Modelling of bed sediment composition changes at the lower shoreface of the Sand Motor

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Abstract

Large perturbations in the coastline, such as the 'Sand Motor' nourishment (~21 million m\textsuperscript{3}) at the Holland coast, can initiate considerable spatial and temporal changes in the median grain size ($D_{50}$) of the sea bed on the lower shoreface. The relevance of hydrodynamic conditions for the development of the heterogeneity in $D_{50}$ at large-scale nourishments was assessed with a numerical model (Delft3D), which required a validation against 2.5 years of $D_{50}$ measurements. A good representation of the observed spatial pattern of $D_{50}$ was obtained independent of a 2DH or 3D approach and initial condition for the $D_{50}$ of the bed. Five sediment size fractions and a multi-layer administration of the bed composition were used. The extent and magnitude of the coarsening of the bed is related to the velocity of the horizontal tide, while a far less pronounced coarsening takes place during energetic conditions (i.e. $H_m \geq 3$ m). Differential suspension behaviour between the size fractions, which are all mobilized at the bed, causes a preferential transport of fine sediment (in alongshore direction) away from the Sand Motor at the lower shoreface (i.e. seaward of MSL -6m). Storm conditions may induce a partial removal of the coarse top-layer due to mobilization of all of the size fractions and mixing with the relatively fine substrate material. Simulations also show that transport of the fine sand fraction extents to much deeper water than for the medium and coarse sand fractions. Models with multiple sediment fractions are therefore required for the assessment of environmental impacts of large-scale coastal structures or land reclamation's and sediment transport on the lower shoreface.

Keywords: Nourishment, Bed sediment, Sorting, Grain size, Numerical modelling

1. Introduction

Spatial heterogeneity of bed sediment composition is observed at many coasts around the world (Holland and Elmore, 2008), but seldom accounted for in morphological or environmental impact studies of coastal interventions (e.g. modelling of sand nourishments; Capobianco et al., 2002). Knowledge of the potential spatial variability of the bed sediment (i.e. grain size and grading) is however considered essential for the understanding of the ecological impact of large-scale coastal interventions. Firstly, bed composition changes affect the ecological habitats for benthic species.

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and fish (e.g. McLachlan, 1996; Knaapen et al., 2003). Small changes in the top-layer grain size can, for example, significantly affect the burrowing ability of juvenile plaice (Gibson and Robb, 1992). Secondly, long-term morphological changes can be affected by bed coarsening when preferential transport of finer sand fractions takes place at large-scale sand nourishments (Van Rijn, 2007b), which is especially relevant for the region outside the surf zone (Huisman et al., 2016).

Spatial heterogeneity of the bed composition of natural coasts is characterized by a fining of sediment grain size in the offshore direction with coarsest sediment being found in the swash zone (Inman, 1953; Somi, 1972; Lin and Zarillo, 1987; Pruszak, 1993; Horn, 1993; Stauble and Cialone, 1996; Kana et al., 2011). In the presence of sub-tidal bars the spatial pattern of the bed sediment composition can vary between different studies. Generally, coarser sediment is observed in the bar troughs and finer sediment on bar crests (Moutzouris et al., 1991; Kato and Yanagishima, 1995), but Van Straaten (1965) and Guillén and Hoekstra (1997) observed coarser material on the bar crests for the Dutch coast. Considerable spatial heterogeneity of the sediment grain size is also observed at rip-bar systems with coarser sediment in the rip-channels (MacMahan et al., 2005; Gallagher et al., 2011; Dong et al., 2015). Coarsening of the bed (change in median grain diameter $D_{50}$ of about +150 μm) as a result of alongshore transport processes was observed at a large-scale sand nourishment at the Dutch coast (‘The Sand Motor’; Huisman et al., 2016). This study also showed that the alongshore changes in $D_{50}$ are related to spatial variability in the hydrodynamic forcing conditions.

The impact of storm conditions at natural coasts typically consists of a coarsening of the sediment grain size. Most prominent coarsening of the median grain diameter ($D_{50}$ up to 100 μm coarser), during a storm event with offshore significant wave height of $H_{m0} = 4$ m, was observed in the swash zone (Stauble and Cialone, 1996). This coarsening gradually decreases in the offshore direction. Terwindt (1962) observed a quite uniform coarsening of ~30 μm from 2 to 6 m water depth at the coast of Katwijk (The Netherlands) after a moderate summer storm ($H_{m0}$ ~2m). Numerical modelling of cross-shore transport sorting during storms also shows coarsening of the nearshore zone and subsequent fining of the offshore sediment at the toe of the deposition profile (Reniers et al., 2013; Sirks, 2013; Broekema et al., 2016). Seasonal variability of the cross-shore distribution of the grain size, as observed by Medina et al. (1994), comprised nearshore bed composition coarsening in winter ($H_{m0,\text{winter}} \approx 1\text{m}$) and restoration to a finer bed composition in summer ($H_{m0,\text{summer}} \approx 1\text{m}$). The largest annual variability in the measured $D_{50}$ was observed in the swash zone (up to 200 μm) at mean sea level (MSL) which gradually decreased to a variability of ~20 μm at MSL ~8 m. Seasonal variability of the $D_{50}$ was, however, found to be almost negligible for a nourishment at the Dutch barrier island of Terschelling (Guillén and Hoekstra, 1996). Guillén and Hoekstra (1996) observed an ‘equilibrium distribution’ of the size fractions, which means that the cross-shore bed composition of each size fraction will be restored over time by the hydrodynamic processes to the natural equilibrium situation. An influence of the width of the littoral zone (which depends on the wave conditions) on the location of transitions in the cross-shore grading of the sediment was suggested by Guillén and Hoekstra (1997).

Spatial variability of the grain size (on cross-shore profiles or alongshore) is often the result of differences in the behaviour of sediment grain size fractions for the same hydrodynamic forcing conditions (e.g. for bi-modal sand in Richmond and Sallenger, 1984). Sorting processes at the scale of the sediment grain can induce sorting mechanisms of which settling, entrainment and transport sorting are considered most relevant (Slingerland and Smith, 1986). Sorting due to settling, for example, plays a role in sedimentary environments where fine grains are deposited over a much larger distance than the coarse grains (Baba and Komar, 1981). Entrainment sorting
is the result of differences in the suspension of sediment grain particles into the water column, which is affected by the size and weight of the particle (Komar, 1987) as well as the density of the grains (Steidtmann, 1982). Investigations on the critical limit for suspension of the sediment into the water column were made by Bagnold (1966) (and other researchers) who indicates that the 'initiation of suspension' is related to the shear velocity at the bed ($u_*$) and the fall velocity ($w_*)$ of the sediment particle (see also Van Rijn, 1993). The finer sediment, that is suspended higher up in the water column (Rouse, 1950), is typically advected over a longer distance by the currents. The availability of the size fractions in the bed is also of relevance for the transport sorting as it determines the (reference) concentrations. These sorting processes may act together and induce a 'preferred transport' of (fine) sediment size fractions at locations where substantial gradients in the hydrodynamic forcing conditions are present. Hiding and exposure mechanisms (i.e. hiding of fine grains and exposure of coarse grains: Egiazaroff, 1965; Ashida and Michiue, 1973), on the other hand, may reduce the preferential transport for conditions which are at (or very close to) the critical shear stress for mobility of the sediment mixture. The individual sediment size fractions in the sand mixture (in unilater flows) are then expected to behave similarly as they are mobilized at the same critical shear stress (Wilcock, 1993). Conditions in the marine environment are, however, typically above the mobility threshold and closer to the critical limit for initiation of suspension as a result of wave stirring (e.g. Holland coast; Huisman et al., 2016).

