

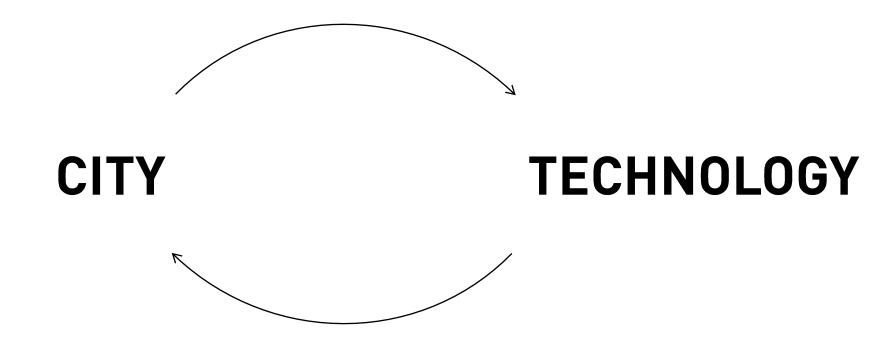
Self-driven MRDH

A Method to Assess the Impact of Automated Vehicles on Urban Liveability in the Rotterdam The Hague Metropolitan Region

Vincent Babeș

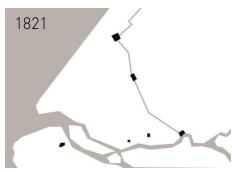
European Post-Master in Urbanism / P5 presentation / 26 June 2017 Mentors: Alexander Wandl, Luisa Calabrese, Paola Pellegrini

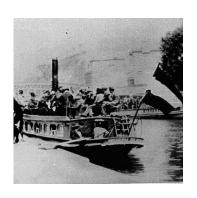




Mobility and the city. Automated vehicles, the next disruption?





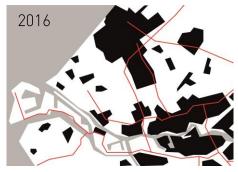




















Sources: www.tijdreis.nl Google, Street View

Mobility and the city. Automated vehicles, the next disruption?

+

SAFETY
AUTONOMY
TIME VALUE
SHARING
LESS PARKING SPACE
LOWER EMMISSIONS



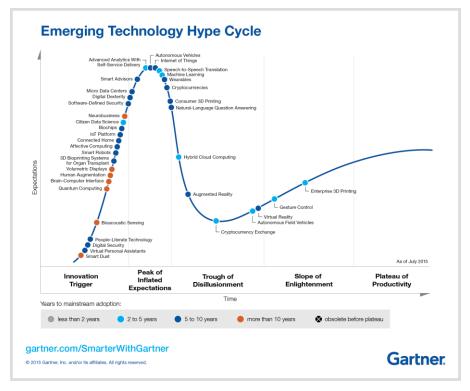
URBAN SPRAWL
ENERGY USE
ETHICS
HEALTH
JOBS

Sources:

Policy and society related implications of automated driving: a a review of literature and directions for future research, Milakis et al, TU Delft, 2015 Smart Mobility and Societal Challenges: an implementation perspective, Jeekel JF, TU Eindhoven, 2016 Social desirability and mobility impacts of early forms of automated vehicles, Pulyaert S, TNO/TU Delft, 2016

Scientific and societal relevance

Development



Mobility trends



Societal impact





Sources:

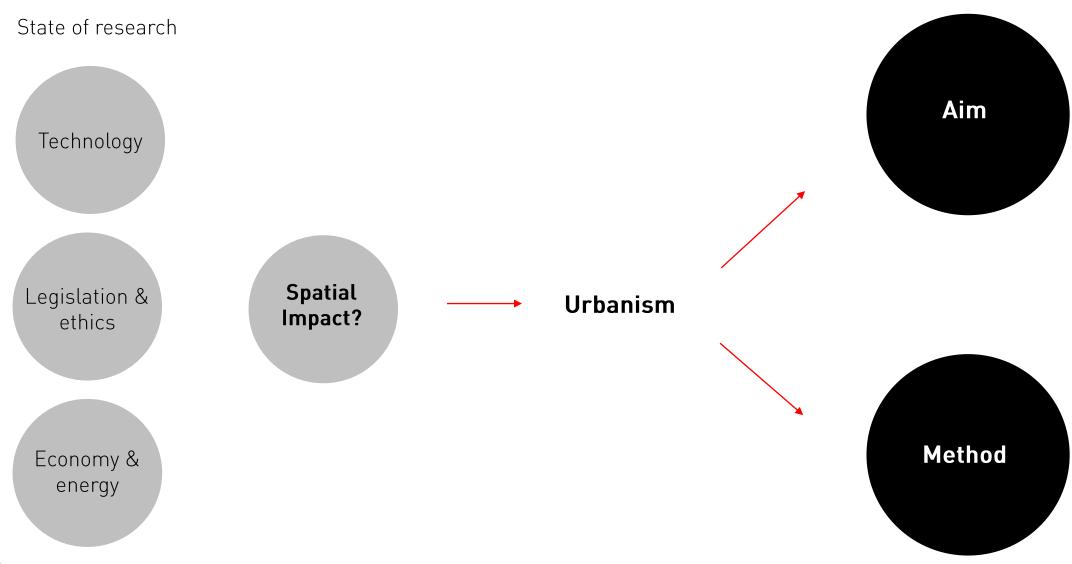
www.gartner.com

Artificial Intelligence and Life in 2030, Report of the 2015 Study Panel, Stanford University
Smart Mobility and Societal Challenges: an implementation perspective, Jeekel JF, TU Eindhoven, 2016
Social desirability and mobility impacts of early forms of automated vehicles, Pulyaert S, TNO/TU Delft, 2016

Problem statement

Despite the potentially important positive and negative effects of automated vehicles on mobility and human life in general, their spatial impacts represent a research gap which must be addressed.

Where does the urbanist stand?



Sources:

Farah, H (2016) State of Art on Infrastructure for Automated Vehicles
Milakis, D, van Arem, B & van Wee, B (2017) "Policy and society related implications of
automated driving: a review of literature and directions for future research"

Aims. Definitions of liveability

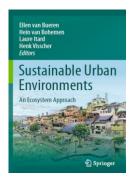
Administrative

Amount of housing Distance to jobs Crime rate Air pollution level



Academic definition

Contact with nature Social encounter Control & safety Prosperity

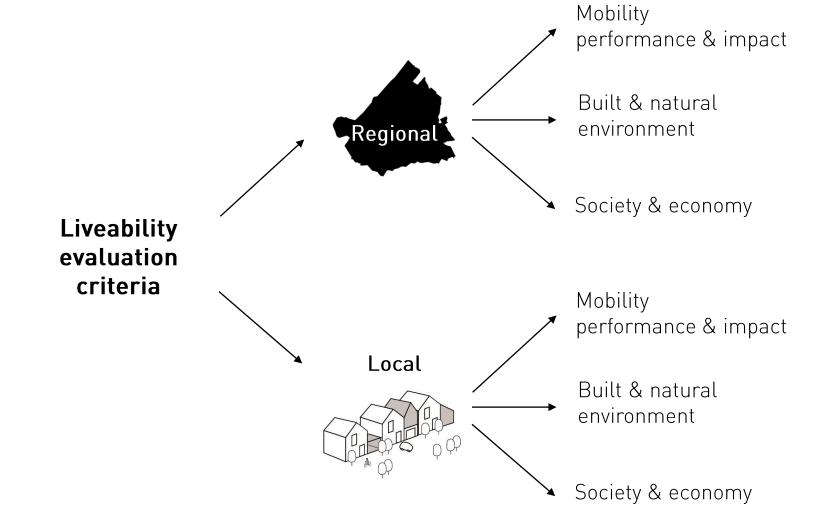


Urban theory

Sidewalk width
Shading
Active ground floors

Sources:

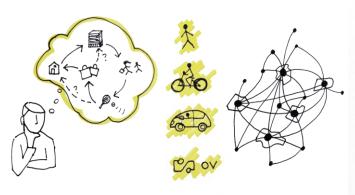
www.leefbaarometer.nl M. v. Dorst, Liveability, 2012 Downtown is for people, J. Jacobs, 1958 Cities for people, J. Gehl, 2010



Aims. Regional criteria of liveability

Mobility system: Coverage, efficiency and modal choice Reduced air and noise pollution Contact with (open) nature

Housing and work premises: sufficient and diverse (type, location)





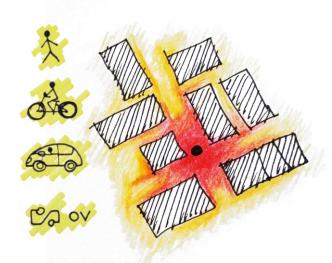






Aims. Local criteria of liveability

Accessibility and spatial integration



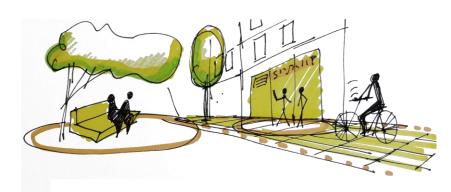
Control and safety



Contact with nature next to home and work



Spaces for socio-economic encounter



Research questions

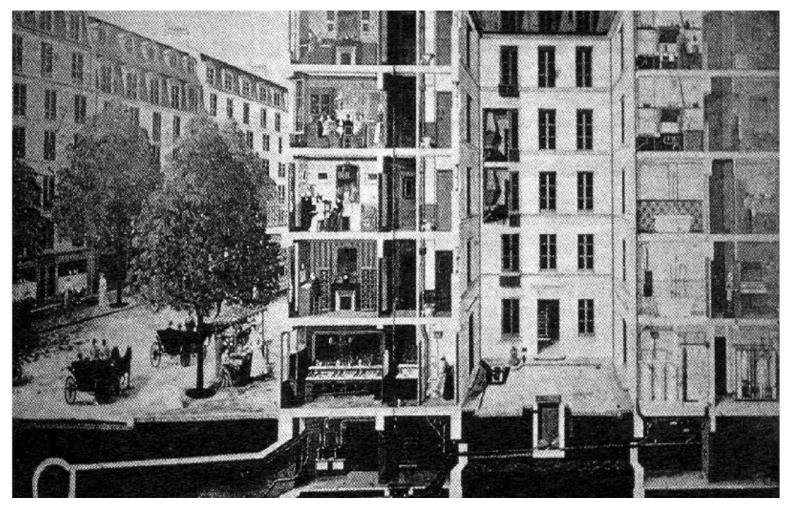
How can we assess the impact of automated vehicles on urban liveability through instruments specific to urbanism?

What directions of research, design and policy should be followed in the future in order to enhance urban liveability in the context of automated vehicle adoption?

Are the tools specific to urbanism useful to assess the impact of automated vehicles on the urban environment?

How can the urbanist/architect be ahead of the times by imagining the living environments and lifestyles resulting from technological innovation?

Building a method. Foresight and through-sight



Haussmann, Boulevard cross-section in Plan for Paris, 1859.

