Enabling actuation and sensing in organs-on-chip using electroactive polymers

Motreuil-Ragot, Paul; Hunt, Andres; Kasi, Danesh; Brajon, Bruno; van den Maagdenberg, Arn M.J.M.; Orlova, Valeria; Mastrangeli, Max; Sarro, Lina

Publication date

2019

Document Version

Final published version

Citation (APA)

Motreuil-Ragot, P., Hunt, A., Kasi, D., Brajon, B., van den Maagdenberg, A. M. J. M., Orlova, V., Mastrangeli, M., & Sarro, L. (2019). *Enabling actuation and sensing in organs-on-chip using electroactive polymers*. Poster session presented at International MicroNanoConference 2019, Utrecht, Netherlands.

Important note

To cite this publication, please use the final published version (if applicable).
Please check the document version above.

Copyright

Other than for strictly personal use, it is not permitted to download, forward or distribute the text or part of it, without the consent of the author(s) and/or copyright holder(s), unless the work is under an open content license such as Creative Commons.

Takedown policy

Please contact us and provide details if you believe this document breaches copyrights.
We will remove access to the work immediately and investigate your claim.

Paul Motreuil-Ragot
PhD student
TU Delft

Scan the QR code to watch a video of vSMCs actuated using IPMC in real condition

Organ on chips (OoCs)

- OoCs make use of soft biocompatible substrates, fluid flow, periodic mechanical loading and other dynamic stimuli to help the cultured cell tissues experience an in vivo-like microenvironment [1]

Pneumatic

Pneumatic-based system are widely used, however:

- They are bulky, expensive and non user friendly method [2]
- Barely no sensing
- Non mass manufacturable and hardly scalable for industry

Electroactive

We use Ionic polymer metal composite (IPMC)[3] for the first time in OoC :

- Compact, cheap and easy to use
- Both actuation and real time sensing
- Scalable (clean room compatible)

Working principle

- The polymer backbone is doped with fixed anions, and we are using sodium cations naturally present in the OoC culture medium.

- In the **actuation mode** (top), the voltage applied between the electrodes induces a displacement of the moving cations and therefore the polymer.

- In the **sensing mode** (bottom), cells contraction deforms the IPMC substrate, triggering cation migration and causing a charge imbalance, measureable as a voltage difference at the electrodes.

Mechanical characterization

A square wave signal of 1 Hz frequency and 5 Vpp amplitude was used to drive the IPMC motion

The impulsive and manually induced displacement was recorded using the electronic control board

Proof of concept device

Gold electrode IPMC Clamp

Electronic board IPMC 12 Well plate

- IPSC Vascular smooth muscles (vSMC) cells have been successfully cultured and actuated for 2h30.

- Am calcein staining images shows no adverse effects on cells culture after actuation.

References

[1] U. Marx et al., "Biology-inspired microphysiological system approaches to solve the prediction dilemma of substance testing" *ALTEX*, 2016

[2] B. Zhang, M. Radisic, "Organ-on-a-chip devices advance to market", *Lab Chip*, 2017

[3] M. Shahinpoor, Y. Bar-Cohen, J. O. Simpson, J. Smith, "Ionic Polymer-Metal Composites (IPMCs) as Biomimetic Sensors, Actuators and Artificial Muscles: A Review," *Smart Materials and Structures*, 1998

Conclusion

- Actuation has been successfully performed for 2h30 with no side effects nor delamination of the human tissue
- 0.1 % strain has been achieved during the actuation mode, close to the strain experienced *in vivo* by vSMCs
- 0.72 V/mm sensitivity has been shown on the sensing mode
- Batch fabrication and downscaling will be targetted in the near future
- Actual sensing of the cells' contraction will be reserved for further work