The modeling of changes in bed sediment composition can be performed either with data-driven models or numerical models. Data driven models use observed knowledge on the sediment distribution at the considered coast to derive the transport processes and/or predict future changes in bed composition. For example, Guillén and Hoekstra (1996) introduced the concept of an equilibrium cross-shore distribution of sediment size fractions for a beach at Terschelling (The Netherlands). Any change to the cross-shore distribution of a size fraction will result in a re-distribution of sediment until the equilibrium cross-shore distribution is restored (Guillén and Hoekstra, 1996). McLaren and Bowler (1985) proposed a method to track the transport direction of (graded) sediment on the basis of spatial differences in the sediment grading. The derived properties of the grading (i.e. mean size, standard deviation and skewness) change in a logical way along the transport path. Other studies, however, suggest that only a better sorting provides a consistent proxy for the pathways of the sediment (Gao and Collins, 1992; Musselink, 1992).

Numerical models (e.g. Delft3D; Lesser et al., 2004) are more suitable than data-driven models for investigating situations where a local equilibrium is not available. Sediment transport rates and bed composition changes are computed per sediment size fraction on the basis of the forcing conditions in the numerical models (Van Rijn, 2007b). Typically an administration of bed composition changes is applied for a discrete number of layers of the bed and an active layer concept (Ashida and Michiue, 1973; Ribberink, 1987). The capability of numerical modelling of sediment transport with multiple size fractions was shown, for example, by Van Rijn (1997) for cross-shore sorting during storms. Furthermore, numerical modelling of sediment sorting was compared to field and laboratory experiments for a river bifurcation in the Netherlands (Slooff and Mosselman, 2012) and detailed sorting at river dunes (Blon and Parker, 2004). Even the generation of river deltas was modelled by Geelense et al. (2011) who found that models could reproduce the typical plan-form shapes of river deltas which depends both on the supply of sediment and local hydrodynamics. Applications of numerical modelling of the redistribution of non-uniform sediment are, however, missing for sand nourishments at natural coast where a large influence of alongshore redistribution of sediment can be expected.
The objective of this work is to assess the relevance of hydrodynamic conditions for the development of heterogeneity in $D_{50}$ just outside the surfzone of a large-scale nourishment. This required a validation of the numerical model Delft3D against observed spatial and temporal changes in $D_{50}$ over a period of 2.5 years after construction of the large-scale 'Sand Motor' nourishment (Stive et al., 2013) to allow the investigation of underlying processes. Simplified hydrodynamic conditions were then used in the model to exemplify the influence of individual conditions.

2. Study Area

The study area is located between Monster and Kijkduin on the southern part of the Holland coast (the Netherlands). A large-scale sand nourishment referred to as the 'Sand Motor' was constructed here from April to June 2011 (~21.5 million m³; Stive et al., 2013). The planform design of the Sand Motor comprised of a hook-shape with a dune lake and open lagoon on the landward side (Figure 1) with an alongshore extent of about 2.5 km and a cross-shore width of about 1 km at the waterline. The foot of the nourishment attaches to the natural bed at a depth of about 10 m.

![Figure 1: Aerial photograph of the Sand Motor after completion (September 2011). Note the clouds of fine-grained material moving to the North. Picture courtesy of Rijkswaterstaat / Joop van Houdt](image)

Bathymetric changes after construction of the Sand Motor were monitored at 1 to 3 month intervals. In the first period after completion a large morphological response of the Sand Motor was observed (de Schipper et al., 2016), as about 1.8 million m³ of sand was spread alongshore. The initial blunt shape was reformed in a smooth planform shape (see Figure 2). The nearshore bathymetry at the Sand Motor is characterized either by sections with a longshore uniform bar-trough system or transverse bars (Rutten et al., 2017).
The Holland coast wave climate is characterized by wind waves which originate either from the South-West (i.e. dominant wind direction) or the North-West (i.e. direction with largest fetch length). The average significant wave height \( H_{m0} \) is about 1 m in summer and 1.7 m in winter (Wijnberg, 2002) with typical winter storms with wave heights \( H_{m0} \) of 4 to 5 m and a wave period of about 10 seconds (Sembiring et al., 2015). The severest storms originate from the North-West and coincide with a storm surge of 0.5 to 2 m. Offshore wave data are available at an offshore platform (‘Europlatform’) at 32 m water depth. The horizontal tide is asymmetric with largest flow velocities towards the North during flood (\(-0.7 \) m/s) and a longer period with ebb-flow in southern direction (\(\sim0.5 \) m/s; Wijnberg, 2002). The tidal wave at this part of the North Sea is a progressive wave with largest flood velocities occurring just before high water. Tidal flow velocities at the Sand Motor are enhanced as a result of contraction of the flow (Radermacher et al., 2017). Mean bed shear stresses as a result of currents and waves \( (\tau_{bw}) \) in the nearshore region of the Holland coast typically range from 0.1 to 10 \( N/m^2 \) (Huisman et al., 2016) which is an order of magnitude larger than the critical threshold for mobilization of the grains \( (\tau_{crit} \text{ of about } 0.04 N/m^2 \text{ for sand with a } D_{50} \text{ of } 300 \mu m) \). The shear stresses in deeper water may, however, be insufficient to fully suspend all sediment grain size fractions in the water column during normal conditions (i.e. less than 0.4 \( N/m^2 \) for 300 \( \mu m \) sand; Van Rijn, 1993).

Sediment sampling at the Sand Motor nourishment revealed large spatial heterogeneity of the \( D_{50} \) which developed after construction (Huisman et al., 2016). Sediment data at the Sand Motor were collected prior, during and (half)yearly after construction of the Sand Motor over a timeframe of 4 years (see Figure 3). Surfzone sediment samples were collected with a Van Veen grab and dry beach samples from land. The Van Veen grab sampler had a radius of about 15 cm and collects sediment from the top 5 to 10 cm of the bed. Typically, about 5 to 12 samples were taken for each transect between MSL-1m and MSL-10m and a few samples on the dry beach. A special survey with short-term (bi-weekly) changes of the bed composition was performed in October 2014.
As detailed in Huisman et al. (2016), the situation before construction of the Sand Motor (T0) was characterized by medium sand at the waterline (D$_{50}$ of 300 to 400 µm) which gradually fines in seaward direction to a D$_{50}$ of about 200 µm at MSL -7m and deeper (Van Straaten, 1965; see T0 situation in Figure 3). Dry beach and dune sediment generally consists of medium sand (200 to 300 µm; Kohlsiek, 1984). Nourished sediment (T1) was relatively uniform and well mixed with an average D$_{50}$ of 278 µm. The situation after construction of the Sand Motor (especially from the T3 survey and onwards) is characterized by significant coarsening of the bed sediment at the exposed part of the Sand Motor (~150 µm) and fining of the bed sediment just North and South of the Sand Motor (up to ~50 µm; Figure 3). A narrower grain size distribution was observed at the Sand Motor with a standard deviation (SD) of 0.4 to 0.6 after construction while the reference situation and nourished sediment were moderately well sorted (i.e. SD ranging from ~0.6 to 0.8). A band with finer sediment was observed in the T2 survey between MSL -4m and MSL -8m, which aligns with observed cross-shore distributions of the D$_{50}$ after a storm (Broekema et al., 2016). The T2 survey is, however, left out of consideration in this research as 1) the main focus is on long-term large-scale patterns of the D$_{50}$ and 2) as there is uncertainty on the quality of the measured D$_{50}$ in deeper water for this survey. The D$_{50}$ in deeper water (far outside the region of influence of the Sand Motor) coarsened much more in the T2 survey (i.e. 50 to 200 µm coarser) than is expected based on understanding of the system, other field investigations or literature. Note that this research uses kilometer marks to describe cross-shore profile sections at the Center of the Sand Motor Peninsula (km 7), Northern flank (km 8) and North of the Sand Motor (km 9).