Building a method. Scenario construction

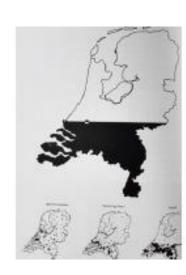
- Recognised method to imagine the future
- In the post-war Dutch planning tradition
- Analytical (Salewski)
- Radical proposal, background for discussion (Vettoretto)











Sources: Constant Nieuwenhuis, New Babylon / Den Haag, 1964. From Salewski, C (2012). Dutch New Worlds. Scenarios in Physical Planning and Design in the Netherlands, 1970-2000, 010 Uitgewerij, Rotterdam

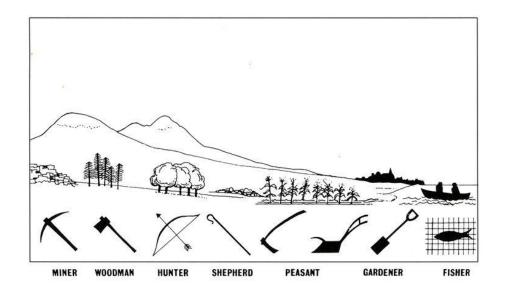
VROM Atelier Randstad 2040, One Architecture, Matthijs Bouw, Randstad 2040, 2008: Kuststad / Coast City. idem.

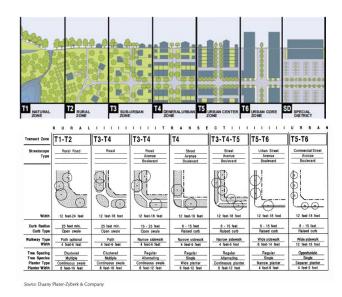
AIR-Alexander, OMA, New Urban Friontiers, 1993: Point City and South City. idem.

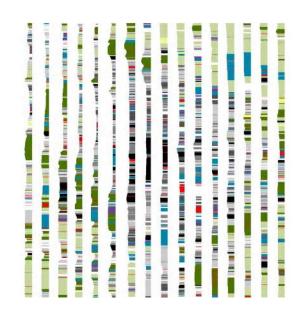
Salewski, C (2012) Dutch New Worlds. Scenarios in Physical Planning and Design in the Netherlands, 1970-2000 Vettoretto, L (2003) Scenarios: an introduction, some case studies and some research prospects, Universita luav di Venezia.

Building a method. Transect analysis

- Recognised territorial analysis method
- Geddes: valley section
- Duany: Smart codes

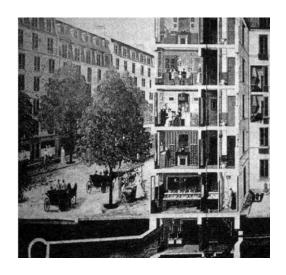






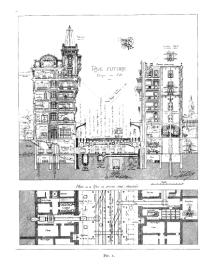
Sources:

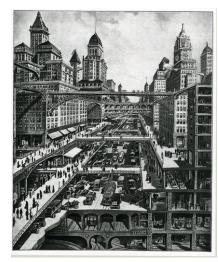
Building a method. Visionary urban sections







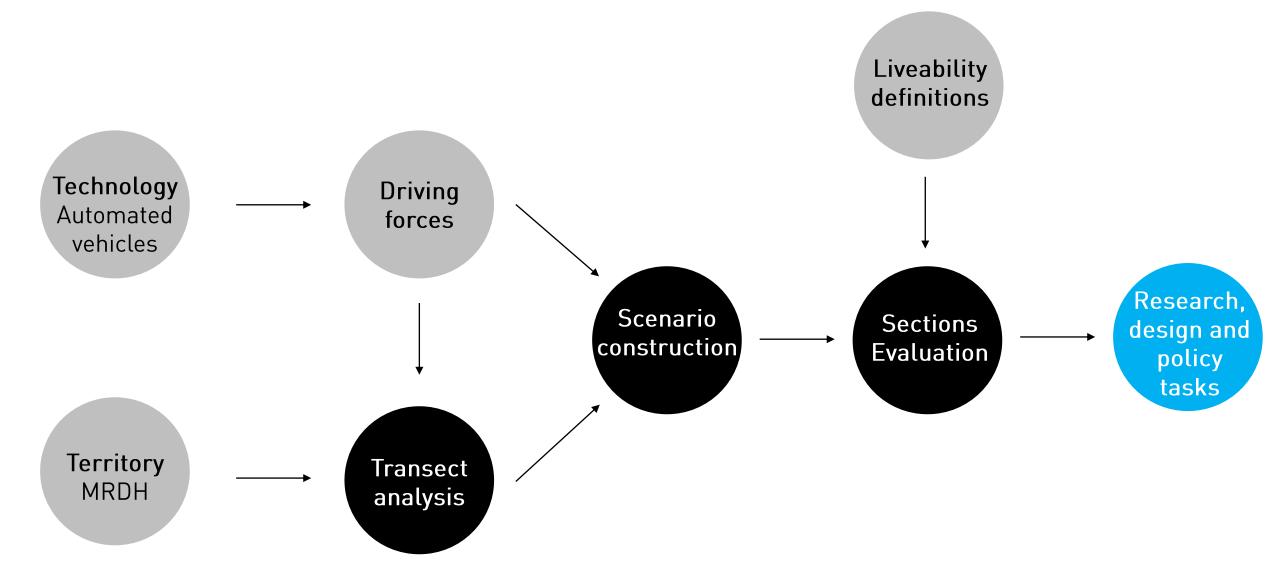






Sources:

George-Eugene Haussmann, Plan for Paris, (1853-1877), boulevard and building section. From Calabrese, LC (2004). Reweaving UMA Ildefons Cerda, Enlargement plan for Barcelona, 1859, typical section. idem.
Eugene Henard, Rue Future, 1911. From Lewis, P, Tsurumaki, M & Lewis, DJ (2016). Manual of section, Princeton Architectural Press, New York.
Harvey Wiley Corbett, City of the Future, 1913. From Lewis, P, Tsurumaki, M & Lewis, DJ (2016). Manual of section, Princeton Architectural Press, New York.
Le Corbusier, Ville Radieuse 1930. From Calabrese, LC (2004). Reweaving UMA.



Automated vehicles. Literature review

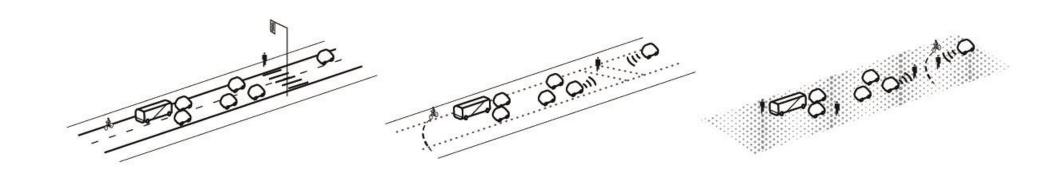
- Level 5 automation: technology is in control in all cases
- Foreseen introduction in the Netherlands in 2025, largely available in 2040
- Spatial impacts: road, networks, fields

Sources:

Development of automated vehicles in the Netherlands: scenarios for 2030 and 2050, Milakis et al, TU Delft, 2016
Autonomous driving and urban land use, Heinrichs, 2016
Policy and society related implications of automated driving: a a review of literature and directions for future research, Milakis et al, TU Delft, 2015
Smart Mobility and Societal Challenges: an implementation perspective, Jeekel JF, TU Eindhoven, 2016
Social desirability and mobility impacts of early forms of automated vehicles, Pulyaert S, TNO/TU Delft, 2016
Farah, H (2016) State of Art on Infrastructure for Automated Vehicles

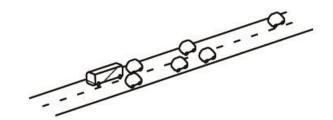
safety and public space quality

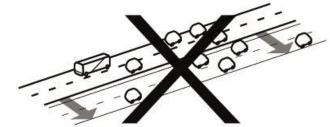
smart sensoring shared space dynamic street management



road capacity

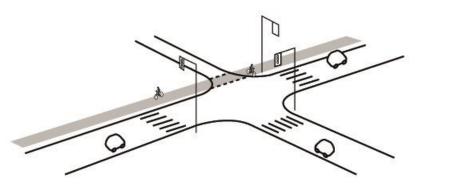
high intensity traffic in the same road space

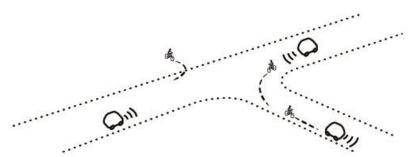




intersection management

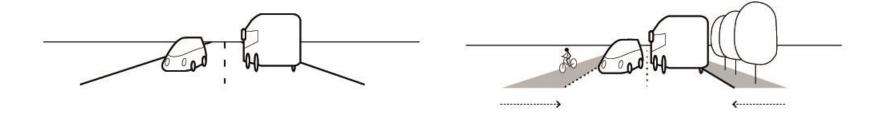
smart sensoring





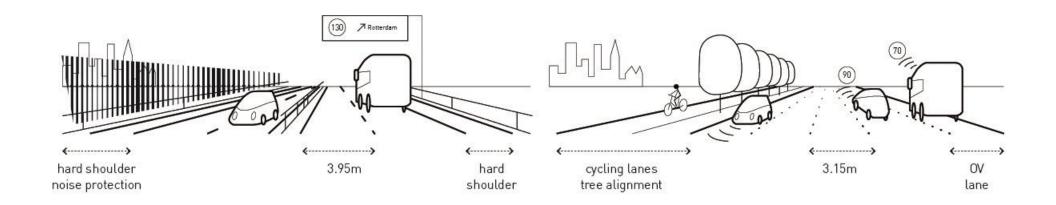
road profiles: provincial road

new design opportunities through narrower lanes



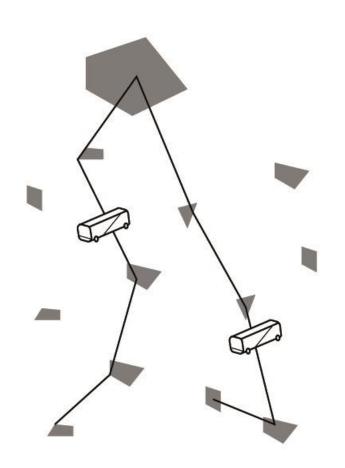
road profiles: motorway

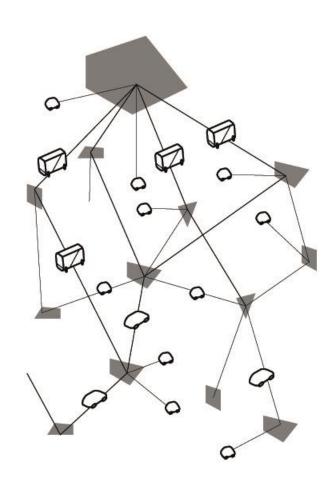
lower investment
less pollution
sharing
active mobility
landscape integration



