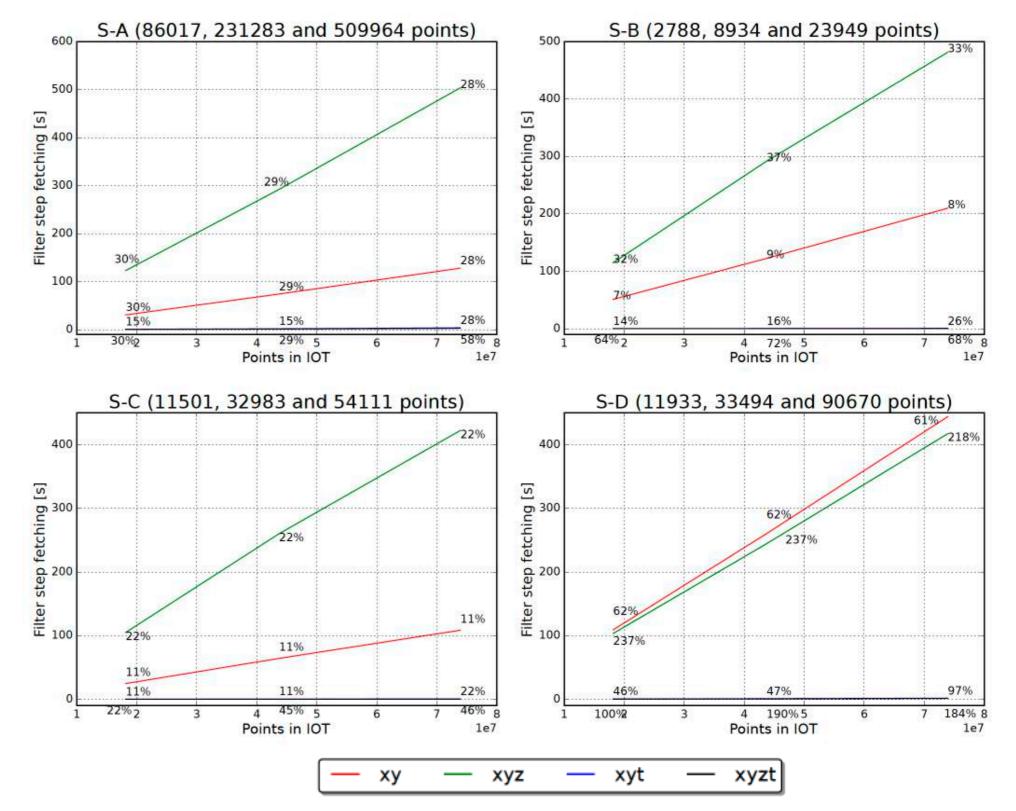


- Test the scalability of the queries
- Focus on the fetching time of the filter step that directly uses the structure. The rest of the steps can be improved in performance and are not analysed.

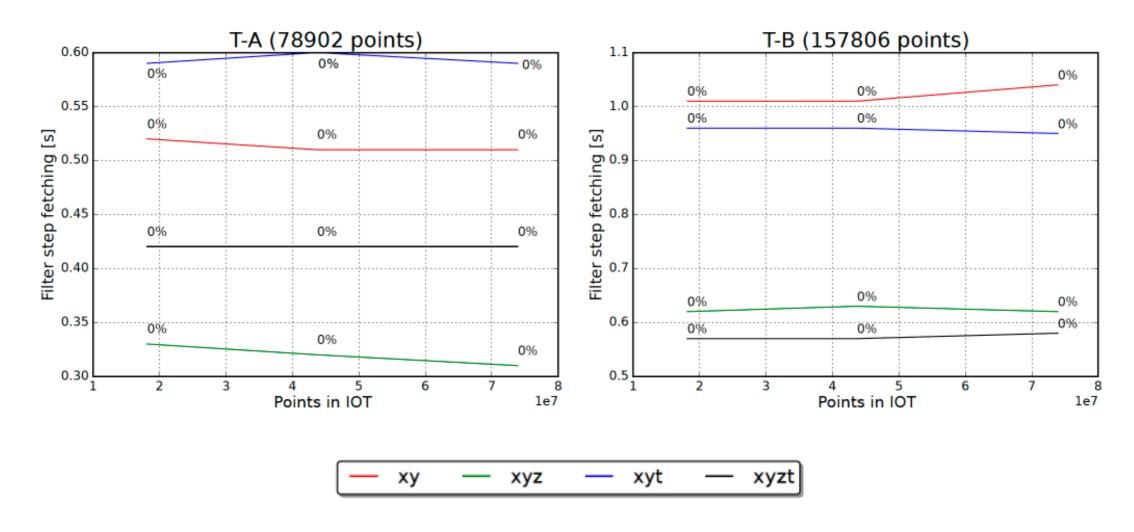
Space – time queries



Space only queries



Time only queries



Conclusion & Future work

Conclusions

- Designed and executed a benchmark for dynamic point clouds
- Two integrations of space and time and, two treatments of z
- Integrated approach presented better query response times, compared to non-integrated for the specific use case (both treatments of z possible)
- Key aspect of the implementation: Index Organised Table

Future work

- Native database functionality (encoding, decoding, range generation)
- Investigate a different SFC
- Investigate parallel processing
- Up-scaled benchmark of trillion points
- Investigate the generation of blocks: compression

Thank you for your attention!



References

- Gaede, V. and Gunther, O. (1998). Multidimensional access methods.
 ACM Computing Surveys (CSUR), 30(2):170–231.
- van Oosterom, P., Martinez-Rubi, O., Ivanova, M., Horhammer, M., Geringer, D., Ravada, S., Tijssen, T., Kodde, M., and Gonc, alves, R. (2015). Massive point cloud data management: Design, implementation and execution of a point cloud benchmark. Computers & Graphics, 49:92-125.