3. Methodology

The evolution of the bed composition at the Sand Motor was investigated with the aid of the numerical model Delft3D (Lesser et al., 2004). A 2.5 year hindcast of the bed sediment compo-
sition changes at the Sand Motor (with a focus on $D_{50}$) was made, which was validated against observed $D_{50}$ from sediment sampling surveys at the Sand Motor (Huisman et al., 2016). The computed bed composition changes over the hindcast period were used to provide insight in the transport rates for each of the sediment size fractions and vertical grading of the bed. The relevance of the hydrodynamic forcing conditions (i.e. tide and waves) for the development of heterogeneity in the $D_{50}$ was then further investigated in models with simplified hydrodynamic conditions.

**Numerical model setup**

The Delft3D model (Lesser et al., 2004) uses the shallow water equations for 2DH and 3D computations of the flow and a wave energy transport model (SWAN) for the wave transformation towards the shore (Booij et al., 1999). The curvi-linear grid covers the southern section of the Holland coast (9 km in alongshore direction and 4 km in cross-shore direction) with a resolution of about 34m x 17m near to the Sand Motor (Figure 4). The initial Sand Motor bathymetry, as measured directly after construction of the Sand Motor on 3 August 2011, was used as a starting point for the numerical models. Both 2DH and 3D modelling approaches were applied (with 12 vertical layers for the 3D model). Measurements from a wave bouy and two ADCP stations were available for validation of the modelled hydrodynamics.
Flow boundary conditions were derived from the CoSMoS model (Sembiring et al., 2015; Barnard et al., 2014) which provides continuous forecasts of the tidal currents and water levels in the North Sea. The water level boundary condition was applied at the seaward boundary of the model, while tidal currents were included as a water level gradient (i.e. Neumann type boundary) at the lateral boundaries. Offshore wave boundary conditions consisted of a full time-series of wave conditions at the 'Europlatform' measurement station from August 2011 to February 2014 (Figure 4). The roller model (Roelvink, 1993) was applied to distribute turbulence of the breaking waves over the surfzone.
Sediment transport was computed for predefined discrete size fractions (Van Rijn, 2007b) with the Transpor2004 formulation (Van Rijn et al., 2004; Van Rijn, 2007a). The reference concentrations of each of the size fractions are scaled according to their relative occurrence to make the transport rates of sediment with multiple size fractions comparable to uniform sediment (Van Rijn et al., 2004). The single fraction formulation performed well in the morphological hindcast of the first year development of the Sand Motor (Luijendijk et al., 2017). The morphological time scale in the model is four times the hydrodynamic time scale (Ranasinghe et al., 2011). The introduced discrepancy between the phase of the tide and the waves was found to have no significant influence on the long-term sorting pattern from a half-year test simulations with a morphological factor of one. Transport rates were calibrated (for all simulations) to 50% of the default uncalibrated value, which provided a good hindcast of the morphological changes at the Sand Motor for the model with a single sediment fraction (i.e. using the same settings as Luijendijk et al., 2017). This calibration parameter is within the typical expected range of the TRANSPOR2004 model as specified in the implementation manual (Van Rijn et al., 2004) and not much lower than the 0.6 which was (among other calibration factors) applied by Grunnet et al. (2005) for a morphological hindcast at Terschelling (The Netherlands). Additional to the overall calibration of the transport, also the transport due to wave skewness and asymmetry has to be adjusted in 2DH models in order to balance the cross-shore transport. The suspended transport due to waves (SUSW) of the 2DH model was set at 20% of the default value. The main reason for the strong reduction of this parameter is that the offshore-directed undertow (which normally balances out the onshore directed transport) cannot be represented in a 2DH model. This ratio of the SUSW parameter is in line with literature suggesting a value of 0% to 50% for 2DH models (Van Rijn et al., 2004; Giardino et al., 2011). It is noted that the SUSW calibration parameter hardly affects the alongshore transport rates.

A multi-layer approach with an active layer was used to administrate the bed composition changes (Ashida and Mochine, 1973; Ribberink, 1987; Sloff and Mosselman, 2012), which means that the contribution of each of the sediment size fractions is administrated per layer and per grid cell. A ’transport layer’ is present at the top of the bed for which the bed composition is adjusted over time as a result of erosion and/or accretion of the modelled sediment size fractions (Figure 5).

![Multi-layer administration within Delft3D](image)
The transport layer moves up and down with the bed when erosion or sedimentation takes place (i.e., with fixed thickness). During accretive situations the transport layer moves upward, which means that 1) newly accreted sediment is mixed proportionally with the existing material in the transport layer and 2) a representative part of the sediment of the transport layer is added to the layer underneath the transport layer (referred to as the 'exchange layer'). Analogously, sediment from the exchange layer is moved back to the transport layer when erosion takes place. The exchange layer has a variable thickness since its upper interface moves with the active layer, while layers below the exchange layer (referred to as 'underlayers') are vertically fixed. The vertical fixation of the underlayers prevents numerical diffusion of sediment into the substrate as a result of (temporary) changes in the morphology of the bed. A description of the mass balance for each sediment size fraction (Slooff and Mosselman, 2012) reads as follows:

\[
\rho_s (1 - \epsilon) \left( \frac{\partial (p_i \delta \lambda)}{\partial t} + p_i (z_0) \frac{\partial z_0}{\partial t} \right) + \frac{\partial q_{xzi}}{\partial x} + \frac{\partial q_{yzi}}{\partial y} = 0
\]

(1)

in which the level of the substrate below the considered layer is denoted as \( z_0 \) and the thickness of the layer as \( \delta \lambda \). The top level of the considered layer is \( z_0 + \delta \lambda \). The proportion of sediment of size fraction \( i \) at a layer is denoted as \( p_i \) which is taken equal to the proportion in the active layer \((p_i,0)\) when sedimentation occurs and equal to the proportion of the layer below the considered layer \((p_i(z))\) during erosion. \( q_{xzi} \) and \( q_{yzi} \) are mass sediment transport components per unit width for fraction \( i \) in the \( x \) and \( y \) direction, which is per definition zero for the exchange layer and underlayers. \( \rho_s \) is the density of the sediment and \( t \) is time.