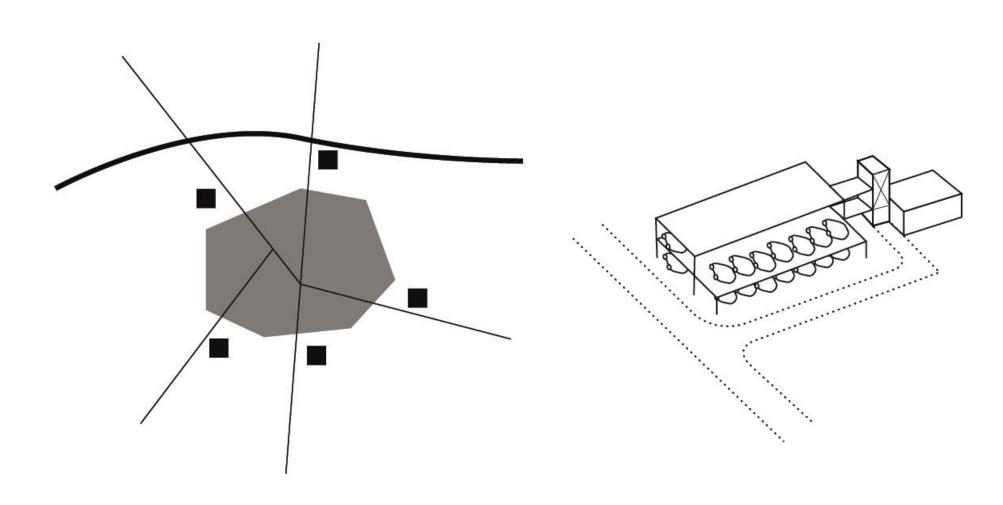
public transport in low density areas

on-demand and economically sustainable coverage of rural areas



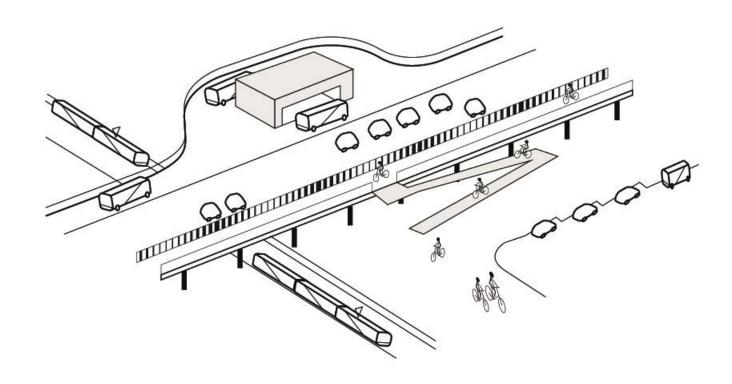


parking racks & service points
self-parking for cars on cheap land



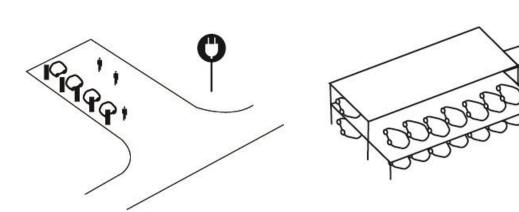
multimodal hubs

synergy of high and low intensity transport modes transfer from long distance to local active mobility

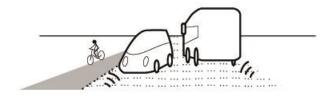


energy

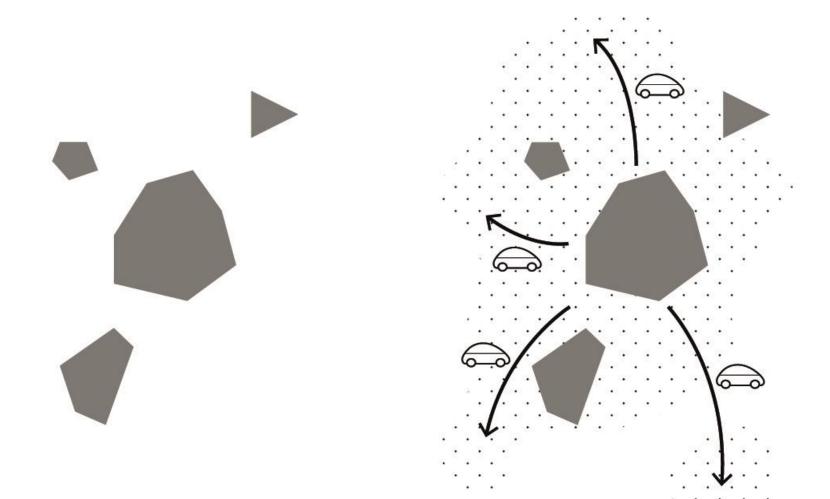
e-charging points charging while parking car as battery solar roads with wireless charging



