Solving Large-Scale Dynamic Collaborative Vehicle Routing Problems
An Auction-Based Multi-Agent Approach

Los, J.

DOI
10.4233/uuid:db6851f3-0fce-4874-949b-e4fe0ec1cadd

Publication date
2021

Document Version
Final published version

Citation (APA)

Important note
To cite this publication, please use the final published version (if applicable).
Please check the document version above.

Copyright
Other than for strictly personal use, it is not permitted to download, forward or distribute the text or part of it, without the consent of the author(s) and/or copyright holder(s), unless the work is under an open content license such as Creative Commons.

Takedown policy
Please contact us and provide details if you believe this document breaches copyrights.
We will remove access to the work immediately and investigate your claim.
Solving Large-Scale Dynamic Collaborative Vehicle Routing Problems
An Auction-Based Multi-Agent Approach

Johan Los holds an MSc degree in Artificial Intelligence from the University of Groningen. He conducted his PhD research at the Department of Maritime and Transport Technology of Delft University of Technology as part of the NWO iCAVE project "Dynamic Fleet Management".