A thickness of the active layer of 0.1 m was applied in the models, as this is considered the zone which is mixed by the waves (see also Slooff et al., 2001). It is noted, that the actual thickness of the top layer has an effect on the rate of initial \( D_{50} \) changes, but had only a small impact on overall \( D_{50} \) after a few years. Twenty underlayers with a thickness of 0.5 m were used in the models to represent the substrate material.

Model run configurations

Hindcast models were set up for the period from August 2011 to February 2014 to assess the performance of a Delft3D model in hindcasting bed sediment composition changes at the Sand Motor. The hindcast models differ with respect to the number of vertical layers in the water column (2DH or 3D) and initial bed composition (Table 1), while the same grid was used for each of the models (34m x 17m). Furthermore, a reference simulation was made with only 1 sediment fraction of 278 \( \mu m \) sand (H0).

<table>
<thead>
<tr>
<th>Run</th>
<th>Vertical layers</th>
<th>Bathymetry*1</th>
<th>Transp. formula</th>
<th>Nr. Initial bed</th>
<th>Tide &amp; Waves</th>
</tr>
</thead>
<tbody>
<tr>
<td>H0</td>
<td>2DH</td>
<td>ZM2011</td>
<td>Tr2004</td>
<td>1</td>
<td>uniform</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Time-series (Aug 2011-Feb 2014)</td>
</tr>
<tr>
<td>H1</td>
<td>2DH</td>
<td>ZM2011</td>
<td>Tr2004</td>
<td>5</td>
<td>uniform</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Time-series (Aug 2011-Feb 2014)</td>
</tr>
<tr>
<td>H2</td>
<td>3D (12)</td>
<td>ZM2011</td>
<td>Tr2004</td>
<td>5</td>
<td>uniform</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Time-series (Aug 2011-Feb 2014)</td>
</tr>
<tr>
<td>H3</td>
<td>3D (12)</td>
<td>ZM2011</td>
<td>Tr2004</td>
<td>5</td>
<td>inbed</td>
</tr>
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<td></td>
<td></td>
<td></td>
<td></td>
<td>Time-series (Aug 2011-Feb 2014)</td>
</tr>
</tbody>
</table>

*1 ZM2011 refers to the Sand Motor bathymetry of August 2011.

The models with a 'uniform' initial bed composition for the whole domain applied a \( D_{50} \) of 278 \( \mu m \) (similar to the Sand Motor sand). The grain size distribution at the Sand Motor was classified
in five size fractions according to Van der Zwaag (2014) (Table 2). The spatially varying initial bed composition (‘imbed’) consisted of the aforementioned sand mixture at the Sand Motor (i.e. \(D_{50}\) of 278 \(\mu\)m) and a natural fines of the sediment in the offshore direction at the adjacent coast (Figure 6). The applied 10th and 90th weight percentile diameter of the sand were respectively a factor 2.2x smaller or larger than the \(D_{50}\) which was similar to the ratio of the observed transect averaged \(D_{50}\), \(D_{10}\) and \(D_{90}\). The sediment at the Sand Motor was specified as separate sediment fractions from those at the adjacent coast, with the aim of discerning the behaviour of the Sand Motor sand from that of the rest of the coast.

![Graph of median grain diameter vs. depth at transect 6 and 7.](image)

**Figure 6:** Cross-shore distribution of the measured \(D_{50}\) at the Sand Motor (T0 survey) and modelled initial bed

<table>
<thead>
<tr>
<th>Class</th>
<th>Lower limit [(\mu)m]</th>
<th>Median [(\mu)m]</th>
<th>Upper limit [(\mu)m]</th>
<th>Mass percentage</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>63</td>
<td>107</td>
<td>150</td>
<td>9.5%</td>
</tr>
<tr>
<td>2</td>
<td>150</td>
<td>181</td>
<td>225</td>
<td>23%</td>
</tr>
<tr>
<td>3</td>
<td>225</td>
<td>256</td>
<td>300</td>
<td>24%</td>
</tr>
<tr>
<td>4</td>
<td>300</td>
<td>363</td>
<td>425</td>
<td>29%</td>
</tr>
<tr>
<td>5</td>
<td>425</td>
<td>513</td>
<td>1180</td>
<td>15%</td>
</tr>
</tbody>
</table>

Table 2: Classification of the sediment distribution at the Sand Motor into five sediment size fractions

The findings in the 3D model hindcast \((H2)\), which was envisaged to provide a good representation of alongshore and cross-shore transport processes, were substantiated more with model configurations with simplified hydrodynamics (i.e. adjusted tide or waves), which aimed at isolating the relative importance of hydrodynamic forcing conditions (i.e. tide, normal waves and storm conditions) on the development of spatial heterogeneity in the \(D_{50}\). Besides an average climate condition with \(H_{m0}\) of 1 m from 310°N (W1) also variations of climate conditions were made with a different wave height (\(H_{m0}\) of 3 m wave height, W2) or with a sequence of a storm condition (\(H_{m0}\) of 3 m) after a moderate condition (\(H_{m0}\) of 1 m; W3). Also the sensitivity of the \(D_{50}\) changes for the wave direction (±30°) was evaluated (W4 and W5). Tidal conditions were investigated by simulating a situation without tide (C1), with only the tide (C2) or with a reduced or enhanced tidal velocity (at 80% or 120% of the actual tide; C3 and C4). Additionally, also the influence of a smaller seaward protrusion (of 200 or 400 m) of the nourishment bathymetry was modelled (B1 and B2). It is noted that the storm conditions (\(H_{m0}\) of 3 m) were
presented after 4 days, which is a realistic persistence for a year with relatively severe conditions along the Dutch coast.

**Methods for quantifying model performance**

The actual performance of the hindcast models was quantified on the basis of an inter-comparison of the modelled and observed $D_{50}$ (Huisman et al., 2016). Both the representation of the along-shore heterogeneity of the $D_{50}$ and the cross-shore distribution of the $D_{50}$ was evaluated. A weighted average of the median grain size per cross-shore transect ($D_{50TR}$) was computed, both for the field surveys and the models, with the aim of comparing the along-shore heterogeneity of the $D_{50}$. This $D_{50TR}$ is defined as:

$$D_{50TR} = \frac{1}{L} \sum_{i=1}^{n} D_{50i} \Delta x_i$$

The contribution of each sample (landward of the MSL -10m contour) was computed by multiplying the median grain size of the sample ($D_{50i}$) with the representative cross-shore extent ($\Delta x_i$, i.e. half of distance to neighboring sample). The summed $D_{50}$ contribution of each sample was divided by the length of the considered transect ($L$). The agreement of the actual modelled and observed $D_{50TR}$ was quantified by means of the squared correlation coefficient ($R^2$). Uncertainty in $D_{50TR}$ as a result of the sampling methodology was estimated at $\sim 11\ \mu m$ (Huisman et al., 2016), while uncertainty in $D_{50}$ of individual samples estimated at $30\ \mu m$. Short-term temporal variability for moderate and storm conditions even amounts to a possible $40$ to $80\ \mu m$ difference for individual samples.