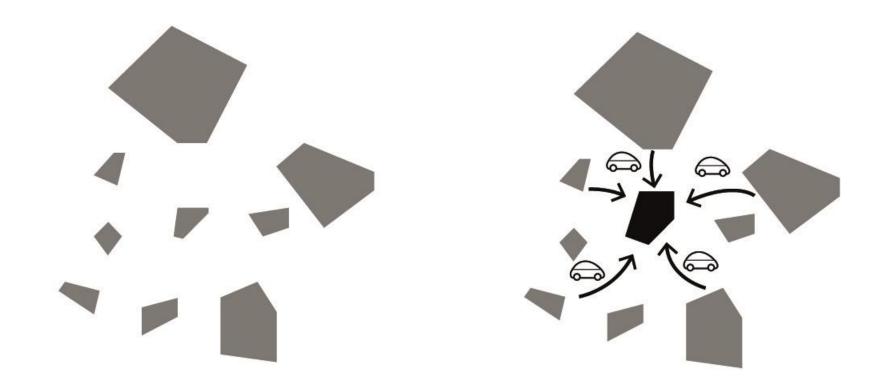




low-density development

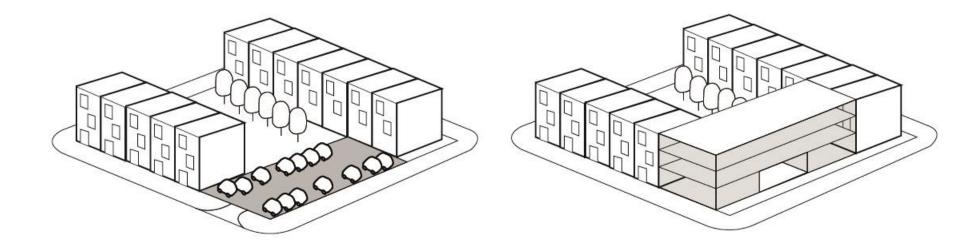


new centralities

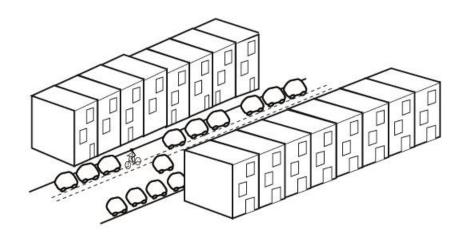


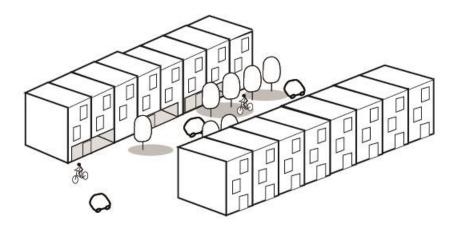
urban infill

less parking requirement enables higher density



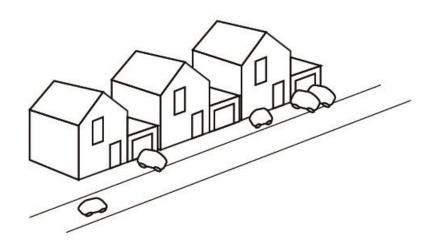
no on-street parking active streetscape

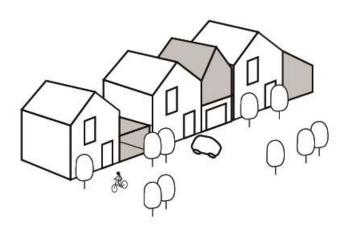




residential parking reconversion

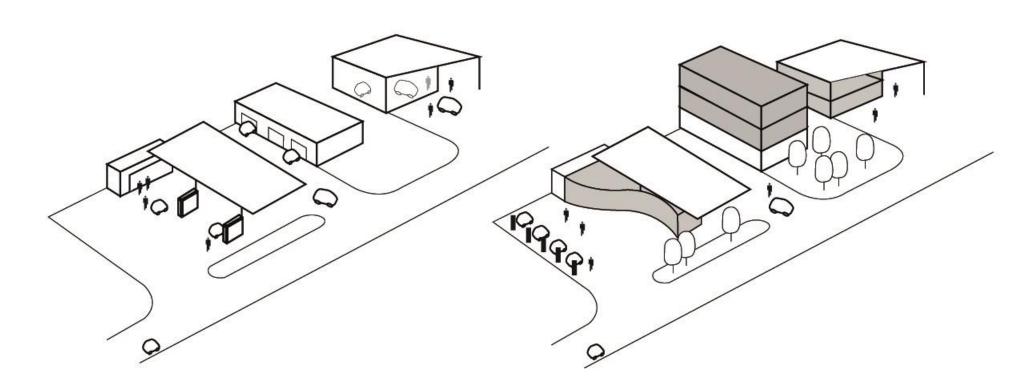
new uses in residential areas

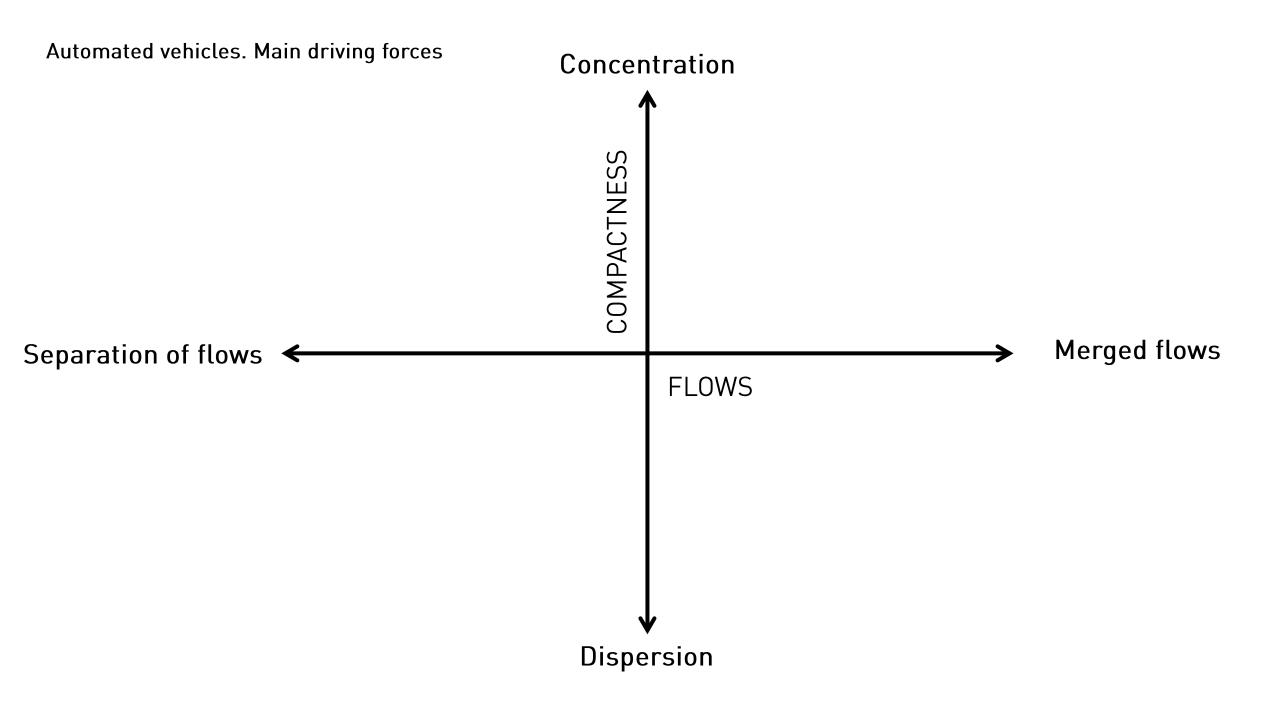




car-related economy

restructuring of car-related economy new uses in attractive areas





MRDH. A dynamic region



2 244 159 inhabitants



2 246 people per 1 km²



municipalities



121 330 companies



170 GDP bn Euros



1165 total area km²



166 / 999 water / land km²



built km²



117 asphalt cover km²

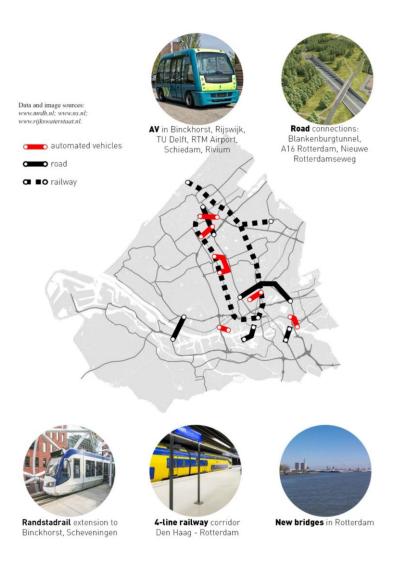
Data sources: OECD Territorial Reviews, Metropolitan Region Rotterdam The Hague; CBS, Wijk- en Buurtkaart 2016; Kadaster Basisregistratie Topografie, Top10NL.

Map source: Google Earth Pro sattelite imagery.



MRDH. Trends of urbanisation and infrastructure

Networks



Fields



Urban expansion north of Rotterdam, aerial view, 2017. Photograph by author.

Urbanization after 2005. Data from Corine Land Cover 2012, CBS and code.waag.org



MRDH. Mapping the mobility landscapes





















MRDH. Spaces of cars on the move

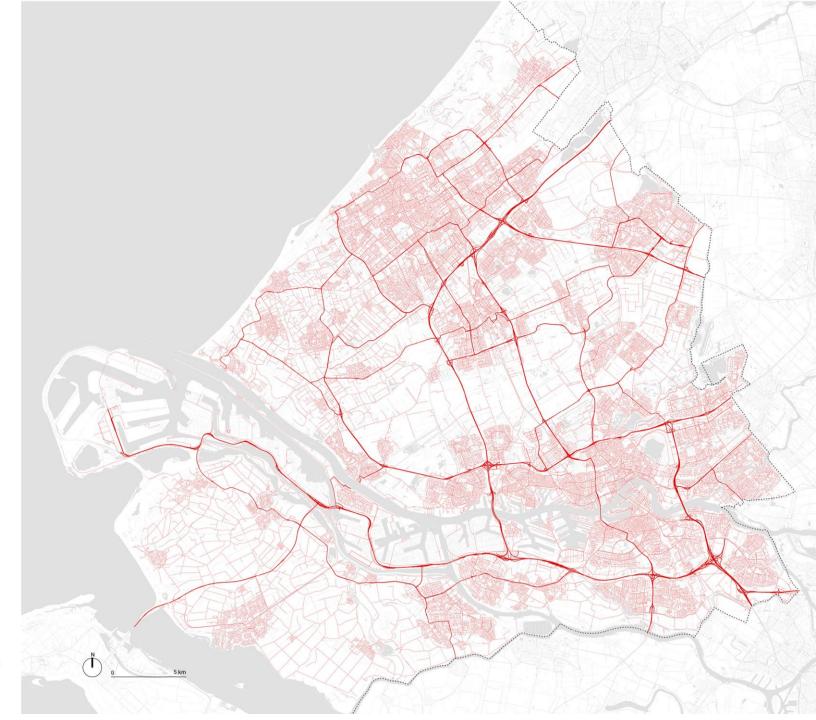
Main road network
Local streets

Main roads 490 km

Secondary roads and urban streets 7915 km

Road network 8405 km

Figure 86. Surfaces occupied by road type. Measured in GIS based on 'wegen_lijn' and 'wegen_vlak' layers from top10nl, CBS 2015.



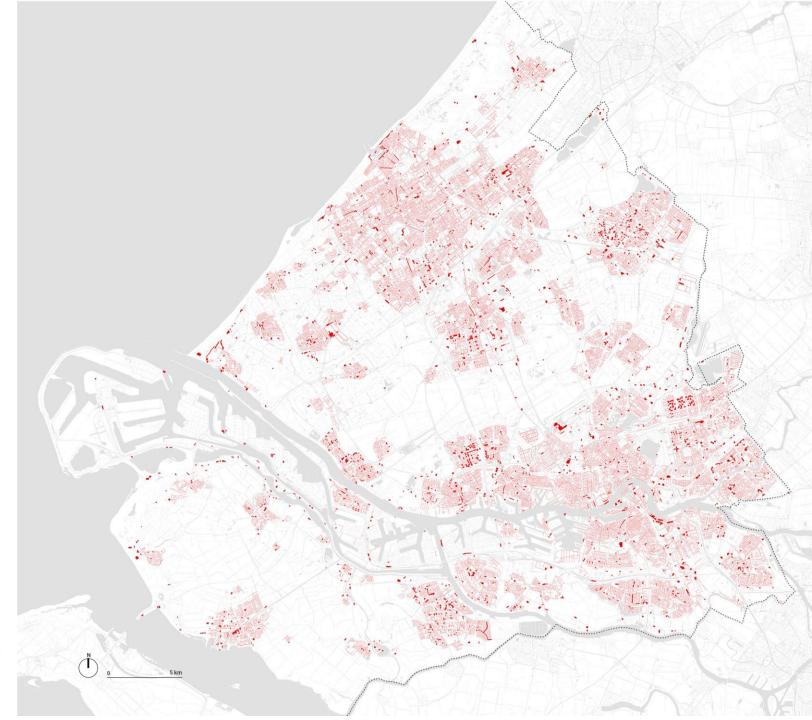
MRDH. Spaces of cars idle

Large parkings
On-street parking

Parking areas 5,8 km²



Figure 88. Surfaces occupied by parking types. Measured in GIS based on 'wegen_lijn', 'wegen_vlak' and 'gebouw' (typegebouw = 'parkdak') layers from top10nl, CBS 2015.