### 4. Hindcast of morphology and bed composition

**Hydrodynamics and Morphology**

Modelled currents and waves for the 2011-2012 winter period matched well with observations at local ADCP stations and a wave buoy (see Appendix A and Luijendijk et al., 2017). The patterns of erosion and sedimentation over the first two years after construction of the Sand Motor (from August 2011 till August 2013) were very similar, showing net erosion at the peninsula of the Sand Motor and accretion at the adjacent coast (Figure 7).
Figure 7: Bathymetric changes in the first two years after construction of the Sand Motor. Panel a shows the volume of erosion at the peninsula (i.e. within red dashed line in panel b), while panels b to f respectively show the surveyed and modelled bathymetric changes (from Aug 2011 to Aug 2013). Note that the MSL to MSL -12m contours for the surveyed and modelled bathymetries of August 2013 are presented respectively as dashed and continuous lines.

The erosion rates in a control area of ~2 km² at the Sand Motor peninsula (Figure 7b) were almost identical to the observed changes (see erosion volumes in Figure 7a). The modelled erosion volumes also aligned well with the observed erosion of about 1.8 million m³ by de Schipper et al. (2016) in the first year after construction of the Sand Motor. Models with multiple sediment fractions provided similar erosion rates as the model with a single sediment fraction (D₅₀ of 278 μm). Reference is made to Luijendijk et al. (2017) for more detailed information on the morphological model performance of a single sediment fraction model.

The erosion and sedimentation patterns in the models (over the first two years) were also well represented in the models (Figure 7b to Figure 7f). The alongshore length of the region with erosion was very similar in the models and the survey, while the cross-shore distribution of the erosion was somewhat more gradual in the models. The most noticeable deviation concerned a seaward shift (of about 150 m) in the modelled location of the coastline on the northern flank of the Sand Motor (Figure 7), which can be seen from the difference between the modelled and surveyed depth contours (i.e. continuous and dashed grey lines). This dissimilarity between
the model and observed changes was slightly smaller in the simulations with multiple sediment fractions (compare panel c with panels d to f in Figure 7). An important notion from the sedimentation-erosion graphs is that most morphological change takes place in the nearshore (landward of MSL - 6m), while field observations of bed composition at the Sand Motor have shown largest \(D_{50}\) changes outside the surfzone (i.e. from MSL -6m in seaward direction; Huismans et al., 2016). Subsequently, the region of interest for studying the \(D_{50}\) changes is not the same as the region where most morphological change takes place.

Overall, the morphological performance of the models is considered adequate for an investigation of the redistribution of the sediment size fractions at the Sand Motor which is expected to depend on the large-scale bathymetric and hydrodynamic characteristics of the Sand Motor (e.g. cross-shore extent, wave transformation and tidal contraction).

**Transport rates**

Computed two-year averaged transport rates at the Sand Motor (Figure 8) showed positive transport gradients at the Sand Motor (i.e. erosive) and negative at the adjacent coast (deposition), which induced a transport away from the Sand Motor. The transport rates of the single and multi-fraction models were similar in the nearshore region (from waterline to MSL-6m; compare \(H0\) and \(H1\) in Figure 8), which is in line with the observed similarities in the computed morphological changes. However, the transport rates in deeper water were enhanced considerably in the multi-fraction models (\(H1\) to \(H3\)) as a result of the much larger mobility of the fine sediment size fractions compared to the average sediment grain size in the single-fraction model (\(H0\)). This holds especially for the 2DH model and to a lesser extent for the 3D model. The 3D model computes smaller sediment concentrations higher up in the profile (using the advection-diffusion equation) where the tidal currents act, while the depth-averaged current velocities in the 2DH and 3D models are very similar. Additionally, overall transport rates were enhanced in the model with the initial spatially varying bed composition (\(H3\)) which had more fine sand available in the bed.

![Transport rate](image)

Figure 8: Time-averaged total transport for different model approaches of runs \(H0\) to \(H3\) (i.e. 2DH or 3D, single or multi-fraction approach and initially uniform or spatial varying bed composition). Note that transport is plotted with a logarithmic scale to visualize also the areas with moderate or low transport rates.
Bed composition changes ($D_{50}$)

The computed bed composition ($D_{50}$) in the numerical models (H1 to H3 in Table 1) changed from a rather uniform initial $D_{50}$ to a situation with considerable spatial heterogeneity in the $D_{50}$ over a period of about 2.5 years (see time evolution of $D_{50}$ in Figure 9). The models show the development of a typical spatial pattern in the $D_{50}$ which is also observed in the measurements surveys (T2 to T5). This consisted of (1) an area with coarser sediment in front of the Sand Motor peninsula (from MSL -4 m to MSL -10 m), (2) a finer sediment composition just North and South of the Sand Motor and (3) a cross-shore variation in the sediment size with coarse sediment in the breaker zone and a fining of the sediment in the offshore direction. Computed 10th and 90th percentile grain size diameter ($D_{10}$ and $D_{90}$) showed similar patterns as the $D_{50}$.

![Figure 9: Development of spatial heterogeneity of the $D_{50}$ over the first 2.5 years after construction of the Sand Motor for the 2D, 3D and 3D-inbed models (H1, H2 and H3). Sediment survey data are shown as coloured markers. Depth contours are shown as continuous grey lines as a bed level in m MSL.](image)

Qualitatively the 3D models (i.e. H2 and H3) provided the best agreement with the $D_{50}$ patterns of the considered surveys (Figure 9), which represented both the magnitude of the coarsening of
the $D_{50}$ in front of the Sand Motor peninsula as well as the fining on the northern side of the Sand Motor. The model with 2D hydrodynamics ($H1$ in Figure 9) showed a less pronounced coarsening in front of the Sand Motor peninsula (MSL -4 m to MSL -12 m) than observed in the surveys (see February and October 2013). The initial bed composition was relevant for bed composition changes in deeper water (i.e. seaward of MSL -12 m at the Sand Motor and seaward of MSL -8 m at the adjacent coast).

The $D_{50}$ patterns of the considered 3D models were very similar, irrespective of the initial condition that was used for the $D_{50}$ of the bed (compare runs $H2$ and $H3$ in Figure 9). Consequently, the $D_{50}$ patterns are considered to be the result of the hydrodynamic forcing conditions which acted on the models over the 2.5 year modelling period and subsequent morphological changes rather than the initial bed condition. Differences between the modelled and observed $D_{50}$ patterns consisted of a relatively wide nearshore region with a coarse bed composition ($D_{50}$ of 350 to 400 μm) and a smaller proportion of finer sand (200 to 250 μm) at ~4 water depth at the northern side of the Sand Motor peninsula compared to the October 2013 and February 2014 surveys (Figure 9). This discrepancy is, however, expected to be related to the more seaward position of the modelled coastline on the northern flank of the Sand Motor compared to the observations (Figure 7) which results in a too seaward position of the surfzone with coarser $D_{50}$. A cross-shore shift of the modelled $D_{50}$ of the bed was therefore used for transects at the northern flank of the Sand Motor in order to obtain an evaluation of the modelled alongshore and cross-shore bed sediment composition changes rather than the morphological performance. For this purpose the difference in depth of the modelled and observed bathymetry was minimized (i.e. the average distance between depth contours from MSL to MSL -10m).

A comparison of modelled transect averaged median grain diameters ($D_{50TR}$) against observations showed that the aggregated model predictions were in good agreement with the data (comparison of $D_{50TR}$ for October 2013 survey in Figure 10a). The 2DH model ($H1$) reproduced a very similar trend of the $D_{50TR}$ with small scatter (i.e. highest $R^2$; Figure 10b), which suggests that 2DH processes provide a large contribution to the development of the alongshore $D_{50}$ heterogeneity which is in line with Huisman et al. (2016). The $D_{50TR}$ at the flanks of the Sand Motor deviated more for the 3D models ($H2$ and $H3$) as a result of the mentioned cross-shore shift in the morphology. The absolute $D_{50TR}$ (i.e. 1 on 1 line in the scatter plots) was, however, better represented in the 3D models ($H2$ and $H3$), which is shown from a closer resemblance of the 1 on 1 line of the average modelled and observed $D_{50TR}$ (Figure 10c and Figure 10d).
The cross-shore variation of the $D_{50}$ at three representative cross-shore transects (at the Peninsula, northern flank and North of the Sand Motor) was well represented in the models (i.e. $R^2$ of 0.4 to 0.9; Figure 11). Especially the 3D models resolved the details of the cross-shore distribution of the sediment, such as the small depression in $D_{50}$ (at $x=300$ m) at the Sand Motor Peninsula in the February 2013 survey and the small increase in $D_{50}$ North of the Sand Motor in the October 2013 survey. The 2DH models provided a more smoothed cross-shore distribution of the $D_{50}$. It is noted that a compensation was made for the bathymetric shift (of about 150 m) for the transect at the Northern flank of the Sand Motor, while transects at the Sand Motor Peninsula and North of the Sand Motor were shifted only marginally (i.e. typically ~40 m). Similar performance was observed for the February 2014 survey (with $R^2$ ranging from 0.4 to 0.9) and the August 2012 survey ($R^2$ of 0.3 to 0.6).
In summary, a 3D model is considered essential to represent both the alongshore and cross-shore patterns of the $D_{50}$ at a large-scale nourishment and surrounding coast, while 2DH models can still reasonably represent the large-scale pattern of the $D_{50}$ and the changes in the $D_{50}$ of the bed in the alongshore direction. Additionally, an accurate initial (spatial varying) bed composition can be relevant for a precise representation of the magnitude of the $D_{50 \text{TR}}$ changes, but is not essential for the $D_{50}$ in the nearshore (i.e. landward of MSL -8m).

**Vertical grading of the bed**

A closer look at the modelled $D_{50}$ at the Sand Motor reveals that bed composition changes predominantly take place in the top-layer of the bed (Figure 12; H2 model). This is especially the case at the central Sand Motor transect, where erosion induced a coarsening of the top-layer material which extents well beyond the initial perimeter of the Sand Motor (Figure 12a). Furthermore, a thin layer of fine sand is present in deeper water just North and South of the Sand Motor (seaward of MSL-10m). On the other hand, a layer of up to a few meters of sediment accumulated at the landward side of the cross-shore profile (Figure 12, panel b and c). The coarser fractions accumulated in the nearshore region ($D_{50} \sim 350 \mu m$) at the banks of the Sand Motor while the finer sediment size fractions are transported to deeper water (100 to 200 $\mu m$ sand at MSL -10m) and further away in alongshore direction from the Sand Motor peninsula. Furthermore, a sequence of upward coarsening developed at the spit of the Sand Motor (see panel b of Figure 12 at $x=3500$ m). Finer sand fractions were deposited here initially, while over time the finer sand was covered by coarser sediment size fractions when the morphological footprint of the Sand Motor became wider. A very similar grading of the bed was found for the
The origin and destination of the Sand Motor sediment (which was marked as a separate fraction) was tracked for each of the size fractions, which shows that the fine sediment size fractions are redistributed over a much larger area than the coarse size fractions (Figure 13). The finest sediment fraction (63 to 150 μm) was transported both inside and outside the surfzone (up to MSL-12m on the northern side of the Sand Motor), while the medium and coarse fractions are transported almost exclusively in the nearshore (about 800 m wide section on the northern and southern side of the Sand Motor). The fine-medium sand fraction (150 to 225 μm) had in-between behaviour and was still distributed partially by the tide. It is noted that the computed cross-shore width of the zone with transport of finer sediment size fractions is also in line with visual observations of fine sand plumes being expelled from the Sand Motor (Figure 1). The observed fining of the bed in deeper water North of the Sand Motor (Figure 12) is therefore expected to be also the result of the abundance of alongshore supply of the finer sand fractions (63 to 225 μm) from the Sand Motor body.
Figure 13: Time-averaged total transport for three sediment size fractions (H2: 3D model). Note that the transport is plotted with a logarithmic scale to visualize also the areas with moderate or low transport rates.

5. Relevance of hydrodynamic conditions

Model simulations with simplified hydrodynamics at the Sand Motor were used to identify the relevance of tide and waves for the generation of the coarsening at the Sand Motor and deposition regions at the adjacent coast. Simulations of storm and normal conditions (Figure 14a and Figure 14b) showed that coarsening of the $D_{50}$ in front of the Sand Motor developed especially during normal wave conditions (run W1), while a less extensive coarsening of the bed developed as a result of the storm wave conditions (run W2). It is noted that the duration of the conditions was scaled down to a realistic duration (respectively 64 and 4 days for the normal and storm wave condition). The precise duration of the simulations was, however, not of influence to the general finding that the storms contribute far less to the coarsening at the Sand Motor, because the size of the coarse patch was still relatively small after a storm condition of a month (i.e. run W2 compared to run W1). This is also shown by a simulation of a storm condition after a period with normal conditions (run W3) which resulted in a small fining of the bed seaward of MSL -8m. The storm conditions, on the other hand, had a clear impact on the deposition regions North and South of the Sand Motor. The magnitude of the fining and area of this region was considerably larger for situations with storm conditions, which is related to the larger supply of sediment that is eroded from the coast.
Figure 14: Modelled spatial pattern of $D_{50}$ as a result of normal or storm conditions for shore-normal and oblique wave incidence using tide at Sand Motor (i.e. same tide signal as hindcast). a) Run W1 with $H_{m0}=1m$; b) Run W2 with $H_{m0}=3m$, $dur=4$ days; c) Run W3 with $H_{m0}=3m$, $dur=2$ days after 64 days with $H_{m0}=1m$; d) Run W5 with $H_{m0}=3m$, $dur=4$ days from 280° N; e) Run W4 with $H_{m0}=1m$ from 280° N.