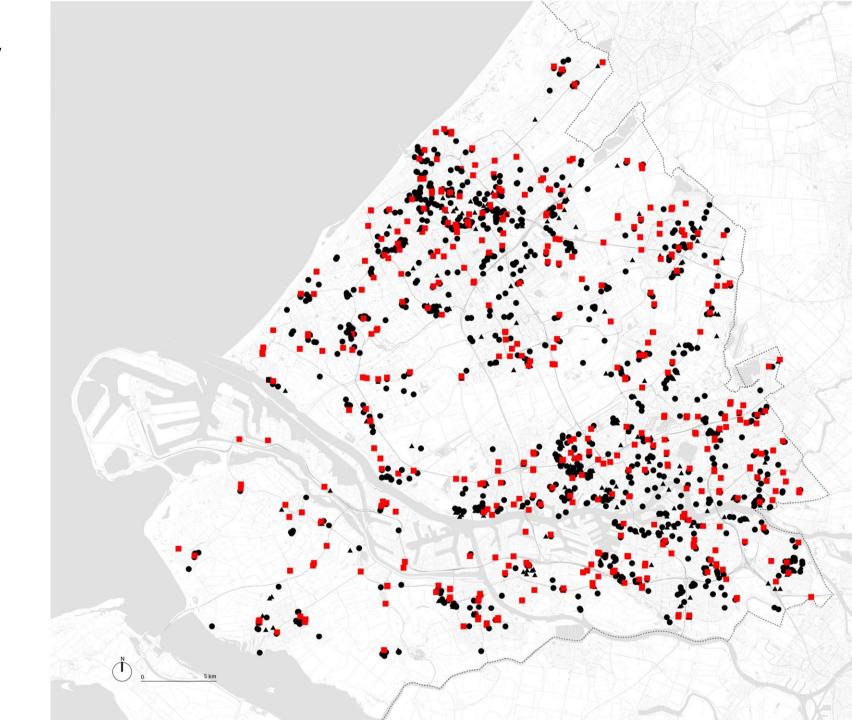
MRDH. Spaces of no car

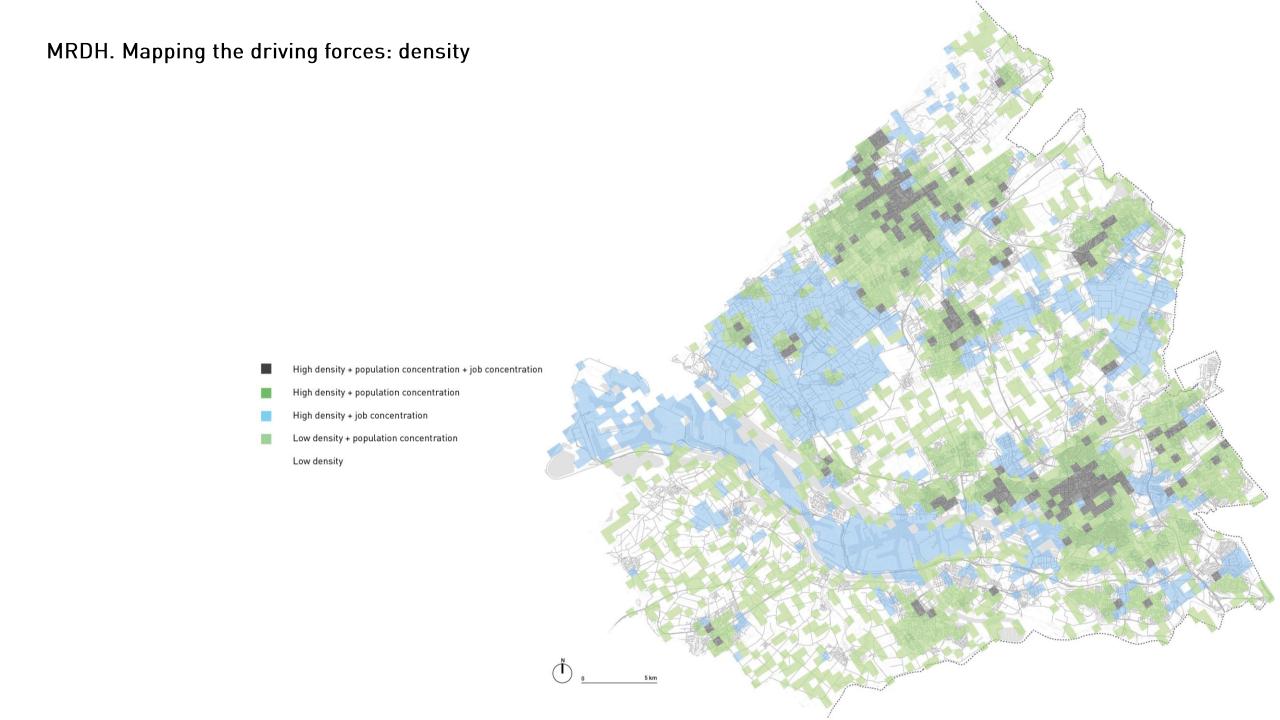
Pedestrian areas
Cycling infrastructure

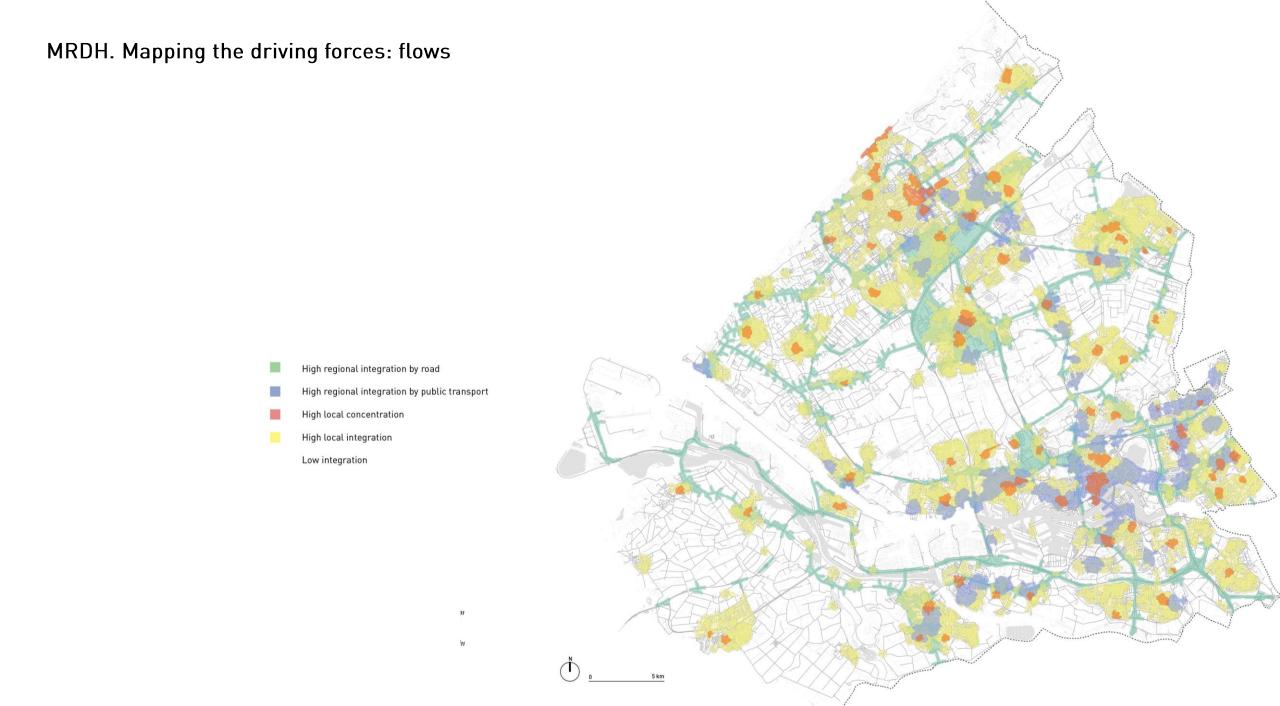


MRDH. Spaces of car-related economy

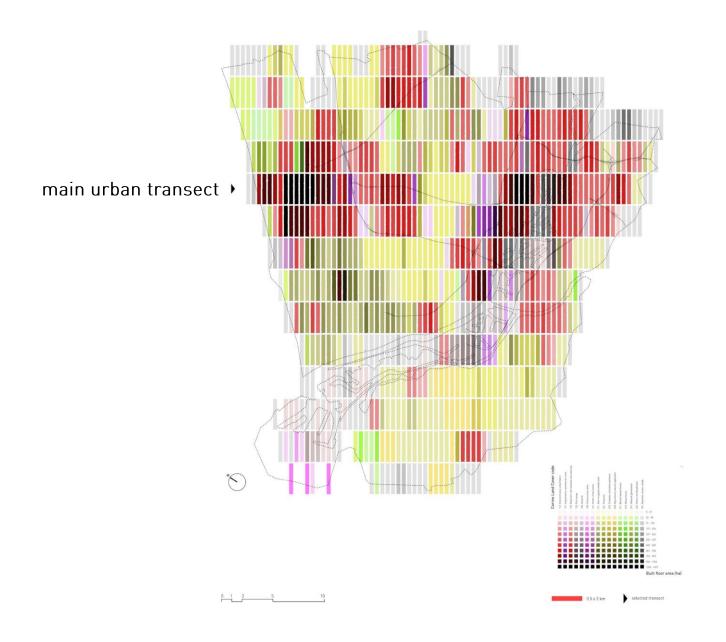
- Fuel stationsCar salesCar service



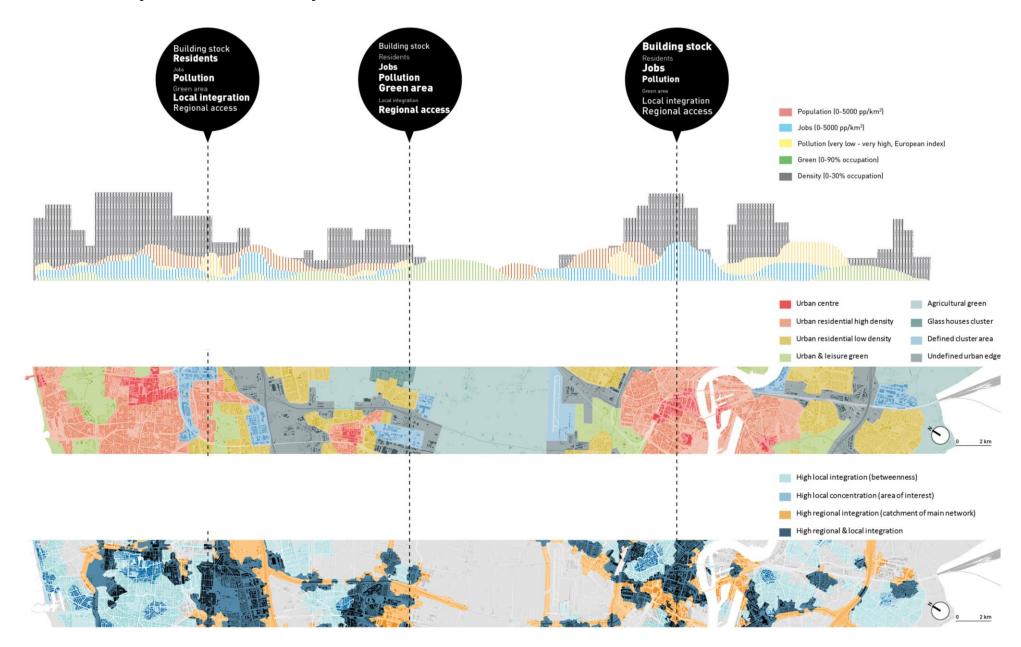




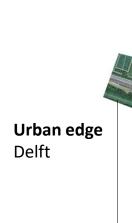
MRDH. Transect choice: density-program matrix



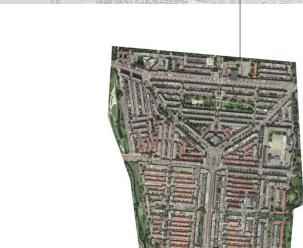
MRDH. Transect analysis and liveability



MRDH. Case study locations







ResidentialThe Hague





Scenario construction: hypotheses and driving forces

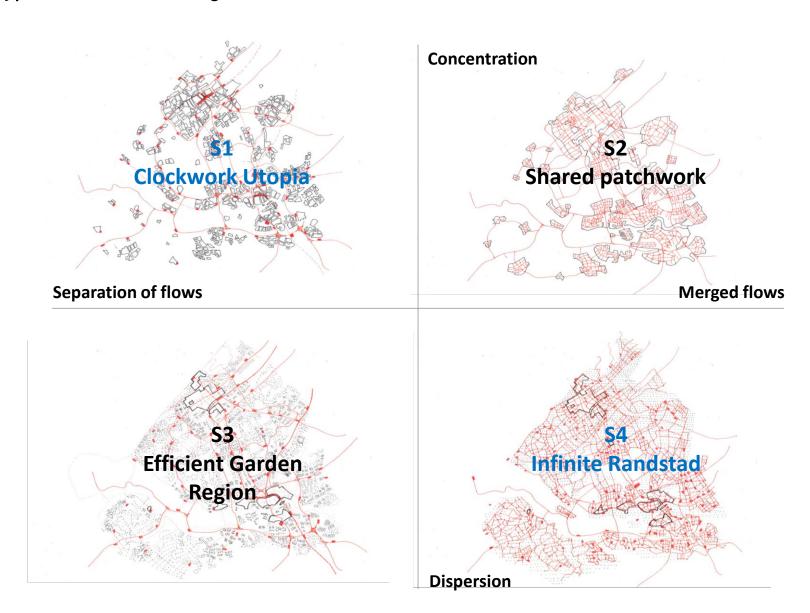
Agenda 2040

380.000 new housing units

80.000 new source: www.worki.places

Fully automated vehicles available from 2025

Source: Milakis et al



Scenario construction. Learning from the visionaries

Scenario 1. Clockwork Utopia



Harvey Wiley Corbett, City of the Future, 1913. From Lewis, P, Tsurumaki, M & Lewis, DJ (2016). Manual of section.



Le Corbusier, Ville Radieuse 1930. From Calabrese, LC (2004). Reweaving UMA.



of flows between 1960 and today. www.citieswithoutground.com



REALISATION

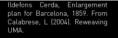




Living street, Ghent, 2015. From www.leefstraat.be



Scenario 2. Horizontal Density





Arturo Soria y Mata, Ciudad Lineal, 1882. From Calabrese, LC (2004). Reweaving UMA.



Jane Jacobs, Downtown is for people, Forbes, 1958.



Jan Gehl, Cities for People, 2010.

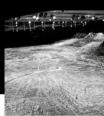
merged flows

separated flows

Figure 125. Visionary projects table, organised by scenario and type. Scenarios 1 and 4 link to most project/vision types, whereas scenarios 2 and 3 are connected to mostly theoretical models or realised projects. Therefore, scenarios 1 and 4 are the most interesting to develop in an explorative direction.



Ebenezer Howard, Garden City,



Norman Bel Geddes, Futurama,

Scenario 3. Efficient Garden Region



61 22 12 72 72 . . 1

Yona Friedman, Urban Design Manhattan, 1969. From Yoos & James, The Multilevel

Metropolis.

Geoffrey Jellicoe, Motopia, 1959



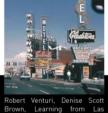
Regional model and activities model of the two networks strategy, Tjallingii, 2015.



Foster & partners, London Cycling Highways, 2015. www.fosterandpartners.com



Frank Lloyd Wright, Broadacre City, model, 1930. From www.



Robert Moses, Grand Central Parkway Queens, 1936. www.corbisimages.com

No-stop City, project, plan. 1969. From www.moma.org

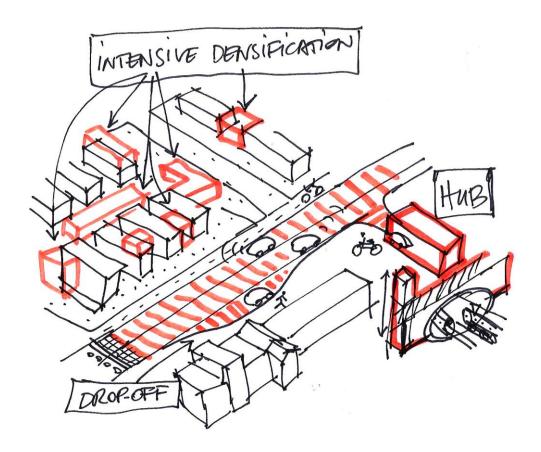


Future of suburbia, Matthew Spremulli, Center for Advanced Urbanism, MIT, 2016.