The direction of the incoming waves had only a small influence on the coarsening of the bed in front of the Sand Motor peninsula with slightly more coarsening for waves from the South-West (W4; Figure 14f). Wave direction did, however, affect the extent and magnitude of the deposition at the flanks of the Sand Motor during storm conditions (W5; Figure 14e), although the magnitude of the storm waves was still dominant.
Figure 15: Modelled spatial pattern of $D_{50}$ as a result of wave conditions ($H_{m0}=1\text{m}$, tide ($\Delta H \approx 1.5\text{m}$ and $U \approx 1\text{m/s}$) or adjustments of the bathymetry (affecting the tide and waves). a) Run C1 with only waves; b) Run C2 with only tide; c) Run C3 with 80% tidal velocities and moderate waves ($H_{m0}=1\text{m}$); d) Run C4 with 120% tidal velocities and moderate waves ($H_{m0}=1\text{m}$); e) Run B1 with 400 m landward shift of bathymetry ($H_{m0}=1\text{m}$ and 100% tide); f) Run B2 with 200 m landward shift ($H_{m0}=1\text{m}$ and 100% tide).

Simulations with either only waves or tide (run C1 and run C2) indicated that waves induce both a coarsening of the bed in the zone with the alongshore wave-driven current as well as patches of fine sand outside the surfzone on the flanks of the Sand Motor (Figure 15a), while tidal conditions were most relevant for the development of the coarsening of the bed outside the surfzone and induced a thinning of the bed in deeper water at the adjacent coast (Figure 15b). The relevance of the tide is even further substantiated from simulations with enhanced and reduced tidal velocities (C3 and C4 in Figure 15c and Figure 15d) which show that the extent and magnitude of the coarse patch in front of the Sand Motor as well as the deposition region at the adjacent coast scale with the tidal velocities. The actual configuration of the Sand Motor also plays a role since spatial variation in $D_{50}$ was hardly present for nourishment configurations with a (200 or 400 m) reduced cross-shore extent of the initial nourishment planform (B1 and B2 in Figure 15e and Figure 15f), which is related to a reduction of the contraction of the tide (i.e. less enhancement of tidal velocities) for these configurations.

In summary, a strong influence of the tidal velocities on the coarsening at the lower shoreface of the Sand Motor was found, which is the result of the enhanced forcing conditions due to the tidal contraction. It is expected that a preferential transport of fine sediment size fractions towards the adjacent coast is present which results in the coarsening of the top-layer of the bed (Huisman
The much smaller coarsening of the \( D_{50} \) for the bathymetries with a reduced seaward protrusion of the nourishment also suggests that the tidal contraction is an important cause for the coarsening of the \( D_{50} \) of the bed. Storm wave conditions on the other hand were found to reduce the coarsening of the bed at the Sand Motor as a result of the mobilization (and suspension) of all of the sediment size fractions, because these conditions remove part of the relatively coarse top layer. It is noted that deposited finer sand at the lower shoreface North and South of the Sand Motor did not necessarily only come from the coarsened region in front of the peninsula, but is occasionally also transported seaward from the nearshore zone during storm events with the undertow current. The extent of the deposition region at the flanks of the Sand Motor is therefore also determined by storm events.

6. Discussion

Our results show that the development of large-scale alongshore \( D_{50} \) heterogeneity at the Sand Motor can be reproduced well with the present numerical model. The observed pattern of coarsening of the \( D_{50} \) in front of the Sand Motor peninsula (in particular outside the surfzone) and fineing at the adjacent coast were reproduced in models with different initial conditions for the \( D_{50} \) of the bed, which suggests that the hydrodynamic processes are responsible for the changes in bed composition (Figure 9). The transect averaged median grain size \( D_{50,TR} \) (Figure 10) was modelled well with 2DH and 3D models \( (R^2 \) of 0.84 to 0.94), while the cross-shore distribution of the \( D_{50} \) and short-term variability during storms was reproduced best with a 3D modelling approach (Figure 11). The inclusion of the initial spatial varying bed composition provided a small improvement of the modelled alongshore heterogeneity of the \( D_{50} \) at the Sand Motor, but may be of larger relevance if the applied nourishment sand is very different from the natural sediment or for situations where morphology is strongly influenced by the bed sediment condition (e.g. tidal estuaries or river bed dynamics; Dastgheib et al., 2008; Blom and Parker, 2004). The differences between the modelled and observed \( D_{50} \) patterns were small and mainly present on the flanks of the Sand Motor, which was also the location where morphology of the bed was somewhat less well predicted (i.e. too small erosion on northern flank of Sand Motor). These secondary discrepancies may relate to a variety of processes, of which their relative importance is not yet known, such as 1) seaward directed rip-currents of the nearshore bar-rip system (Gallagher et al., 2011), 2) alongshore directed currents from the sides to the center of the Sand Motor due to large-scale tidal eddies (Radermacher et al., 2017) and 3) secondary currents as a result of the fresh water plume of the Rhine (Visser et al., 1994) which can generate an onshore current near the bed in intermediate water depth (i.e. from the lower shoreface up to about 6 m water depth; Meirelles et al., 2017).

Large-scale coarsening of the \( D_{50} \) of the bed just outside the surfzone (i.e. seaward of MSL -6m) of large-scale nourishments (such as the 'Sand Motor') is mainly the result of the tidal currents (Figure 14). The local contraction of the tide results in a more frequent exceedence of the critical bed shear stresses for suspension of especially the finer sediment size fractions (\( \gamma_{crit,sus} \); Van Rijn, 2007a) and subsequently also in a larger entrainment (Komar, 1987) and enhanced transport rate (Steidtmann, 1982) of these fine sand fractions. The difference in the suspension behaviour of the fine and coarse size fractions is expected to be largest during quiet and moderate wave conditions when the fine sand fraction is suspended while the coarse sand fraction is not, which is shown schematically in Figure 16 for a location on the lower shoreface of a large-scale nourishment (based on information on sediment concentrations from the Sand Motor model at 11 m water depth). A preferential transport of the finer sediment size fractions away from the Sand Motor is therefore present during normal conditions (Huismann et al., 2016), which removes
the fine sediment size fractions from the top-layer of the bed at the lower shoreface of the Sand Motor (Figure 12). It is noted that this process of coarsening by removal of the fine sediment fraction takes place even when the actual morphological changes are small. Over time the discrepancy in transport rates between the fine and coarse size fractions is expected to reduce, as concentrations of fine material in the bed will decrease. Eroded fine sediment from the lower shoreface of the Sand Motor is transported predominantly in northward direction to the adjacent coast (Figure 13; MSL -8m to MSL -12m), which is the result of the tidal asymmetry with larger north-going flood velocities, which explains the relatively large size of the fine sediment patch on the northern side of the Sand Motor (compared to the small fine sediment patch at the southern side). A nourishment with a smaller seaward protrusion (i.e. reduction of 25% or 50%) shows a less pronounced coarsening of the bed since the tidal contraction -which is considered the principal driver for the erosion of the bed- is reduced considerably. This suggests also that alongshore heterogeneity in $D_{50}$ is likely to develop at other coastal structures which induce a contraction of the tide (e.g. port structures).

![Figure 16: Schematic of the difference in suspension behaviour of fine and coarse sand fractions for moderate and storm conditions.](image)

Figure 16: Schematic of the difference in suspension behaviour of fine and coarse sand fractions for moderate and storm conditions. The modelled time-averaged sediment concentrations at a location seaward of Sand Motor peninsula (E71856m, N45337m, RD at 11 m water depth) of the 3D model (H2) are presented as circular markers for the coarse and fine sand fraction. Note that the typical range of bed shear stresses for normal and storm conditions is shown below the graph (see Huisman et al., 2016).