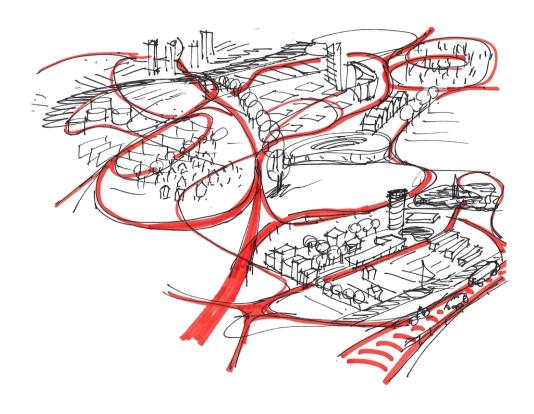
Scenario 4. Infinite Randstad

REALISATION

S1 Clockwork Utopia



S4
Infinite Randstad



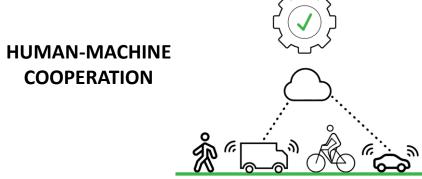
S1

Clockwork Utopia

HUMAN
CONTROL

HUMAN-MACHIN
COOPERATION

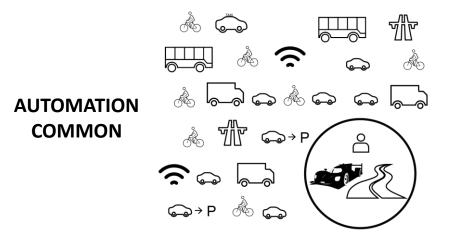




S1 Clockwork Utopia

AUTOMATION EXCEPTION

S4
Infinite Randstad



S1 Clockwork Utopia

MOBILITY SYSTEM

MULTIMODAL

S4
Infinite Randstad



S1 Clockwork Utopia

S4
Infinite Randstad

SHARED

PUBLIC TIME





INDIVIDUAL

PRIVATE TIME

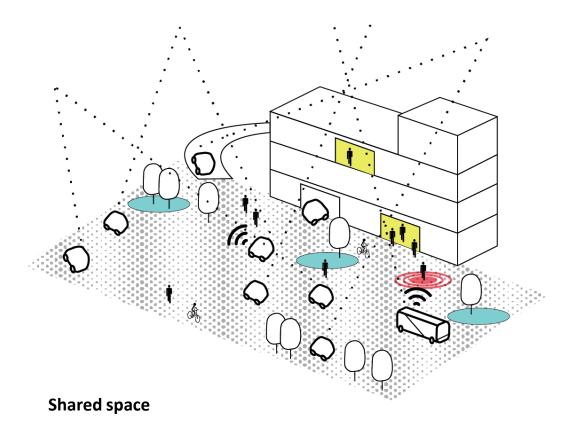






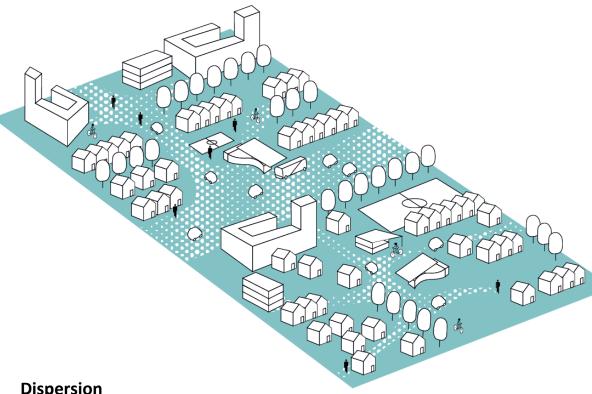
S1 Clockwork Utopia Separation of flows

S4
Infinite Randstad

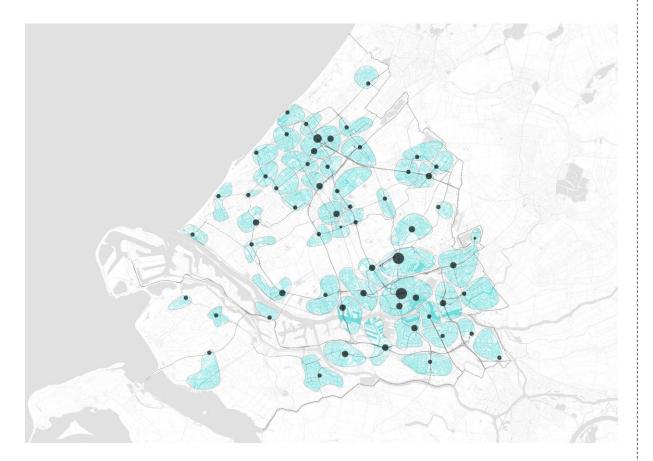


S1 Clockwork Utopia Concentration Dispersion

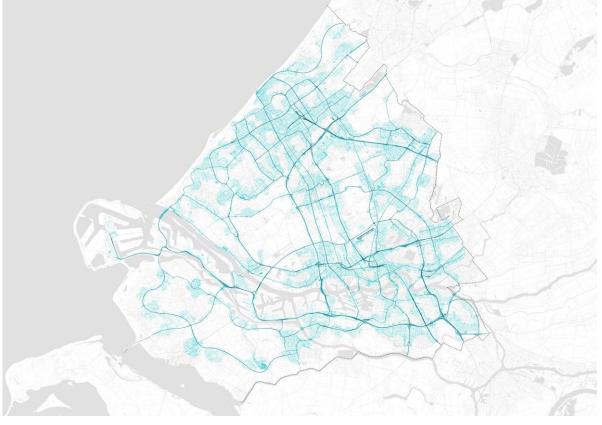
S4
Infinite Randstad



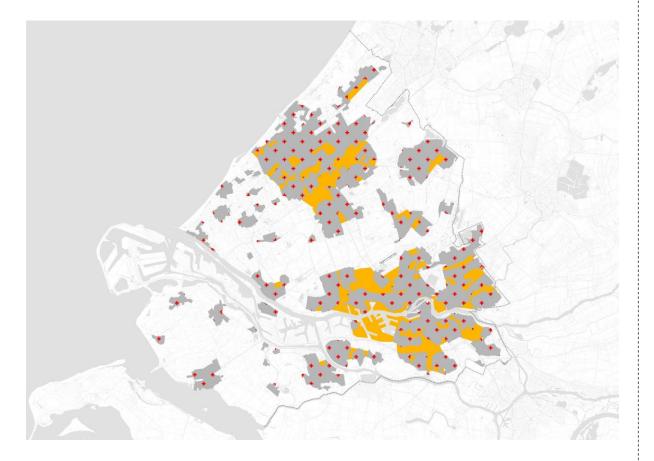
S1 Clockwork Utopia



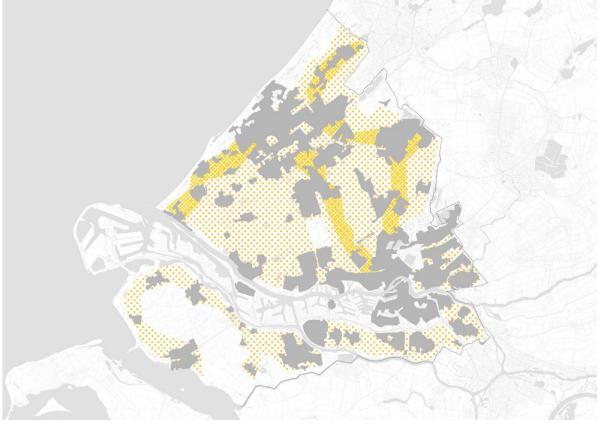
S4
Infinite Randstad



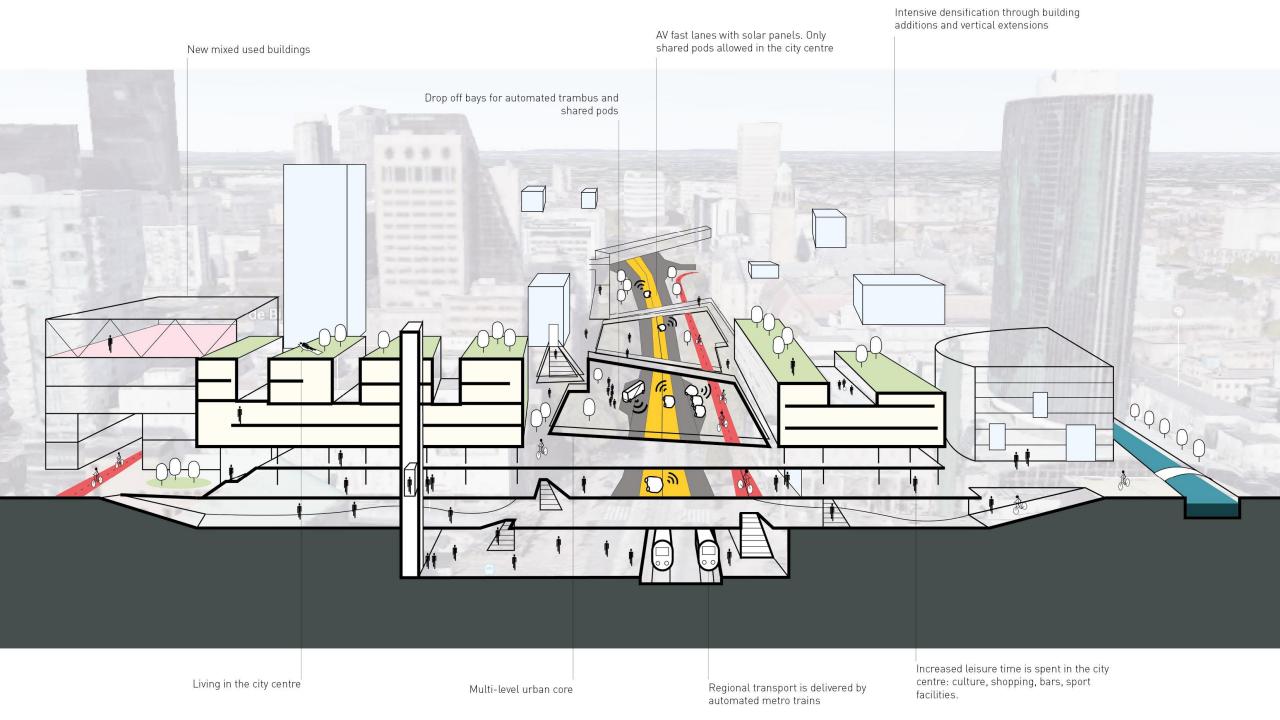
S1 Clockwork Utopia

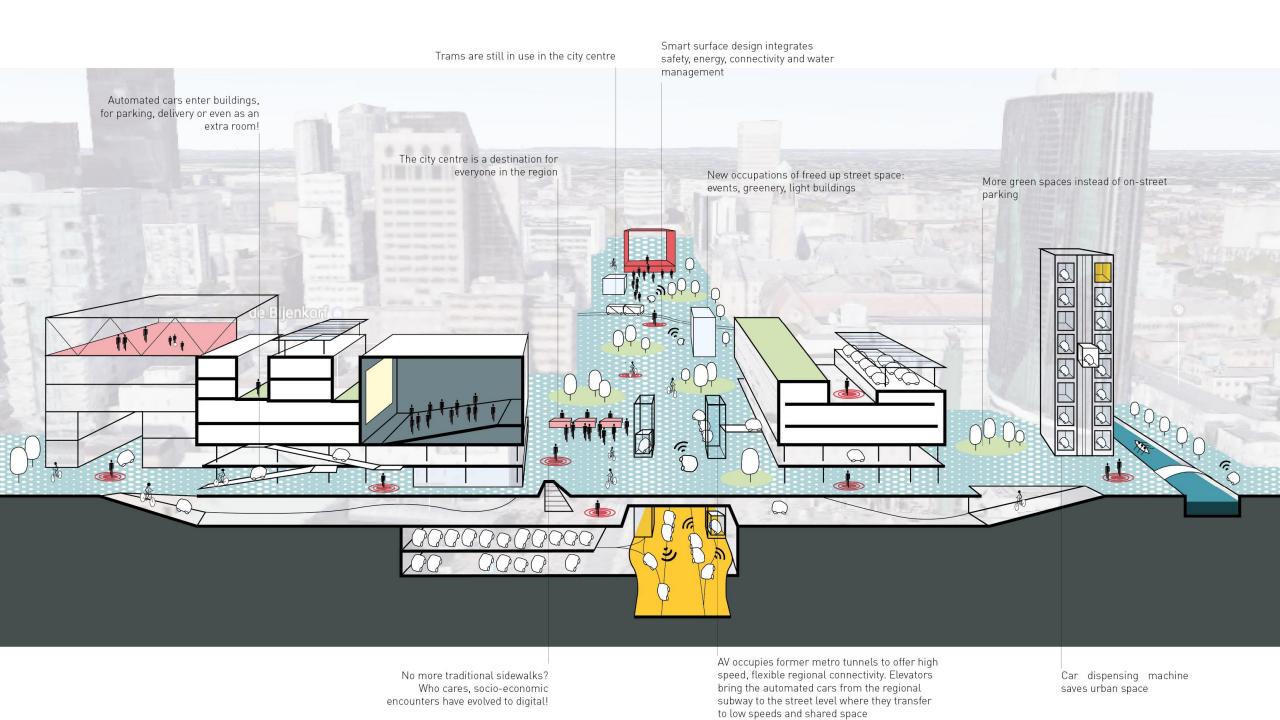


S4
Infinite Randstad

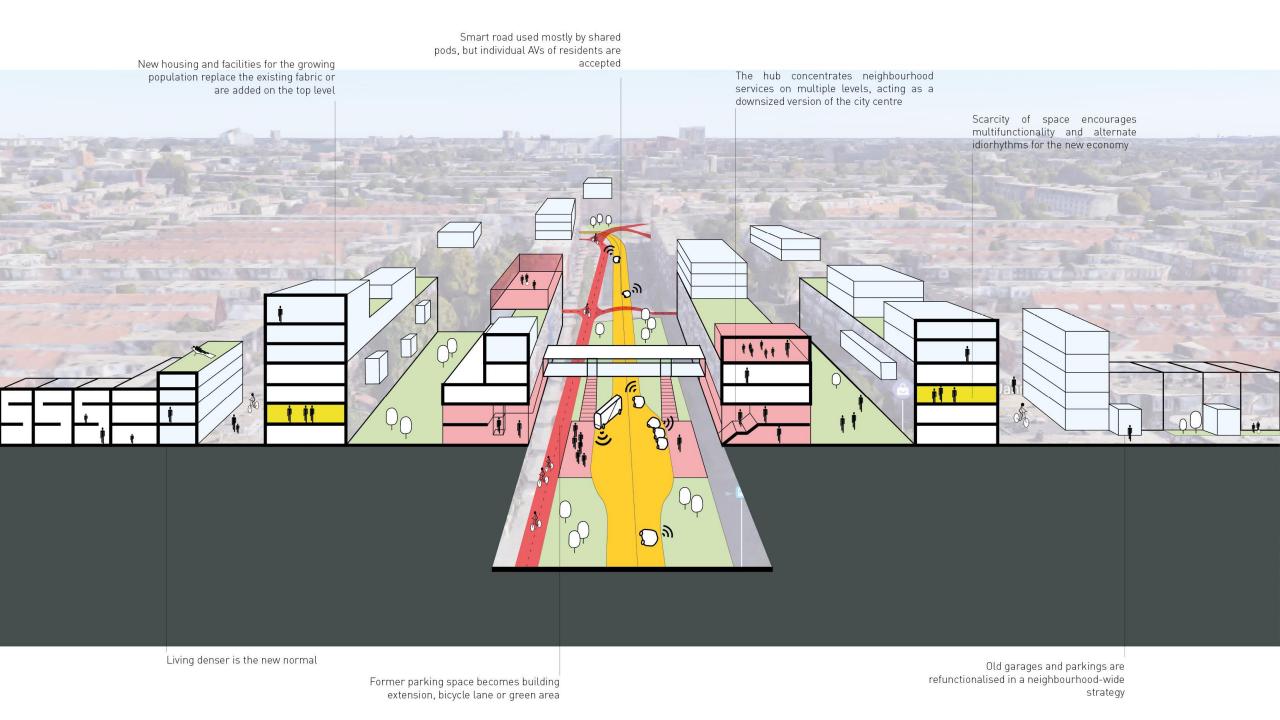


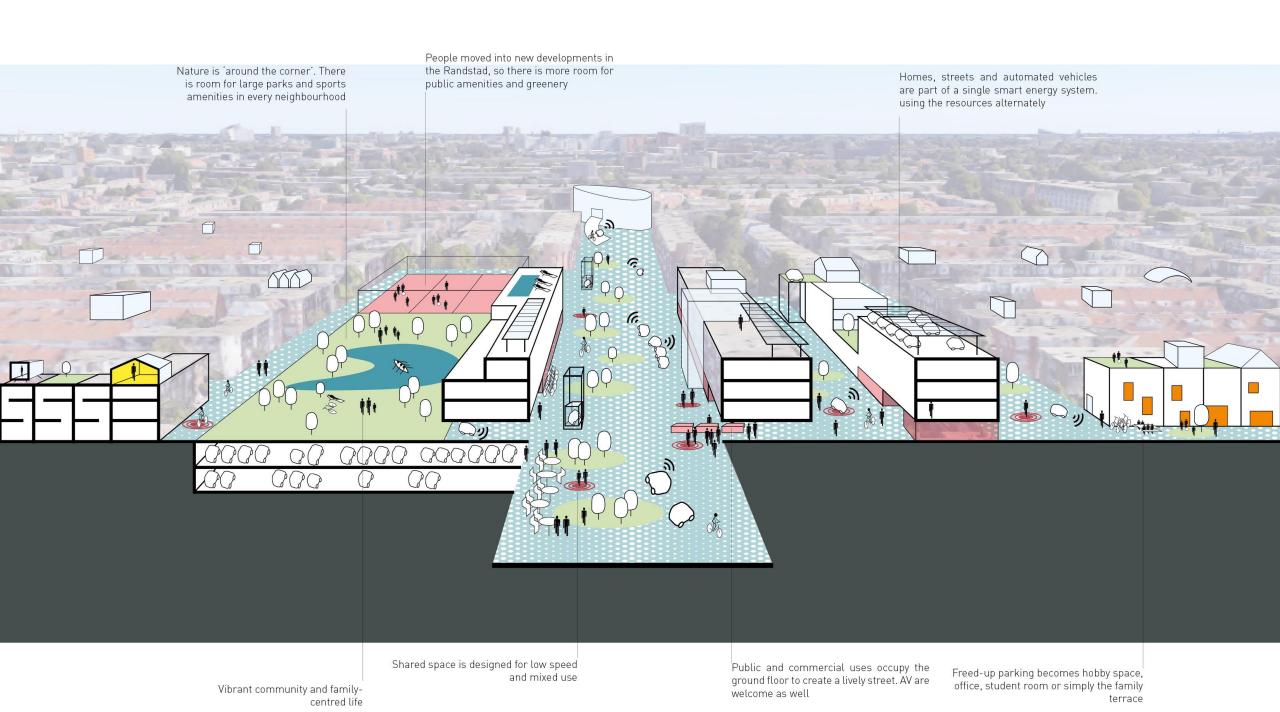




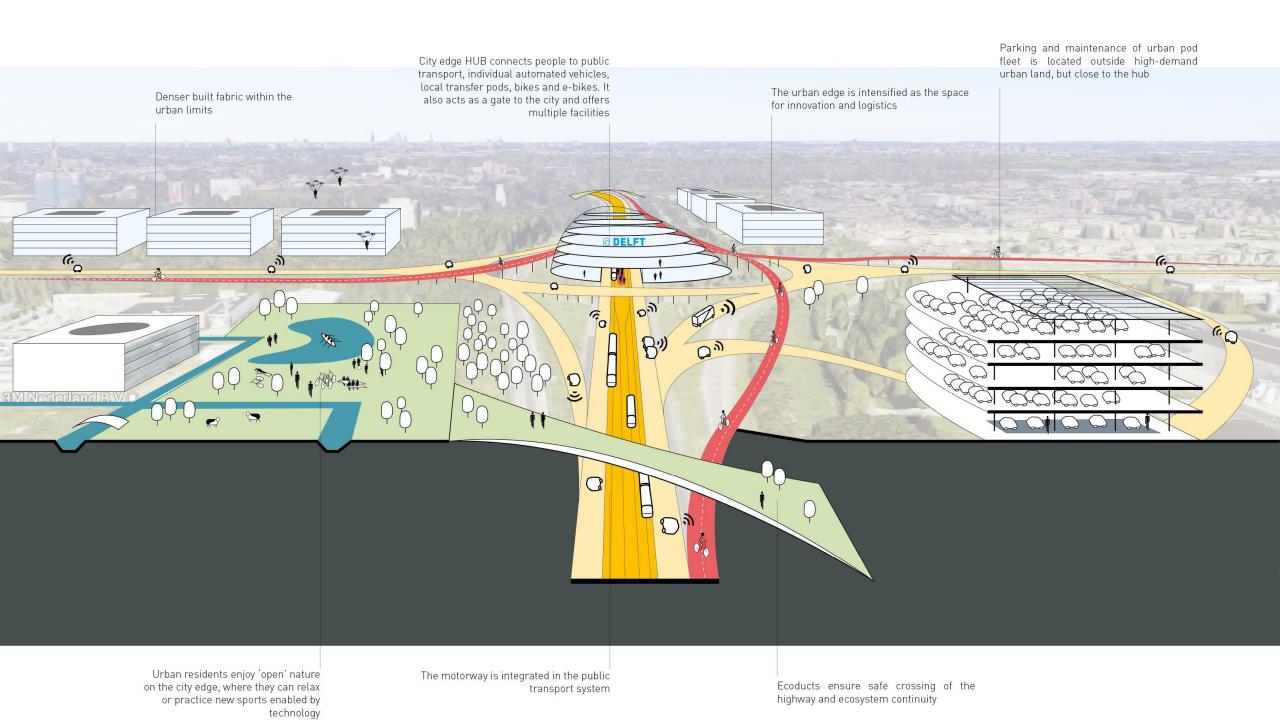


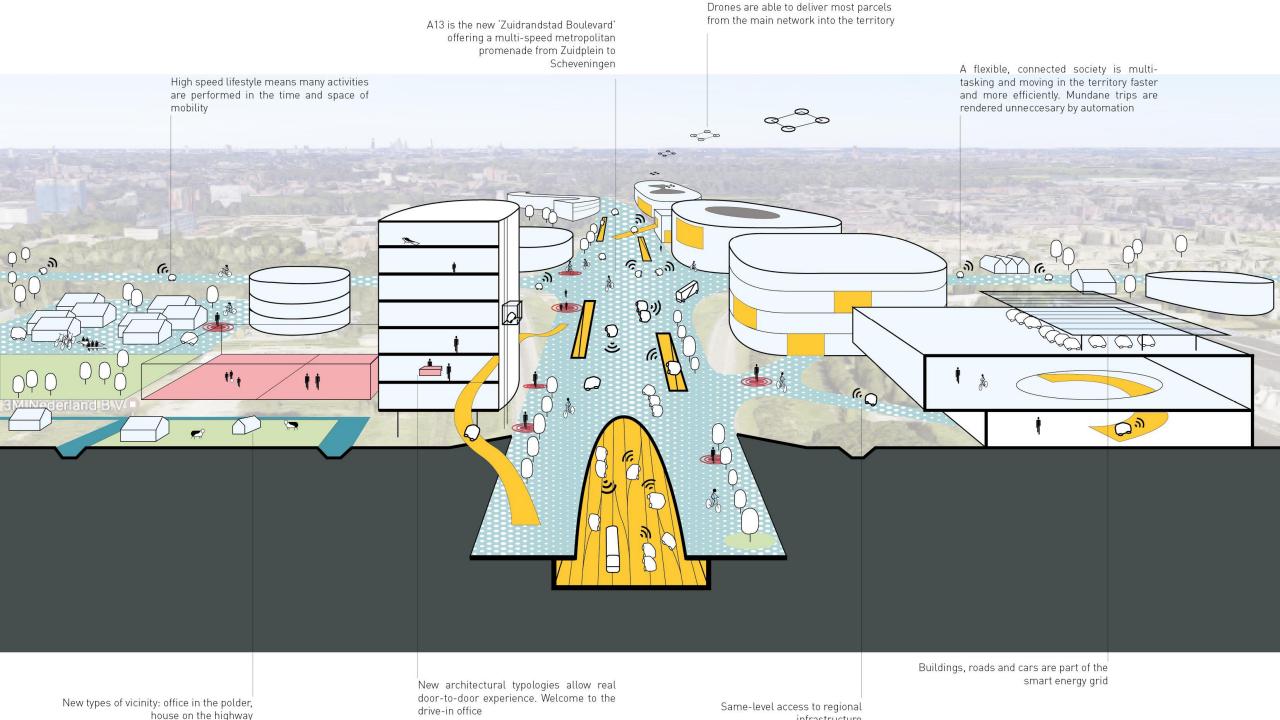






Scenario development. Clockwork Utopia and Infinite Randstad Urban edge Delft





Reflection

How can we assess the impact of automated vehicles on urban liveability through instruments specific to urbanism? Liveability definitions Technology **Driving** Automated forces vehicles Research, Scenario **Sections** design and construction Evaluation policy tasks Territory Transect MRDH analysis