Extreme wave conditions reduce the magnitude and size of the coarse sediment patch at the lower shoreface of the Sand Motor (i.e. roughly from MSL -6m to MSL -12m), while waves would typically generate a coarsening of the $D_{50}$ in the surfzone (Terwindt, 1962; Stabiale and Cialone, 1996). Additionally, deposition of (relatively fine) sand from the nearshore region can take place at intermediate depths (i.e. between MSL -4m and -8m) during storm events (Reniers
et al., 2013; Broekema et al., 2016) which was also observed in the model, but cannot explain the
reduction of the size of the coarse sediment patch at the lower shoreface (i.e. in deeper water).
Instead, the fining of the $D_{50}$ at the lower shoreface during a storm is considered the result of
1) the mobilization of all the size fractions (i.e. when both fine and coarse sand fractions are
suspended in the water column; Figure 16) and 2) mixing of the coarse top-layer of the bed
with relatively fine substrate sediment. Consequently, both the fine sand as well as the coarse
top-layer are (partially) removed during a storm event. The small influence of the direction of
the waves (Figure 14) on the coarse sediment patch is considered an indication that especially
the stirring of the waves is of influence to the development of the coarse sediment patch. It is
noted that such a relative thinning of the $D_{50}$ of the lower shoreface during was also observed
during the storm of 22 October 2014 (Huisman et al., 2016).

The cross-shore extent of the region with transport of the finer sand fractions at a large-scale
nourishment is much wider than the cross-shore footprint of the coarser sand fractions (Figure 13).
This indicates that the medium and coarser sand fractions (>225 μm) are transported
mainly by the wave-driven alongshore current, while the finer sand fractions (65 to 225 μm)
are also mobilized by the tide. Consequently, the redistribution behaviour of the coarse and
fine sand fractions is different. Especially the sediment redistribution in the zone outside the
surfzone will be dominated by the behaviour of the finest sand fraction, which means that an
approach with a uniform sediment grain size will underestimate the transport rates in deeper
water. Theoretically, the alongshore transport of different size fractions (in deeper water) may
even be bi-directional (e.g. if the tide velocities are very a-symmetrical or when waves approach
from one side), similar to the observed bi-directional cross-shore transport of bi-modal sand at
Duck (Richmond and Sallenger, 1984). Modelling of the morphological changes in deeper water
therefore requires an approach with multiple sediment size fractions. The multi-fraction approach
is essential for the evaluation of the environmental impact of a large-scale nourishment (or port
construction). Models with uniform sediment can, however, still be applied well for situations
where all of the sediment size fractions are mobilized, such as the assessment of the lifetime
of sand nourishments for which the dominant processes take place in the nearshore region. Initial
erosion volumes at the Sand Motor could, for example, be hindcasted well with both the single
and multi-fraction models (Figure 7; Luijendijk et al., 2017).

7. Conclusions

The numerical model Delft3D was applied for a 2.5 year hindcast of bed sediment composition
($D_{50}$) at a large-scale sand nourishment (‘Sand Motor’). Our findings indicate that the observed
spatial pattern of the $D_{50}$ at the Sand Motor (i.e. coarsening of the bed at the lower shoreface
(i.e. outside the surfzone) in front of the peninsula and fining in deeper water just North and
South of the Sand Motor) was reproduced well with the Delft3D model independent of the starting
condition of the $D_{50}$ of the bed. Both 2DH and 3D models reproduce alongshore variation
in the $D_{50}$ at such a large-scale nourishment ($R^2$ of 0.84 to 0.94) while cross-shore variation is
represented only in a 3D model.

The development of the coarsening of the (top-layer of the) bed in front of a large-scale nourish-
ment (or other coastal structure) is attributed mainly to the contraction of the tide. The
locally enhanced current velocities result in a more frequent exceedence of the critical bed shear
stress for suspension of the sediment, which induces enhanced entrainment of especially the fine
sand fractions and subsequent preferential transport of the fine sand fraction to the adjacent
coast. Storm wave conditions, on the other hand, can induce a partial removal of the coarse top-layer of the bed on the lower shoreface (i.e. between MSL-6m and MSL-12m) in front of the large-scale nourishment. This is due to mobilization (and erosion) of both the coarse and fine sand fractions of the coarse top-layer and mixing with the relatively fine substrate sediment. Additionally, storm wave conditions induce a relative fining in deeper water at the flanks of the large-scale nourishment.

The finer sand fractions of a large-scale nourishment are distributed over a considerably larger (cross-shore) area than the coarser sand fractions. Typically, the coarse sand fractions are transported only in the surfzone by the wave-driven longshore current while the fine sand travels also in deeper water with the tide. A modelling approach with multiple sediment size fractions is therefore required when the transport rates or morphological changes in deeper water are investigated. It is emphasized that this is of relevance for the assessment of the environmental impact (bed composition changes $D_{50}$) of any coastal measure with a large seaward protrusion (i.e. which creates contraction of the tide). An approach with a single sediment size fraction can, however, still provide a good performance for situations where all of the sediment size fractions are suspended into the water column. For example, when the erosion volume of a (nearshore) nourishment is investigated which is mainly determined by sediment transport in the nearshore zone.

Acknowledgments

The European Research Council of the European Union is acknowledged for the funding provided for this research by the ERC-advanced Grant 291206-NEMO.

This research is additionally supported through the NatureCoast project (no. 12686) by the Dutch Technology Foundation STW, which is part of the Netherlands Organisation for Scientific Research (NWO), and which is partly funded by the Ministry of Economic Affairs. This research is additionally supported by the Dutch Technology Foundation STW Grant 12686: Nature-driven Nourishments of Coastal Systems (NatureCoast). The STW foundation is part of the Netherlands Organisation for Scientific Research (NWO), which is partly funded by the Dutch Ministry of Economic Affairs. Sampling data for the years 2010, 2012 and October 2013 were collected with support of the European Fund for Regional Development (EFRO) which was taken care of by Jeroen Wijisman of IMARES and Pieter-Koen Tommon of Deltares. Jelle van der Zwaag is acknowledged for exploring the potential for assessing sediment sorting within Delft3D models.

References


Appendix A. Validation of modelled hydrodynamics

Modeled wave conditions matched well with wave buoy measurements at 11m water depth ($x=70.7$ and $y=451.8$ km in RD coordinates) for the 2011-2012 winter period (Figure A.1). Small deviations were noticeable during quiet conditions with wind from land. These mild conditions are, however, not expected to be very relevant for the large-scale morphological changes.

![Wave Height](image1)

**Figure A.1:** Computed and measured significant wave height ($H_{m0}$), period ($T_{m0}$) and direction at the location of the wave buoy for the 2011-2012 winter period.

Modeled current velocities were validated with measurements at ADCP stations E and F, which were located respectively 1.5 and 3 km North of the Sand Motor (Figure 4) respectively in 5m and 8m water depth in the August 2012 validation period. Reference is also made to Luijendijk et al. (2017) who also validated currents at ADCP F. Current velocities were well represented at both stations (Figure A.2), which provides confidence in the representation of the horizontal tide in the model.
Figure A.2: Computed and measured depth-averaged currents at ADCP stations E (left panel) and F (right panel).