Reflection

What directions of research, design and policy should be followed in the future in order to enhance urban liveability in the context of automated vehicle adoption?

RESEARCH

- Electric vehicles
- Synergies with other mobility trends
- Pedestrian & cyclist safety
- Societal acceptance of AV
- Urban sprawl impact

DESIGN

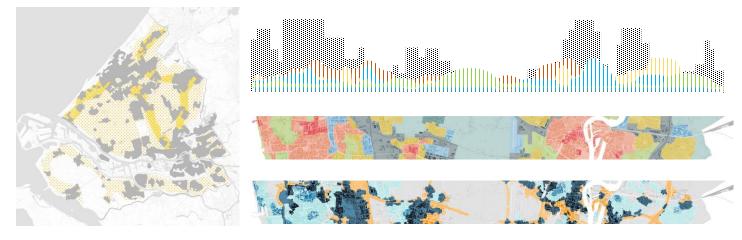
- Design of street profile
- Transfer hubs
- Accessibility
- Social and economic encounter in shared space
- New programs

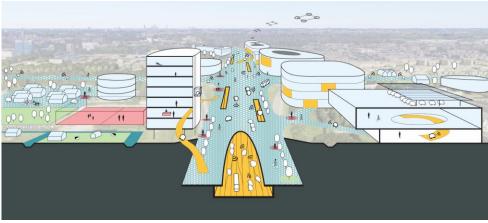
POLICY

- Encourage sharing and electric
- Limit city centre access
- Serve marginal areas
- Parking areas
- Tackle economic disruptions
- Encourage active mobility

Reflection. Methods

Are the tools specific to urbanism useful to assess the impact of automated vehicles on the urban environment?

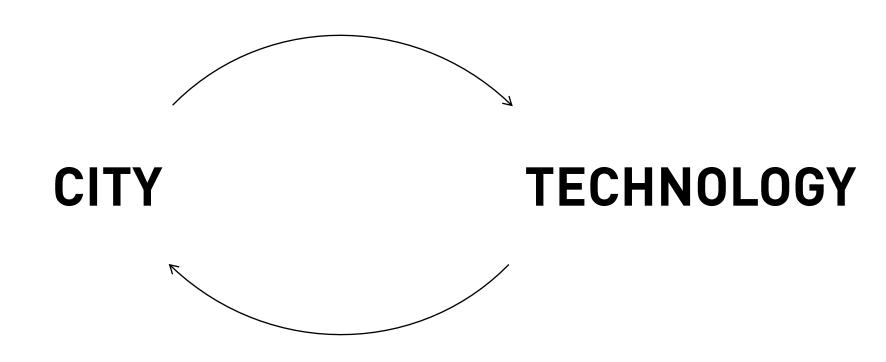


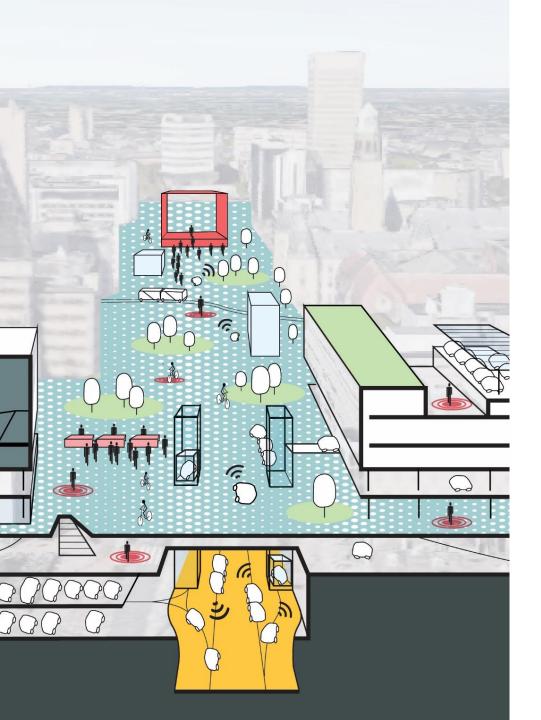


SCENARIO TRANSECT SECTION

Reflection. Forerunners not followers

How can the urbanist/architect be ahead of the times by imagining the living environments and lifestyles resulting from technological innovation?





Self-driven MRDH

A Method to Assess the Impact of Automated Vehicles on Urban Liveability in the Rotterdam The Hague Metropolitan Region

Vincent Babeș

European Post-Master in Urbanism / P5 presentation / 26 June 2017 Mentors: Alexander Wandl, Luisa Calabrese, Paola Pellegrini

